```
> restart:
  with(linalg):
  with (Linear Algebra):
  with(DifferentialGeometry):
  with (Tools):
  with(PDEtools, casesplit, declare):
  with(DEtools, gensys):
   interface(rtablesize=infinity):
DGsetup([x,y,z,p], [c,g1,g3],
           Variete_groupe_coordonnees):
  declare(F(x,y,z,p));
                     F(x, y, z, p) will now be displayed as F
                                                                       (1)
> Fp := diff(F(x,y,z,p), p);
  Fpp := diff(F(x,y,z,p), p,p);
  Fxy := diff(F(x,y,z,p), x,y);
                               Fp := F_p
                              Fpp := F_{p,p}
                              Fxy := F_{x, y}
                                                                       (2)
> ## INTRODUCE A BASIC INITIAL COFRAME
   ## L := evalDG(dz-p*dx-F(x,y,z,p)*dy);
   ## M := evalDG(dp);
   ## N1 := evalD\hat{\mathbf{G}}(\mathbf{dx} + \mathbf{Fp} * \mathbf{dy});
   ## N2 := evalDG(Fpp*dy);
> ## INTRODUCE A BASIC INITIAL COFRAME
  L := evalDG(dz-p*dx-(1/2)*p^2*dy);
  M := evalDG(dp);
  N1 := evalDG(dx+p*dy);
  N2 := evalDG(dy);
                        L := -p \, dx - \frac{p^2 \, dy}{2} + dz
                               M := dp
                            N1 := dx + p dy
                               N2 := dy
                                                                       (3)
```

> Ginverse := inverse(G);
$$Ginverse := \begin{bmatrix} \frac{1}{glc} & 0 & 0 & 0 \\ 0 & \frac{1}{c} & 0 & 0 \\ \frac{g3}{gl^2} & 0 & \frac{1}{gl} & 0 \\ -\frac{cg3^2}{2gl^3} & 0 & -\frac{cg3}{gl^2} & \frac{c}{gl} \end{bmatrix}$$
(5)

$$dG := evalDG(ExteriorDerivative(G));$$

$$dG := \begin{bmatrix} g1 dc + c dg1 & 0 dx & 0 dx & 0 dx \\ 0 dx & dc & 0 dx & 0 dx \\ -g3 dc - c dg3 & 0 dx & dg1 & 0 dx \\ -\frac{g3^2 dc}{2 g1} + \frac{g3^2 c dg1}{2 g1^2} - \frac{g3 c dg3}{g1} & 0 dx & dg3 - \frac{g1 dc}{c^2} + \frac{dg1}{c} \end{bmatrix}$$
(6)

$$MC := evalDG(dG.Ginverse);$$

$$\begin{bmatrix}
\frac{dc}{c} + \frac{dgl}{gl} & 0 \, dx & 0 \, dx & 0 \, dx \\
0 \, dx & \frac{dc}{c} & 0 \, dx & 0 \, dx
\end{bmatrix}$$

$$-\frac{g3 \, dc}{gl \, c} + \frac{g3 \, dgl}{gl^2} - \frac{dg3}{gl} & 0 \, dx & \frac{dgl}{gl} & 0 \, dx
\end{bmatrix}$$

$$0 \, dx & 0 \, dx & \frac{g3 \, dc}{gl \, c} - \frac{g3 \, dgl}{gl^2} + \frac{dg3}{gl} - \frac{dc}{c} + \frac{dgl}{gl}$$

$$0 \, dx & 0 \, dx & \frac{g3 \, dc}{gl \, c} - \frac{g3 \, dgl}{gl^2} + \frac{dg3}{gl} - \frac{dc}{c} + \frac{dgl}{gl}$$

> oldcoframe := Vector([L,M,N1,N2]);

$$oldcoframe := \begin{bmatrix} -p \ dx - \frac{p^2 \ dy}{2} + dz \\ dp \\ dx + p \ dy \\ dy \end{bmatrix}$$
 (8)

```
> newcoframe := evalDG(G.oldcoframe);

newcoframe :=

-c g I p dx - \frac{c g I p^2 dy}{2} + c g I dz
c dp
(c g 3 p + g I) dx + \left(g I p + \frac{1}{2} c g 3 p^2\right) dy - c g 3 dz
\frac{g 3 (c g 3 p + 2 g I) dx}{2 g I} + \frac{\left(c^2 g 3^2 p^2 + 4 c g I g 3 p + 4 g I^2\right) dy}{4 c g I} - \frac{g 3^2 c dz}{2 g I}
```

> AA := MC[3,3];
BB := MC[2,2];
CC := MC[2,1];
DD := MC[3,1];
SS := MC[4,1];
TT := MC[4,3];
L1 := newcoframe[1];
M1 := newcoframe[3];
N21 := newcoframe[4];

$$AA := \frac{dgl}{gl}$$

$$BB := \frac{dc}{c}$$

$$DD := -\frac{g3 dc}{gl c} + \frac{g3 dgl}{gl^2} - \frac{dg3}{gl}$$

$$Ll := -c gl p dx - \frac{c gl p^2 dy}{2} + c gl dz$$

$$Ml := c dp$$

$$Nll := (c g3 p + gl) dx + \left(gl p + \frac{1}{2} c g3 p^2\right) dy - c g3 dz$$

$$N2l := \frac{g3 (c g3 p + 2 gl) dx}{2 gl} + \frac{(c^2 g3^2 p^2 + 4 c gl g3 p + 4 gl^2) dy}{4 c gl} - \frac{g3^2 c dz}{2 gl}$$
(10)

> coframeloop1 := FrameData([AA,BB,DD,Ll,Ml,N11,N21],coframe1): > DGsetup(coframeloop1, [E], [aa,bb,dd,lambda,mu,nu[1],nu[2]], verbose); The following coordinates have been protected: [x, y, z, p, c, g1, g3]The following vector fields have been defined and protected: [E1, E2, E3, E4, E5, E6, E7] The following differential 1-forms have been defined and protected: $[aa, bb, dd, \lambda, \mu, v_1, v_2]$ frame name: coframe1 (11)> dlambda:=evalDG(ExteriorDerivative(lambda)) $dlambda := aa \wedge \lambda + bb \wedge \lambda + \frac{g3 \lambda}{g1} \wedge \mu - \mu \wedge \nu_1$ (12)dmu := evalDG(ExteriorDerivative(mu)); $dmu := bb \wedge u$ (13)> dnu1 := evalDG(ExteriorDerivative(nu[1])); $dnu1 := aa \wedge v_1 + dd \wedge \lambda - \frac{g3^2 \lambda}{2 gI^2} \wedge \mu + \mu \wedge v_2$ (14)> dnu2 := evalDG(ExteriorDerivative(nu[2])); $dnu2 := aa \wedge v_2 - bb \wedge v_2 - dd \wedge v_1 - \frac{g3^2 \mu}{2 gI^2} \wedge v_1 + \frac{g3 \mu}{gI} \wedge v_2$ (15)VERY CRUCIAL STEP: DEFINE DUAL VECTOR FIELD OF THE (COFRAME := > ### MAPLE DOES NOT ALLOW ABSORPTION DIRECTLY BY 1-FORMS ### ABSORPTION HAVE TO BE DONE BY (VECTOR FIELDS := DB $cobasis := \left[\frac{dgl}{gl}, \frac{dc}{c}, -\frac{g3 dc}{gl c} + \frac{g3 dgl}{gl^2} - \frac{dg3}{gl}, -c gl p dx - \frac{c gl p^2 dy}{2} + c gl dz, \right]$ (16)

```
c dp, (c g3 p + g1) dx + \left(g1 p + \frac{1}{2} c g3 p^{2}\right) dy - c g3 dz, \frac{g3 (c g3 p + 2 g1) dx}{2 g1} + \frac{\left(c^{2} g3^{2} p^{2} + 4 c g1 g3 p + 4 g1^{2}\right) dy}{4 c g1} - \frac{g3^{2} c dz}{2 g1}
```

> DB:=DualBasis(cobasis)

$$DB := \left[gl \ D_gl + g3 \ D_g3, c \ D_c - g3 \ D_g3, -gl \ D_g3, \frac{g3 \ (c \ g3 \ p + 2 \ gl) \ D_x}{2 \ gl^3} \right]$$

$$- \frac{c \ g3^2 \ D_y}{2 \ gl^3} + \frac{(c \ g3 \ p + 2 \ gl)^2 \ D_z}{4 \ c \ gl^3}, \frac{D_p}{c}, \frac{(c \ g3 \ p + gl) \ D_x}{gl^2} - \frac{c \ g3 \ D_y}{gl^2}$$

$$+ \frac{(c \ g3 \ p + 2 \ gl) \ p \ D_z}{2 \ gl^2}, - \frac{c \ p \ D_x}{gl} + \frac{c \ D_y}{gl} - \frac{c \ p^2 \ D_z}{2 \ gl} \right]$$

```
Dlambda := A_1 gl D_g l + g3 D_g 3 + B_1 c D_c - g3 D_g 3 + D_1 - g1 D_g 3
   + \frac{g3 (c g3 p + 2 g1) D_{x}}{2 g1^{3}} - \frac{c g3^{2} D_{y}}{2 g1^{3}} + \frac{(c g3 p + 2 g1)^{2} D_{z}}{4 c g1^{3}}
     Dmu := A_2 gl D_g l + g3 D_g 3 + B_2 c D_c - g3 D_g 3 + D_2 - g1 D_g 3 + \frac{D_p}{c}
Dnu1 := A_3 \ g1 \ D\_g1 + g3 \ D\_g3 + B_3 \ c \ D\_c - g3 \ D\_g3 + D_3 \ -g1 \ D\_g3
    + \frac{(c g3 p + g1) D_{x}}{g1^{2}} - \frac{c g3 D_{y}}{g1^{2}} + \frac{(c g3 p + 2 g1) p D_{z}}{2 g1^{2}}
Dnu2 := A_4 gl D_g l + g 3 D_g 3 + B_4 c D_c - g 3 D_g 3 + D_4 - g l D_g 3 + - \frac{c p D_x}{\sigma l}
                                                                             (19)
   +\frac{cD_y}{gl}-\frac{cp^2D_z}{2gl}
  > LTensor := [
  Hook([DB[4],DB[5]],ExteriorDerivative(L1)),
  Hook([DB[4],DB[6]],ExteriorDerivative(L1)),
  Hook([DB[4],DB[7]],ExteriorDerivative(L1)),
  Hook([DB[5],DB[6]],ExteriorDerivative(L1)),
  Hook([DB[5],DB[7]],ExteriorDerivative(L1)),
  Hook([DB[6],DB[7]],ExteriorDerivative(L1))];
  MTensor :=[
  Hook([DB[4],DB[5]],ExteriorDerivative(M1)),
  Hook([DB[4],DB[6]],ExteriorDerivative(M1)),
  Hook([DB[4],DB[7]],ExteriorDerivative(M1)),
  Hook([DB[5],DB[6]],ExteriorDerivative(M1)),
  Hook([DB[5],DB[7]],ExteriorDerivative(M1)),
  Hook([DB[6],DB[7]],ExteriorDerivative(Ml))];
  N1Tensor :=[
  Hook([DB[4],DB[5]],ExteriorDerivative(N11)),
  Hook([DB[4],DB[6]],ExteriorDerivative(N11)),
  Hook([DB[4],DB[7]],ExteriorDerivative(N11)),
  Hook([DB[5],DB[6]],ExteriorDerivative(N11)),
  Hook([DB[5],DB[7]],ExteriorDerivative(N11)),
  Hook([DB[6],DB[7]],ExteriorDerivative(N11))];
  N2Tensor:= [
  Hook([DB[4],DB[5]],ExteriorDerivative(N21)),
  Hook([DB[4],DB[6]],ExteriorDerivative(N21)),
  Hook([DB[4],DB[7]],ExteriorDerivative(N21)),
  Hook([DB[5],DB[6]],ExteriorDerivative(N21)),
  Hook([DB[5],DB[7]],ExteriorDerivative(N21)),
  Hook([DB[6],DB[7]],ExteriorDerivative(N21))];
```

```
LTensor := \left[ \frac{g^3}{gI}, 0, 0, -1, 0, 0 \right]
MTensor := \left[ 0, 0, 0, 0, 0, 0 \right]
NITensor := \left[ -\frac{g^3}{2gI^2}, 0, 0, 0, 1, 0 \right]
N2Tensor := \left[ 0, 0, 0, -\frac{g^3}{2gI^2}, \frac{g^3}{gI}, 0 \right]
(20)
```

```
LTensorm := [Hook([Dlambda,Dmu],ExteriorDerivative(L1)),
 Hook([Dlambda,Dnu1],ExteriorDerivative(L1)),
 Hook([Dlambda,Dnu2],ExteriorDerivative(L1)),
 Hook([Dmu,Dnul],ExteriorDerivative(Ll)),
 Hook([Dmu,Dnu2],ExteriorDerivative(L1)),
 Hook([Dnu1,Dnu2],ExteriorDerivative(L1));
 MTensorm := [Hook([Dlambda,Dmu],ExteriorDerivative(Ml)),
 Hook([Dlambda,Dnu1],ExteriorDerivative(M1)),
 Hook([Dlambda,Dnu2],ExteriorDerivative(M1)),
 Hook([Dmu,Dnul],ExteriorDerivative(Ml)),
 Hook([Dmu,Dnu2],ExteriorDerivative(M1)),
 Hook([Dnu1,Dnu2],ExteriorDerivative(M1))];
 N1Tensorm := [Hook([Dlambda,Dmu],ExteriorDerivative(N11)),
 Hook([Dlambda,Dnu1],ExteriorDerivative(N11)),
 Hook([Dlambda,Dnu2],ExteriorDerivative(N11)),
 Hook([Dmu,Dnul],ExteriorDerivative(N11)),
 Hook([Dmu,Dnu2],ExteriorDerivative(N11)),
 Hook([Dnu1,Dnu2],ExteriorDerivative(N11))];
 N2Tensorm := [Hook([Dlambda,Dmu],ExteriorDerivative(N21)),
 Hook([Dlambda,Dnu1],ExteriorDerivative(N21)),
 Hook([Dlambda,Dnu2],ExteriorDerivative(N21)),
 Hook([Dmu,Dnu1],ExteriorDerivative(N21)),
 Hook([Dmu,Dnu2],ExteriorDerivative(N21)),
 Hook([Dnu1,Dnu2],ExteriorDerivative(N21))];
        LTensorm := \left[ -\frac{A_2 gI + B_2 gI - g3}{gI}, -A_3 - B_3, -A_4 - B_4, -1, 0, 0 \right]
                      \mathit{MTensorm} := [B_1, 0, 0, -B_3, -B_4, 0]
           \textit{N1Tensorm} := \left[ -\frac{2 \, g I^2 \, \mathbf{D}_2 + g 3^2}{2 \, g I^2}, A_1 - \mathbf{D}_3, \, -\mathbf{D}_4, A_2, \, 1, \, -A_4 \right]
\textit{N2Tensorm} := \left[0, -D_1, A_1 - B_1, -\frac{2 g l^2 D_2 + g 3^2}{2 g l^2}, \frac{A_2 g l - B_2 g l + g 3}{g l}, A_3 - B_3 + D_4\right]
```

> Tensors := [op(LTensor), op(MTensor), op(N1Tensor), op(N2Tensor)]
$$Tensors := \left[\frac{g3}{gI}, 0, 0, -1, 0, 0, 0, 0, 0, 0, 0, 0, -\frac{g3^2}{2gI^2}, 0, 0, 0, 1, 0, 0, 0, 0, -\frac{g3^2}{2gI^2}, \frac{g3}{gI}, 0 \right]$$
 (22)

(N2Tensorm)]
$$eqabsorb := \left[-\frac{A_2 gl + B_2 gl - g3}{gl}, -A_3 - B_3, -A_4 - B_4, -1, 0, 0, B_1, 0, 0, -B_3, -B_4, 0, -\frac{2 gl^2 D_2 + g3^2}{2 gl^2}, A_1 - D_3, -D_4, A_2, 1, -A_4, 0, -D_1, A_1 - B_1, -\frac{2 gl^2 D_2 + g3^2}{2 gl^2}, -\frac{A_2 gl - B_2 gl + g3}{gl}, A_3 - B_3 + D_4 \right]$$
(23)

eqabsorb := [op(LTensorm), op(MTensorm), op(N1Tensorm), op

> nops(eqabsorb);
24 (24)
> for i from 1 to nops(eqabsorb) do
expand(eqabsorb[i]=0)
od;

$$-A_2 - B_2 + \frac{g^3}{gI} = 0$$

$$-A_3 - B_3 = 0$$

$$-A_4 - B_4 = 0$$

$$-1 = 0$$

$$0 = 0$$

$$0 = 0$$

$$0 = 0$$

$$B_1 = 0$$

$$0 = 0$$

$$0 = 0$$

$$-B_3 = 0$$

$$-B_4 = 0$$

$$0 = 0$$

$$-D_2 - \frac{g3^2}{2 g I^2} = 0$$

$$A_1 - D_3 = 0$$

$$-D_4 = 0$$

$$A_2 = 0$$

$$1 = 0$$

$$-A_4 = 0$$

$$0 = 0$$

$$-D_1 = 0$$

$$A_1 - B_1 = 0$$

$$-D_2 - \frac{g3^2}{2 g I^2} = 0$$

$$A_2 - B_2 + \frac{g3}{gI} = 0$$

$$A_3 - B_3 + D_4 = 0$$
(25)

```
[0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -1, 0, 0, 0]
 [0, -1, 0, 0, 0, 0, 0, 0, -1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -1],
 [0, 0, -1, 0, 0, 0, 0, 0, 0, -1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
 [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -1, 0, 0, 0, 0, 0, 0, 0, 0, -1, 0, 0]
 [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
 > noyau := kernel(ABS Eqst)
(27)
 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0
 for ii from 1 to nops(noyau) do
 LC[ii] := convert(op(ii,noyau), list, nested=false)
    LC_3 := [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -1, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0]
   LC_5 := [0, 1, 0, 0, 0, 0, 0, 0, 0, -2, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 1]
```

> Tensorv := convert(Tensors, Vector);

(29)

```
\frac{g3}{g1}
                     0
                      0
                     -1
                      0
                      0
                      0
                      0
                      0
                      0
                      0
Tensorv :=
                    2g\overline{l^2}
                      0
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                      0
                      1
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                      0
                      0
```

(29)

```
0
-1
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```

> ABS_Eqs := genmatrix(eqabsorb, variables)

(31)

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```

```
|> ##
|> ## SET UP THE MATRIX THE DESCRIBES THE EQUATION OF ABSORPTION
|> ##
```

> Total := augment(ABS_Eqs, Tensors)

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\frac{g3}{g1}
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```

(32)

```
> Totale := gausselim(Total)
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| > ##
| > ## NEXT: TO REMOVE THE INCONSISTENCIES IN LINEAR EQUATION BY
| REMOVING LAST FEW ROWS
| > ## M1 IS NOT A Matrix, PROCEED WITH CONVERSION
| > ##
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> M1 := convert(Totale, Matrix)
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type(M1,Matrix)
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> ## > ## SOLVE ABSORPTION EQUATION > ##

> ABSOL := LinearSolve(M1coh)

$$ABSOL := \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ -\frac{g^3}{gl} \\ 0 \\ 0 \\ 0 \\ \frac{g^3^2}{2 g l^2} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$
(37)

> whattype(ABSOL)

Vector column (38)> ABSOLa:= convert(ABSOL,Array) (39)(40)PROCEED WITH ABSORPTION BY VECTOR FIELDS ADlambda := -ABSOLa[1]*DB[1]-ABSOLa[5]*DB[2]-ABSOLa[9]*DB[3]+DB[4]; -ABSOLa[2]*DB[1]-ABSOLa[6]*DB[2]-ABSOLa[10]*DB[3]+DB[5] ADnu1 := -ABSOLa[3]*DB[1]-ABSOLa[7]*DB[2]-ABSOLa[11]*DB[3]+DB[6]ADnu2 := -ABSOLa[4]*DB[1]-ABSOLa[8]*DB[2]-ABSOLa[12]*DB[3]+DB[7]ADaa := g1 D g1 + g3 D g3ADbb := cD c - g3D g3 $ADlambda := \frac{g3 (c g3 p + 2 g1) D_x}{2 g1^3} - \frac{c g3^2 D_y}{2 g1^3} + \frac{(c g3 p + 2 g1)^2 D_z}{4 c g1^3}$ $ADmu := \frac{g3 c D_c - g3 D_g3}{g1} - \frac{g3^2 - g1 D_g3}{2g1^2} + \frac{D_p}{c}$ $ADnul := \frac{(c g3 p + g1) D_x}{gl^2} - \frac{c g3 D_y}{gl^2} + \frac{(c g3 p + 2 g1) p D_z}{2 gl^2}$ $ADnu2 := -\frac{c p D_x}{gl} + \frac{c D_y}{gl} - \frac{c p^2 D_z}{2 gl}$ (41)

> Sfinal := [ADaa, ADbb, ADdd, ADlambda, ADmu, ADnu1, ADnu2] $Sfinal := \left[gl \ D_gl + g3 \ D_g3, c \ D_c - g3 \ D_g3, -gl \ D_g3, \frac{g3 \ (c \ g3 \ p + 2 \ gl) \ D_x}{2 \ gl^3} \right]$ (42)

$$-\frac{c\,g3^2\,D__y}{2\,g\,l^3} + \frac{(c\,g3\,p + 2\,g\,l)^2\,D__z}{4\,c\,g\,l^3}, \frac{g3\,c\,D__c - g3\,D__g3}{g\,l} - \frac{g3^2\,-g\,l\,D__g3}{2\,g\,l^2} + \frac{D__p}{c}, \frac{(c\,g3\,p + g\,l)\,D__x}{g\,l^2} - \frac{c\,g3\,D__y}{g\,l^2} + \frac{(c\,g3\,p + 2\,g\,l)\,p\,D__z}{2\,g\,l^2}, -\frac{c\,p\,D__x}{g\,l} + \frac{c\,D__y}{g\,l} - \frac{c\,p^2\,D__z}{2\,g\,l}$$

> Bfinal := evalDG(DualBasis(Sfinal))

$$Bfinal := \left[\frac{dgl}{gl}, -\frac{g3 c dp}{gl} + \frac{dc}{c}, \frac{g3^2 c dp}{2 gl^2} - \frac{g3 dc}{gl c} + \frac{g3 dgl}{gl^2} - \frac{dg3}{gl}, -c gl p dx \right]$$

$$-\frac{c gl p^2 dy}{2} + c gl dz, c dp, (c g3 p + gl) dx + \frac{(c g3 p + 2 gl) p dy}{2} - c g3 dz,$$

$$\frac{g3 (c g3 p + 2 gl) dx}{2 gl} + \frac{(c g3 p + 2 gl)^2 dy}{4 gl c} - \frac{g3^2 c dz}{2 gl}$$

> ESTRUCTURE := FrameData(Bfinal, final)

$$ESTRUCTURE := \begin{bmatrix} d \Theta l = 0, d \Theta 2 = \Theta 3 \land \Theta 5, d \Theta 3 = -\Theta 2 \land \Theta 3, d \Theta 4 = \Theta 1 \land \Theta 4 \\ + \Theta 2 \land \Theta 4 - \Theta 5 \land \Theta 6, d \Theta 5 = \Theta 2 \land \Theta 5, d \Theta 6 = \Theta 1 \land \Theta 6 + \Theta 3 \land \Theta 4 + \Theta 5 \land \Theta 7, \\ d \Theta 7 = \Theta 1 \land \Theta 7 - \Theta 2 \land \Theta 7 - \Theta 3 \land \Theta 6 \end{bmatrix}$$

$$(44)$$