Foundations of Software Fall 2023

Week 3

1

3

Review (and more details)

2

Recall: Simple Arithmetic Expressions

The set $\ensuremath{\mathcal{T}}$ of terms is defined by the following abstract grammar:

Recall: Inference Rule Notation

More explicitly: The set ${\mathcal T}$ is the $\mathit{smallest}$ set closed under the following rules.

$$\label{eq:true} \begin{split} & true \in \mathcal{T} & & false \in \mathcal{T} & 0 \in \mathcal{T} \\ & \frac{t_1 \in \mathcal{T}}{succ \ t_1 \in \mathcal{T}} & \frac{t_1 \in \mathcal{T}}{pred \ t_1 \in \mathcal{T}} & \frac{t_1 \in \mathcal{T}}{iszero \ t_1 \in \mathcal{T}} \\ & \frac{t_1 \in \mathcal{T} \quad t_2 \in \mathcal{T} \quad t_3 \in \mathcal{T}}{if \ t_1 \ then \ t_2 \ else \ t_3 \in \mathcal{T}} \end{split}$$

Generating Functions

Each of these rules can be thought of as a generating function that, given some elements from \mathcal{T} , generates some other element of \mathcal{T} . Saying that \mathcal{T} is closed under these rules means that \mathcal{T} cannot be made any bigger using these generating functions — it already contains everything "justified by its members."

$$\begin{split} & \text{true} \in \mathcal{T} & \text{false} \in \mathcal{T} & 0 \in \mathcal{T} \\ & \underbrace{t_1 \in \mathcal{T}}_{\text{succ } t_1 \in \mathcal{T}} & \underbrace{t_1 \in \mathcal{T}}_{\text{pred } t_1 \in \mathcal{T}} & \underbrace{t_1 \in \mathcal{T}}_{\text{iszero } t_1 \in \mathcal{T}} \\ & \underbrace{t_1 \in \mathcal{T}}_{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 \in \mathcal{T}}_{\text{3}} \end{split}$$

Let's write these generating functions explicitly.

```
\begin{array}{lll} F_1(U) &=& \{ \text{true} \} \\ F_2(U) &=& \{ \text{false} \} \\ F_3(U) &=& \{ 0 \} \\ F_4(U) &=& \{ \text{succ } \mathbf{t}_1 \mid \mathbf{t}_1 \in U \} \\ F_5(U) &=& \{ \text{pred } \mathbf{t}_1 \mid \mathbf{t}_1 \in U \} \\ F_6(U) &=& \{ \text{iszero } \mathbf{t}_1 \mid \mathbf{t}_1 \in U \} \\ F_7(U) &=& \{ \text{if } \mathbf{t}_1 \text{ then } \mathbf{t}_2 \text{ else } \mathbf{t}_3 \mid \mathbf{t}_1, \mathbf{t}_2, \mathbf{t}_3 \in U \} \end{array}
```

Each one takes a set of terms ${\cal U}$ as input and produces a set of "terms justified by ${\cal U}$ " as output.

If we now define a generating function for the whole set of inference rules (by combining the generating functions for the individual rules),

$$F(U) = F_1(U) \cup F_2(U) \cup F_3(U) \cup F_4(U) \cup F_5(U) \cup F_6(U) \cup F_7(U)$$

then we can restate the previous definition of the set of terms $\ensuremath{\mathcal{T}}$ like this:

Definition:

- ▶ A set U is said to be "closed under F" (or "F-closed") if $F(U) \subseteq U$.
- ▶ The set of terms $\mathcal T$ is the smallest F-closed set. (I.e., if $\mathcal O$ is another set such that $F(\mathcal O)\subseteq \mathcal O$, then $\mathcal T\subseteq \mathcal O$.)

Our alternate definition of the set of terms can also be stated using the generating function F:

$$S_0 = \emptyset$$

$$S_{i+1} = F(S_i)$$

$$S = \bigcup_i S_i$$

Compare this definition of ${\cal S}$ with the one we saw last time:

$$\begin{array}{lll} \mathcal{S}_0 & = & \emptyset \\ \mathcal{S}_{i+1} & = & \left\{ \texttt{true}, \texttt{false}, 0 \right\} \\ & \cup & \left\{ \texttt{succ } \texttt{t}_1, \texttt{pred } \texttt{t}_1, \texttt{iszero } \texttt{t}_1 \mid \texttt{t}_1 \in \mathcal{S}_i \right\} \\ & \cup & \left\{ \texttt{if } \texttt{t}_1 \texttt{ then } \texttt{t}_2 \texttt{ else } \texttt{t}_3 \mid \texttt{t}_1, \texttt{t}_2, \texttt{t}_3 \in \mathcal{S}_i \right\} \end{array}$$

$$S = \bigcup_i S_i$$

We have "pulled out" F and given it a name.

8

6

7

Note that our two definitions of terms characterize the same set from different directions:

- "from above," as the intersection of all F-closed sets;
- "from below," as the limit (union) of a series of sets that start from ∅ and get "closer and closer to being F-closed."

Proposition 3.2.6 in the book shows that these two definitions actually define the same set.

Warning: Hard hats on for the next slide!

9

Structural Induction

The principle of structural induction on terms can also be re-stated using generating functions:

```
Suppose T is the smallest F-closed set.
```

```
If, for each set U, from the assumption "P(u) holds for every u \in U" we can show "P(v) holds for any v \in F(U)," then P(t) holds for all t \in T.
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```

Why?

11

11

Structural Induction

Why? Because:

- ▶ We assumed that T was the *smallest F*-closed set, i.e., that $T \subseteq O$ for any other F-closed set O.
- ▶ But showing

```
for each set U,
given P(u) for all u \in U
we can show P(v) for all v \in F(U)
```

amounts to showing that "the set of all terms satisfying P" –call it O– is itself an F-closed set. (recall: O is F-closed if $F(O) \subseteq O$)

▶ Since $T \subseteq O$, every element of T satisfies P.

Structural Induction

```
If, for each term s,
given P(r) for all immediate subterms r of s
we can show P(s),
then P(t) holds for all t.
```

Recall, from the definition of \mathcal{S} , it is clear that, if a term \mathbf{t} is in \mathcal{S}_i , then all of its immediate subterms must be in \mathcal{S}_{i-1} , i.e., they must have strictly smaller depths. Therefore:

```
If, for each term s,
given P(r) for all immediate subterms r of s
we can show P(s),
then P(t) holds for all t.
```

Slightly more explicit proof:

- Assume that for each term s, given P(r) for all immediate subterms of s, we can show P(s).
- ► Then show, by induction on i, that P(t) holds for all terms t with depth i.
- ▶ Therefore, P(t) holds for all t.

Operational Semantics and Reasoning

15

13

14

Recall: Abstract Machines

An abstract machine consists of:

- ▶ a set of *states*
- ▶ a transition relation on states, written →

For the simple languages we are considering at the moment, the term being evaluated is the whole state of the abstract machine.

16

```
Recall: Syntax for Booleans

Terms and values

t ::= terms
constant true
false constant false
if t then t else t values
true true value
false false false value
```

Recall: Operational Semantics for Booleans

The evaluation relation $t \longrightarrow t'$ is the smallest relation closed under the following rules:

```
\begin{array}{c} \text{if true then } t_2 \text{ else } t_3 \longrightarrow t_2 \quad \text{(E-IFTRUE)} \\ \\ \text{if false then } t_2 \text{ else } t_3 \longrightarrow t_3 \quad \text{(E-IFFALSE)} \\ \\ \\ \frac{t_1 \longrightarrow t_1'}{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 \longrightarrow \text{if } t_1' \text{ then } t_2 \text{ else } t_3} \text{(E-IF)} \end{array}
```

An example

```
Let t be the term if true then (if false then false else true) else false
```

Clicker question: What is t' in $t \longrightarrow t'$?

A. t' = true

 $B. \ t' = if \ true \ then \ true \ else \ false$

C. t'=if false then false else true

 $\ensuremath{\mathsf{D}}.$ There is no such $\ensuremath{\mathsf{t}}'$

E. I don't know

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18

Derivations

We can record the "justification" for a particular pair of terms that are in the evaluation relation in the form of a tree.

(on the board)

Terminology:

- ▶ These trees are called *derivation trees* (or just *derivations*).
- ▶ The final statement in a derivation is its conclusion.
- We say that the derivation is a witness for its conclusion (or a proof of its conclusion) it records all the reasoning steps that justify the conclusion.

20

Observation

Lemma: Suppose we are given a derivation tree ${\cal D}$ witnessing the pair $({\bf t},{\bf t}')$ in the evaluation relation. Then either

- 1. the final rule used in $\mathcal D$ is E-IFTRUE and we have t=if true then t_2 else t_3 and $t'=t_2$, for some t_2 and t_3 , or
- 2. the final rule used in $\mathcal D$ is E-IFFALSE and we have t=if false then t_2 else t_3 and $t'=t_3$, for some t_2 and t_3 , or
- 3. the final rule used in \mathcal{D} is E-IF and we have $\mathsf{t} = \mathsf{if} \ \mathsf{t}_1$ then t_2 else t_3 and $\mathsf{t}' = \mathsf{if} \ \mathsf{t}'_1$ then t_2 else t_3 , for some $\mathsf{t}_1, \, \mathsf{t}'_1, \, \mathsf{t}_2$, and t_3 ; moreover, the immediate subderivation of $\mathcal D$ witnesses $(\mathsf{t}_1, \, \mathsf{t}'_1) \in \longrightarrow$.

21

Induction on Derivations

We can now write proofs about evaluation "by induction on derivation trees."

Given an arbitrary derivation $\mathcal D$ with conclusion $t \longrightarrow t'$, we assume the desired result for its immediate sub-derivation (if any) and proceed by a case analysis (using the previous lemma) of the final evaluation rule used in constructing the derivation tree.

E.g....

Induction on Derivations — Example

Theorem: If $t \longrightarrow t'$, i.e., if $(t, t') \in \longrightarrow$, then size(t) > size(t'). **Proof:** By induction on a derivation \mathcal{D} of $t \longrightarrow t'$.

- 1. Suppose the final rule used in \mathcal{D} is E-IFTRUE, with t=if true then t_2 else t_3 and $t'=t_2$. Then the result is immediate from the definition of \emph{size} .
- 2. Suppose the final rule used in $\mathcal D$ is E-IFFALSE, with $\mathsf t=\mathsf i\mathsf f$ false then $\mathsf t_2$ else $\mathsf t_3$ and $\mathsf t'=\mathsf t_3$. Then the result is again immediate from the definition of size .
- 3. Suppose the final rule used in \mathcal{D} is E-IF, with $\mathbf{t}=\mathbf{if}\ \mathbf{t}_1$ then \mathbf{t}_2 else \mathbf{t}_3 and $\mathbf{t}'=\mathbf{if}\ \mathbf{t}_1'$ then \mathbf{t}_2 else \mathbf{t}_3 , where $(\mathbf{t}_1,\mathbf{t}_1')\in\longrightarrow$ is witnessed by a derivation \mathcal{D}_1 . By the induction hypothesis, $\mathit{size}(\mathbf{t}_1) > \mathit{size}(\mathbf{t}_1')$. But then, by the definition of size , we have $\mathit{size}(\mathbf{t}) > \mathit{size}(\mathbf{t}')$.

Normal forms

A *normal form* is a term that cannot be evaluated any further — i.e., a term t is a normal form (or "is in normal form") if there is no t' such that $t \longrightarrow t'$.

A normal form is a state where the abstract machine is halted — i.e., it can be regarded as a "result" of evaluation.

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Recall that we intended the set of *values* (the boolean constants true and false) to be exactly the possible "results of evaluation." Did we get this definition right?

24

Values = normal forms

Theorem: A term ${\bf t}$ is a value iff it is in normal form.

The \Longrightarrow direction is immediate from the definition of the evaluation relation.

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Proof

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For the \longleftarrow direction,

25

25

Values = normal forms

Theorem: A term t is a value iff it is in normal form.

The \Longrightarrow direction is immediate from the definition of the evaluation relation.

For the \longleftarrow direction, it is convenient to prove the contrapositive: If t is not a value, then it is not a normal form.

25

26

Values = normal forms

Theorem: A term t is a value iff it is in normal form. **Proof:**

The \Longrightarrow direction is immediate from the definition of the evaluation relation.

For the \longleftarrow direction, it is convenient to prove the contrapositive: If t is not a value, then it is not a normal form. The argument goes by induction on t.

Note, first, that t must have the form if t_1 then t_2 else t_3 (otherwise it would be a value). If t_1 is true or false, then rule $\operatorname{E-IfTrue}$ or $\operatorname{E-IfFALSE}$ applies to t, and we are done. Otherwise, t_1 is not a value and so, by the induction hypothesis, there is some t_1' such that $t_1 \longrightarrow t_1'$. But then rule E-IF yields

if t_1 then t_2 else $t_3 \longrightarrow if$ t_1' then t_2 else t_3

i.e., t is not in normal form.

25

 $\mathtt{t} \longrightarrow \mathtt{t}'$

Numbers

New syntactic forms

t ::= ... 0 succ t pred t iszero t v ::= ...

successor predecessor zero test

nv ::= 0 succ nv

nv

values numeric value

constant zero

terms

numeric values zero value successor value New evaluation rules

 $\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{succ} \ \mathtt{t}_1 \longrightarrow \mathtt{succ} \ \mathtt{t}_1'}$ (E-Succ)

 $\texttt{pred} \ 0 \longrightarrow 0$ (E-PredZero)

 $\texttt{pred (succ nv}_1) \longrightarrow \texttt{nv}_1$ (E-PredSucc)

 $\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{pred} \ \mathtt{t}_1 \longrightarrow \mathtt{pred} \ \mathtt{t}_1'}$ (E-Pred)

 $\texttt{iszero} \ \mathtt{0} \longrightarrow \mathtt{true}$ (E-IszeroZero)

iszero (succ nv_1) \longrightarrow false (E-ISZEROSUCC)

 $\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{iszero} \ \mathtt{t}_1 \longrightarrow \mathtt{iszero} \ \mathtt{t}_1'}$ (E-IsZero)

Are all normal forms still values?

Clicker question: Propose a term that is in normal form but is *not* a value

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Stuck terms

Formally, a stuck term is one that is a normal form but not a value.

Stuck terms model run-time errors.

28

Multi-step evaluation.

The multi-step evaluation relation, \longrightarrow *, is the reflexive, transitive closure of single-step evaluation.

I.e., it is the smallest relation closed under the following rules:

$$\frac{\mathsf{t}\longrightarrow \mathsf{t}'}{\mathsf{t}\longrightarrow^*\mathsf{t}'}$$

$$\frac{t \longrightarrow^* t' \qquad t' \longrightarrow^* t''}{t \longrightarrow^* t''}$$

Termination of evaluation

Theorem: For every t there is some normal form t' such that

Proof:

30

31

Termination of evaluation

Theorem: For every ${\tt t}$ there is some normal form ${\tt t}'$ such that

▶ First, recall that single-step evaluation strictly reduces the size

if
$$t \longrightarrow t'$$
, then $size(t) > size(t')$

Now, assume (for a contradiction) that

 $t_0, t_1, t_2, t_3, t_4, \ldots$

is an infinite-length sequence such that

$$t_0 \longrightarrow t_1 \longrightarrow t_2 \longrightarrow t_3 \longrightarrow t_4 \longrightarrow \cdots$$

▶ Then
$$size(t_0) > size(t_1) > size(t_2) > size(t_3) > \dots$$

▶ But such a sequence cannot exist — contradiction!

Termination Proofs

Most termination proofs have the same basic form:

Theorem: The relation $R \subseteq X \times X$ is terminating — i.e., there are no infinite sequences x_0 , x_1 , x_2 , etc. such that $(x_i, x_{i+1}) \in R$ for each i.

Proof:

- 1. Choose
 - ▶ a well-founded set (W, <) i.e., a set W with a partial order < such that there are no infinite descending chains $w_0 > w_1 > w_2 > \dots$ in W
 - ► a function f from X to W
- 2. Show f(x) > f(y) for all $(x, y) \in R$
- 3. Conclude that there are no infinite sequences x_0 , x_1 , x_2 , etc. such that $(x_i, x_{i+1}) \in R$ for each i, since, if there were, we could construct an infinite descending chain in W

32

34

Reading for next week

► Chapter 5 – Untyped Lambda Calculus (20 pages!)

The Lambda Calculus

33

The lambda-calculus

What are your questions?

The lambda-calculus

- ▶ If our previous language of arithmetic expressions was the simplest nontrivial programming language, then the lambda-calculus is the simplest *interesting* programming language...
 - ► Turing complete
 - higher order (functions as data)
- ▶ Indeed, in the lambda-calculus, *all* computation happens by means of function abstraction and application.
- ► The foundation of many real-world programming language designs (including ML, Haskell, Scheme, Lisp, ...)

Evaluation puzzlers (1)

```
Let t be the term
```

 $(\lambda x. \lambda y. y x) (\lambda z. z)$

Clicker question: What is t' in $t \longrightarrow t'$?

- A. $t' = (\lambda y. y) (\lambda z. z)$
- B. $t' = \lambda y$. (y (λz . z))
- $\mathsf{C.}\ \mathsf{t'} = \lambda \mathsf{z.}\ \mathsf{z}$
- D. There is no such t'

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Evaluation puzzlers (2)

Let t be the term

 $(\lambda x. \lambda y. x) (\lambda z. y z)$

Clicker question: What is t' in $t \longrightarrow t'$?

- A. $t' = \lambda y$. $(\lambda z$. y z)
- B. $t' = \lambda z$. y z
- C. $t' = \lambda y$. $(\lambda w. w. z)$
- D. There is no such t'

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37

35

38

Evaluation puzzlers (3)

```
Let t be the term  ((\lambda x. \ x) \ y) \ ((\lambda z. \ z) \ (\lambda w. \ w))  Clicker question: What is t' in t \longrightarrow t'?  A. \ t' = ((\lambda x. \ x) \ y) \ (\lambda w. \ w)  B. t' = y \ ((\lambda z. \ z) \ (\lambda w. \ w))  y C. t' = ((\lambda z. \ z) \ (\lambda w. \ w))  y D. There is no such t'   URL: ttpoll.eu  Session ID: cs452
```

Intuitions

Suppose we want to describe a function that adds three to any number we pass it. We might write

```
plus3 \ x = succ \ (succ \ (succ \ x)) That is, "plus3 x is succ (succ (succ x))."
```

39

Intuitions

Suppose we want to describe a function that adds three to any number we pass it. We might write

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\label{eq:plus3} plus3 \ x = succ \ (succ \ (succ \ x)) That is, "plus3 x is succ (succ (succ x))."
```

Q: What is plus3 itself?

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Suppose we want to describe a function that adds three to any number we pass it. We might write

succ (succ (succ x)).

A: plus3 is the function that, given x, yields

40

40

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Suppose we want to describe a function that adds three to any number we pass it. We might write

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plus3 x = succ (succ (succ x))
That is, "plus3 x is succ (succ (succ x))."
Q: What is plus3 itself?
A: plus3 is the function that, given x, yields
```

A: plus3 is the function that, given x, yields succ (succ (succ x)).

```
plus3 = \lambda x. succ (succ (succ x))
```

This function exists independent of the name plus3.

 λx . t is written "fun $x \to t$ " in OCaml and " $x \Rightarrow t$ " in Scala.

40

42

```
So plus3 (succ 0) is just a convenient shorthand for "the function that, given x, yields succ (succ (succ x)), applied to succ 0."
```

41

Abstractions over Functions

Consider the λ -abstraction

```
g = \lambda f. f (f (succ 0))
```

Note that the parameter variable ${\tt f}$ is used in the function position in the body of ${\tt g}$. Terms like ${\tt g}$ are called higher-order functions. If we apply ${\tt g}$ to an argument like plus3, the "substitution rule" yields a nontrivial computation:

Abstractions Returning Functions

Consider the following variant of g:

```
double = \lambda f. \lambda y. f (f y)
```

l.e., double is the function that, when applied to a function f, yields a function that, when applied to an argument y, yields f (f y).

Example

The Pure Lambda-Calculus

As the preceding examples suggest, once we have $\lambda\text{-abstraction}$ and application, we can throw away all the other language primitives and still have left a rich and powerful programming language.

In this language — the "pure lambda-calculus" — everything is a function

- ► Variables always denote functions
- ► Functions always take other functions as parameters
- ▶ The result of a function is always a function

45

Formalities

Syntax

```
\begin{array}{cccc} t & ::= & & terms \\ & x & & variable \\ & \lambda x \cdot t & & abstraction \\ & t & t & application \end{array}
```

Terminology:

- \blacktriangleright terms in the pure λ -calculus are often called λ -terms
- \blacktriangleright terms of the form $\lambda x\,.\,\,$ t are called $\lambda\text{-}abstractions$ or just abstractions

47

46

Syntactic conventions

Since λ -calculus provides only one-argument functions, all multi-argument functions must be written in curried style.

The following conventions make the linear forms of terms easier to read and write:

Application associates to the left

E.g.,
$$t$$
 u v means $(t$ $u)$ v , not t $(u$ $v)$

▶ Bodies of λ - abstractions extend as far to the right as possible E.g., λx . λy . x y means λx . $(\lambda y$. x y), not λx . $(\lambda y$. x) y

48

Scope

The λ -abstraction term $\lambda x.t$ binds the variable x.

The *scope* of this binding is the *body* t.

Occurrences of x inside t are said to be *bound* by the abstraction.

Occurrences of \mathbf{x} that are *not* within the scope of an abstraction binding \mathbf{x} are said to be *free*.

Test:

$$\lambda$$
x. λ y. x y z

49

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Test:

$$\lambda$$
x. λ y. x y z

$$\lambda x$$
. (λy . z y) y

Values

 $\mathtt{v} ::= egin{array}{ccc} ext{values} & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & \\ & & & \\ & & & \\ & \\ & & \\ & \\ & & \\ & \\ & \\ & & \\ & \\ & \\ & \\ & \\ &$

49

Operational Semantics

Computation rule:

$$(\lambda x.t_{12}) \ v_2 \longrightarrow [x \mapsto v_2]t_{12}$$
 (E-APPABS)

Notation: $[x\mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

Operational Semantics

Computation rule:

$$(\lambda x.t_{12}) \ v_2 \longrightarrow [x \mapsto v_2]t_{12}$$
 (E-AppAbs)

Notation: $[x \mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

Congruence rules:

$$\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{t}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{t}_1' \ \mathtt{t}_2} \tag{E-App1)$$

$$\frac{\mathtt{t}_2 \longrightarrow \mathtt{t}_2'}{\mathtt{v}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{v}_1 \ \mathtt{t}_2'} \tag{E-App2)$$

51

Terminology

A term of the form $(\lambda x.t)$ v — that is, a λ -abstraction applied to a *value* — is called a *redex* (short for "reducible expression").

Classical Lambda Calculus

53

52

Alternative evaluation strategies

Strictly speaking, the language we have defined is called the *pure*, *call-by-value lambda-calculus*.

The evaluation strategy we have chosen — \it{call} by \it{value} — $\it{reflects}$ standard conventions found in most mainstream languages.

Some other common ones:

- ► Call by name (cf. Haskell)
- ► Normal order (leftmost/outermost)
- ► Full (non-deterministic) beta-reduction

Full beta reduction

The classical lambda calculus allows full beta reduction.

- \blacktriangleright The argument of a $\beta\text{-reduction}$ to be an arbitrary term, not just a value.
- ▶ Reduction may appear anywhere in a term.

54

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- ▶ Reduction may appear anywhere in a term.

Computation rule:

$$(\lambda x.t_{12})$$
 $t_2 \longrightarrow [x \mapsto t_2]t_{12}$ (E-AppAbs)

Full beta reduction

The classical lambda calculus allows full beta reduction.

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- Reduction may appear anywhere in a term.

Computation rule:

$$(\lambda x.t_{12})$$
 $t_2 \longrightarrow [x \mapsto t_2]t_{12}$ (E-APPABS)

Congruence rules:

$$\frac{\mathtt{t}_1 \longrightarrow \mathtt{t}_1'}{\mathtt{t}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{t}_1' \ \mathtt{t}_2} \tag{E-App1}$$

$$\frac{\mathtt{t}_2 \longrightarrow \mathtt{t}_2'}{\mathtt{t}_1 \ \mathtt{t}_2 \longrightarrow \mathtt{t}_1 \ \mathtt{t}_2'} \tag{E-App2)$$

$$\frac{\mathsf{t} \longrightarrow \mathsf{t}'}{\lambda \mathsf{x}.\mathsf{t} \longrightarrow \lambda \mathsf{x}.\mathsf{t}'} \tag{E-Abs}$$

55

55

Substitution revisited

Remember: $[x \mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

This is trickier than it looks!

For example:

$$\begin{array}{rcl} & (\lambda x. & (\lambda y. & x)) & y \\ \longrightarrow & [x \mapsto y]\lambda y. & x \\ & = & ??? \end{array}$$

Substitution revisited

Remember: $[x\mapsto v_2]t_{12}$ is "the term that results from substituting free occurrences of x in t_{12} with v_2 ."

This is trickier than it looks!

For example:

$$\begin{array}{rcl} & (\lambda x. & (\lambda y. & x)) & y \\ \longrightarrow & [x \mapsto y] \lambda y. & x \\ = & ??? \end{array}$$

Solution:

need to rename bound variables before performing the substitution.

$$(\lambda x. (\lambda y. x)) y$$

$$= (\lambda x. (\lambda z. x)) y$$

$$\longrightarrow [x \mapsto y] \lambda z. x$$

$$= \lambda z. y$$

56

Alpha conversion

Renaming bound variables is formalized as $\alpha\text{-conversion}.$ Conversion rule:

$$\frac{\mathbf{y} \not\in \mathbf{fv(t)}}{\lambda \mathbf{x}. \ \mathbf{t} =_{\alpha} \lambda \mathbf{y}. [\mathbf{x} \mapsto \mathbf{y}] \mathbf{t}} \tag{a}$$

Equivalence rules:

$$\frac{\mathsf{t}_1 =_\alpha \mathsf{t}_2}{\mathsf{t}_2 =_\alpha \mathsf{t}_1} \tag{α-Symm}$$

$$\frac{\mathtt{t}_1 =_\alpha \mathtt{t}_2 \qquad \mathtt{t}_2 =_\alpha \mathtt{t}_3}{\mathtt{t}_1 =_\alpha \mathtt{t}_3} \qquad \qquad (\alpha\text{-Trans})$$

Congruence rules: the usual ones.

Confluence

56

57

Full β -reduction makes it possible to have different reduction paths.

Q: Can a term evaluate to more than one normal form?

Confluence

Full β -reduction makes it possible to have different reduction paths.

Q: Can a term evaluate to more than one normal form?

The answer is no; this is a consequence of the following

Theorem [Church-Rosser]

Let \mathbf{t} , \mathbf{t}_1 , \mathbf{t}_2 be terms such that $\mathbf{t} \longrightarrow^* \mathbf{t}_1$ and $\mathbf{t} \longrightarrow^* \mathbf{t}_2$. Then there exists a term \mathbf{t}_3 such that $\mathbf{t}_1 \longrightarrow^* \mathbf{t}_3$ and $\mathbf{t}_2 \longrightarrow^* \mathbf{t}_3$.

Programming in the Lambda-Calculus

58

Multiple arguments

Consider the function ${\tt double}$, which returns a function as an argument.

```
double = \lambda f. \lambda y. f (f y)
```

This idiom — a λ -abstraction that does nothing but immediately yield another abstraction — is very common in the λ -calculus.

In general, λx . λy . t is a function that, given a value v for x, yields a function that, given a value u for y, yields t with v in place of x and u in place of y.

That is, λx . λy . t is a two-argument function.

(Recall the discussion of currying in OCaml.)

The "Church Booleans"

60

61

Functions on Booleans

```
not = \lambdab. b fls tru
```

That is, not is a function that, given a boolean value v, returns fls if v is tru and tru if v is fls.

Functions on Booleans

```
and = \lambdab. \lambdac. b c fls
```

That is, and is a function that, given two boolean values v and w, returns w if v is tru and fls if v is fls

Thus and v w yields tru if both v and w are tru and fls if either v or w is fls.

62

Pairs

```
pair = \lambda f. \lambda s. \lambda b. b f s
fst = \lambda p. p tru
snd = \lambda p. p fls
```

That is, pair v w is a function that, when applied to a boolean value b, applies b to v and w.

By the definition of booleans, this application yields v if b is tru and w if b is fls, so the first and second projection functions fst and snd can be implemented simply by supplying the appropriate boolean.

Example

64

65

Church numerals

Idea: represent the number $\it n$ by a function that "repeats some action $\it n$ times."

```
\begin{array}{l} c_0 \; = \; \lambda s. \;\; \lambda z. \;\; z \\ c_1 \; = \; \lambda s. \;\; \lambda z. \;\; s \;\; z \\ c_2 \; = \; \lambda s. \;\; \lambda z. \;\; s \;\; (s \; z) \\ c_3 \; = \; \lambda s. \;\; \lambda z. \;\; s \;\; (s \; (s \; z)) \end{array}
```

That is, each number n is represented by a term c_n that takes two arguments, s and z (for "successor" and "zero"), and applies s, n times, to z.

66

Functions on Church Numerals

Successor:

67

Functions on Church Numerals

Successor:

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
```

67

Functions on Church Numerals

Successor:

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
```

Addition:

Functions on Church Numerals

Successor:

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
```

Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

Successor:

Functions on Church Numerals

Successor:

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
```

Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

Multiplication:

67

Functions on Church Numerals

Successor:

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
```

Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

Multiplication:

times = λ m. λ n. m (plus n) c₀

Zero test:

 $scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)$

Functions on Church Numerals

Successor:

BCC - All. AB. AZ. B (II B Z)

 ${\sf Addition:}$

plus = λm . λn . λs . λz . m s (n s z)

Multiplication:

times = λm . λn . m (plus n) c_0

67

67

Functions on Church Numerals

```
Successor:
```

```
scc = \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
```

Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

Multiplication:

```
times = \lambdam. \lambdan. m (plus n) c<sub>0</sub>
```

Zero test:

```
iszro = \lambdam. m (\lambdax. fls) tru
```

67

Functions on Church Numerals

Successor:

```
scc = \lambda n. \lambda s. \lambda z. s (n s z)
```

Addition:

```
plus = \lambda m. \lambda n. \lambda s. \lambda z. m s (n s z)
```

Multiplication:

```
times = \lambdam. \lambdan. m (plus n) c<sub>0</sub>
```

Zero test:

```
iszro = \lambdam. m (\lambdax. fls) tru
```

What about predecessor?

67

Predecessor

```
zz = pair c_0 c_0
```

ss = λ p. pair (snd p) (scc (snd p))

prd = λ m. fst (m ss zz)

Recursion in the Lambda-Calculus

69

Recursion and divergence

Recursion and divergence are intertwined, so we need to consider divergent terms.

 $= (\lambda x. x x) (\lambda x. x x)$

Note that ${\tt omega}$ evaluates in one step to itself! So evaluation of omega never reaches a normal form: it diverges.

70

Recursion and divergence

Recursion and divergence are intertwined, so we need to consider divergent terms.

 $(\lambda x. x x) (\lambda x. x x)$

Note that omega evaluates in one step to itself! So evaluation of omega never reaches a normal form: it diverges.

Being able to write a divergent computation does not seem very useful in itself. However, there are variants of omega that are very useful...

Recall: Normal forms

- A normal form is a term that cannot take an evaluation step.
- A stuck term is a normal form that is not a value.

Does every term evaluate to a normal form?

No, omega is not in normal form.

But are there any stuck terms in the pure λ -calculus?

Recall: Normal forms

- A normal form is a term that cannot take an evaluation step.
- A stuck term is a normal form that is not a value.

Does every term evaluate to a normal form?

No, omega is not in normal form.

71

71

Towards recursion: Iterated application

Suppose ${\tt f}$ is some $\lambda\text{-abstraction,}$ and consider the following variant of <code>omega:</code>

```
Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))
```

72

```
Towards recursion: Iterated application
```

Suppose ${\bf f}$ is some $\lambda\text{-abstraction,}$ and consider the following variant of omega:

```
Y_f = (\lambda x. f (x x)) (\lambda x. f (x x))
```

Now the "pattern of divergence" becomes more interesting:

```
\begin{array}{c} Y_f \\ = \\ (\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x)) \\ \longrightarrow \\ f \ ((\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x))) \\ \longrightarrow \\ f \ (f \ ((\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x))))) \\ \longrightarrow \\ f \ (f \ ((\lambda x. \ f \ (x \ x)) \ (\lambda x. \ f \ (x \ x))))) \\ \longrightarrow \\ \cdots \end{array}
```

72

 Y_f is still not very useful, since (like omega), all it does is diverge. Is there any way we could "slow it down"?

Delaying divergence

```
poisonpill = \lambda y. omega
```

Note that poisonpill is a value — it will only diverge when we actually apply it to an argument. This means that we can safely pass it as an argument to other functions, return it as a result from functions, etc.

```
\begin{array}{c} (\lambda \mathtt{p.} \ \mathsf{fst} \ (\mathsf{pair} \ \mathtt{p} \ \mathsf{fls}) \ \mathsf{tru}) \ \mathsf{poisonpill} \\ \longrightarrow \\ \mathsf{fst} \ (\mathsf{pair} \ \mathsf{poisonpill} \ \mathsf{fls}) \ \mathsf{tru} \\ \longrightarrow^* \\ \underbrace{ \begin{array}{c} \mathsf{poisonpill} \ \mathsf{tru} \\ \longrightarrow \\ \mathsf{omega} \\ \longrightarrow \\ \cdots \end{array}}_{\mathsf{omega}}
```

74

A delayed variant of omega

Here is a variant of omega in which the delay and divergence are a bit more tightly intertwined:

$$\begin{array}{rcl} & \text{omegav} & = \\ \lambda \mathbf{y}. & (\lambda \mathbf{x}. & (\lambda \mathbf{y}. & \mathbf{x} & \mathbf{y})) & (\lambda \mathbf{x}. & (\lambda \mathbf{y}. & \mathbf{x} & \mathbf{y})) & \mathbf{y} \end{array}$$

Note that omegav is a normal form. However, if we apply it to any argument v, it diverges:

75

Another delayed variant

Suppose f is a function. Define

```
z_f = \lambda y. (\lambda x. f (\lambda y. x x y)) (\lambda x. f (\lambda y. x x y)) y
```

This term combines the "added \mathbf{f} " from \mathbf{Y}_f with the "delayed divergence" of omegav.

76

If we now apply \mathbf{z}_f to an argument $\mathbf{v},$ something interesting happens:

```
\begin{array}{c} \mathbf{z_f} \ \mathbf{v} \\ = \\ \\ \underline{(\lambda \mathbf{y}.\ (\lambda \mathbf{x}.\ \mathbf{f}\ (\lambda \mathbf{y}.\ \mathbf{x}\ \mathbf{x}\ \mathbf{y}))\ (\lambda \mathbf{x}.\ \mathbf{f}\ (\lambda \mathbf{y}.\ \mathbf{x}\ \mathbf{x}\ \mathbf{y}))\ \mathbf{y}\ \mathbf{v}} \\ - \\ \underline{(\lambda \mathbf{x}.\ \mathbf{f}\ (\lambda \mathbf{y}.\ \mathbf{x}\ \mathbf{x}\ \mathbf{y}))\ (\lambda \mathbf{x}.\ \mathbf{f}\ (\lambda \mathbf{y}.\ \mathbf{x}\ \mathbf{x}\ \mathbf{y}))}\ \mathbf{v} \\ - \\ \mathbf{f}\ (\lambda \mathbf{y}.\ (\lambda \mathbf{x}.\ \mathbf{f}\ (\lambda \mathbf{y}.\ \mathbf{x}\ \mathbf{x}\ \mathbf{y}))\ (\lambda \mathbf{x}.\ \mathbf{f}\ (\lambda \mathbf{y}.\ \mathbf{x}\ \mathbf{x}\ \mathbf{y}))\ \mathbf{y})\ \mathbf{v} \\ = \\ \mathbf{f}\ \mathbf{z_f}\ \mathbf{v} \end{array}
```

Since \mathbf{z}_f and \mathbf{v} are both values, the next computation step will be the reduction of \mathbf{f} \mathbf{z}_f — that is, before we "diverge," \mathbf{f} gets to do some computation.

Now we are getting somewhere.

Recursion

Let

```
 \begin{array}{rcl} {\bf f} & = & \lambda {\rm fct.} \\ & & \lambda {\rm n.} \\ & & {\rm if n=0 \ then \ 1} \\ & & {\rm else \ n \ * \ (fct \ (pred \ n))} \end{array}
```

f looks just like the ordinary factorial function, except that, in place of a recursive call in the last lime, it calls the function fct, which is passed as a parameter.

N.b.: for brevity, this example uses "real" numbers and booleans, infix syntax, etc. It can easily be translated into the pure lambda-calculus (using Church numerals, etc.).

We can use z_f to "tie the knot" in the definition of ${\tt f}$ and obtain a real recursive factorial function:

```
\begin{array}{c} z_f \ 3 \\ \longrightarrow^* \\ f \ z_f \ 3 \\ = \\ (\lambda f c t. \ \lambda n. \ \ldots) \ z_f \ 3 \\ \longrightarrow \longrightarrow \\ \text{if 3=0 then 1 else } 3 * (z_f \ (pred \ 3)) \\ \longrightarrow^* \\ 3 * (z_f \ (pred \ 3))) \\ \longrightarrow \\ 3 * (z_f \ 2) \\ \longrightarrow^* \\ 3 * (f \ z_f \ 2) \\ \ldots \end{array}
```

79

```
A Generic z
```

If we define

```
i.e., z = \\ \lambda f. \ \lambda y. \ (\lambda x. \ f \ (\lambda y. \ x \ x \ y)) \ (\lambda x. \ f \ (\lambda y. \ x \ x \ y)) \ y
```

 $z = \lambda f. z_f$

then we can obtain the behavior of z_f for any ${\tt f}$ we like, simply by applying ${\tt z}$ to ${\tt f}.$

```
{	t z} {	t f} \longrightarrow {	t z}_f
```

80

```
For example:
```

```
fact = z ( \lambdafct.

\lambdan.

if n=0 then 1

else n * (fct (pred n)) )
```

Technical Note

The term \boldsymbol{z} here is essentially the same as the \mathtt{fix} discussed the book.

z is hopefully slightly easier to understand, since it has the property that z f v \longrightarrow * f (z f) v, which fix does not (quite) share.

81

Reading for next week Chapter 8 – Typed Arithmetic Expressions