

### Facility Location.

**Theorem (p.33)** : For the local center,  $x_e$ , on an edge  $(p,q)$ ,

$$m(x_e) \geq \frac{m(p)+m(q)-c(p,q)}{2}, \quad \text{where, } c(p,q) \text{ denotes the length of } (p,q).$$

Proof: Consider a point  $x$  on  $e$  with distance  $x$  from  $p$ .  $p \bullet \text{---} |x \text{---} \bullet q$

For  $x=0$ , the point is  $p$ . For  $x=c(p,q)$  the point is  $q$ .

$$d(x,p)=x \text{ and } d(x,q)=c(p,q)-x.$$

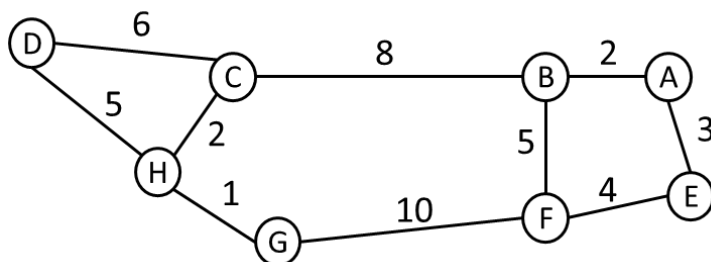
Therefore, we have  $m(p) \leq m(x)+x$  and  $m(q) \leq m(x)+c(p,q)-x$ , since it is always possible to reach  $p$  by a path to  $x$  plus  $d(p,x)$ , and it is always possible to reach  $q$  by a path to  $x$  plus  $d(x,q)$ .

Summing up the above inequations, we get  $m(q)+m(p) \leq 2m(x)+x -c(p,q)-x =2m(x)+c(p,q)$ .

The above is valid for every  $x$ , in particular, for  $x=x_e$ .

By switching sides, we get  $m(x_e) \geq \frac{m(p)+m(q)-c(p,q)}{2}$

**Example of 2-approximation to k-center (p.37)** Let  $k=3$



Assume that  $A$  is selected as a first node.

The furthest node is  $D$  – since  $d(D,A)=16$ . So  $D$  is added.

The next furthest node is  $F$  – since  $d(F,\{A,B\})=7$

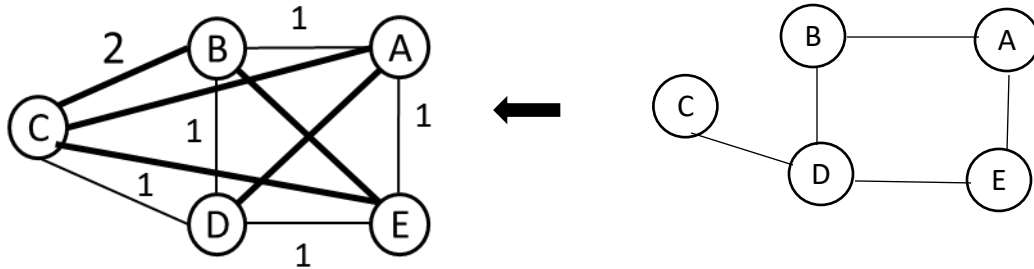
$X_3 = \{A,D,F\}$ . The value of this solution is 6 –  $d(C,X_3)=d(G,X_3)=6$ .

A better solution is  $\{B,F,H\}$  – its value is 5.

For  $k=2$ , the algorithm halts with  $\{A,D\}$ ,  $d(f,X_2)=7$ .

$OPT(k=2)=\{B,H\}$ , value =5 (achieved by  $E$  and  $F$ ).

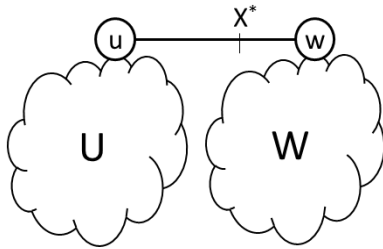
**Example - no (2-ε)-approximation (p. 40).**



**Hakimi's Theorem:** At least one optimal set of k-medians exist solely on the nodes of G (p. 43).

Proof: Assume that  $k=1$ .

Let  $x^*$  be the optimal 1-median. If  $x^*$  is a node – we are done. Otherwise,  $x^*$  is located on some edge  $(u,w)$ . Split the graph's nodes into two disjoint sets  $V=U \cup W$  such that  $v \in U$  if and only if a shortest path from  $v$  to  $x^*$  passes through  $v$  (otherwise,  $v \in W$ )



Compare  $\sum_{v \in U} h(v)$  with  $\sum_{v \in W} h(v)$ . Assume w.l.o.g. that  $\sum_{v \in U} h(v) \geq \sum_{v \in W} h(v)$ . We show that  $x^*$  can be replaced by the node  $u$  without hurting the objective function value.

$$\begin{aligned}
 J(x^*) &= \sum_{v \in V} h(v)d(v, x^*) = \sum_{v \in U} h(v)[d(v, u) + d(u, x^*)] + \sum_{v \in W} h(v)d(v, x^*) = \\
 &\quad \sum_{v \in U} h(v)d(v, u) + \sum_{v \in U} h(v)d(u, x^*) + \sum_{v \in W} h(v)d(v, x^*) \geq \\
 \text{assumption} \quad &\geq \sum_{v \in U} h(v)d(v, u) + \sum_{v \in W} h(v)d(u, x^*) + \sum_{v \in W} h(v)d(v, x^*) = \\
 &\quad \geq \sum_{v \in U} h(v)d(v, u) + \sum_{v \in W} h(v)[d(u, x^*) + d(v, x^*)] \geq \quad \text{Triangle inequality} \\
 &\geq \sum_{v \in U} h(v)d(v, u) + \sum_{v \in W} h(v)d(u, v) = \sum_{v \in V} h(v)d(u, v) = J(u).
 \end{aligned}$$

For  $k > 1$ , a similar approach works for every facility located along an edge.