# Pattern Recognition - Exam

(08/04/2015) 2h30: open book exam with a pocket calculator

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# Exercise: Machine Learning Theory MCQ (3 points)

- -Circle the letter corresponding to the correct answer (only one is correct).
- -You can leave questions unanswered. Each correct answer adds one point.
- -Each incorrect answer subtracts half a point.
  - 1. A training set of labeled examples is a sample drawn over a space  $\mathcal{Z} = \mathcal{X} \times \mathcal{Y}$ , where  $\mathcal{X}$  is the feature space and  $\mathcal{Y}$  is the set of classes. What does  $\mathcal{Z} = \mathcal{X} \times \mathcal{Y}$  mean?
    - a.  $\mathcal{Z}$  is a joint space over  $\mathcal{X}$  and  $\mathcal{Y}$ .
    - b.  $\mathcal{Z}$  corresponds to the product of the features by the class.
    - c.  $\mathcal{Z}$  is a finite set of examples jointly drawn from  $\mathcal{X}$  and  $\mathcal{Y}$ .
  - 2. Why is h called *hypothesis* in machine learning?
    - a. Because h is like a random guessing.
    - b. Because a statistical test is performed on h w.r.t. an alternative hypothesis.
    - c. Because h corresponds to one of the possible models which fit the data.
  - 3. What is the right assertion:
    - a. The higher the variance, the higher the risk of overfitting.
    - b. The smaller the bias, the smaller the variance.
    - c. The total error of a classifier is the sum of the bias and the variance.
  - 4. The following three hypotheses are supposed to be consistent with respect to a given training set S. According to Occam's razor principle, what is the best one?

a. 
$$y = 2x^2 + x + 1$$
.

b. 
$$y = \sqrt{5}x + 2\sqrt{\pi}$$
.

c. 
$$(x-1)^2 + (y-1)^2 = 2$$
.

- 5. The higher the number of iterations T of Adaboost
  - a. The smaller  $\prod_{t=1}^{T} Z_t$ .
  - b. The larger the risk of overfitting.
  - c. The higher the Vapnik-Chervonenkis dimension of the weak classifiers.

- 6. The true risk of a kNN algorithm
  - a. Always decreases when k grows.
  - b. Is lower bounded by  $\epsilon^*$ .
  - c. Tends towards 0 when the number of training examples tends to the infinity.

### Exercise 2: Decision Trees (3 points)

Consider the following set of training examples:

Ex	Target	a1	a2
1	+	F	F
2	+	F	$\mathbf{T}$
3	-	F	$\mathbf{F}$
4	+	Т	$\mathbf{F}$
5	-	T	$\mathbf{T}$
6	-	F	$\mathbf{T}$
7	_	T	$\mathbf{F}$
8	+	F	$\mathbf{T}$

- 1. (0.5 pt) What is the entropy of this collection of training examples with respect to the target attribute?
- 2. (1 pt) What is the information gain of a1 and a2 on these training examples?
- 3. (1 pt) Draw the decision tree returned by the ID3 algorithm on this example (use the mode of the Target as prediction in each leaf, in case of a tie, you can predict +)
- 4. (0.5 pt) What would be the accuracy of your tree on the following test set:

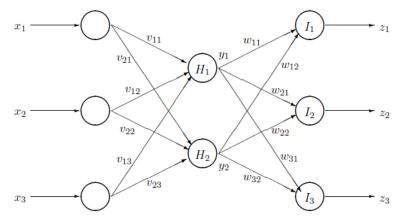
Ex	Target	a1	a2
9	-	Т	F
10	-	F	$\mathbf{T}$

#### Exercise 3: Artificial Neural Networks (3 point)

Consider a unique neuron with 4 entries, a weight vector equal to  $\mathbf{w} = [1, 2, 3, 4]^T$  and a bias  $\theta = 0$  (zero). Its activation function is linear with a proportionality constant equal to 2 (i.e. f(x) = 2x).

1. (1 pt) If the input vector is  $\mathbf{x} = [4, 8, 5, 6]^T$ , what would be the output of the neuron? (the possible answers are A = 1. B = 56. C = 59. D = 112. E = 118. Explain your answer).

Now we work with the following network:



An input example  $\mathbf{x} = [x1, x2, x3]^T$  (with true label  $\mathbf{t} = [t1, t2, t3]^T$ ) is presented to the network. The computed output is  $\mathbf{z} = [z1, z2, z3]^T$ .

- 2. (0.75 pt) What would be the usual computing sequence to train this network using a standard back-propagation algorithm? (the possible answers are A, B, C and D. Explain very briefly why you chose an answer)
  - A. (1) compute yj = f(Hj), (2) compute zk = f(Ik),
    - (3) update vji, (4) update wkj.
  - B. (1) compute yj = f(Hj), (2) compute zk = f(Ik),
    - (3) update wkj , (4) update vji.
  - C. (1) compute yj = f(Hj), (2) update vji,
    - (3) compute zk = f(Ik), (4) update wkj.
  - D. (1) compute zk = f(Ik), (2) update wkj,
    - (3) compute yj = f(Hj), (4) update vji.
- 3. (1.25 pts)The weight vector of the network is  $v1 = [0.4, -0.6, 1.9]^T$ ,  $v2 = [-1.2, 0.5, -0.7]^T$ ,  $w1 = [1.0, -3.5]^T$ ,  $w2 = [0.5, -1.2]^T$ ,  $w3 = [0.3, 0.6]^T$ . For each neuron, the bias  $\theta$  is fixed to 0. The activation function of each neuron is a sigmoid. If the input vector is  $x = [1.0, 2.0, 3.0]^T$ , what would be the output computed for  $y_1$  (only the output of the first hidden layer). (the possible answers are A= -2.300, B= 0.091, C= 0.644, D= 0.993, E= 4.900. Explain your answer)

#### Exercise 4: SVM and Optimization (7 points)

- 4.1 True or false (1.5 points)
  - 1. The dual form of the SVM soft margin does not verify the strong duality property.
  - 2. The kernel trick cannot be used in the perceptron learning algorithm.
  - 3. Optimizing the margin leads to better generalization bound.
- **4.2 Optimization (3 points)** Let  $S = \{(\mathbf{x_i}, y_i)\}_{i=1}^n$  be a learning sample such that  $\mathbf{x_i} \in \mathbb{R}^d$  and  $y_i \in \{-1, 1\}$ , consider now the following optimization problem:

$$\label{eq:continuity} \begin{aligned} & \min_{\mathbf{w},b} & & \|\mathbf{w}\|_1 \\ \text{subject to} & & \ell_i(\langle \mathbf{w}, \mathbf{x_i} \rangle + b) \geq 2, & & 1 \leq i \leq n. \end{aligned}$$

- 1. Relax the problem to allow some amount of constraint violation (introduce slack variables).
- 2. Reformulate the resulting problem to avoid using the  $\|\cdot\|_1$  norm and put it in standard form.

**4.3 - SVM dual formulation (2.5 points)** We would like to implement an SVM solver with AMPL. We assume to have access to a parameter file encoding the learning data, as presented below:

```
set dim:= 1 2;
set examples:= 1 2 3 4;
param points :=
    1 1 1
    1 2 1
    2 1 0
    2 2 1
    3 1 1
    3 2 0
    4 1 2
    4 2 0;

param labels := 1 1
    2 1
    3 -1
    4 -1;
```

Write an AMPL code corresponding to an implementation of the SVM soft-margin dual form.

## Exercise 5: HMM (4 points)

We would like to create a tool able to produce some human laugh such has *hahaha* or *hihihi*. To simplify, we assume that this tool can only produce 3 sounds denoted by the following symbols: ha, hi, hou and we build the tool with 3 blocks able to produce the sounds. Each block can generate the sounds randomly such that:

- the first block can only produce ha or hi, and the probability of getting an hi is strictly greater than the proba of getting an ha,
- the second can only generate hou, hi in a uniform way,
- the last one can generate the 3 sounds such that the probability of ha is greater than the sum of the probability of hi and hou.

In this context, a sequence ha ha hi hi hou represents a sequence of sounds produced randomly by the blocks. To generate a sequence, we fix a target length, say n, and we generate n sounds with the tool. Then a first block is chosen randomly from a uniform distribution among the 3 blocks. Then, we choose randomly a sound among the possible ones in the considered block, again according to a uniform distribution over the sounds. Then, we move to the next block, all the blocks have the same probability to be chosen from given a block.

- 1. Propose a way to model this tool by a HMM. Draw the HMM graphically (states, transitions and probabilities).
- 2. Compute the probability to generate the sequence hou hou ha.
- 3. What is the most likely sequence of states that explains the previous sequence?