Windward:

DATA ANALYSIS TASK

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# The task is to identify a specific type of dock according to AIS data

# The analyze Algorithm steps:

1. Getting the data:

Read the CSV data to a Pandas Dataframe

Grouping by MMSI, instantiate ship Models

2. cleaning

Each ship record that is inconsistent (had encountered changes) in the size, Class, and distances, are discarded

Ships with a mismatch in the size and distances are discarded

3. analyzing ships:

Each ship, when **speed is 0** (stopped) for **at least 4 (configurable) hours**, was counted as docked for that period. The docking locations were saved

4. analyzing docking locations:

Each saved docking location, that its distance is larger than the configurable resolution, instantiates a dock Model

#### The dock model has:

Latitude, longitude and heading

And from the docked ships we can learn: the min/max size/width of the ships in can consist and the classes of ships docked

In addition I used Google Static Map API to get a satellite image and the

Elevation API (which was according to the documentation to give the depth, but only gives sea level according to my observations)

# About the data

#### General info about the given data

[56057 rows x 12 columns]

Columns:

Time, MMSI, Latitude, Longitude, Speed, Heading, Class, Size, DistanceToBow, DistanceToStern, DistanceToPort

Date format: "yyyy-MM-dd hh:mm:ss"

len (set(df['MMSI']))

There are 327 different MMSI

max(df['Latitude'])

52.01082999999999

min(df['Latitude'])

51.844949999999997

max(df['Longitude'])

4.5812230000000005

min(df['Longitude'])

3.950333000000001

Stats:

30 ships has metadata consistency problem

109 ships are not well measured

215 ships are bigger the 200

# Extra: Histogram tool

The docks can be briefly identified using a histogram plot of all data's longitude and latitude, assuming that a position should be occurring a lot more where it represents a dock ( a ship transmitted a lot from the same position: the location can be obtained by comparing the occurrences of the specific coordinate. Figure [1] and Figure [2]

A docking state can be flagged also where the heading of ship equals to one of the occurring heading in the heading histogram Figure [3]

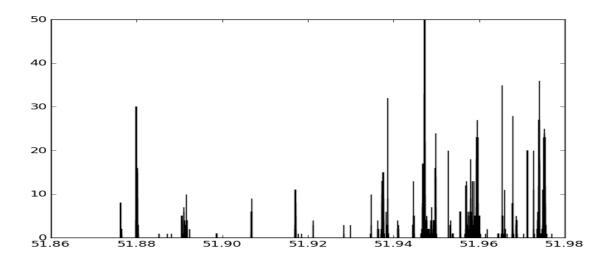


Figure 1histogram of ships longitudes

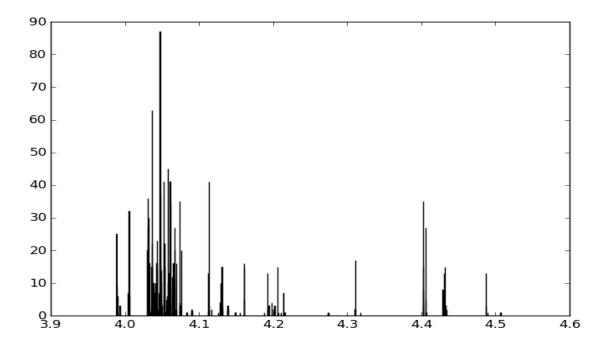


Figure 2 histogram of ships latitudes

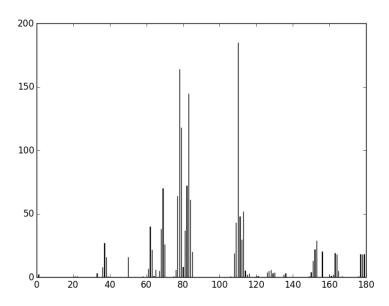


Figure 3 Heading angle of all ships

# System design and assumptions

#### Data Integrity tests:

- Consistency of data that is entered manually: 'MMSI','Class', 'Size', 'DistanceToBow',
  'DistanceToStern', 'DistanceToPort', 'DistanceToStarboard'
- 2. size == distance to bow + distance to stern width < size</p>

#### **Configuration:**

All system configuration and parameters controlled via the configuration module

#### Assumptions

#### Docking locations assumptions:

- 1. Docking meaning speed =0
- 2. minimal docking time: 4 hours (configurable)
- 3. heading = constant on docking ( not used)
- 4. Elevation (depth) google api only sea level acquired, can disqualify terrain errors
- 5. What google api: locations (optional)
- 6. satellite image with orientation [2]

#### Relevant ship assumptions:

- 1. minimal size of ship = 250m (configurable)
- 2. not marked as classes: "High speed craft", "Military or law", "Fishing", "Passenger", "Pleasure"
- 3. are consistent in entered parameters (mmsi, class, size and distances ) meaning the AIS was set professionally and is reliable

### A talk about distances and Angles

```
x amount of size (in meters) is equivalent to : r\alpha = 6378134 \text{ m , rb} = 6356752.31 \text{ m (Wikipedia[1])} a. earth is sphere: b. earth is ellipsoid- [out of scope] we will talk only on the sphere case r = (ra + rb)/2 = 6367443.155 \text{ m} \Delta x = (\Delta \log/360) * pi * r \Delta y = (\Delta \log/360) * pi * r
```

(Or in short, multiply by  $\alpha$  = 55566.424 do get the distance between two angles)

Now let's calculate the Google maps zoom size:

a \* Angle= Distance

We want to see about 5 cm: 200 m ratio (sized ship), meaning: 200/0.05 =times: 4000

Where zoom = 1, the closest zoom we have is  $2^2 = 4096$ .

Meaning a fraction of times 4096 of each axis comparing to full map: zoom=1 ->[-180:180],[-90:90]

Given L is the latitude axis length, L / 4096 =  $\Delta y$  = a \*  $\Delta lat$ 

```
\Deltalimit_latitude, \Deltalimit_logitude = Lx, Ly / (a*4096)
```

```
a = 55566.424, Ly = 40007860 m, Lx =40075016 m
```

let's determine minimal angular resolution: let say 100 m [0.1?], (minimal angle of where we wish to classify an object in space. Well take it slightly less than the ships size)

Meaning:

```
\( \text{\text{alat reolution}} = 100 / ( \text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\tincet{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\texi}\text{\text{\text{\text{\texi}\text{\text{\text{\text{\text{\text{\texi}\text{\text{\text{\texiclex{\tii}\tin\tint{\text{\texit{\texicr{\texiclex{\texiclex{\texi}\ti}
```

Meaning we need only 5 numbers after a decimal point accuracy

**REMARK-** it turned out I could not predict the Google Api Zoom scale, but this exercise did a great deal to understand and asses the resolution

# Results:

On the setting of resolution = 0.001647 degrees: the system detected 58 docks.

Here are the first 4 out of total 58 desired docks found (can be maybe calibrated to more, with the cost of duplicates by setting the resolution)

more images can be found at:

https://picasaweb.google.com/116781616540240633183/PredictedDocks

The code:

https://github.com/forye/docks\_images

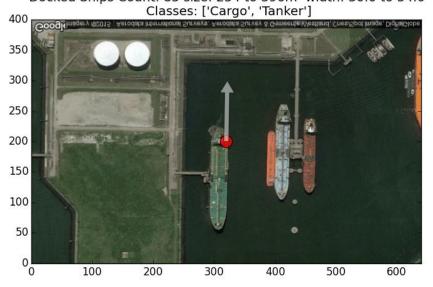
After installing all the correct module, run get\_docks\_candidates.py, to replicate the results,

Play with the configuration at config\configuration.py

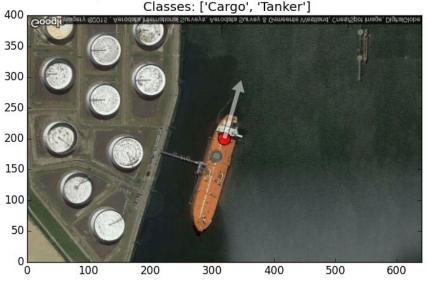
Longitude:4.43041 Latitude:51.89093 Heading:63 Elevation:0.644188463688 Docked Ships Count: 49 size: 254 to 300m width: 30.0 to 48.0 Classes: ['Cargo', 'Tanker']



Longitude:4.138867 Latitude:51.95333 Heading:359 Elevation:0 Docked Ships Count: 85 size: 254 to 396m width: 30.0 to 54.0



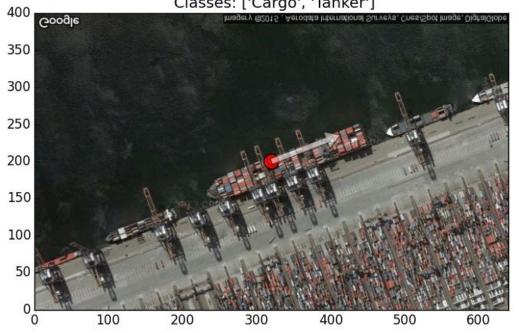
Longitude:4.160717 Latitude:51.94468 Heading:344 Elevation:0 Docked Ships Count: 43 size: 254 to 396m width: 30.0 to 54.0 Classes: ['Cargo', 'Tanker']



Longitude:4.036292 Latitude:51.97386 Heading:291 Elevation:0

Docked Ships Count: 56 size: 254 to 400m width: 30.0 to 60.0

Classes: ['Cargo', 'Tanker']



# references

[1] Wikipedia

https://en.wikipedia.org/wiki/Earth

[2] Google Static Maps API

https://developers.google.com/maps/documentation/static-maps/

[3] Google Elevation API

https://developers.google.com/maps/documentation/elevation/intro

[4] GitHub public repository: the code, resources and results

https://github.com/forye/docks\_images.git