Model order reduction of deep structured state-space models: A system-theoretic approach

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SIA) LRU reduction

Deep structured state-space models

Growing interest within the machine-learning community. They dominate long-range sequence learning where Transformers suffer the $\mathcal{O}(N^2)$ scaling.

- Interconnection of linear dynamical systems with static non-linearities (and Normalization layers, skip connection, ...)
- The architecture should ring a bell to sysid researchers.

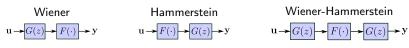
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The classic block-oriented modeling framework.





E.W. Bai, F. Giri Block-oriented nonlinear system identification. Springer, 2010

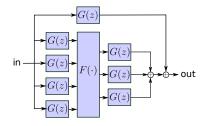
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The dynoNet architecture

LTI blocks for deep learning also in our 2021 dynoNet architecture

dynoNet architecture

Python code



```
 \begin{aligned} & \text{G1} = \text{LinearMimo} \left(1, \ 4, \ \ldots\right) \ \# \ a \ \textit{SIMO} \ \ tf \\ & \text{F} = \text{StaticNonLin} \left(4, \ 3, \ \ldots\right) \ \# \ a \ \textit{static NN} \\ & \text{G2} = \text{LinearMimo} \left(3, \ 1, \ \ldots\right) \ \# \ a \ \textit{MISO} \ \ tf \\ & \text{G3} = \text{LinearSiso} \left(1, \ 1, \ \ldots\right) \ \# \ a \ \textit{SISO} \ \ tf \\ & \text{def model} \left(\text{in\_data}\right) : \\ & \text{y1} = \text{G1} \left(\text{in\_data}\right) : \\ & \text{z1} = \text{F(y1)} \\ & \text{y2} = \text{G2} \left(\text{z1}\right) \\ & \text{out} = \text{y2} + \text{G3} \left(\text{in\_data}\right) \end{aligned}
```



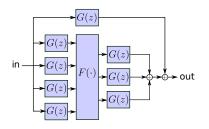
M. Forgione and D.Piga. dynoNet: A Neural Network architecture for learning dynamical systems. International Journal of Adaptive Control and Signal Processing, 2021

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```
G1 = LinearMimo(1, 4, ...) # a SIMO tf
F = StaticNonLin(4, 3, ...) # a static NN
G2 = LinearMimo(3, 1, ...) # a MISO tf
G3 = LinearSiso(1, 1, ...) # a SISO tf

def model(in_data):
    y1 = G1(in_data)
    z1 = F(y1)
    y2 = G2(z1)
    out = y2 + G3(in_data)
```



M. Forgione and D.Piga. dynoNet: A Neural Network architecture for learning dynamical systems. International Journal of Adaptive Control and Signal Processing, 2021

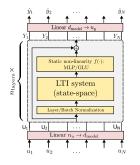
Differentiable transfer functions are now also in the torchaudio library.



https://pytorch.org/audio/main/generated/torchaudio.functional.lfilter.html

Deep Structured State-Space Model Architecture

- Architecture with normalization layers, skip connections, (dropout).
- State-space parameterization of the linear dynamical system



Focus on making the LTI system learning fast and well-posed.



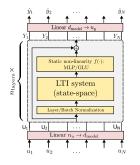
A. Gu, K. Goel, C. Ré. Efficiently Modeling Long Sequences with Structured State Spaces. ICLR, 2022

Our idea: bring in model order reduction to simplify these architectures!

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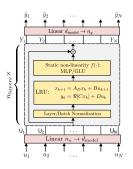
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Deep Linear Recurrent Unit

We consider the deep LRU architecture recently introduced by DeepMind:



A. Orvieto et al. Resurrecting Recurrent Neural Networks for Long Sequences. ICML, 2023



- Discrete-time, MIMO LTI system
- Complex diagonal state-transition matrix A_D :

$$A_D = \operatorname{diag}(\lambda_1, \lambda_2, \dots, \lambda_{n_x})$$

- ullet Stable parameterization with $|\lambda_i| < 1$
- Implementation with either:
 - $ightharpoonup \mathcal{O}(N)$ sequential ops (standard recursion)
 - ightharpoonup N parallel jobs, $\mathcal{O}(\log N)$ ops each (parallel scan)

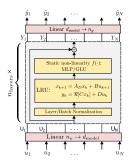
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Consider a LTI state-space system partitioned as:

$$\begin{bmatrix} x_1(k) \\ x_2(k) \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} x_1(k-1) \\ x_2(k-1) \end{bmatrix} + \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} u(k),$$
$$y(k) = \begin{bmatrix} C_1 & C_2 \end{bmatrix} \begin{bmatrix} x_1(k) \\ x_2(k) \end{bmatrix} + Du(k),$$

The states x_2 can be removed by:

- Truncation \Rightarrow keep (A_{11}, B_1, C_1, D)
- Singular Perturbation \Rightarrow solve for $x_2(k) = x_2(k-1)$

Reduction is often applied to systems in

- ullet Modal form (A diagonal, states sorted from slowest to fastest)
- Balanced form (states sorted for decreasing Hankel singular values)

We tested all combinations: MT, MSP, BT, BSP.

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Regularization for MOR

Regularization introduced to enhance the MOR:

$$\theta^* = \arg\min_{\theta \in \Theta} \frac{1}{N} \sum_{k=1}^{N} (y_k - \hat{y}_k(\theta))^2 + \gamma \mathcal{R}(\theta),$$

Modal ℓ_1

$$\mathcal{R}(\theta) = \sum_{j=1}^{n_x} |\lambda_j|$$

- Push some modes λ_j towards 0
- Tailored for modal reduction MT/MSP

Hankel nuclear norm (HNN)

$$\mathcal{R}(\theta) = \sum_{j=1}^{n_x} \sigma_j$$

- ullet Push some HSV σ_j towards 0
- Tailored for balanced reduction BT/BSP
- Modal ℓ_1 efficient (λ_i are on the diagonal of A_D)
- ullet HNN also efficient exploiting diagonal A_D structure. . .

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(IDSIA) LRU reduction

Hankel nuclear norm minimization

- Minimium realization order of a linear system G = rank of the $(\infty\text{-dimensional})$ Hankel operator H.
- ullet To obtain lower order models: we can minimize the rank of H, however, rank minimization is hard to solve!
- The HNN $\sum_{j=1}^{n_x} \sigma_j$ is often used as a convex surrogate of the rank of of H.
- The choice of HNN regularization is further motivated by the bound:

$$||G - G_r||_{\mathcal{H}_{\infty}} \le 2 \sum_{j=r+1}^{n_x} \sigma_j,$$

valid when G_r is obtained with balanced reduction methods BT/BSP

If we push some HSVs of G towards zero, we can then then find an (almost) equivalent reduced G_r with balanced reduction methods!

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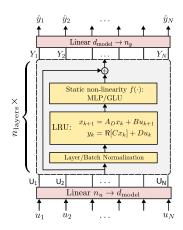
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Example

Experiments on the F16 ground vibration benchmark.

Deep LRU with:

- $n_{\rm lavers} = 6$ layers
- $n_x = 100$ states per layer
- $d_{\rm model} = 50$ units per layer
- Layer Normalization
- MLP non-linearity



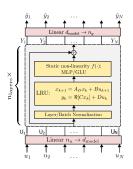
https://github.com/forgi86/lru-reduction

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Nominal results

Training repeated with:

- No regularization
- Modal ℓ_1 regularization
- Hankel norm regularization.



Results on test set FullMSine_Level6_Validation

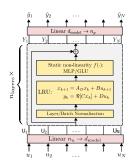
			NRMSE			NRMSE			NRMSE
No reg.									
	85.4								0.254

In line with literature. Regularization has a large effect on the LTI blocks!

Nominal results

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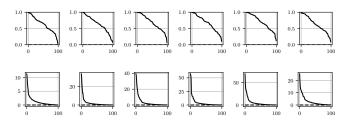


Results on test set FullMSine_Level6_Validation:

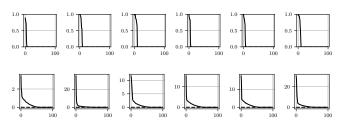
Regularization	Channel 1			Channel 2			Channel 3		
	fit	RMSE	NRMSE	fit	RMSE	NRMSE	fit	RMSE	NRMSE
No reg.	86.5	0.180	0.134	90.0	0.167	0.099	76.2	0.368	0.237
Modal ℓ_1	85.4	0.195	0.145	89.8	0.171	0.102	74.5	0.395	0.254
Hankel norm	85.8	0.190	0.142	89.0	0.185	0.110	75.5	0.379	0.245

In line with literature. Regularization has a large effect on the LTI blocks!

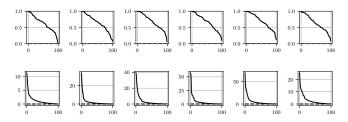
No regularization: eigenvalues magnitude (top) and HSV (bottom)



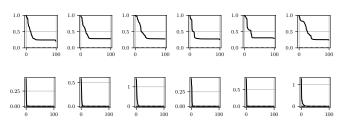
Modal ℓ_1 regularization: eigenvalues magnitude (top) and HSV (bottom)



No regularization: eigenvalues magnitude (top) and HSV (bottom)



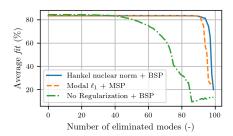
HNN regularization: eigenvalues magnitude (top) and HSV (bottom)



Performance of all Regularization/Reduction combinations assessed.

	Re	Reduction Method				
Regularization Method	ВТ	BSP	МТ	MSP		
No Regularization Modal ℓ_1 Hankel nuclear norm	28 56 89	43 73 91	3 0 18	35 91 76		

Table: Number of states eliminated s.t. performance decrease is less than 1%



- Best results with Hankel nuclear norm + balanced singular perturbation and modal ℓ_1 + modal singular perturbation
- Without regularization, MOR is significantly less effective

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Conclusions & future research

Preliminary efforts to improve deep SSMs with System Theoretic tools. MOR + tailor-made regularization to reduce state dimensionality.

Future research:

- More extensive simulations (e.g., effect of the regularization strength)
- Other model order reduction (e.g., Kyrilov-based) and regularizers
- Reduction also of layers and channels
- Application to other models where LTI blocks are key, e.g.
 - Koopman-based
 - dynoNet
 - Other deep SSMs

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Thank you. Questions?

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- Modal reduction is almost directly applicable to the LRU, which is already in modal (diagonal) form.
 - Sort system (A_D, B, C, D) for decreasing eigenvalues magnitude
 - Eliminate fastest modes
- Balanced reduction techniques require a three-step procedure:
 - **1** Balance (A_D, B, C, D) to a non-diagonal (A_b, B_b, C_d, D)
 - 2 Reduce (A_b, B_b, C_b, D) to a non-diagonal (A_r, B_r, C_r, D)
 - 3 Diagonalize (A_r, B_r, C_r, D) to fit the LRU structure

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