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#### High Performance Modeling



#### Welcome

#### High Performance Modeling



#### Distributed Training

#### Rise in computational requirements

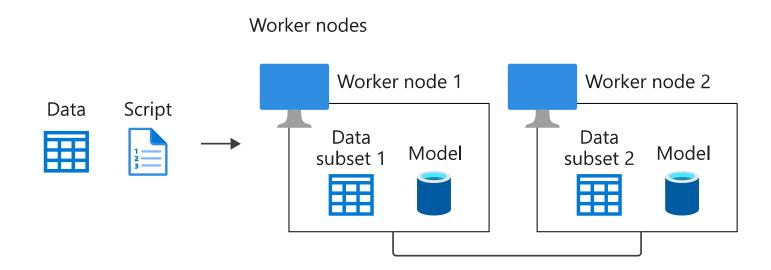
- At first, training models is quick and easy
- Training models becomes more time-consuming
  - With more data
  - With larger models
- Longer training -> More epochs -> Less efficient
- Use distributed training approaches



#### Types of distributed training

- **Data parallelism**: In data parallelism, models are replicated onto different accelerators (GPU/TPU) and data is split between them
- Model parallelism: When models are too large to fit on a single device then they can be divided into partitions, assigning different partitions to different accelerators

#### Data parallelism



#### Distributed training using data parallelism

Synchronous training

• All workers train and complete updates in sync

• Supported via all-reduce architecture

Asynchronous Training

• Each worker trains and completes updates separately

Supported via parameter server architecture

 More efficient, but can result in lower accuracy and slower convergence

#### Making your models distribute-aware

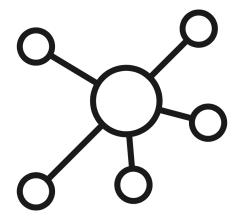
- If you want to distribute a model:
  - Supported in high-level APIs such as Keras/Estimators
  - For more control, you can use custom training loops

#### tf.distribute.Strategy

- Library in TensorFlow for running a computation in multiple devices
- Supports distribution strategies for high-level APIs like Keras and custom training loops
- Convenient to use with little or no code changes

#### Distribution Strategies supported by tf.distribute.Strategy

- One Device Strategy
- Mirrored Strategy
- Parameter Server Strategy
- Multi-Worker Mirrored Strategy
- Central Storage Strategy
- TPU Strategy



#### One Device Strategy

- Single device no distribution
- Typical usage of this strategy is testing your code before switching to other strategies that actually distribute your code

#### Mirrored Strategy

- This strategy is typically used for training on one machine with multiple GPUs
  - Creates a replica per GPU <> Variables are mirrored
  - Weight updating is done using efficient cross-device communication algorithms (all-reduce algorithms)

#### Parameter Server Strategy

- Some machines are designated as workers and others as parameter servers
  - Parameter servers store variables so that workers can perform computations on them
- Implements asynchronous data parallelism by default

#### Fault tolerance

- Catastrophic failures in one worker would cause failure of distribution strategies.
- How to enable fault tolerance in case a worker dies?
  - By restoring training state upon restart from job failure
  - Keras implementation: BackupAndRestore callback

#### **High Performance Modeling**



## High-performance Ingestion

#### Why input pipelines?

Data at times can't fit into memory and sometimes, CPUs are under-utilized in compute intensive tasks like training a complex model

You should avoid these inefficiencies so that you can make the most of the hardware available  $\rightarrow$  Use input pipelines

#### tf.data: TensorFlow Input Pipeline



Local (HDD/SSD)

Remote (GCS/HDFS)

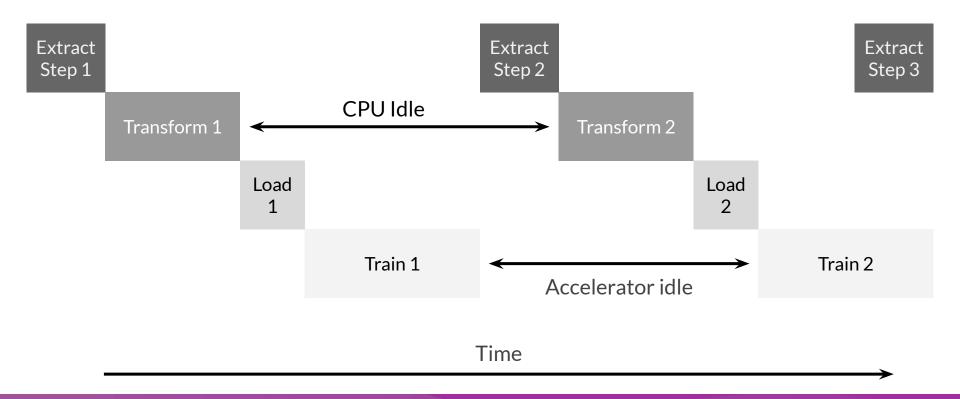
Shuffling & Batching

Decompression Augmentation Vectorization

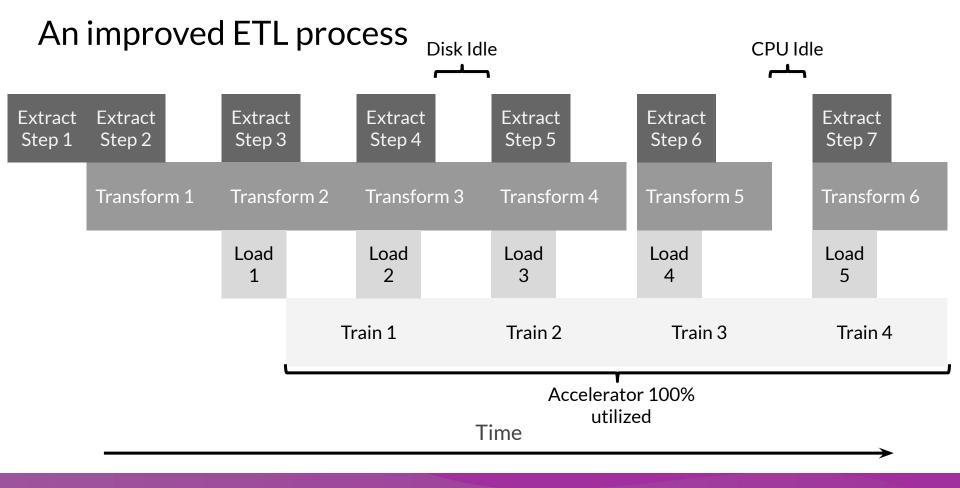
. .

Load **transformed data** to an **accelerator** 

#### Inefficient ETL process







#### Pipelining

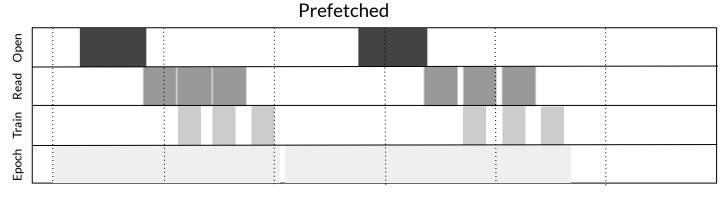
**CPU** Prepare 1 idle Prepare 2 idle Prepare 3 idle GPU/TPU idle Train 1 idle Train 2 idle Train 3 Without pipelining Time **CPU** Prepare 1 Prepare 2 Prepare 3 Prepare 4 Train 1 Train 2 Train 3 GPU/TPU idle With pipelining Time



#### How to optimize pipeline performance?

- Prefetching
- Parallelize data extraction and transformation
- Caching
- Reduce memory

#### Optimize with prefetching



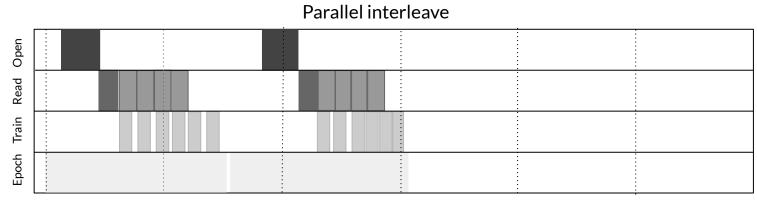
Time (s)

```
benchmark(
    ArtificialDataset()
    .prefetch(tf.data.experimental.AUTOTUNE)
)
```

#### Parallelize data extraction

- Time-to-first-byte: Prefer local storage as it takes significantly longer to read data from remote storage
- Read throughput: Maximize the aggregate bandwidth of remote storage by reading more files

#### Parallel interleave



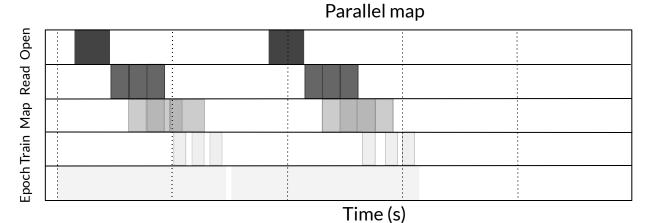
```
Time (s)
```

```
benchmark(
    tf.data.Dataset.range(2)
    .interleave(
        ArtificialDataset,
        num_parallel_calls=tf.data.experimental.AUTOTUNE
    )
)
```

#### Parallelize data transformation

- Post data loading, the inputs may need preprocessing
- Element-wise preprocessing can be parallelized across CPU cores
- The optimal value for the level of parallelism depends on:
  - Size and shape of training data
  - Cost of the mapping transformation
  - Load the CPU is experiencing currently
- With tf.data you can use AUTOTUNE to set parallelism automatically

#### Parallel mapping

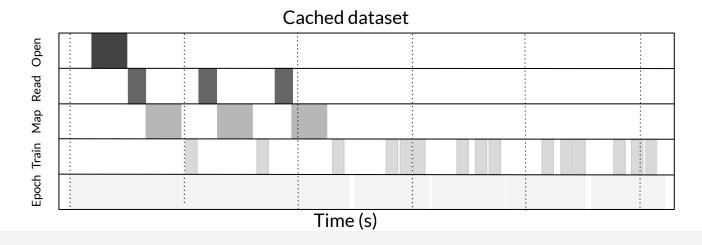


```
benchmark(
    ArtificialDataset()
    .map(
        mapped_function,
        num_parallel_calls=tf.data.AUTOTUNE
    )
)
```

#### Improve training time with caching

- In-memory: tf.data.Dataset.cache()
- Disk:tf.data.Dataset.cache(filename=...)

#### Caching



```
benchmark(
    ArtificialDataset().map(mapped_function).cache(),5
)
```

#### High performance modeling



# Training Large Models The Rise of Giant Neural Nets and Parallelism

#### Rise of giant neural networks

- In 2014, the ImageNet winner was GoogleNet with 4 mil. parameters and scoring a 74.8% top-1 accuracy
- In 2017, Squeeze-and-excitation networks achieved 82.7% top-1 accuracy with 145.8 mil. Parameters

36 fold increase in the number of parameters in just 3 years!

#### Issues training larger networks

- GPU memory only increased by factor ~ 3
- Saturated the amount of memory available in Cloud TPUs
- Need for large-scale training of giant neural networks

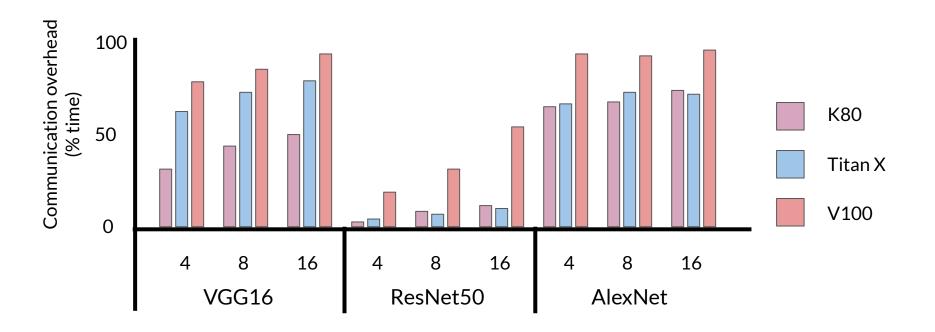
#### Overcoming memory constraints

- Strategy #1 Gradient Accumulation
  - Split batches into mini-batches and only perform backprop after whole batch
- Strategy #2 Memory swap
  - Copy activations between CPU and memory, back and forth

#### Parallelism revisited

- Data parallelism: In data parallelism, models are replicated onto different accelerators (GPU/TPU) and data is split between them
- Model parallelism: When models are too large to fit on a single device then they can be divided into partitions, assigning different partitions to different accelerators

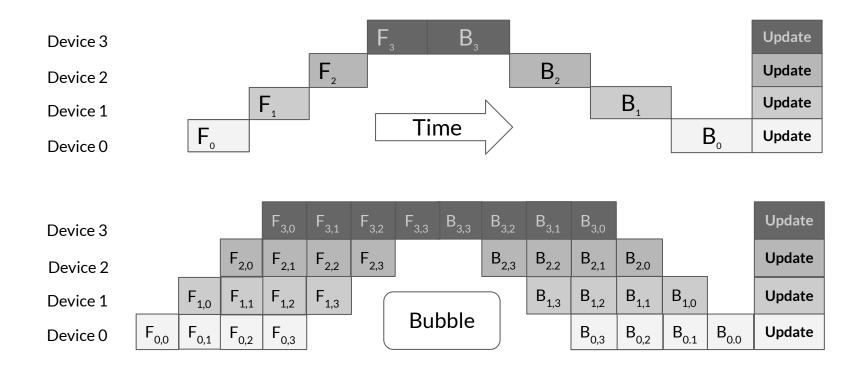
#### Challenges in data parallelism



#### Challenges keeping accelerators busy

- Accelerators have limited memory
- Model parallelism: large networks can be trained
  - But, accelerator compute capacity is underutilized
- Data parallelism: train same model with different input data
  - But, the maximum model size an accelerator can support is limited

#### Pipeline parallelism



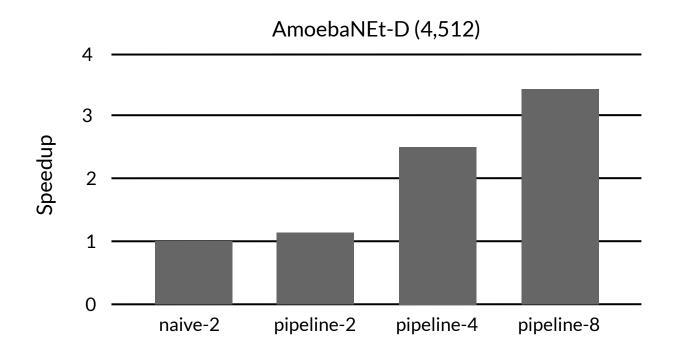
#### Pipeline parallelism

- Integrates both data and model parallelism:
  - Divide mini-batch data into micro-batches
  - Different workers work on different micro-batches in parallel
  - Allow ML models to have significantly more parameters

#### GPipe - Key features

- Open-source TensorFlow library (using Lingvo)
- Inserts communication primitives at the partition boundaries
- Automatic parallelism to reduce memory consumption
- Gradient accumulation across micro-batches, so that model quality is preserved
- Partitioning is heuristic-based

#### **GPipe Results**





# **Knowledge Distillation**



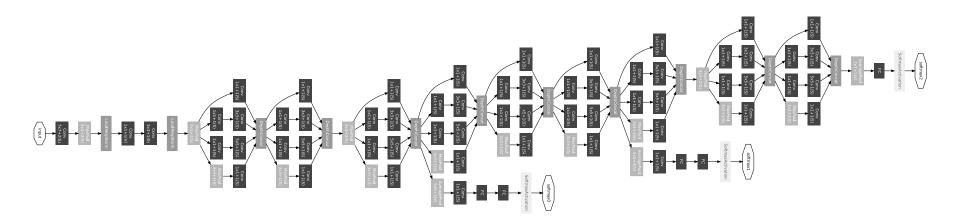
# Teacher and Student Networks

#### Sophisticated models and their problems

- Larger sophisticated models become complex
- Complex models learn complex tasks
- Can we express this learning more efficiently?

Is it possible to 'distill' or concentrate this complexity into smaller networks?

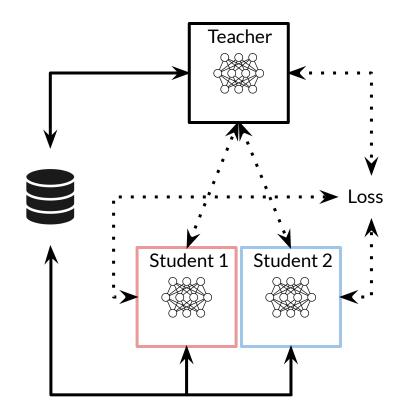
## GoogLeNet



#### Knowledge distillation

 Duplicate the performance of a complex model in a simpler model

 Idea: Create a simple 'student' model that learns from a complex 'teacher' model



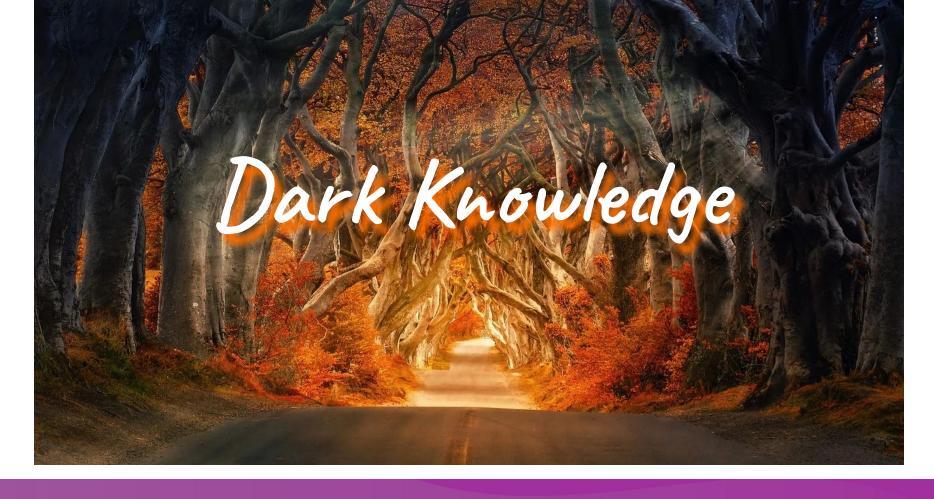
# **Knowledge Distillation**



# Knowledge Distillation Techniques

#### Teacher and student

- Training objectives of the models vary
- Teacher (normal training)
  - maximizes the actual metric
- Student (knowledge transfer)
  - matches p-distribution of the teacher's predictions to form 'soft targets'
  - 'Soft targets' tell us about the knowledge learned by the teacher



### Transferring "dark knowledge" to the student

 Improve softness of the teacher's distribution with 'softmax temperature' (T)

 As T grows, you get more insight about which classes the teacher finds similar to the predicted one

$$p_i = \frac{\exp\left(\frac{z_i}{T}\right)}{\sum_j \exp\left(\frac{z_j}{T}\right)}$$

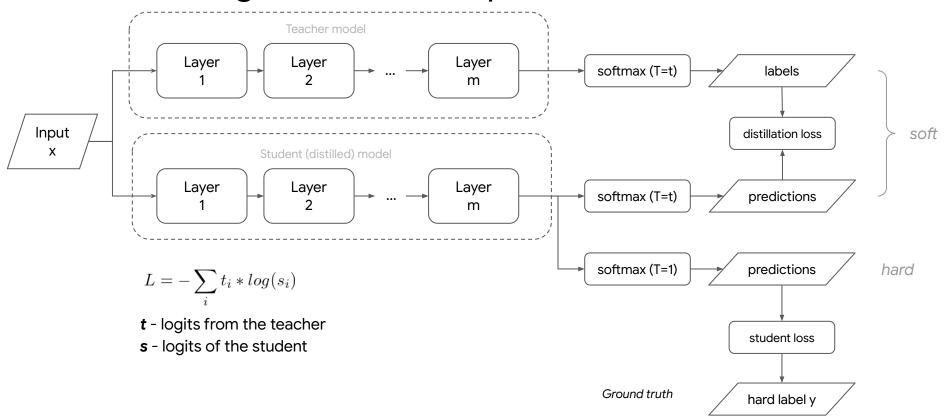
#### **Techniques**

- Approach #1: Weigh objectives (student and teacher) and combine during backprop
- Approach #2: Compare distributions of the predictions (student and teacher) using KL divergence

#### KL divergence

$$L = (1 - \alpha) L_H + \alpha L_{KL}$$

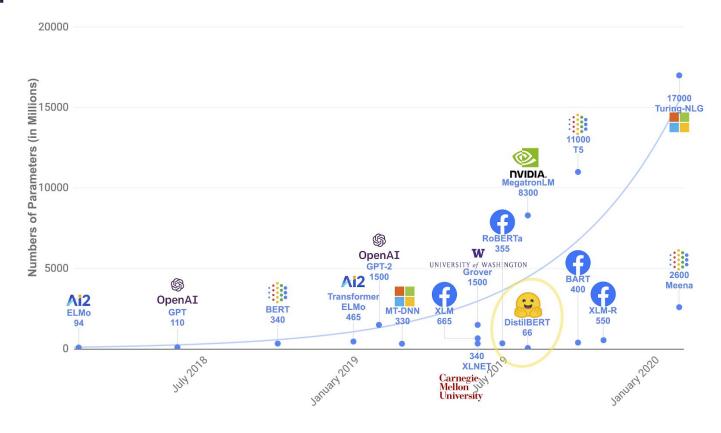
#### How knowledge transfer takes place



#### First quantitative results of distillation

Model	Accuracy	Word Error Rate (WER)
Baseline	58.9%	10.9%
10x Ensemble	61.1%	10.7%
Distilled Single Model	60.8%	10.7%

#### **DistilBERT**

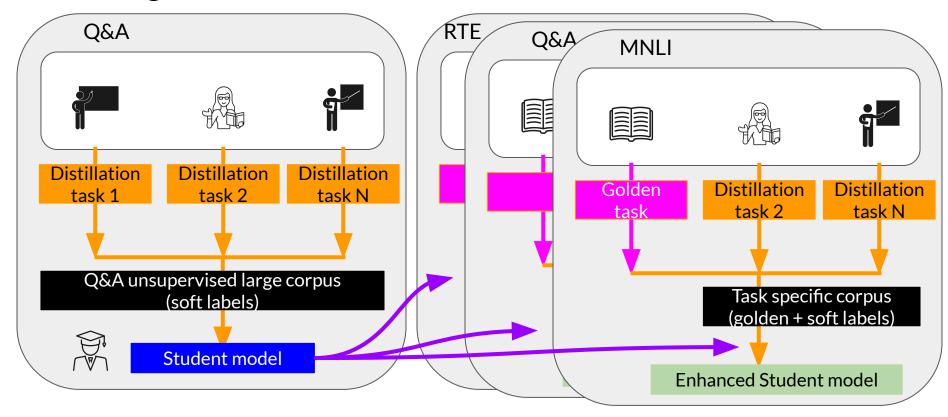


# **Knowledge Distillation**

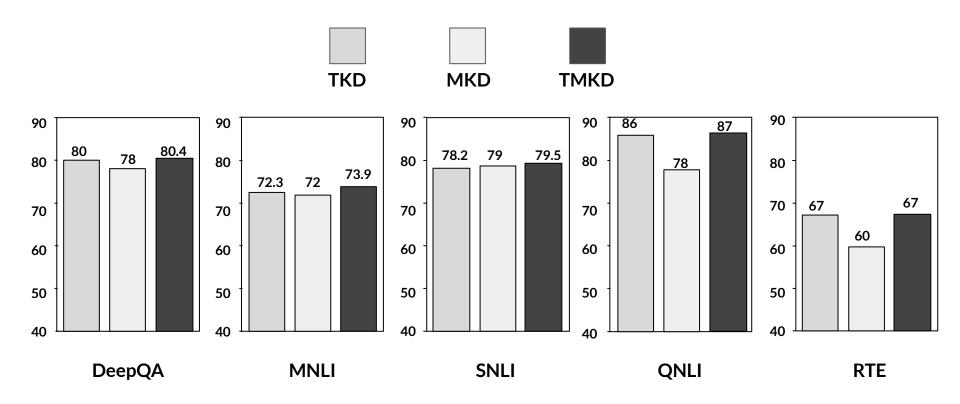


Case Study - How to Distill Knowledge for a Q&A Task

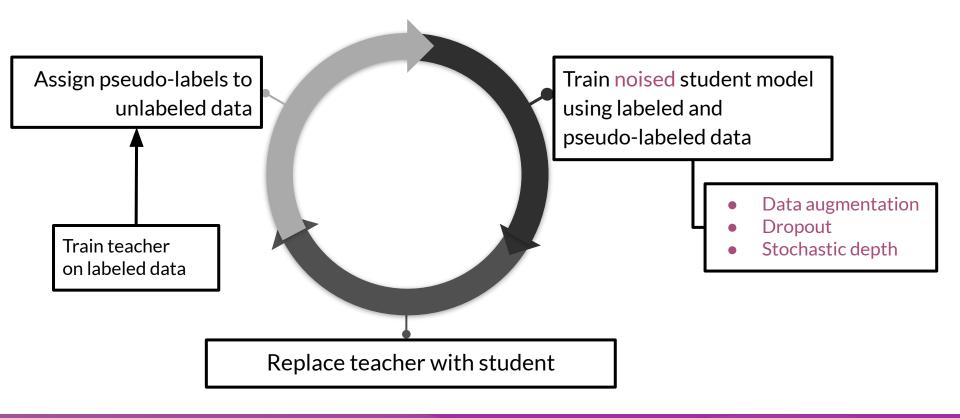
#### Two-stage multi-teacher distillation for Q & A



#### Impact of two-stage knowledge distillation



#### Make EfficientNets robust to noise with distillation



#### Results of noisy student training

