Foundations of Software Fall 2020

Week 9

Different Kinds of Maps

What is missing?

```
Term \rightarrow Term (\lambda x.t)

Type \rightarrow Term (\Lambda X.t)
```

Different Kinds of Maps

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```

Agenda today:

- ► Type operators
- ► Dependent types

Type Operators and System F_{ω}

Type Operators

Example. Type operators in Scala:

```
type MkFun[T] = T => T
val f: MkFun[Int] = (x: Int) => x
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Two Problems:

- ► Type checking of type operators
- ► Equivalence of types

Kinding

Problem: avoid meaningless types, like MkFun[Int, String].

Kinding

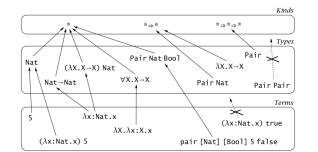
```
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```
 \begin{tabular}{lll} * & & & & & & & & \\ * & \Rightarrow & & & & & & \\ * & \Rightarrow & * & & & & \\ * & \Rightarrow & * & & & & \\ * & \Rightarrow & * & & & \\ * & \Rightarrow & * & & & \\ * & \Rightarrow & * & & & \\ * & \Rightarrow & * & \\ * & \Rightarrow & \Rightarrow & \\ *
```

Kinding

Problem: avoid meaningless types, like MkFun[Int, String].

```
 \begin{array}{lll} * & & \text{proper types, e.g. } \textit{Bool, Int} \rightarrow \textit{Int} \\ * \Rightarrow * & & \text{type operators: map proper type to proper type} \\ * \Rightarrow * \Rightarrow * & & \text{two-argument operators} \\ (* \Rightarrow *) \Rightarrow * & & \text{type operators: map type operators to proper types} \\ \end{array}
```



Equivalence of Types

Problem: all the types below are equivalent

```
egin{aligned} \textit{Nat} & \rightarrow \textit{Bool} & \textit{Nat} & \rightarrow \textit{Id} \; \textit{Bool} & \textit{Id} \; \textit{Nat} & \rightarrow \textit{Id} \; \textit{Bool} \\ \textit{Id} \; \textit{Nat} & \rightarrow \; \textit{Bool} & \textit{Id} \; (\textit{Nat} & \rightarrow \; \textit{Bool}) & \textit{Id} \; (\textit{Id} \; (\textit{Id} \; \textit{Nat} & \rightarrow \; \textit{Bool}) \\ \end{aligned}
```

We need to introduce definitional equivalence relation on types, written $S \equiv \mathcal{T}$. The most important rule is:

$$(\lambda X :: K.S) T \equiv [X \mapsto T]S$$
 (Q-APPABS)

And we need one typing rule:

$$\frac{\Gamma \vdash t : S \qquad S \equiv T}{\Gamma \vdash t : T}$$
 (T-Eq)

First-class Type Operators

Scala supports passing type operators as argument:

```
def makeInt[F[_]](f: () => F[Int]): F[Int] = f()
makeInt[List](() => List[Int](3))
```

makeInt[Option](() => None)

First-class type operators supports *polymorphism* for type operators, which enables more patterns in type-safe functional programming.

System F_{ω}

```
Formalizing first-class type operators leads to \textit{System } \textit{F}_{\omega}:
```

Dependent Types

Why Does It Matter?

Example 1. Track length of vectors in types:

```
 \begin{array}{lll} \textit{Vector} & :: & \textit{Nat} \rightarrow * \\ \textit{first} & : & (\textit{n:Nat}) \rightarrow \textit{Vector} \ (\textit{n}+1) \rightarrow \textit{D} \\ \end{array}
```

 $(x:S) \to T$ is called dependent function type. It is impossible to pass a vector of length 0 to the function *first*.

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```

 $(x:S) \to T$ is called dependent function type. It is impossible to pass a vector of length 0 to the function *first*.

Example 2. Safe formatting for *sprintf*:

```
\begin{array}{lll} \textit{sprintf} & : & (\textit{f:Format}) \rightarrow \textit{Data(f)} \rightarrow \textit{String} \\ \\ \textit{Data([])} & = & \textit{Unit} \\ \textit{Data("\%d" :: cs)} & = & \textit{Nat} * \textit{Data(cs)} \\ \textit{Data("\%s" :: cs)} & = & \textit{String} * \textit{Data(cs)} \\ \\ \textit{Data(c :: cs)} & = & \textit{Data(cs)} \\ \end{array}
```

Dependent Function Type (a.k.a. ☐ Types)

A dependent function type is inhabited by a dependent function:

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 : $(x:S) \rightarrow T$

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$$(x:S) \rightarrow T = S \rightarrow T$$
 where x does not appear free in T

By Curry-Howard correspondence, it corresponds to universal quantification:

$$(x:A) \to B(x) \longleftrightarrow \forall x:A.B(x)$$

First-Order Dependent Types

First-Order Dependent Types: λLF

System $\lambda \mathit{LF}$ generalizes STLC with dependent function types and $\mathit{type\ families}$.

Type or family variables X can only be declared in the typing context Γ . E.g., we may assume $Vector :: Nat \rightarrow *$ as a type family variable.

System λLF : Kinds

Kinds can distinguish proper types from type families.

System λLF : Kinding

Kinding ensures that types are well-formed $\Gamma \vdash T :: K$

$$\frac{X :: K \in \Gamma \qquad \Gamma \vdash K}{\Gamma \vdash X :: K}$$
 (K-Var)

$$\frac{\Gamma \vdash T_1 :: * \qquad \Gamma, x : T_1 \vdash T_2 :: *}{\Gamma \vdash (x : T_1) \rightarrow T_2 :: *}$$
 (K-PI)

$$\frac{\Gamma \vdash S :: (x:T) \to K \qquad \Gamma \vdash t : T}{\Gamma \vdash S t :: [x \mapsto t]K}$$
 (K-App)

$$\frac{\Gamma \vdash T :: K \qquad \Gamma \vdash K \equiv K'}{\Gamma \vdash T :: K'}$$
 (K-Conv)

System *\lambda LF*: Typing

Typing ensures that terms are well-formed $\Gamma \vdash t :: T$

$$\frac{x:T\in\Gamma\qquad\Gamma\vdash T::*}{\Gamma\vdash x:T} \tag{T-Var}$$

$$\frac{\Gamma \vdash S :: * \qquad \Gamma, x : S \vdash t : T}{\Gamma \vdash \lambda x : S . t : (x : S) \to T}$$
 (T-Abs)

$$\frac{\Gamma \vdash t_1 : (x:S) \to T \qquad \Gamma \vdash t_2 : S}{\Gamma \vdash t_1 \; t_2 :: [x \mapsto t_2]T}$$
 (T-App)

$$\frac{\Gamma \vdash t : T \qquad \Gamma \vdash T \equiv T' :: *}{\Gamma \vdash t : T'}$$
 (T-Conv)

System *\(\lambde{LF}\)*: Equivalence Rules

With types in kinds, and terms in types, equivalence becomes more complex than System F_{ω} .

$$Vector((\lambda n: \mathbb{N}.n*n)2) \leftrightarrow Vector 4$$

 λLF defines on several equivalence relations:

- ▶ kind equivalence $\Gamma \vdash K \equiv K'$
- ▶ type equivalence $\Gamma \vdash T \equiv T' :: *$
- ▶ term equivalence $\Gamma \vdash t \equiv t' : T$

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- ▶ kind equivalence $\Gamma \vdash K \equiv K'$
- ▶ type equivalence $\Gamma \vdash T \equiv T' :: *$
- ▶ term equivalence $\Gamma \vdash t \equiv t' : T$

For decidable type checking, type systems usually embrace

- **definitional equality**, i.e. equality by definition (e.g. x := 3)
- **computational equality**, usually β -equality and η -equality.

System λLF : Kind Equivalence

$$\frac{\Gamma \vdash T_1 \equiv T_2 :: * \qquad \Gamma, x : T_1 \vdash K_1 \equiv K_2}{\Gamma \vdash (x : T_1) \to K_1 \equiv (x : T_2) \to K_2}$$
 (QK-PI)

$$\frac{\Gamma \vdash K}{\Gamma \vdash K \equiv K}$$
 (QK-Refl)

$$\frac{\Gamma \vdash K_1 \equiv K_2}{\Gamma \vdash K_2 \equiv K_1}$$
 (QK-SYM)

$$\frac{\Gamma \vdash K_1 \equiv K_2 \qquad \Gamma \vdash K_2 \equiv K_3}{\Gamma \vdash K_1 \equiv K_3} \qquad \text{(QK-Trans)}$$

System λLF : Type Equivalence

$$\frac{\Gamma \vdash S_1 \equiv T_1 :: * \qquad \Gamma, x : T_1 \vdash S_2 \equiv T_2 :: *}{\Gamma \vdash (x : S_1) \rightarrow S_2 \equiv (x : T_1) \rightarrow T_2 :: *} \quad \text{(QT-Pi)}$$

$$\frac{\Gamma \vdash S_1 \equiv S_2 :: (x:T) \to K \qquad \Gamma \vdash t_1 \equiv t_2 : T}{\Gamma \vdash S_1 \ t_1 \equiv S_2 \ t_2 :: [x \mapsto t_1] K}$$
(QT-App)

$$\frac{\Gamma \vdash T :: K}{\Gamma \vdash T \equiv T :: K}$$
 (QT-Refl)

$$\frac{\Gamma \vdash T_1 \equiv T_2 :: K}{\Gamma \vdash T_2 \equiv T_1 :: K}$$
 (QT-Sym)

$$\frac{\Gamma \vdash T_1 \equiv T_2 :: \mathcal{K} \qquad \Gamma \vdash T_2 \equiv T_3 :: \mathcal{K}}{\Gamma \vdash T_1 \equiv T_3 :: \mathcal{K}} \text{ (QT-Trans)}$$

System λLF : Term Equivalence

$$\frac{\Gamma \vdash S_1 \equiv S_2 :: * \qquad \Gamma, x : S_1 \vdash t_1 \equiv t_2 : T}{\Gamma \vdash \lambda x : S_1 \cdot t_1 \equiv \lambda x : S_2 \cdot t_2 : (x : S_1) \to T}$$
 (Q-Abs)

$$\frac{\Gamma \vdash t_1 \equiv s_1 : (x : S) \rightarrow T \qquad \Gamma \vdash t_2 \equiv s_2 : S}{\Gamma \vdash t_1 \ t_2 \equiv s_1 \ s_2 : [x \mapsto t_2]T} \quad \text{(Q-App)}$$

$$\frac{\Gamma, x: S \vdash t: T \qquad \Gamma \vdash s: S}{\Gamma \vdash (\lambda x: S.t) \ s \equiv [x \mapsto s]t: [x \mapsto s]T} \qquad \text{(Q-Beta)}$$

$$\frac{\Gamma \vdash t : (x:S) \to T \qquad x \notin FV(t)}{\Gamma \vdash \lambda x : S.t \ x \equiv t : (x:S) \to T} \tag{Q-Eta}$$

$$\frac{\Gamma \vdash t : T}{\Gamma \vdash t \equiv t :: T} \text{ (Q-Refl)} \qquad \frac{\Gamma \vdash t \equiv s : T}{\Gamma \vdash s \equiv t : T} \text{ (Q-Sym)}$$

$$\frac{\Gamma \vdash t_1 \equiv t_2 : T \qquad \Gamma \vdash t_2 \equiv t_3 : T}{\Gamma \vdash t_1 \equiv t_3 : T} \qquad \text{(Q-Trans)}$$

Strong Normalization

Given the following β -reduction rules

$$\frac{t_1 \longrightarrow t_1'}{\lambda x : \mathcal{T}_1.t_1 \longrightarrow \lambda x : \mathcal{T}_1.t_1'} \qquad \qquad (\beta\text{-Abs})$$

$$\frac{t_1 \longrightarrow t_1'}{t_1 \ t_2 \longrightarrow t_1' \ t_2} \tag{β-App1)}$$

$$\frac{t_2 \longrightarrow t_2'}{t_1 \ t_2 \longrightarrow t_1 \ t_2'} \tag{β-App2)}$$

$$(\lambda x: T_1.t_1)t_2 \longrightarrow [x \mapsto t_2]t_1$$
 $(\beta$ -AppAbs)

Theorem [Strong Normalization]: if $\Gamma \vdash t : T$, then there is no infinite sequence of terms t_i such that $t = t_1$ and $t_i \longrightarrow t_{i+1}$.

The Calculus of Constructions

The Calculus of Constructions: Syntax

The semantics is the usual β -reduction.

The Calculus of Constructions: Typing

$$\vdash * : \Box \text{ (T-Axiom)} \qquad \qquad \frac{x: T \in \Gamma}{\Gamma \vdash x: T} \text{ (T-Var)}$$

$$\frac{\Gamma \vdash S : s_1 \qquad \Gamma, x : S \vdash t : T}{\Gamma \vdash \lambda x : S . t : (x : S) \to T}$$
 (T-Abs)

$$\frac{\Gamma \vdash t_1 : (x : S) \to T \qquad \Gamma \vdash t_2 : S}{\Gamma \vdash t_1 \ t_2 : [x \mapsto t_2]T} \tag{T-App)}$$

$$\frac{\Gamma \vdash S : s_1 \qquad \Gamma, x : S \vdash T : s_2}{\Gamma \vdash (x : S) \to T : s_2}$$
 (T-PI)

$$\frac{\Gamma \vdash t : T \qquad T \equiv T' \qquad \Gamma \vdash T' : s}{\Gamma \vdash t : T'} \qquad \text{(T-Conv)}$$

The equivalence relation $T\equiv T'$ is based on β -reduction.

Four Kinds of Lambdas

Example	Туре
λx : $\mathbb{N}.x + 1$	$\mathbb{N} \to \mathbb{N}$
$\lambda f:\mathbb{N} \to \mathbb{N}.f \ x$	$(\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$

Four Kinds of Lambdas

Example	Type
$\lambda x: \mathbb{N}.x + 1$	$\mathbb{N} \to \mathbb{N}$
$\lambda f: \mathbb{N} \to \mathbb{N}.f \times$	$(\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$
λX :*. λx : X . x	$(X:*) \rightarrow X \rightarrow X$
$\lambda F:* \to *.\lambda x:F \mathbb{N}.x$	$(F:* \to *) \to (F \mathbb{N}) \to (F \mathbb{N})$

Four Kinds of Lambdas

Example	Type
$\lambda x: \mathbb{N}.x + 1$	$\mathbb{N} o \mathbb{N}$
$\lambda f:\mathbb{N} \to \mathbb{N}.f \times$	$(\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$
λX :*. λx : X . x	$(X:*) \rightarrow X \rightarrow X$
λF :* \rightarrow *. λx : $F \mathbb{N}$. x	$(F:* o *) o (F\;\mathbb{N}) o (F\;\mathbb{N})$
λX :*. X	$* \rightarrow *$
λF :* \rightarrow *. F \mathbb{N}	(* o *) o *

Four Kinds of Lambdas

Example	Туре
$\lambda x: \mathbb{N}.x + 1$	$\mathbb{N} o \mathbb{N}$
$\lambda f: \mathbb{N} \to \mathbb{N}.f \times$	$(\mathbb{N} \to \mathbb{N}) \to \mathbb{N}$
λX :*. λx : X . x	$(X:*) \rightarrow X \rightarrow X$
$\lambda F:* \to *.\lambda x: F \mathbb{N}. x$	$(F:* o *) o (F\;\mathbb{N}) o (F\;\mathbb{N})$
λX :*. X	$* \rightarrow *$
λF :* \to *. F $\mathbb N$	(* o *) o *
$\lambda n:\mathbb{N}.Vec\ n$	$\mathbb{N} o *$
$\lambda f: \mathbb{N} \to \mathbb{N}$. Vec $(f 6)$	$(\mathbb{N} \to \mathbb{N}) \to *$

Strong Normalization

Theorem [Strong Normalization]: if $\Gamma \vdash t : T$, then there is no infinite sequence of terms t_i such that $t = t_1$ and $t_i \longrightarrow t_{i+1}$.

Question: Why the property is important?

Pure Type Systems

Dependent Types in Practice

Proof Assistants

Dependent type theories are at the foundation of proof assistants, like Coq, Agda, etc.

By Curry-Howard Correspondence

- $\qquad \qquad \textbf{proofs} \longleftrightarrow \textbf{programs}$
- ▶ propositions ←→ types

Coq is based on *Calculus of Inductive Construction*, which is an extension of CC with inductive definition.

Proofs in Coq: Example

```
Inductive nat : Type :=
    | 0
    | S (n : nat).

Fixpoint double (n : nat) : nat :=
    match n with
    | 0 => 0
    | S n' => S (S (double n'))
    end.

Inductive even : nat -> Prop :=
    | even0 : even 0
    | evenS : forall x:nat, even x -> even (S (S x)).
```

Proofs in Coq: Example, Continued

Dependent Types in Programming Languages

Despite the huge success in proof assistants, its adoption in programming languages is limited.

- ► Scala supports *path-dependent types* and *literal types*.
- ▶ Dependent Haskell is proposed by researchers.

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Challenge: the decidability of type checking.

Problem with Type Checking: Vector Again

Value constructors:

```
 \begin{array}{lll} \textit{Vec} & : & \mathbb{N} \to * \\ \textit{nil} & : & \textit{Vec} \ 0 \\ \textit{cons} & = & \lambda n : \mathbb{N} . D \to \textit{Vec} \ n \to \textit{Vec} \ n + 1 \\ \end{array}
```

Appending vectors:

```
\begin{array}{ll} \textit{append} & : & (\textit{m} : \mathbb{N}) \to (\textit{n} : \mathbb{N}) \to \textit{Vec } \textit{m} \to \textit{Vec } \textit{n} \to \textit{Vec } (\textit{m} + \textit{n}) \\ \textit{append} & = & \lambda \textit{m} : \mathbb{N} . \, \lambda \textit{n} : \mathbb{N} . \, \lambda \textit{l} : \textit{Vec } \textit{m} . \, \lambda \textit{t} : \textit{Vec } \textit{n}. \\ & \textit{match } \textit{l} \textit{ with } \\ & | \textit{nil} \Rightarrow \textit{t} \\ & | \textit{cons } \textit{r} \times \textit{y} \Rightarrow \textit{cons } (\textit{r} + \textit{n}) \times (\textit{append } \textit{r} \textit{ n} \textit{ y} \textit{ t}) \end{array}
```

Question: How does the type checker know r + 1 + n = r + n + 1?