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Rockchip RKNN-DEMO Developer Guide

(Product R&D Dept.3)

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Preface

Overview

This document mainly introduce how to use RKNN_DEMO in Rockchip processor.

Product Version

Chipset	Kernel version
RK3399PRO	4.4

Intended Audience

This document is mainly suitable for below engineers:

- Field Application Engineer
- Software Development Engineer

Revision History

Date	Version	Author	Revision Description
2018-12-8	0.1.0	LHP	Initial version
2019-02-15	0.2.0	LHP	Support both RK1808 and RK3399pro SDK
2019-06-05	0.3.0	Caesar Wang	Add rknn_demo FAQ

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1 Run RKNN_DEMO

1.1 Overview

The rknn_demo module configuration directory is "<SDK>/buildroot/package/rockchip/rknn_demo" and the code directory is "<SDK>/external/rknn_demo". It is mainly used to collect images through USB camera and then send them to NPU for processing and display the results through MiniGUI. The currently supported model is "mobilenet_ssd".

1.2 Kernel Configuration

The required configurations are enabled in SDK by default, the mainly dependences are RGA and USB camera. If they are not enabled, please go to kernel to check the historical changes of related config.

Because RKNN interfaces and model of rk1808 and rk3399pro are different, you can configure according to chip type in the configuration file, mainly basing on BR2_PACKAGE_RK1808 and BR2_PACKAGE_RK3399PRO. When it is rk1808, the value of the macro "NEED_RKNNAPI" used in the code is 0 and the value is 1 when it is rk3399pro,

1.3 NPU Related

The model files have been compiled into the board by default in the SDK. The corresponding file macro and directory are as follows:

```
#define MODEL_NAME "/usr/share/rknn_demo/mobilenet_ssd.rknn"
#define BOX_PRIORS_TXT_PATH "/usr/share/rknn_demo/box_priors.txt"
#define LABEL_NALE_TXT_PATH "/usr/share/rknn_demo/coco_labels_list.txt"
```

Before the model runs, make sure the related files exist.

1.4 Compile and Run

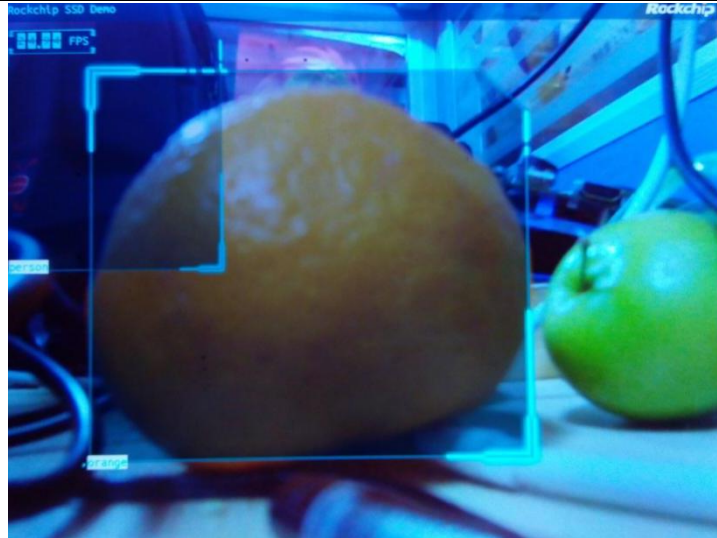
You can compile modules in the SDK directory with the command "make rknn_demo" and generate the rknn_demo executable file. Before copy to the board, make sure USB camera is plugged in, and run "rknn_demo" command directly.

Note: should not be coexist with other UIs. Please delete the related UI startup commands before starting. The board's default UI is QT, you can run the command:

```
/etc/init.d/S50launcher stop
```

The normal running frame rate is around 25~30fps. If the frame rate is not enough, the USB camera input frame rate may not be enough. It is recommended to face bright light or replace the USB camera. Unstable connection of USB camera will cause abnormal operation. So please keep a stable connection.

The operation result are as follows:



2 RKNN_DEMO Development

2.1 File Directory Introduction

The config.in is a configuration file, the rknn_demo.mk is the basic compilation file in which copy of resource is done. Detailed commands please refer to RKNN_DEMO_INSTALL_TARGET_CMDS.

The CMakeLists.txt is compiled file in the “src/” code directory. You can add your own files to compile in RKNN_DEMO_SRC.

The rknn_camera.c is the main file which is used to start MiniGUI main window and initialize modules. The MiniGUIMain is the main function entry. The Rknn_ui_show creates a main window for MiniGUI. The rknn_demo_init will start two threads: post and run. Run is used for capturing image and NPU processing, and sends the result to post thread which receives the processing result of NPU and doing post-processing, and outputs the result to display.

The “src/rknn/ssd” is SSD related processing file. In the ssd.c, the ssd_run function loads the model and obtains the buf of USB camera through the cameraRun function, and outputs to the registration function ssd_camera_callback. In the ssd_camera_callback function, yuv_draw function sends video data to MiniGUI layer for RGA synthesis of video data and UI data. YUV420toRGB24_RGA convert video data from 640*480 nv12 format to 300*300 rgb888 format which will be sent to the ssd_rknn_process function for processing.

The src/ui/ssd is UI display file for SSD. The caption_create function paints title bar and displays it in caption_wnd_proc; the fps_create function paints frame rate bar and displays it in fps_wnd_proc; the ssd_paint_object paints region of detected object and the processing result of SSD is sent here for display. Detailed MiniGUI development and processing, please refer to related open source materials.

3 RKNN_DEMO FAQ

3.1 How to Switch to a Different Type of Panel

The “/external/minigui” is selected VOP0(VOPB) for display by default. Ensure that the display device (EDP/HDMI/MIPI..) is placed on VOPB.

3.2 How to Switch Display Resolution

The default resolution is 2048x1536 on RK3399PRO EVB at present. If you need to switch resolution to 1920x1080, the following configuration is needed:

#rknn_demo/minigui/MiniGUI-1920x1080.cfg and ui/ssd/ssd_ui.c where the resolution should be changed to 1920x1080.

Finally change package/rockchip/rknn_demo/rknn_demo.mk in the buildroot:

```
ifeq ($(BR2_PACKAGE_RK3399PRO),y)
-RKNN_DEMO_MINIGUI_CFG=minigui/MiniGUI-2048x1536.cfg
+RKNN_DEMO_MINIGUI_CFG=minigui/MiniGUI-1920x1080.cfg
endif
```