Chapter 2: Multi-armed Bandits

2.1 A k-armed Bandit Problem

game rule

- k options, each has a random numerical reward
- **objective**: maximize expected total reward over time

2.2 Action-value Methods

Sample-average method

$$Q_t(a) \doteq \frac{\text{sum of rewards when } a \text{ taken prior to } t}{\text{number of times } a \text{ taken prior to } t} = \frac{\sum_{i=1}^{t-1} R_i \cdot 1_{A_i = a}}{\sum_{i=1}^{t-1} 1_{A_i = a}}$$

 $Q_t(a)$ converges to $q_st(a)$ when the denominator goes to infinity.

• greedy action method

$$A_t \doteq rg \max_x Q_t(a)$$

No exporation, only exploitation

• ϵ -greedy action method

With probability ϵ , choose an action randomly equiprobably.

2.3 The 10-armed Testbed

 ϵ -greedy betters off greedy when:

- reward variance is large
- reward is nonstationary

2.4 Incremental Implementation

$$egin{aligned} Q_{n+1} &= rac{1}{n} \sum_{i=1}^n R_i \ &= rac{1}{n} \Biggl(R_n + (n-1) rac{1}{n-1} \sum_{i=1}^{n-1} R_i \Biggr) \ &= rac{1}{n} (R_n + (n-1) Q_n) \ &= Q_n + rac{1}{n} [R_n - Q_n] \end{aligned}$$

The general form of it is:

 $NewEstimate \leftarrow OldEstimate + StepSize[Target - OldEstimate]$

The expression [Target - OldEstimate] is an *error* in the estimate.

StepSize is denoted as α or $\alpha_t(a)$.

2.5 Tracking a Nonstationary Problem

If we take constant StepSize $\alpha \in (0,1]$, we have:

$$Q_{n+1} \doteq Q_n + \alpha [R_n - Q_n]$$

And thus

$$Q_{n+1} = Q_n + \alpha [R_n - Q_n]$$

$$= \alpha R_n + (1 - \alpha)Q_n$$

$$= \alpha R_n + (1 - \alpha)\alpha R_{n-1} + (1 - \alpha)^2 Q_{n-1}$$
...
$$= (1 - \alpha)^n Q_1 + \sum_{i=1}^n \alpha (1 - \alpha)^{n-i} R_i$$

In this case, Q_{n+1} is called an *exponential recency-weighted average* of past rewards and Q_1 .

$\{lpha_n(a)\}$ convergence condition

A well-known result in stochastic approximation theory gives us the conditions required to assure convergence with probability 1:

$$\sum_{n=1}^{\infty}lpha_n(a)=\infty \ \ ext{and} \ \ \sum_{n=1}^{\infty}lpha_n^2(a)<\infty$$

- The first condition is required to guarantee that the steps are large enough to eventually overcome any initial conditions or random fluctuations.
- The second condition guarantees that eventually the steps become small enough to assure convergence.
- 1. In sample average method, $\alpha_n(a) = \frac{1}{n}$ is bound to converge.
- 2. Constant $\alpha_n(a) = \alpha$ may not converge, but can respond to changes in nonstationary setup well. *Nonstationary problems are common in RL.*