

## Example: Ordinary Kriging with Three Points

### Data Points

- Known data points:  $Z(x_1), Z(x_2), Z(x_3)$
- Unsampld location:  $x_0$

### Weights

Weights to be determined:  $\lambda_1, \lambda_2, \lambda_3$  such that the estimate  $\hat{Z}(x_0)$  at location  $x_0$  is a weighted sum of the known values:

$$\hat{Z}(x_0) = \lambda_1 Z(x_1) + \lambda_2 Z(x_2) + \lambda_3 Z(x_3)$$

### Function to Minimize

In ordinary kriging, the goal is to minimize the estimation variance, which can be expressed as:

$$\text{Var}(\hat{Z}(x_0)) = \sum_{i=1}^3 \sum_{j=1}^3 \lambda_i \lambda_j \gamma(x_i, x_j) + \sum_{i=1}^3 \lambda_i \gamma(x_i, x_0)$$

### Constraint

The constraint is that the sum of the weights must equal 1:

$$\sum_{i=1}^3 \lambda_i = 1$$

### Lagrangian Function

The Lagrangian function for ordinary kriging is:

$$L(\lambda_1, \lambda_2, \lambda_3, \mu) = \sum_{i=1}^3 \sum_{j=1}^3 \lambda_i \lambda_j \gamma(x_i, x_j) + \sum_{i=1}^3 \lambda_i \gamma(x_i, x_0) + \mu \left( \sum_{i=1}^3 \lambda_i - 1 \right)$$

where  $\gamma(x_i, x_j)$  is the semivariance between points  $x_i$  and  $x_j$ , and  $\mu$  is the Lagrange multiplier.

## Partial Derivatives

Taking the partial derivatives with respect to  $\lambda_i$  and  $\mu$ :

$$\frac{\partial L}{\partial \lambda_i} = \sum_{j=1}^3 \lambda_j \gamma(x_i, x_j) + \gamma(x_i, x_0) + \mu = 0 \quad \text{for } i = 1, 2, 3$$

$$\frac{\partial L}{\partial \mu} = \sum_{i=1}^3 \lambda_i - 1 = 0$$

## System of Equations

Rearranging the partial derivatives, we get the following system of equations:

$$\begin{cases} \lambda_1 \gamma(x_1, x_1) + \lambda_2 \gamma(x_1, x_2) + \lambda_3 \gamma(x_1, x_3) + \mu = \gamma(x_1, x_0) \\ \lambda_1 \gamma(x_2, x_1) + \lambda_2 \gamma(x_2, x_2) + \lambda_3 \gamma(x_2, x_3) + \mu = \gamma(x_2, x_0) \\ \lambda_1 \gamma(x_3, x_1) + \lambda_2 \gamma(x_3, x_2) + \lambda_3 \gamma(x_3, x_3) + \mu = \gamma(x_3, x_0) \\ \lambda_1 + \lambda_2 + \lambda_3 = 1 \end{cases}$$

By solving this system of equations, we can determine the weights  $\lambda_1$ ,  $\lambda_2$ , and  $\lambda_3$  that minimize the estimation variance while ensuring the sum of the weights is one.