Copyright Notice

These slides are distributed under the Creative Commons License.

<u>DeepLearning.Al</u> makes these slides available for educational purposes. You may not use or distribute these slides for commercial purposes. You may make copies of these slides and use or distribute them for educational purposes as long as you cite <u>DeepLearning.Al</u> as the source of the slides.

For the rest of the details of the license, see https://creativecommons.org/licenses/by-sa/2.0/legalcode



Welcome



Hyperparameter tuning

- Neural architecture search (NAS) is is a technique for automating the design of artificial neural networks
- It helps finding the optimal architecture
- This is a search over a huge space
- AutoML is an algorithm to automate this search

Types of parameters in ML Models

- Trainable parameters:
 - Learned by the algorithm during training
 - e.g. weights of a neural network
- Hyperparameters:
 - set before launching the learning process
 - not updated in each training step
 - e.g: learning rate or the number of units in a dense layer

Manual hyperparameter tuning is not scalable

- Hyperparameters can be numerous even for small models
- e.g shallow DNN:
 - Architecture choices
 - activation functions
 - Weight initialization strategy
 - o Optimization hyperparameters such as learning rate, stop condition
- Tuning them manually can be a real brain teaser
- Tuning helps with model performance

Automating hyperparameter tuning with Keras Tuner

- Automation is key: open source resources to the rescue
- Keras Tuner:
 - Hyperparameter tuning with Tensorflow 2.0.
 - Many methods available



Keras Autotuner Demo

Setting up libraries and dataset

```
import tensorflow as tf
from tensorflow import keras
mnist = tf.keras.datasets.mnist
(x_train, y_train),(x_test, y_test) = mnist.load_data()
x train, x test = x train / 255.0, x test / 255.0
```

Deep learning "Hello world!"

```
model = tf.keras.models.Sequential([
 tf.keras.layers.Flatten(input shape=(28, 28)),
 tf.keras.layers.Dense(512, activation='relu'),
 tf.keras.layers.Dropout(0.2),
 tf.keras.layers.Dense(10, activation='softmax')
model.compile(optimizer='adam',
              loss='sparse categorical crossentropy',
              metrics=['accuracy'])
model.fit(x train, y train, epochs=5)
model.evaluate(x test, y test)
```

Model performance

```
Epoch 1/5
1875/1875 - 10s 5ms/step - loss: 0.3603 - accuracy: 0.8939
Epoch 2/5
1875/1875 - 10s 5ms/step - loss: 0.1001 - accuracy: 0.9695
Epoch 3/5
1875/1875 - 10s 5ms/step - loss: 0.0717 - accuracy: 0.9781
Epoch 4/5
1875/1875 - 10s 5ms/step - loss: 0.0515 - accuracy: 0.9841
Epoch 5/5
1875/1875 - 10s 5ms/step - loss: 0.0432 - accuracy: 0.9866
```



Parameters rational: if any

```
model = tf.keras.models.Sequential([
  tf.keras.layers.Flatten(input shape=(28, 28)),
  tf.keras.layers.Dense(512, activation='relu'),
 tf.keras.layers.Dropout(0.2),
 tf.keras.layers.Dense(10, activation='softmax')
model.compile(optimizer='adam',
              loss='sparse categorical crossentropy',
              metrics=['accuracy'])
model.fit(x train, y train, epochs=5)
model.evaluate(x test, y test)
```

Is this architecture optimal?

- Do the model need more or less hidden units to perform well?
- How does model size affect the convergence speed?
- Is there any trade off between convergence speed, model size and accuracy?
- Search automation is the natural path to take
- Keras tuner built in search functionality.

Automated search with Keras tuner

```
# First, install Keras Tuner
!pip install -q -U keras-tuner
# Import Keras Tuner after it has been installed
import kerastuner as kt
```



Building model with iterative search

```
def model_builder(hp):
 model = keras.Sequential()
 model.add(keras.layers.Flatten(input_shape=(28, 28)))
  hp_units = hp.Int('units', min_value=16, max_value=512, step=16)
 model.add(keras.layers.Dense(units=hp_units, activation='relu'))
 model.add(tf.keras.layers.Dropout(0.2))
 model.add(keras.layers.Dense(10))
 model.compile(optimizer='adam',loss='sparse_categorical_crossentropy',
   metrics=['accuracy'])
  return model
```



Search strategy

```
tuner = kt.Hyperband(model_builder,
                      objective='val_accuracy',
                      max_epochs=10,
                      factor=3.
                      directory='my_dir',
                       project_name='intro_to_kt')
 Other flavors: RandomSearch // BayesianOptimization // Sklearn
```

Callback configuration

```
stop_early =
    tf.keras.callbacks.EarlyStopping(monitor='val_loss',
                                      patience=5)
tuner.search(x_train,
             y_train,
             epochs=50,
             validation_split=0.2,
             callbacks=[stop_early])
```

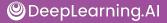
Search output

```
Trial 24 Complete [00h 00m 22s]
val_accuracy: 0.3265833258628845
Best val_accuracy So Far: 0.5167499780654907
Total elapsed time: 00h 05m 05s
Search: Running Trial #25
                                      |Best Value So Far
Hyperparameter
                |Value
units
                  1192
            |10
tuner/epochs
                                      12
tuner/initial_e... | 4
                                      10
tuner/bracket
                                      12
tuner/round
                  11
                                      10
tuner/trial_id
                  |a2edc917bda476c...|None
```



Back to your model

```
model = tf.keras.models.Sequential([
  tf.keras.layers.Flatten(input_shape=(28, 28)),
  tf.keras.layers.Dense(48, activation='relu'),
  tf.keras.layers.Dropout(0.2),
  tf.keras.layers.Dense(10, activation='softmax')
```



Training output

```
Epoch 1/5
1875/1875 - 3s 1ms/step - loss: 0.6427 - accuracy: 0.8090
Epoch 2/5
           3s 1ms/step - loss: 0.2330 - accuracy: 0.9324
1875/1875 -
Epoch 3/5
1875/1875 -
           3s 1ms/step - loss: 0.1835 - accuracy: 0.9448
Epoch 4/5
1875/1875 - 3s 1ms/step - loss: 0.1565 - accuracy: 0.9515
Epoch 5/5
1875/1875 - 3s 1ms/step - loss: 0.1393 - accuracy: 0.9564
```



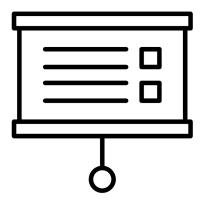
AutoML



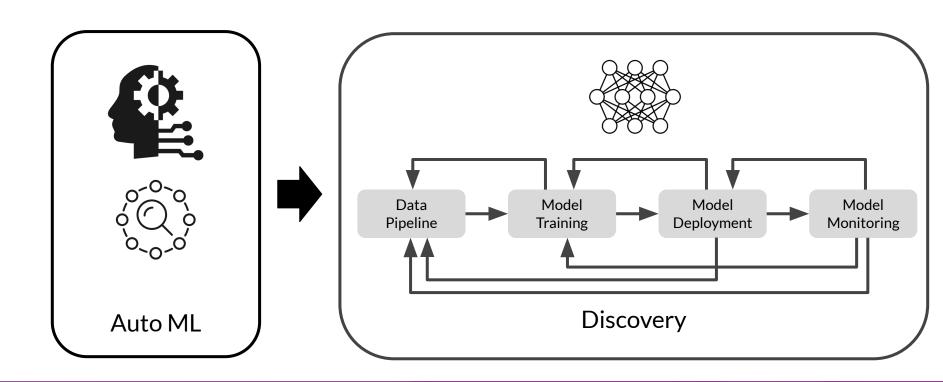
Intro to AutoML

Outline

- Introduction to AutoML
- Neural Architecture Search
- Search Space and Search Strategies
- Performance Estimation
- AutoML on the Cloud

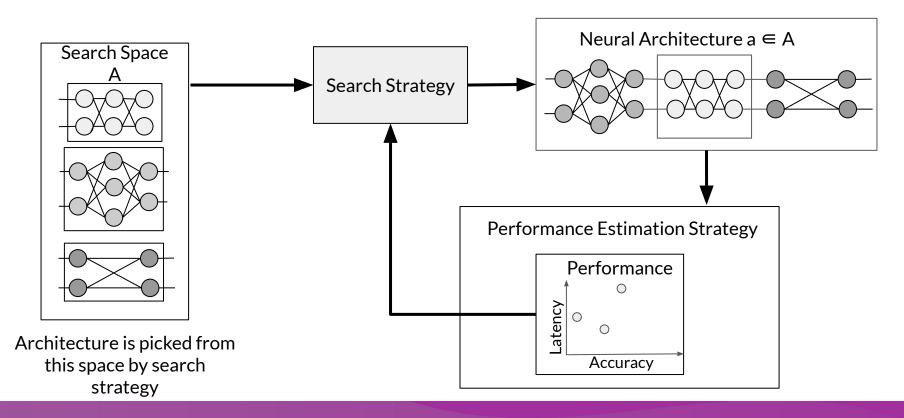


Automated Machine Learning (AutoML)

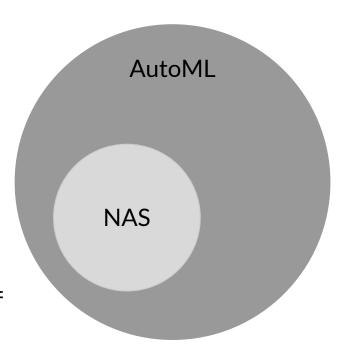


AutoML automates the entire ML workflow

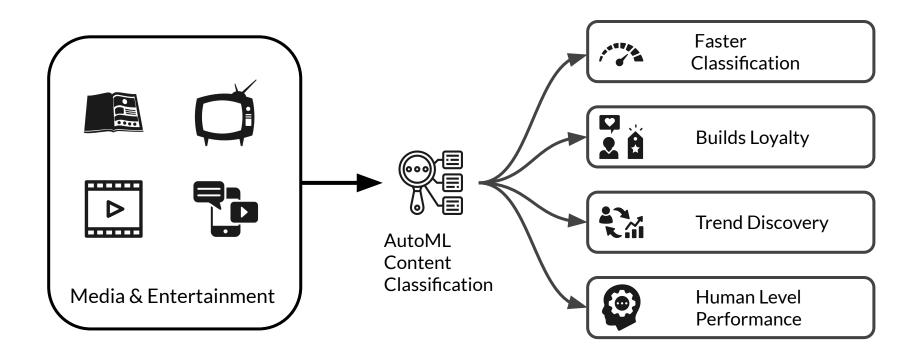
Data Data Feature Ingestion Validation Engineering Train Model Model



- AutoML automates the development of ML models
- AutoML is not specific to a particular type of model.
- Neural Architecture Search (NAS) is a subfield of AutoML
- NAS is a technique for automating the design of artificial neural networks (ANN).



Real-World example: Meredith Digital

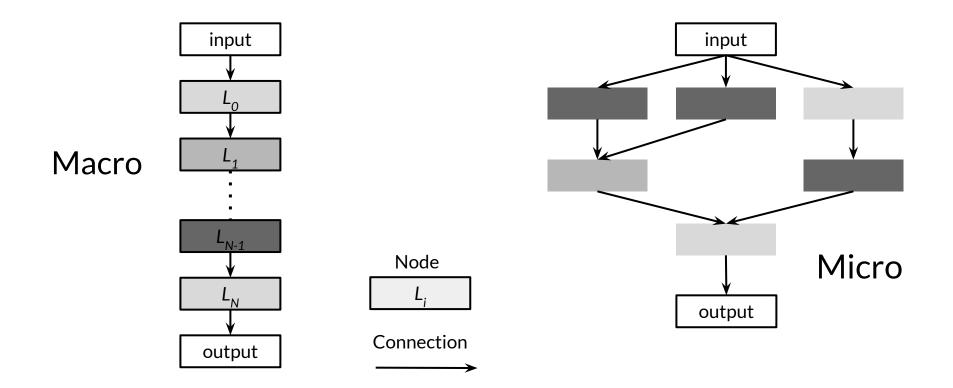


AutoML



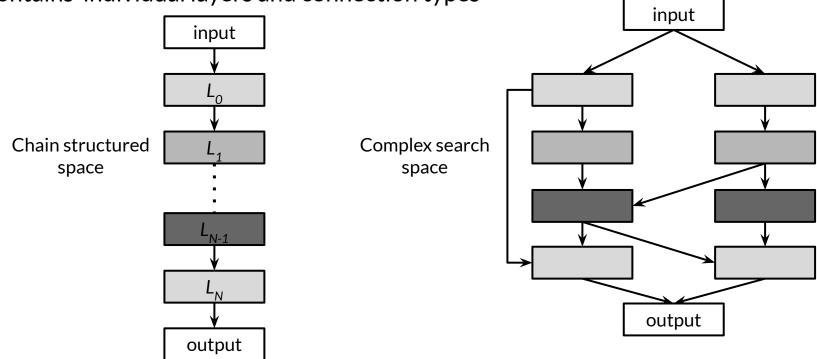
Understanding Search Spaces

Types of Search Spaces

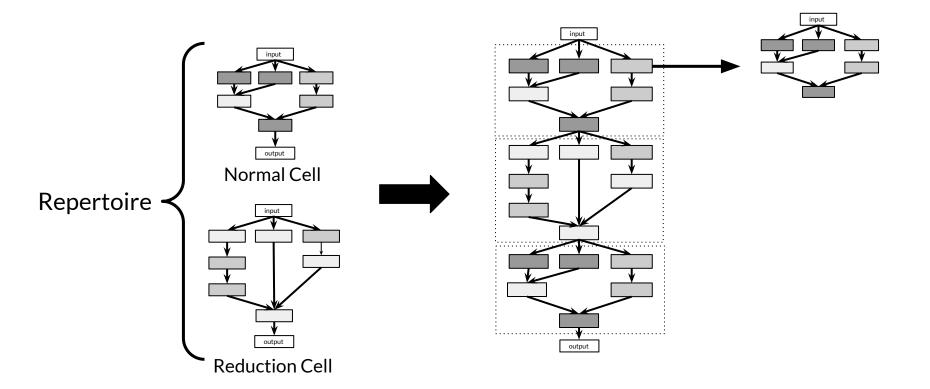


Macro Architecture Search Space

Contains individual layers and connection types



Micro Architecture Search Space



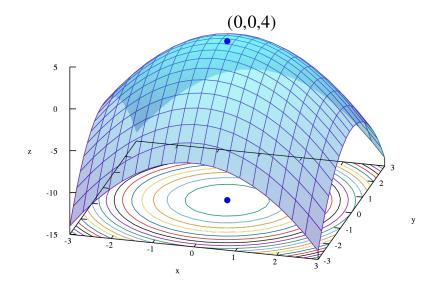
AutoML



Search Strategies

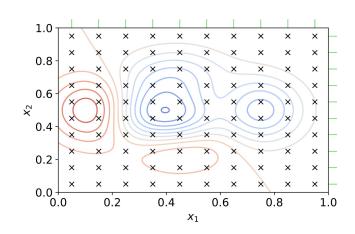
A Few Search Strategies

- 1. Grid Search
- 2. Random Search
- 3. Bayesian Optimization
- 4. Evolutionary Algorithms
- 5. Reinforcement Learning



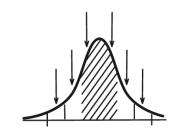
Grid Search and Random Search

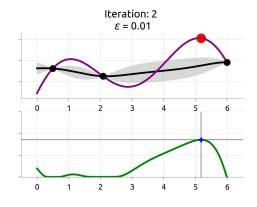
- Grid Search
 - Exhaustive search approach on fixed grid values
- Random Search
- Both suited for smaller search spaces.
- Both quickly fail with growing size of search space.



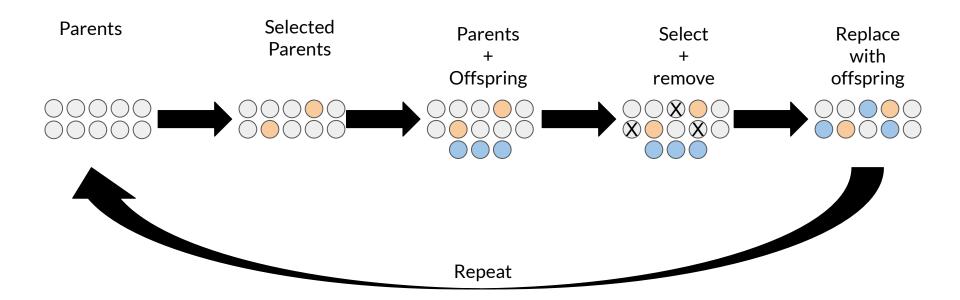
Bayesian Optimization

- Assumes that a specific probability distribution, is underlying the performance.
- Tested architectures constrain the probability distribution and guide the selection of the next option.
- In this way, promising architectures can be stochastically determined and tested.





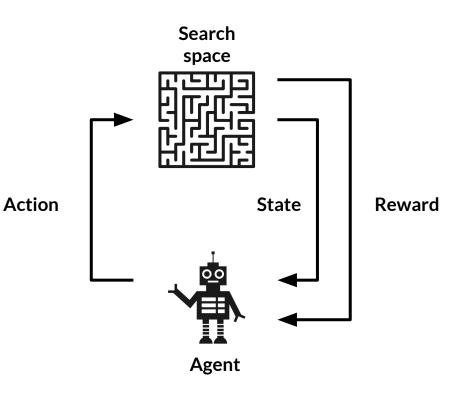
Evolutionary Methods



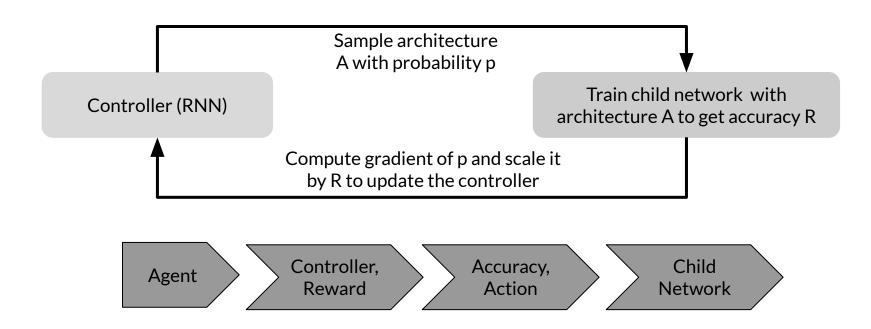
Reinforcement Learning

- Agents goal is to maximize a reward
- The available options are selected from the search space

 The performance estimation strategy determines the reward



Reinforcement Learning for NAS

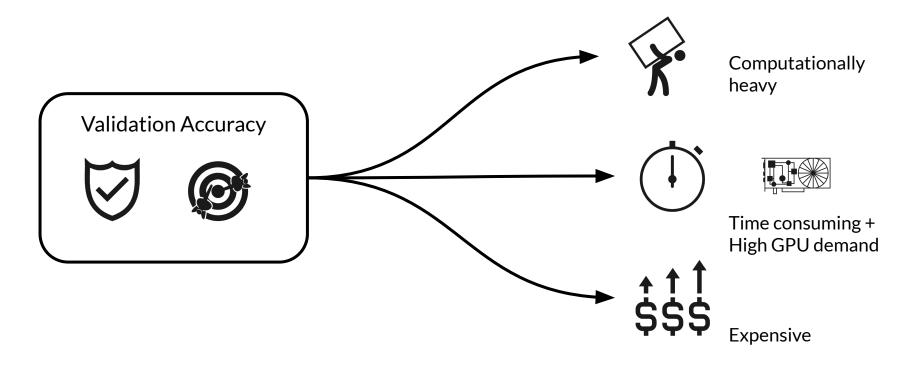


AutoML



Measuring AutoML Efficacy

Performance Estimation Strategy

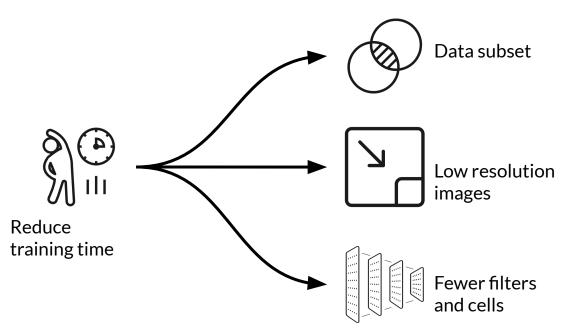


Strategies to Reduce the Cost

- 1. Lower fidelity estimates
- 2. Learning Curve Extrapolation
- 3. Weight Inheritance/ Network Morphisms



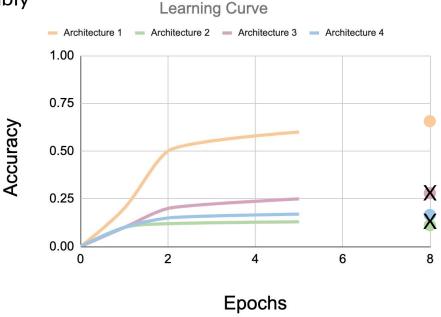
Lower Fidelity Estimates



- Reduce cost but underestimates performance
- Works if relative ranking of architectures does not change due to lower fidelity estimates
- Recent research shows this is not the case

Learning Curve Extrapolation

- Requires predicting the learning curve reliably
- Extrapolates based on initial learning.
- Removes poor performers



Weight Inheritance/Network Morphisms

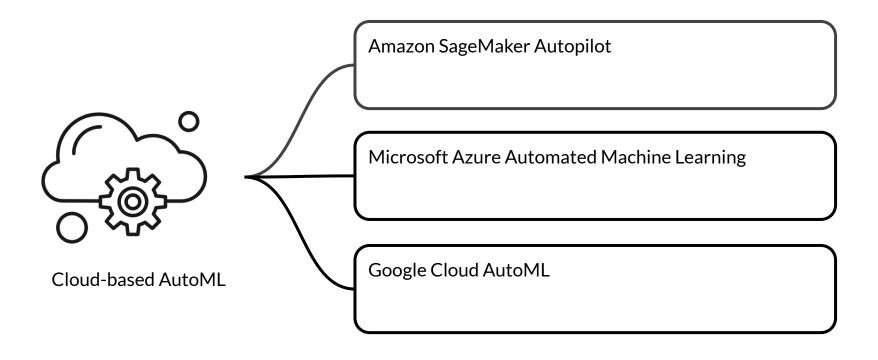
- Initialize weights of new architectures based on previously trained architectures
 - Similar to transfer learning
- Uses Network Morphism
- Underlying function unchanged
 - New network inherits knowledge from parent network.
 - Computational speed up: only a few days of GPU usage
 - Network size not inherently bounded

AutoML



AutoML on the Cloud

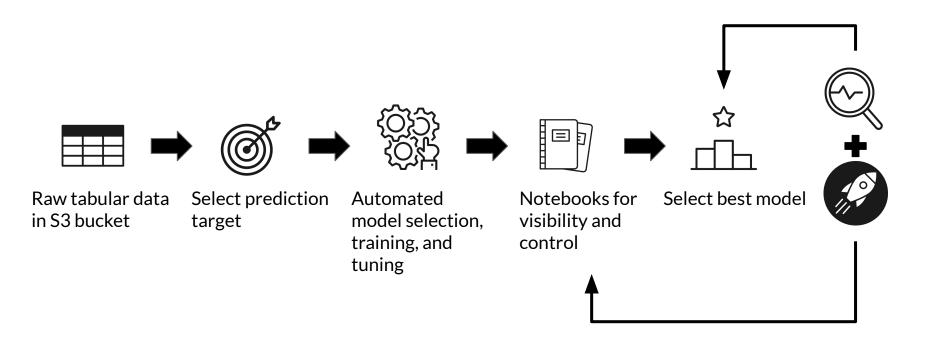
Popular Cloud Offerings



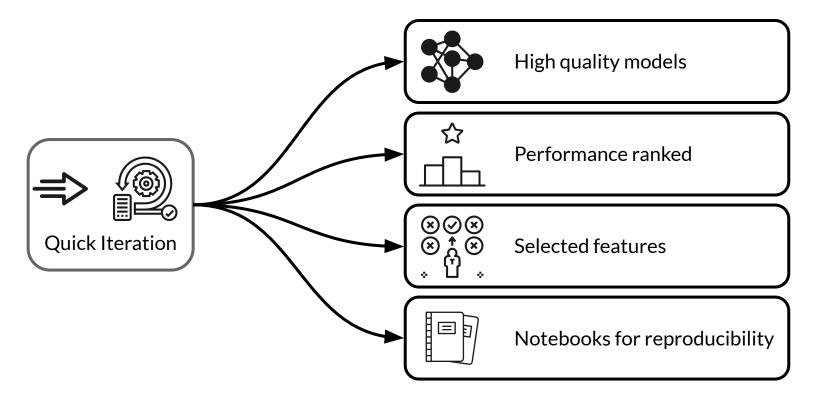
Amazon SageMaker Autopilot



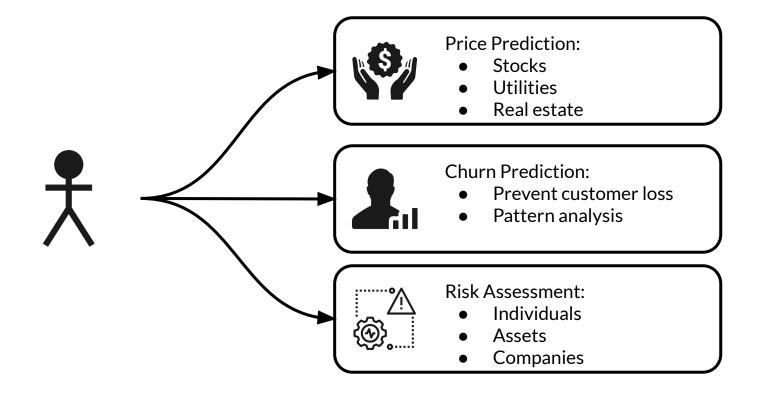
Amazon SageMaker Autopilot



Key features

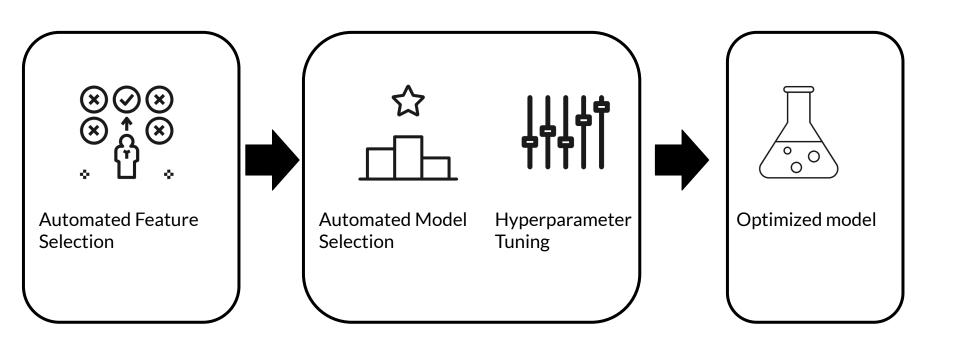


Typical use cases

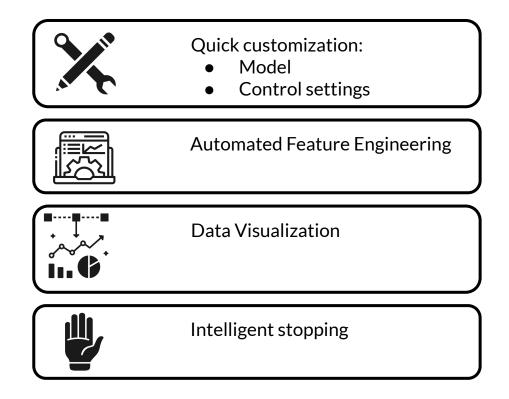


Microsoft Azure Automated Machine Learning

Microsoft Azure AutoML



Key features



Key features



- Experiment summaries
- Metric visualizations



Model Interpretability

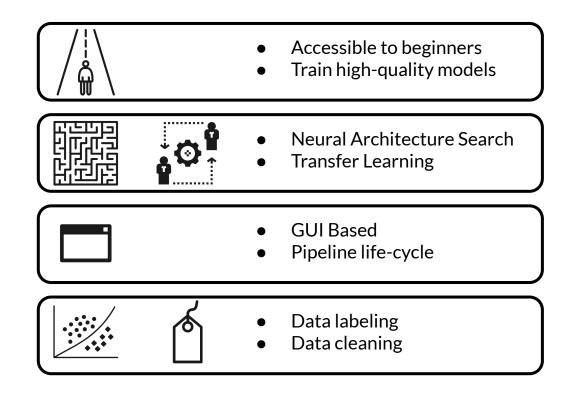


Pattern Discovery

Google Cloud AutoML



Google Cloud AutoML



Cloud AutoML Products

Sight	Auto ML Vision	Auto ML Video Intelligence
	Derive insights from images in the cloud or at the edge.	Enable powerful content discovery and engaging video experiences.
Language	AutoML Natural Language	Auto ML Translation
	Reveal the structure and meaning of text through machine learning.	Dynamically detect and translate between languages.
Structured Data	AutoML Tables Automatically build and deploy state-of-the-art machine learning models on structured data.	

AutoML Vision Products

Auto ML Vision Classification

AutoML Vision Edge Image Classification

AutoML Vision Object Detection

AutoML Vision Edge Object Detection

AutoML Video Intelligence Products

AutoML Video Intelligence Classification

Enables you to train machine learning models, to classify shots and segments on your videos according to your own defined labels.

AutoML Video Object detection

Enables you to train machine learning models to detect and track multiple objects, in shots and segments.

So what's in the secret sauce?

How do these Cloud offerings perform AutoML?

- We don't know (or can't say) and they're not about to tell us
- The underlying algorithms will be similar to what we've learned
- The algorithms will evolve with the state of the art

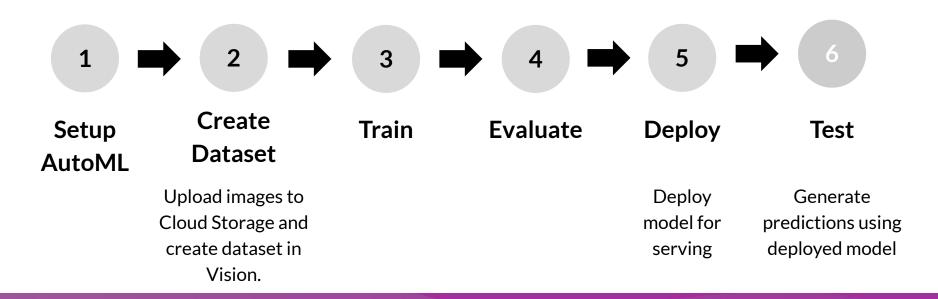


AutoML

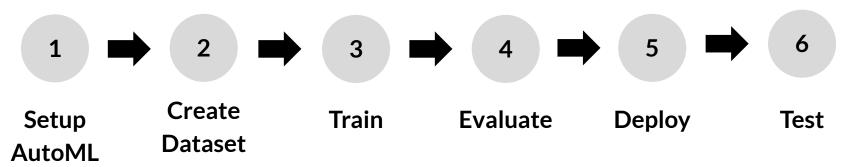


Assignment Setup

Steps to Classify Images using AutoML Vision







- Qwiklabs provides real cloud environments that help developers and IT professionals learn cloud platforms and software.
- Check tutorial on Qwiklabs basics



It's your turn!