

Instructions of Running

➤ Install the following libraries

1. **json**
2. **matplotlib**
3. **numpy**
4. **scipy**
5. **multiprocessing**
6. **threadpool**

➤ Run the server

The server script needs **2 command line parameters**, the first one is the port number for listening, the other parameter is the number of process for serving the clients.

Example running method:

```
>> python3 server.py 55703 4
```

➤ Run the client

The client script needs **6 command line parameters**, the meaning of each parameter:

1. Target server IP address
2. Port number on which the server listens for connections
3. Index of the client robot
4. Initial x coordinate of the client robot
5. Initial y coordinate of the client robot
6. Initial heading angle of the client robot

Example running method:

```
>> python3 client.py localhost 55703 1 10 10 0
```

➤ Run the client multiple times

Create multiple robot clients on the server, each client robot should have **a unique Index of the client robot parameter (parameter 3)**. Otherwise, the client would not be served **unless the previous client with the same Index of the client robot has completed the task**, which is simply **tracking the target path until the end**.

Example running method:

```
>> python3 client.py localhost 55703 2 60 10 0
```

```
>> python3 client.py localhost 55703 3 60 60 0
```

```
>> python3 client.py localhost 55703 4 10 10 0
```

```
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```