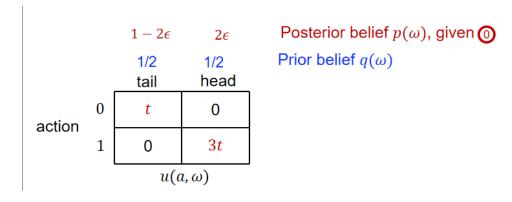
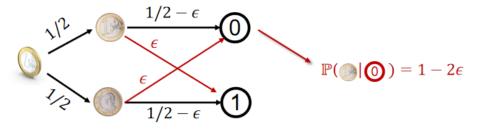
# Lecture 11: The Valuation and Pricing of Information

## I.Economic Foundations of Value of Information

|        |   | Coin s | state $\omega$ |                          |
|--------|---|--------|----------------|--------------------------|
|        |   | 1/2    | 1/2            | Prior belief $q(\omega)$ |
|        |   | tail   | head           |                          |
| action | 0 | 2t     | 0              |                          |
|        | 1 | 0      | 2t             |                          |
|        |   | u(a    | ι, ω)          | •                        |

Without information, decision maker (DM) gets  $\max_a \left[\mathbb{E}_{\omega \sim q} u(a,\omega)\right] = t$  With my (full) information, DM gets  $\mathbb{E}_{\omega \sim q}[\max_a u(a,\omega)] = 2t$  Value of (full) info =  $\mathbb{E}_{\omega \sim q}[\max_a u(a,\omega)] - \max_a \left[\mathbb{E}_{\omega \sim q} u(a,\omega)\right]$ 





# Noisy information revelation

Realistically, can think of 0 as noisy prediction of state  $\omega$  (e.g., stock trend, purchase prob)

Question: What is the value of this noisy signal 0?

- $\bullet~$  Without knowing this signal, DM takes action 1
- With this signal 0, DM takes action 0(assuming  $\varepsilon$  very small)
- However, true distribution is the posterior p regardless

Value of knowing 
$$0 = \mathbb{E}_{\omega \sim p}[u(0, \omega)] - \mathbb{E}_{\omega \sim p}u(1, \omega)$$

**Definition**(**FK'19**):Consider an arbitrary desicion making problem  $u(a, \omega)$ , suppose a signal updates the DM's belief about state  $\omega$  from  $q \in \Delta(\Omega)$  to  $p \in \Delta(\Omega)$ , the value of this signal is defined as

$$D^u(p;q) = \mathbb{E}_{\omega \sim p}[u(a^*(p),\omega)] - \mathbb{E}_{\omega \sim p}u(a^*(q),\omega)$$

Example 1:

- $a \in A = \Delta(\Omega) \to \text{action}$  is to pick a distribution over states
- $u(a,\omega) = \log a_{\omega}$
- Which action  $a \in \Delta(\Omega)$  maximizes expected utility  $\mathbb{E}_{\omega \sim p}[u(a,\omega)]$ ?

$$a^*(p) = p$$

$$D^u(p;q) = \sum_{\omega} p_{\omega} \log \frac{p_{\omega}}{q_{\omega}} \qquad \text{KL-divergence}$$

Example 2:

- $a \in A = \Delta(A) \rightarrow \text{action}$  is to pick a distribution over states
- $u(a,\omega) = -\|a e_{\omega}\|^2$

$$a^*(p) = p$$

$$D^u(p;q) = \|p-q\|^2$$
 Squared distance

#### Some obvious properties

- Non-negativity:  $D^u(p;q) \geq 0$
- Null information has no value:  $D^{u}(q;q) = 0$
- Order-invariant: if DM receives signal  $\sigma_1, \sigma_2$ , the order of receiving them does not affect final expected total value

In this case, we say D(p;q) is a valid measure for value of information

**Theorem 1(FK'19)**: Consider any D(p;q) function. There exists a decision problem  $u(a,\omega)$  such that

$$D^u(p;q) = \mathbb{E}_{\omega \sim p}[u(a^*(p),\omega)] - \mathbb{E}_{\omega \sim p}u(a^*(q),\omega)$$

if and only if D(p;q) satisfies

- Non-negativity:  $D^u(p;q) \geq 0$
- Null information has no value:  $D^u(q;q) = 0$
- Order-invariant: if DM receives signal  $\sigma_1, \sigma_2$ , the order of receiving them does not affect final expected total value

#### Theorem 2(FK'19):

- 1. For any concave function H, its Bregman divergence is a valid measure for value of information.
- 2. Conversely, for any valid measure D(p;q) for value of information,

$$H(q) = \sum_{\omega} q^{\omega} D(e_{\omega}, q)$$

is a concave function whosw Bregman divergence is D(p;q)

Why useful?

• Many functions - even natural ones like  $l_2$  distance  $\|p-q\|$ - are not valid measures

- In fact, any metric is not valid, since metric cannot be a Bregman divergence
- There are efficient ways to tell whether a D(p,q) is valid

## **II.Optimal Pricing of Information**

#### 1.Plans

- Vignette 1: closed-form optimal mechanism for structed setups
- Vignette 2: algorithmic solution for general setups
- Vignette 3: from distilled data (i.e. information) to raw data

#### 2.A Model of Information Pricing

- One seller, one buyer
- Buyers is a decision marker who faces a binary choice: an active action 1 and a passive action 0: Active action: come to talk, approve loan, invest stock X, etc.
- Payoff of passive action  $\equiv 0$
- Payoff of active action=  $v(\omega, t) = v_1(\omega)[t + \rho(\omega)]$ 
  - $\omega$  is a state of nature, t is buyer type
  - Assume  $v(\omega,t)$  is linear and non-decreasing in  $t \in [t_1,t_2]$
- Information structure:
  - Seller observes  $\omega$ , and buyer knows t

**Mechanism design question**: How can seller optimally sell her information about  $\omega$  to the buyer?

#### 3.Design Space

Standard revelation principle implies optimal mechanism can w.l.o.g be a menu  $\left\{\pi_t, p_t\right\}_{t \in T}$ 

- $\pi_t: \Omega \to S$  is an experiment (which generates signals) for type i
- $p_t \in \mathbb{R}$  is t's payment
- Each type is incentivized to report type truthfully

Concrete design question: design IC  $\{\pi_t, p_t\}_{t \in T}$  to maximize seller's revenue

#### 4. How Does It Differ from Selling Goods?

- Each experiment is like an item
  - ► In this sense, we are selling infinitely many goods
  - ▶ In fact, we are even "designing the goods"
- Participation constraint is different
  - Without any information, type t's utility is  $\max\{\overline{v}(t), 0\}$

$$\overline{v}(t) = \int_{\omega \in \Omega} v(\omega, t) g(\omega) d\omega$$

Ex-ante expected utility of action 1

#### 5. Threshold experiments turn out to suffice

Recall 
$$v(\omega, t) = v_1(\omega)[t + \rho(\omega)]$$

**Def.**  $\pi_t$  is a threshold experiment if  $\pi_t$  simply reveals  $\rho(\omega) \geq \theta(t)$  or not some buyer-type-dependent threshold  $\theta(t)$ 

Threshold is on  $\rho(\omega)$ 

#### 6. Virtual Value Functions

Recall virtual value function in [Myerson'81]:  $\varphi(t) = t - \frac{1 - F(t)}{f(t)}$ 

#### Def.

- Lower virtual value function:  $\varphi(t) = t \frac{1 F(t)}{f(t)}$  Upper virtual value function:  $\overline{\varphi}(t) = t + \frac{F(t)}{f(t)}$
- Mixed virtual value function:  $\varphi_c(t) = c\varphi(t) + (1-c)\overline{\varphi}(t)$

Note: "upper" or "lower" is due to:

$$\varphi(t) \leq t \leq \overline{\varphi}(t)$$

#### 7. The Optimal Mechanism

Depend on two problem-related constants:

$$V_L = \max\{v(t_1), 0\} + \int_{t_1}^{t_2} \int_{q: \rho(q) \geq -\varphi^+(x)} g(q) v_1(q) dq dx$$

$$V_{H} = \max\{v(t_{1}), 0\} + \int_{t_{1}}^{t_{2}} \int_{q: \rho(q) \geq -\overline{\varphi}^{+}(x)} g(q) v_{1}(q) dq dx$$

Note:

$$V_L < V_H$$

### Theorem([LSX'21])

1. If  $\overline{v}(t_2) \leq V_L$ , the mechanism with threshold experiments  $\theta^*(t) = -\varphi(t)$  and following payment function represents an optimal mechanism:

$$p^*(t) = \int_{\omega \in \Omega} \pi^*(\omega,t) g(\omega) v(\omega,t) d\omega - \int_{t_1}^t \int_{\omega \in \Omega} \pi^*(\omega,x) g(\omega) v_1(\omega) d\omega dx$$

2. If  $\overline{v}(t_2) \geq V_H$ , the mechanism wit threshold experiments  $\theta^*(t) = -\overline{\varphi}(t)$  and following payment function represents an optimal mechanism:

$$p^*(t) = \int_{\omega \in \Omega} \pi^*(\omega,t) g(\omega) v(\omega,t) d\omega + \int_t^{t_2} \int_{\omega \in \Omega} \pi^*(\omega,x) g(\omega) v_1(\omega) d\omega dx - \overline{v}(t_2)$$

3. If  $V_L \leq \overline{v}(t_2) \leq V_H$ , the mechanism with threshold experiments  $\theta^*(t) = -\varphi_c(t)$  and following payment function represents an optimal mechanism

$$p^*(t) = \int_{\omega \in \Omega} \pi^*(\omega,t) g(\omega) v(\omega,t) d\omega - \int_{t_1}^{t_2} \int_{\omega \in \Omega} \pi^*(\omega,x) g(\omega) v_1(\omega) d\omega dx$$

where constant c is chosen such that

$$\int_{t_1}^{t_2} \int_{\omega: \rho(\omega) \geq \varphi_c^+(x)} g(\omega) v_1(\omega) d\omega dx = \overline{v}(t_2)$$

#### 8. Remarks

• Threshold mechanisms are common in real life: House/car inspections, stock recommendations: information seller only need to reveal it "passed" or "deserves a buy" or not

• Optimal mechanism has personalized thresholds and payments, tailored to accommodate different level of risk each buyer type can take: Different from optimal pricing of physical goods

What if seller is restricted to sell the same information to every buyer (e.g., due to regulation)? How will revenue change?

- This is the optimal price (Merson reserve) in previous example
- Revenue can be arbitrarily worse
- $\frac{1}{e}$  approximation of optimal revenue if the value of full information as a function of t has monotone hazard rate

#### 9. Additional Properties of Optimal Mechanism

# III.Summary and Open Problems