

Deep Learning with Jax

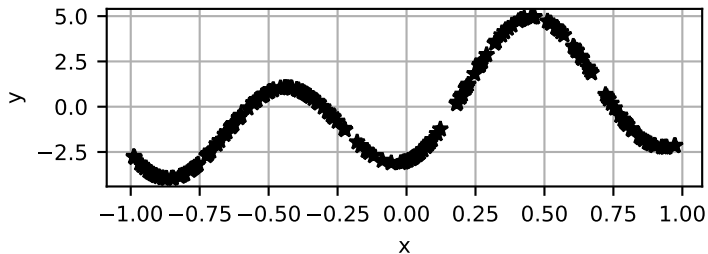
Feed-forward neural networks

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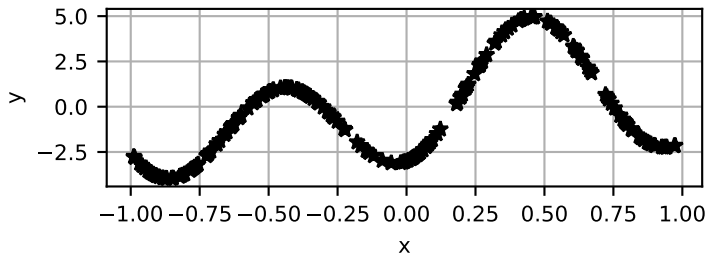
A non-linear dataset

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x_train.shape, y_train.shape
```

```
((200, 1), (200, 1))
```

Feed-forward neural network

- A one-hidden-layer feed-forward neural network:

$$y = W_2 \tanh(W_1 x + b_1) + b_2$$

with tunable weights W_1, b_1, W_2, b_2 .

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- If we prefer a single parameter vector:

$$p = \text{vec}(W_1, b_1, W_2, b_2), \quad W_1 \in \mathbb{R}^{n_h \times n_x}, b_1 \in \mathbb{R}^{n_h}, W_2 \in \mathbb{R}^{n_y \times n_h}, b_2 \in \mathbb{R}^{n_y}.$$

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In our SISO problem $n_x = 1, n_y = 1$. We can choose n_h (hyper-parameter).

Feed-forward neural network

In code, it is convenient to organize parameters in a *dictionary*

```
def nn(p, x):  
    z = jnp.tanh(p["W1"] @ x + p["b1"])  
    y = p["W2"] @ z + p["b2"]  
    return y
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The parameter dictionary may be initialized like this:

```
nx = 1; ny = 1; nh = 16  
params = {  
    "W1": jr.normal(key_W1, shape=(nh, nx)),  
    "b1": jr.normal(key_b1, shape=(nh,)),  
    "W2": jr.normal(key_W2, shape=(ny, nh)),  
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}
```

Better initializations exist (Kaiming, Glorot,...). Key for big nets, omitted for simplicity.

Feed-forward neural network implementation

- Let us apply the neural network to a data point:

```
nn(params, x_train[0])
```

```
Array([4.4949026], dtype=float32)
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- To process a *batch*, we must *vectorize* the `nn` function wrt its second argument.

```
# do nothing for first arg, add batch axis 0 for 2nd arg  
batched_nn = jax.vmap(nn, in_axes=(None, 0))
```

```
y_hat = batched_nn(params, x_train);  
y_hat.shape
```

```
(200, 1)
```

Setting up the loss

- Define the loss as a function

```
def loss_fn(p, y, x):  
    y_hat = batched_nn(p, x)  
    loss = jnp.mean((y - y_hat) ** 2)  
    return loss
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loss_grad_fn = jax.value_and_grad(loss_fn, 0)  
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```
loss_grad_fn(params, y_train, x_train)
```

```
(Array(24.432558, dtype=float32),  
 {'W1': Array([[ -0.9182231 ],  
                [ -0.32852545],  
                [ -0.28115115],
```


Fitting the neural net

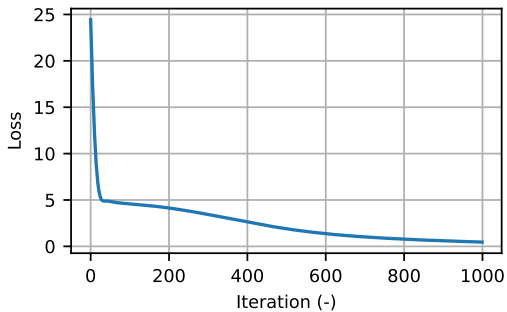
The *boilerplate* training code. Use optax instead of gradient descent from scratch...

```
optimizer = optax.adam(learning_rate=1e-2) # optax.{sgd, adam, ...}  
opt_state = optimizer.init(params)
```

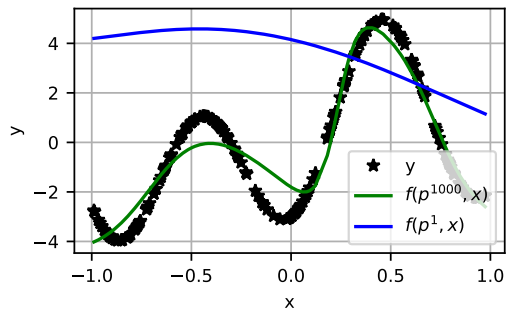
```
# Training loop  
LOSS = []  
for iter in range(1000):  
    loss_val, grads = loss_grad_fn(params, y_train, x_train)  
  
    updates, opt_state = optimizer.update(grads, opt_state)  
    params = optax.apply_updates(params, updates)  
  
    LOSS.append(loss_val)
```

Results

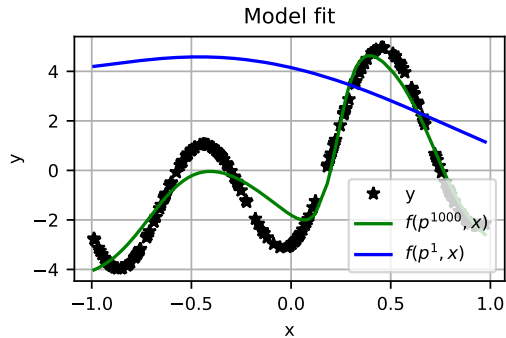
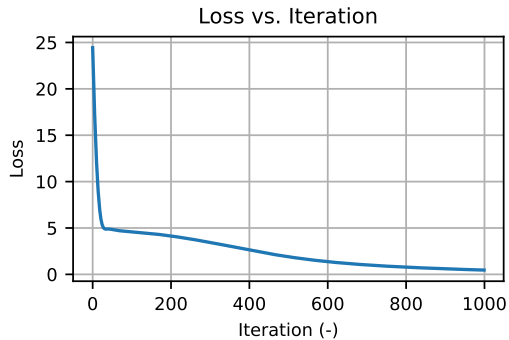
Loss vs. Iteration



Model fit

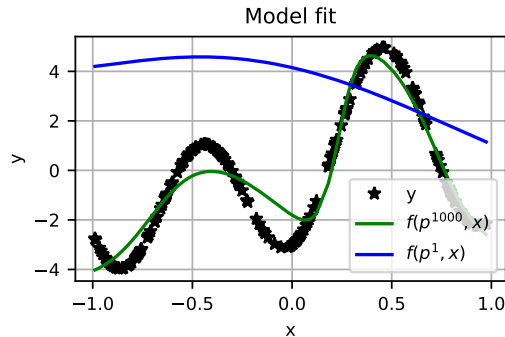
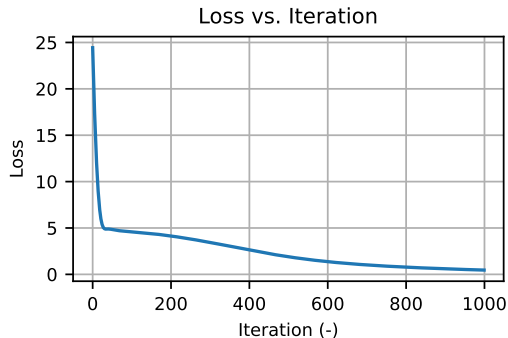


Results



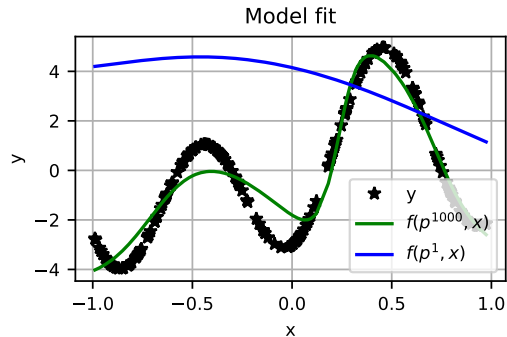
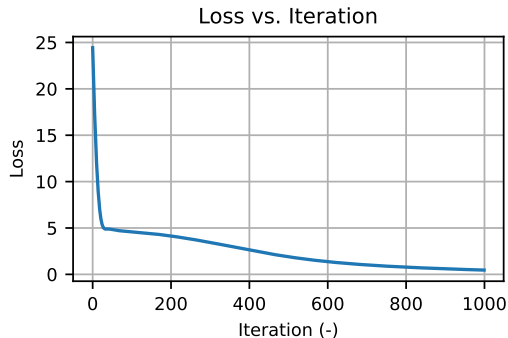
- Good fit without knowing the model structure

Results



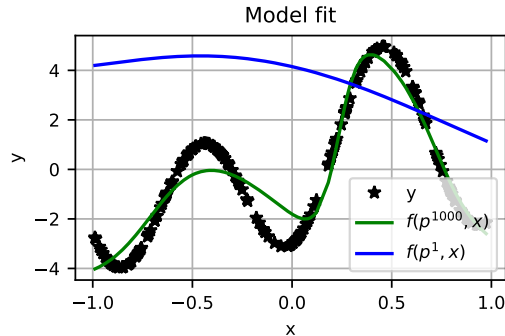
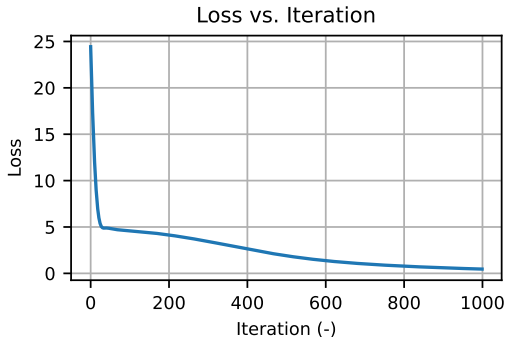
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- Good fit without knowing the model structure
- Can be improved with hyperparameter tuning, better optimizer and initialization...
- Extension to MIMO is trivial - just change n_x, n_y
- Extension to dynamical systems tomorrow

- Try out different hyper-parameters (e.g., hidden layers n_h , non-linearity function)
- Try out different initialization and optimization settings
- Define and train a neural network with 2 hidden layers
- Replicate the 2D example in the introductory slides
- Add mini-batching
 - At each optimization step, sample a *subset* of training instances