بسم الله الرحمن الرحيم

ا «سیستم عامل»

جلسه ۸: کنترل همروندی — مانیتور

یادآوری

سمافور

Semaphore S has a value, S.val, and a thread list, S.list.

```
Wait (5)
    5.val = 5.val - 1
    If S.val < 0
                                        /* negative value of S.val */
        { add calling thread to S.list; /* is # waiting threads */
                                                /* sleep */
                 block;
Signal (S)
    5.val = 5.val + 1
    If S.val <= 0
        { remove a thread T from S.list;
                 wakeup (T);
```

مانيتور

Monitors

- It is difficult to produce correct programs using semaphores
 - * correct ordering of down and up is tricky!
 - * avoiding race conditions and deadlock is tricky!
 - boundary conditions are tricky!
- Can we get the compiler to generate the correct semaphore code for us?
 - * what are suitable higher level abstractions for synchronization?

Monitors

- Related shared objects are collected together
- Compiler enforces encapsulation/mutual exclusion
 - * Encapsulation:
 - Local data variables are accessible only via the monitor's entry procedures (like methods)
 - * Mutual exclusion
 - A monitor has an associated mutex lock
 - Threads must acquire the monitor's mutex lock before invoking one of its procedures

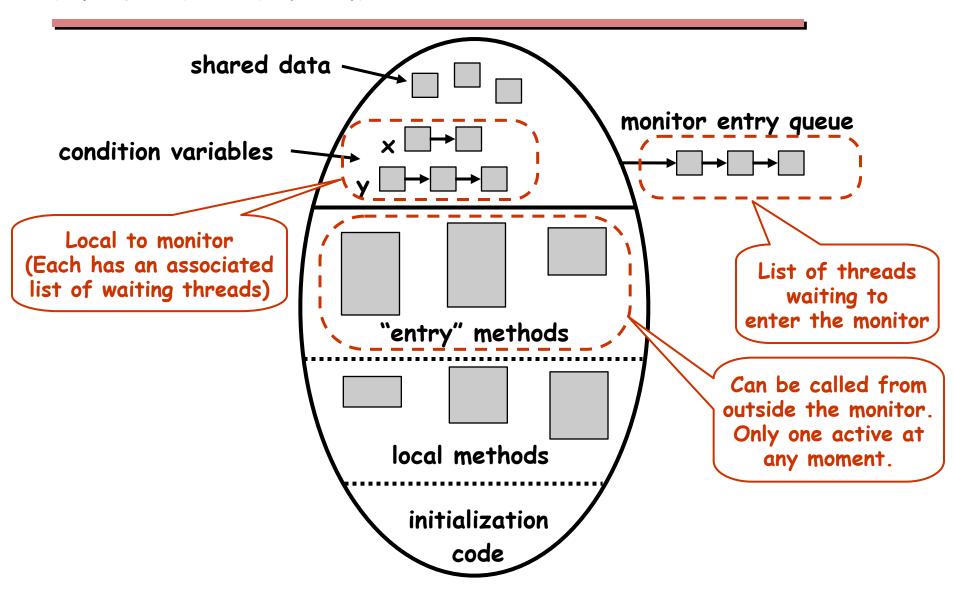
Monitors and condition variables

- But we need two flavors of synchronization
 - * Mutual exclusion
 - Only one at a time in the critical section
 - Handled by the monitor's mutex
 - * Condition synchronization
 - Wait until a certain condition holds
 - Signal waiting threads when the condition holds

Monitors and condition variables

- Condition variables (cv) for use within monitors
 - * cv.wait(mon-mutex)
 - thread blocked (queued) until condition holds
 - Must not block while holding mutex!
 - monitor mutex must be released!
 - * cv.signal()
 - signals the condition and unblocks (dequeues) a thread

Monitor structures



Monitor example for mutual exclusion

```
process Producer
begin
                                   monitor: BoundedBuffer
  loop
                                   var
                                        buffer : ...;
    char "c">
                                        nextIn, nextOut :... ;
    BoundedBuffer.deposit(c)
  end loop
                                     entry deposit(c: char)
end Producer
                                        begin
                                        end
                                     entry remove(var c: char)
process Consumer
                                        begin
begin
  loop
                                        end
    BoundedBuffer.remove(c)
    <consume char "c">
                                   end BoundedBuffer
  end loop
end Consumer
```

Observations

- That's much simpler than the semaphore-based solution to producer/consumer (bounded buffer)!
- ... but where is the mutex?
- ... and what do the bodies of the monitor procedures look like?

Monitor example with condition variables

```
entry deposit(c:char)
begin
  if (fullCount = n) then
      wait(notFull)
  end if

buffer[nextIn] := c
  nextIn := nextIn+1 mod n
  fullCount := fullCount+1

signal(notEmpty)
end deposit
```

```
entry remove(var c: char)
begin
  if (fullCount = 0) then
    wait(notEmpty)
  end if

c := buffer[nextOut]
  nextOut := nextOut+1 mod n
  fullCount := fullCount-1

signal(notFull)
end remove
```

end BoundedBuffer

Condition variables

"Condition variables allow processes to synchronize based on some state of the monitor variables."

Condition variables in producer/consumer

"NotFull" condition
"NotEmpty" condition

- Operations Wait() and Signal() allow synchronization within the monitor
- When a producer thread adds an element...
 - * A consumer may be sleeping
 - * Need to wake the consumer... Signal

Condition synchronization semantics

"Only one thread can be executing in the monitor at any one time."

Scenario:

- * Thread A is executing in the monitor
- * Thread A does a signal waking up thread B
- * What happens now?
- * Signaling and signaled threads can not both run!
- * ... so which one runs, which one blocks, and on what queue?

Monitor design choices

- Condition variables introduce a problem for mutual exclusion
 - only one process active in the monitor at a time, so what to do when a process is unblocked on signal?
 - * must not block holding the mutex, so what to do when a process blocks on wait?

Monitor design choices

- Choices when A signals a condition that unblocks B
 - A waits for B to exit the monitor or block again
 - * B waits for A to exit the monitor or block
 - Signal causes A to immediately exit the monitor or block (... but awaiting what condition?)
- Choices when A signals a condition that unblocks B & C
 - * B is unblocked, but C remains blocked
 - * C is unblocked, but B remains blocked
 - * Both B & C are unblocked ... and compete for the mutex?
- Choices when A calls wait and blocks
 - * a new external process is allowed to enter
 - * but which one?

Option 1: Hoare semantics

- What happens when a Signal is performed?
 - * signaling thread (A) is suspended
 - * signaled thread (B) wakes up and runs immediately

Result:

- * B can assume the condition is now true/satisfied
- * Hoare semantics give strong guarantees
- * Easier to prove correctness
- When B leaves monitor, A can run.
 - A might resume execution immediately
 - · ... or maybe another thread (C) will slip in!

Option 2: MESA Semantics (Xerox PARC)

What happens when a Signal is performed?

- * the signaling thread (A) continues.
- * the signaled thread (B) waits.
- * when A leaves monitor, then B runs.

<u>Issue:</u> What happens while B is waiting?

* can the condition that caused A to generate the signal be changed before B runs?

In MESA semantics a signal is more like a hint

* Requires B to recheck the condition on which it waited to see if it can proceed or must wait some more

Code for the "deposit" entry routine

```
monitor BoundedBuffer
  var buffer: array[n] of char
     nextIn, nextOut: int = 0
     cntFull: int = 0
     notEmpty: Condition
     notFull: Condition
  entry deposit(c: char)
     if cntFull == N
       notFull.Wait()
     endIf
     buffer[nextIn] = c
     nextIn = (nextIn+1) \mod N
     cntFull = cntFull + 1
     notEmpty.Signal()
   endEntry
  entry remove()
endMonitor
```

Code for the "deposit" entry routine

```
monitor BoundedBuffer
  var buffer: array[n] of char
     nextIn, nextOut: int = 0
     cntFull: int = 0
     notEmpty: Condition
     notFull: Condition
  entry deposit(c: char)
     while cntFull == N
       notFull.Wait()
     endWhile
     buffer[nextIn] = c
     nextIn = (nextIn+1) \mod N
     cntFull = cntFull + 1
     notEmpty.Signal()
   endEntry
  entry remove()
endMonitor
```

Code for the "remove" entry routine

```
monitor BoundedBuffer
  var buffer: array[n] of char
     nextIn, nextOut: int = 0
     cntFull: int = 0
     notEmpty: Condition
     notFull: Condition
  entry deposit(c: char)
  entry remove()
     if cntFull == 0
       notEmpty.Wait()
     endIf
     c = buffer[nextOut]
     nextOut = (nextOut+1) \mod N
     cntFull = cntFull - 1
     notFull.Signal()
   endEntry
endMonitor
```

Code for the "remove" entry routine

```
monitor BoundedBuffer
  var buffer: array[n] of char
     nextIn, nextOut: int = 0
     cntFull: int = 0
     notEmpty: Condition
     notFull: Condition
  entry deposit(c: char)
  entry remove()
     while cntFull == 0
       notEmpty.Wait()
     endWhile
     c = buffer[nextOut]
     nextOut = (nextOut+1) \mod N
     cntFull = cntFull - 1
     notFull.Signal()
   endEntry
endMonitor
```

"Hoare Semantics"

What happens when a Signal is performed?

The signaling thread (A) is suspended.

The signaled thread (B) wakes up and runs immediately.

B can assume the condition is now true/satisfied

From the original Hoare Paper:

"No other thread can intervene [and enter the monitor] between the signal and the continuation of exactly one waiting thread."

"If more than one thread is waiting on a condition, we postulate that the signal operation will reactivate the longest waiting thread. This gives a simple neutral queuing discipline which ensures that every waiting thread will eventually get its turn."

- Thread A holds the monitor lock
- Thread A signals a condition that thread B was waiting on
- Thread B is moved back to the ready queue?
 - * B should run immediately
 - * Thread A must be suspended...
 - the monitor lock must be passed from A to B
- When B finishes it releases the monitor lock
- Thread A must re-acquire the lock
 - * A is blocked, waiting to re-aquire the lock

Problem:

 Possession of the monitor lock must be passed directly from A to B and then eventually back to A

Implementation Ideas:

- Consider a signaled thread like B to be "urgent" after
 A releases the monitor lock
 - Thread C trying to gain initial entry to the monitor is not "urgent"
- Consider two wait lists associated with each
 MonitorLock (so now this is not exactly a mutex)
 - UrgentlyWaitingThreads
 - NonurgentlyWaitingThreads
- * Want to wake up urgent threads first, if any
- * Alternatively, B could be added to the front of the monitor lock queue

- Recommendation for Project 4 implementation:
 - * Do not modify the mutex methods provided, because future code will use them
 - * Create new classes:
 - MonitorLock -- similar to Mutex
 - · HoareCondition -- similar to Condition

Brinch-Hansen Semantics

Hoare Semantics

- * On signal, allow signaled process to run
- * Upon its exit from the monitor, signaling process continues.

Brinch-Hansen Semantics

- * Signaler must immediately exit following any invocation of signal
- * Restricts the kind of solutions that can be written
- * ... but monitor implementation is easier

Message Passing

Message Passing

- Interprocess Communication
 - via shared memory
 - * across machine boundaries
- Message passing can be used for synchronization or general communication
- Processes use send and receive primitives
 - receive can block (like waiting on a Semaphore)
 - send unblocks a process blocked on receive (just as a signal unblocks a waiting process)

Producer-consumer with message passing

The basic idea:

- * After producing, the producer sends the data to consumer in a message
- * The system buffers messages
 - The producer can out-run the consumer
 - The messages will be kept in order
- * But how does the producer avoid overflowing the buffer?
 - After consuming the data, the consumer sends back an "empty" message
 - Consumer starts by sending N empty messages
- * A fixed number of messages (N=100)
- * The messages circulate back and forth.

Producer-consumer with message passing

```
thread consumer
  var c, em: char
  while true
    Receive(producer, &c) -- Wait for a char
    Send(producer, &em) -- Send empty message back
    // Consume char...
  endWhile
end
```

Producer-consumer with message passing

```
thread producer
  var c, em: char
  while true
    // Produce char c...
    Receive(consumer, &em) -- Wait for an empty msg
    Send(consumer, &c) -- Send c to consumer
  endWhile
end
```

Design choices for message passing

Option 1: Mailboxes

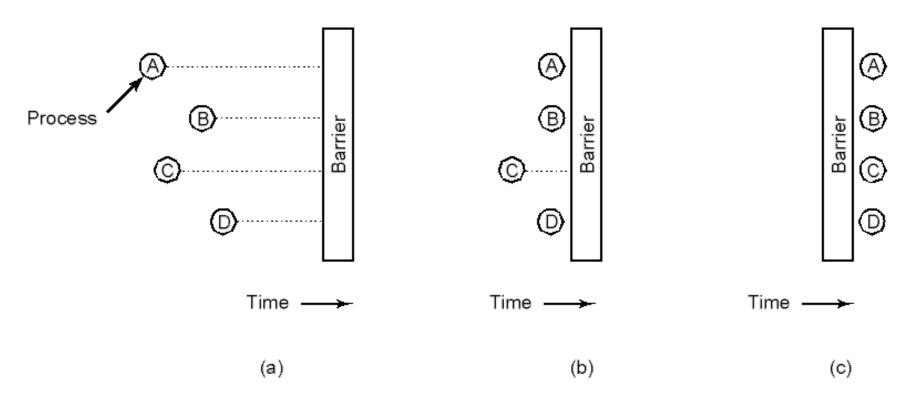
- * System maintains a buffer of sent, but not yet received, messages
- * Must specify the size of the mailbox ahead of time
- * Sender will be blocked if the buffer is full
- * Receiver will be blocked if the buffer is empty

Design choices for message passing

Option 2: No buffering

- * If Send happens first, the sending thread blocks
- * If Receive happens first, the receiving thread blocks
- * Sender and receiver must Rendezvous (ie. meet)
- * Both threads are ready for the transfer
- * The data is copied / transmitted
- * Both threads are then allowed to proceed

Barriers



- * Processes approaching a barrier
- * All processes but one blocked at barrier
- Last process arrives; all are let through

Review of a Practical Concurrent Programming Issue - Reentrant Functions

Reentrant code

A function/method is said to be reentrant if...

A function that has been invoked may be invoked again before the first invocation has returned, and will still work correctly

In the context of concurrent programming...

A reentrant function can be executed simultaneously by more than one thread, with no ill effects

Reentrant Code

Consider this function...

```
var count: int = 0
function GetUnique () returns int
  count = count + 1
  return count
endFunction
```

What if it is executed by different threads concurrently?

Reentrant Code

Consider this function...

```
var count: int = 0
function GetUnique () returns int
  count = count + 1
  return count
endFunction
```

- What if it is executed by different threads concurrently?
 - * The results may be incorrect!
 - * This routine is not reentrant!

When is code reentrant?

- Some variables are
 - * "local" -- to the function/method/routine
 - * "global" -- sometimes called "static"
- Access to local variables?
 - * A new stack frame is created for each invocation
 - * Each thread has its own stack
- What about access to global variables?
 - * Must use synchronization!

Does this work?

```
var count: int = 0
    myLock: Mutex

function GetUnique () returns int
    myLock.Lock()
    count = count + 1
    myLock.Unlock()
    return count
endFunction
```

What about this?

```
var count: int = 0
    myLock: Mutex

function GetUnique () returns int
    myLock.Lock()
    count = count + 1
    return count
    myLock.Unlock()
endFunction
```

Making this function reentrant

```
var count: int = 0
    myLock: Mutex
function GetUnique () returns int
  var i: int
  myLock.Lock()
  count = count + 1
  i = count
  myLock.Unlock()
  return i
endFunction
```

Quiz

- What is the difference between a monitor and a semaphore?
 - * Why might you prefer one over the other?
- How do the wait/signal methods of a condition variable differ from the wait/signal methods of a semaphore?
- What is the difference between Hoare and Mesa semantics for condition variables?
 - * What implications does this difference have for code surrounding a wait() call?

نویسنده و خواننده

مثالی از کنترل همروندی:

The readers and writers problem

- Multiple readers and writers want to access a database (each one is a thread)
- Multiple readers can proceed concurrently
- Writers must synchronize with readers and other writers
 - * only one writer at a time!
 - * when someone is writing, there must be no readers!

Goals:

- Maximize concurrency.
- * Prevent starvation.

Designing a solution

- How will we model the readers and writers?
- What state variables do we need?
 - * .. and which ones are shared?
 - * and how will we protect them?
- How will the writers wait?
- How will the writers wake up?
- How will readers wait?
- How will the readers wake up?
- What problems do we need to look out for?

Is this a valid solution to readers & writers?

```
var mut: Mutex = unlocked
                                  Reader Thread:
    db: Semaphore = 1
                                    while true
    rc: int = 0
                                      Lock (mut)
                                      rc = rc + 1
                                      if rc == 1
                                        Wait (db)
Writer Thread:
                                      endIf
  while true
                                      Unlock (mut)
    ... Remainder Section...
                                      ... Read shared data...
    Wait (db)
                                      Lock (mut)
    ...Write shared data...
                                      rc = rc - 1
    Signal (db)
                                      if rc == 0
  endWhile
                                        Signal (db)
                                      endIf
                                      Unlock (mut)
```

... Remainder Section...

endWhile

Readers and writers solution

- Does the previous solution have any problems?
 - * is it "fair"?
 - * can any threads be starved? If so, how could this be fixed?
 - * ... and how much confidence would you have in your solution?

Quiz

- What is a race condition?
- How can we protect against race conditions?
- Can locks be implemented simply by reading and writing to a binary variable in memory?
- How can a kernel make synchronization-related system calls atomic on a uniprocessor?
 - * Why wouldn't this work on a multiprocessor?
- Why is it better to block rather than spin on a uniprocessor?
- Why is it sometimes better to spin rather than block on a multiprocessor?

Quiz

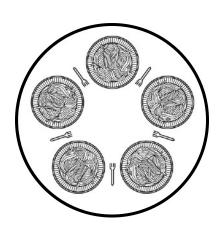
- When faced with a concurrent programming problem, what strategy would you follow in designing a solution?
- What does all of this have to do with Operating Systems?

غذاى فيلسوفان

مثالی از کنترل همروندی:

Dining philosophers problem

- Five philosophers sit at a table
- One chopstick between each philosopher (need two to eat)



Each philosopher is modeled with a thread

```
while(TRUE) {
   Think();
   Grab first chopstick;
   Grab second chopstick;
   Eat();
   Put down first chopstick;
   Put down second chopstick;
}
```

- Why do they need to synchronize?
- How should they do it?

Is this a valid solution?

```
#define N 5

Philosopher(i) {
    while(TRUE) {
        Think();
        take_chopstick(i);
        take_chopstick((i+1)% N);
        Eat();
        put_chopstick(i);
        put_chopstick((i+1)% N);
    }
}
```

Problems

Potential for deadlock!

Working towards a solution ...

```
take_chopsticks(i)
#define N 5
Philosopher() {
  while(TRUE) {
    Think();
    take chopstick(i);
                                     put_chopsticks(i)
    take chopstick((i+1)% N);
    Eat();
    put chopstick(i);
    put chopstick((i+1)% N);
```

Working towards a solution ...

```
#define N 5

Philosopher() {
    while(TRUE) {
        Think();
        take_chopsticks(i);
        Eat();
        put_chopsticks(i);
    }
}
```

Taking chopsticks

```
int state[N]
semaphore mutex = 1
semaphore sem[i]
```

```
take_chopsticks(int i) {
  wait(mutex);
  state [i] = HUNGRY;
  test(i);
  signal(mutex);
  wait(sem[i]);
}
```

```
// only called with mutex set!

test(int i) {
  if (state[i] == HUNGRY &&
      state[LEFT] != EATING &&
      state[RIGHT] != EATING) {
      state[i] = EATING;
      signal(sem[i]);
  }
}
```

Putting down chopsticks

```
int state[N]
semaphore mutex = 1
semaphore sem[i]
```

```
put_chopsticks(int i) {
   wait(mutex);
   state [i] = THINKING;
   test(LEFT);
   test(RIGHT);
   signal(mutex);
}
```

```
// only called with mutex set!

test(int i) {
  if (state[i] == HUNGRY &&
      state[LEFT] != EATING &&
      state[RIGHT] != EATING) {
      state[i] = EATING;
      signal(sem[i]);
  }
}
```

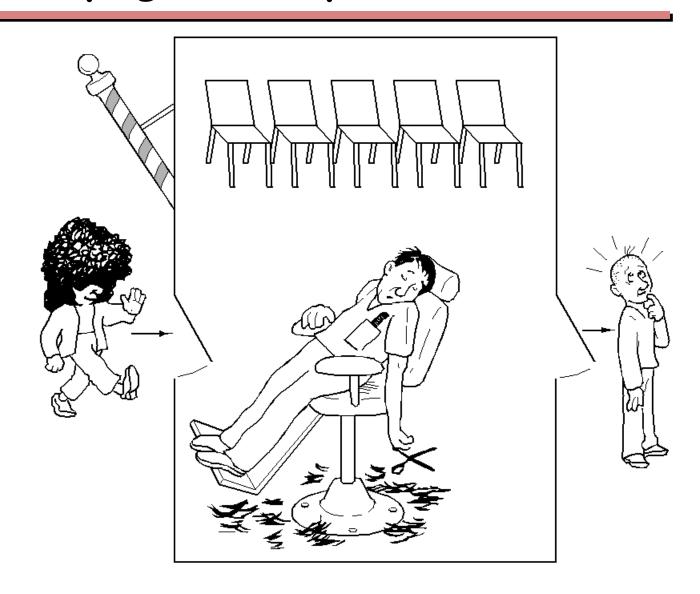
Dining philosophers

- Is the previous solution correct?
- What does it mean for it to be correct?
- Is there an easier way?

آرایشگر

مثالی از کنترل همروندی:

The sleeping barber problem



The sleeping barber problem

Barber:

- * While there are people waiting for a hair cut, put one in the barber chair, and cut their hair
- * When done, move to the next customer
- * Else go to sleep, until someone comes in

Customer:

- * If barber is asleep wake him up for a haircut
- * If someone is getting a haircut wait for the barber to become free by sitting in a chair
- * If all chairs are all full, leave the barbershop

Designing a solution

- How will we model the barber and customers?
- What state variables do we need?
 - * .. and which ones are shared?
 - * and how will we protect them?
- How will the barber sleep?
- How will the barber wake up?
- How will customers wait?
- What problems do we need to look out for?

Is this a good solution?

const CHAIRS = 5

var customers: Semaphore

barbers: Semaphore

```
lock: Mutex
numWaiting: int = 0

Barber Thread:
while true
Wait(customers)
Lock(lock)
numWaiting = numWaiting-1
Signal(barbers)
Unlock(lock)
```

CutHair()

endWhile

```
Lock(lock)
if numWaiting < CHAIRS
  numWaiting = numWaiting+1
  Signal(customers)
  Unlock(lock)
  Wait(barbers)
  GetHaircut()
else -- give up & go home
  Unlock(lock)
endIf</pre>
```