

Type 1 Formalism : Context sensitive Grammar

- Type 1 languages are described by Type 1 grammars. LHS of Type 1 grammar is not longer than RHS.
- Type 1 Grammars (Context sensitive Grammars) are represented by productions of the form
$$\alpha \rightarrow \beta \quad \text{where } |\alpha| \leq |\beta|. \quad \alpha, \beta \in (V \cup T)^*$$
- Type 1 Languages are recognised using Linear Bounded Automata (LBA)

e.g. of Context Sensitive Grammar is

$$\begin{aligned}S &\rightarrow SBC \\S &\rightarrow aC \\B &\rightarrow a \\CB &\rightarrow BC \\Ba &\rightarrow aa \\C &\rightarrow b.\end{aligned}$$

No ϵ in CSL

LBA can accept ϵ but CSs do not contain ϵ is a contradiction

LBA is equivalent to CSs
as long as languages are ϵ free

A language is Context Sensitive if and only if it can be generated by a grammar in which every production has the form:

$$\alpha A \beta \rightarrow \alpha X \beta$$

where α, β and X are strings of terminals & non-terminals, with $X \neq \epsilon$ and A is a non-terminal.

- i) Check whether the string abaabb is accepted by the following context sensitive Grammar.

$$S \rightarrow SBC$$

$$S \rightarrow aC$$

$$B \rightarrow a$$

$$CB \rightarrow BC$$

$$Ba \rightarrow aa$$

$$C \rightarrow b$$

(a) $S \Rightarrow SBC$ (using $S \rightarrow SBC$)

$$\Rightarrow SBCBC$$
 (using $S \rightarrow SBC$)

$$\Rightarrow aCBCBC$$
 (using $S \rightarrow aC$)

$$\Rightarrow abBCBC$$
 (using $C \rightarrow b$)

$$\Rightarrow abaCBC$$
 (using $B \rightarrow a$)

$$\Rightarrow abaBBC$$
 (using $CB \rightarrow BC$)

$$\Rightarrow abaacc$$
 (using $B \rightarrow a$)

~~$$\Rightarrow abaccb$$
 (using $C \rightarrow b$)~~

~~$$\Rightarrow abaabb$$
 (using $C \rightarrow b$)~~

Thus the string abaabb is accepted by the given grammar.

Linear Bounded Automata

A Linear Bounded Automata (LBA) is a restricted form of non-deterministic turing machine which has a single tape and whose length is not infinite but bounded by a linear function of the length of the input string.

It is denoted as : (q-tuples)

$$M = (\mathcal{Q}, \Sigma, \Gamma, \delta, q_0, B, \$, F)$$
 where

\mathcal{Q} - is the finite set of states.

Σ - is the finite set of input symbols.

Γ - finite non-empty set of tape symbols.
 $\Gamma \subseteq (\Sigma \cup \{B\})$

B - $B \in \Gamma$ is the blank.

$q_0 \in \mathcal{Q}$ is the initial state

$F \subseteq \mathcal{Q}$ is the set of final states.

$\$, \$$ are symbols in Σ .

$\$$ - left end marker, prevents read/write head from getting off the left end of tape.

$\$$ - right end marker, prevents read/write head from getting off the right end of tape.

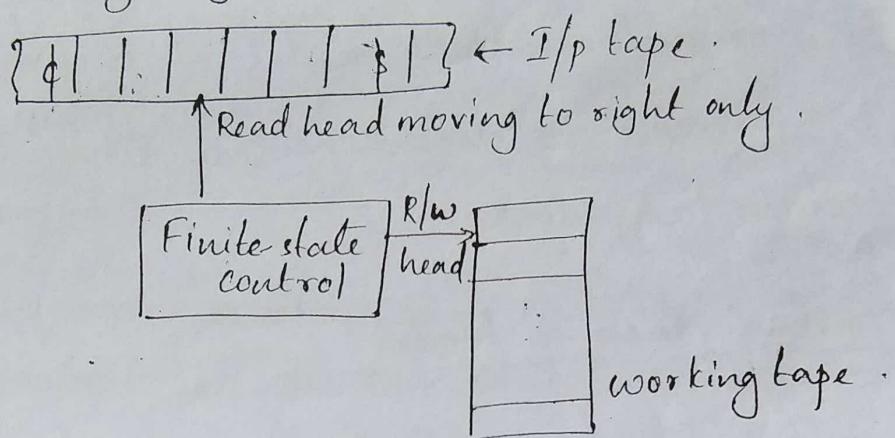
$$\delta - \mathcal{Q} \times \Gamma \rightarrow \mathcal{Q} \times \Gamma \times \{L, R\}$$

i.e δ is the transition function mapping (q, x) onto (q', y, D) where D denotes the direction of movement of R/w head ; $D = L \text{ or } R$

Model of LBA

(11)

There are two tapes : one is called the i/p tape & the other is working tape. On the i/p tape, the head never points left and never moves to the left. On the working tape, the head can modify the contents, without any restriction in any way.



Whenever we process any string in LBA, we assume that the i/p string is enclosed within the endmarkers < & >.

i: Consider an LBA defined as :

$$Q = \{q_0, q_1, q_2, q_3, q_4\}$$

$$\Sigma = \{a, b, c\}$$

$$\Gamma = \{a, b, c, \#\}$$

$$\delta(q_1, a) = (q_2, \#, R) \quad \delta(q_3, c) = (q_4, \#, L) \dots$$

$$\delta(q_2, a) = (q_2, a, R)$$

$$\delta(q_2, \#) = (q_2, \#, R)$$

In the above, the transition $\delta(q_1, a) = (q_2, \#, R)$ means, LBA on state q_1 , head points to symbol a , remains in state q_2 , replaces a with $\#$ and head turns towards right by one cell.

08/02/22

Module 5

Turing Machine

Turing machine provides an ideal mathematical model of a computer.

Turing m/c was developed by Alan Turing in 1936.

Turing m/cs are @ useful in several ways.

* It accepts type-0 languages.

* It can also be used for computing functions.

* Turing m/cs are used for determining the undecidability & certain languages.

* It is also used for measuring the space & time complexity of problems.

Turing machine Model

Turing m/c can be thought of as finite control connected to a R/w (Read/write) head. It has one tape which is divided into a no. of cells.

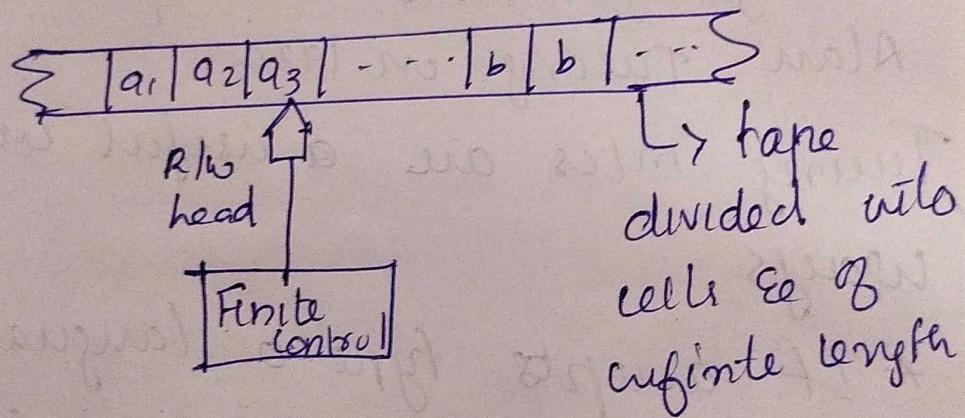


Fig: Turing m/c model

Each cell can store only one symbol. The M_p to be the O/P from the finite state automaton all effected by the R/w head which

can examine one cell at a time.

In one move, the m/c examines the present symbol under the R/w head

on top the tape is the present state of an automaton to determine.

i) a new symbol to be written on the tape in the cell under the R/w head.

ii) a motion of the R/w head along the tape either the head moves one cell left (L), or one cell right (R).

iii) the next state of the automaton and

iv) whether to halt, halt or not.

Definition of TM

A turing m/c M is a 7 tuple.

$M = (Q, \Sigma, \Gamma, \delta, q_0, b, F)$

Q = is a finite nonempty set of states

$\Sigma\Gamma$ = is a finite nonempty set of tape symbols.

$b \in \Gamma$ or the blank

$\Sigma - \{b\}$ a nonempty set of I/P symbols & is a subset of Γ $a \in b \notin \Sigma$

s - a state transition function mapping (q, x) onto (q', y, D) where D denotes the direction of movement of R/W head.

$D = L$ or R according as the move. is to the left or right.

$q_0 \in Q$ is the initial state &

$F \subseteq Q$ is the set of final states

Notes:-

1) The acceptability of a string is decided by the reachability from the initial state to some final state. So the final states are also called acceptable states

2) s may not be defined for some elements of $Q \times \Gamma$.

Representation of Turing Machines

We can describe a TM employing:

1) Instantaneous descriptions using move alns

2) Transition table

3) Transition diagram (transition graph).

Representation by instantaneous descriptions.

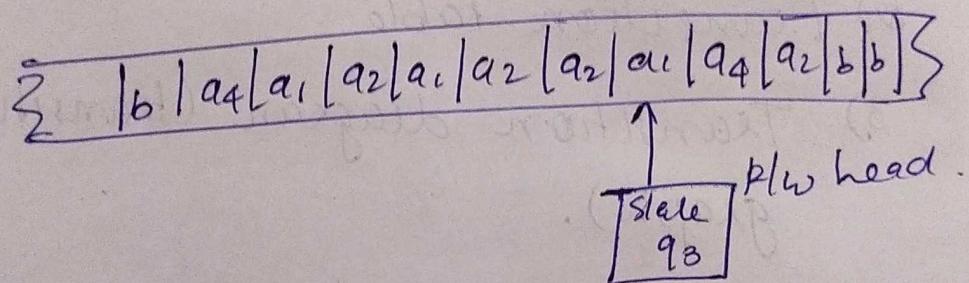
An ID of an a TM. M is a string $\alpha \beta \gamma$, where β is the

Present state of M

& the entire I/P string is split into α & γ , the first symbol of γ is the current symbol σ under the R/W head & γ has all the subsequent

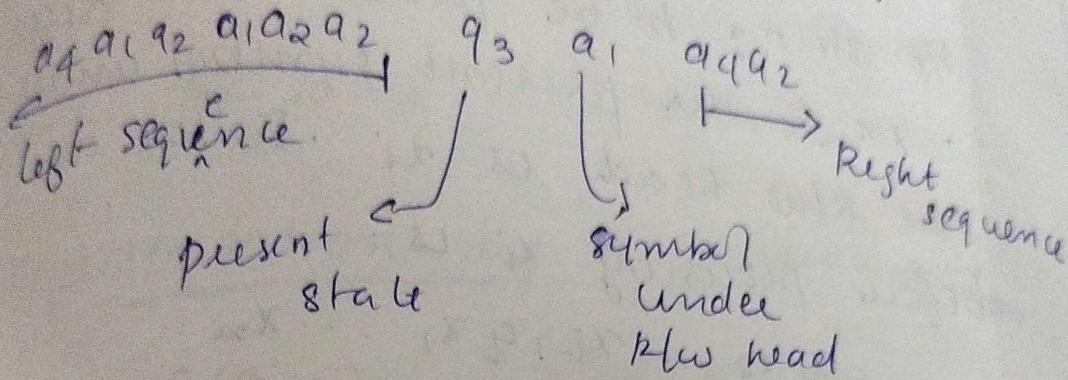
The symbols of the up string is
the string a is the substring of
the up string formed by all the
symbols to the left a .

Eg: A snapshot of TM is shown
in the figure.



The present symbol under the
Rlw head is a_1 . The present
state is q_3 . So, a_1 is written to
the right of q_3 .
The nonblank symbols to the
left of a_1 from the string $a_4 a_1 a_2 a_1$
 $a_2 a_2$ which is written to the left
of q_3 . The sequence of non blank
symbols to the right of a_1 is $a_2 \rightarrow a_2$.

thus the ID is as given in fig.



Notes

1) for construction the ID, insert the current state in the T.P. string to the left of the symbol under the R/w head.

2) The blank symbol may occur as part of left .. or right substring. +

Moves in a TM

As in the case of pda, $\delta(q, x)$ induces a change in ID of the TM. We call this change in ID

or move.

Suppose $s(q_i, x_i) = (P, q_i, w)$. The IP string to be processed is $x_1 x_2 \dots x_n$ & the present symbol under RW head is x_i . So the ID before processing x_i is.

$x_1 x_2 \dots x_{i-1} q x_i \dots x_n$.

After processing x_i , the resulting ID is

$x_1 x_2 \dots x_{i-2} P x_{i-1} y x_{i+1} \dots x_n$

This change of ID is represented by

$x_1 x_2 \dots x_{i-1} q x_i \dots x_n \xrightarrow{*} x_1 x_2 \dots x_{i-2} P$

$x_{i-1} y x_{i+1} \dots x_n$.

If $s(q_i, x_i) = (P, q_i, \lambda)$ then

change of ID is represented by

$x_1 x_2 \dots x_{i-1} q x_i \dots x_n \xrightarrow{*} x_1 x_2 \dots x_{i-1} y$
 $x_{i+1} \dots x_n$.

The symbol ~~+~~ $\xrightarrow{*}$ denotes the
 reflexive-transitive closure of
 the relation $\xrightarrow{*}$

If $I_1 + \dots + I_n$, then we can
split this as $I_1 + I_2 + \dots + I_{n-1} + I_n$ for some IDs $I_2 \dots I_{n-1}$.

Representation by Transition Table.

If $\delta(q, a) = (\gamma, \alpha, B)$, we
write $\alpha B \gamma$ under the a column
in the q -row, if it $(\alpha B \gamma)$
means that α is written in the
current cell, B gives the movement
of the head (L or R) and γ denotes
the new states into which the
TM enters.

e.g. consider a TM, with 5 states
 $q_1 \dots q_5$. The tape symbols are
 $0, 1$ & b . The transition table is
given as follows.

Present state	τ_{ape}	τ_{symbol}	
	b	o	l
$\rightarrow q_1$	$1Lq_2$	ORq_1	
q_2	bRq_3	OLq_2	$1Lq_2$
q_3		bRq_4	bRq_5
q_4	ORq_5	ORq_4	LRq_4
(q_5)	OLq_2		

Representation by Transition

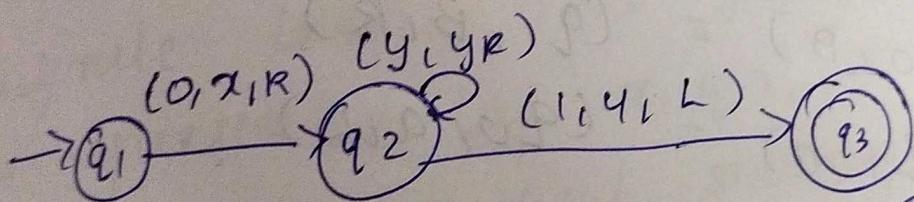
Diagram

The states are represented by vertices. Directed edges are used to represent transition of states. The labels are triples of the form (α, β, γ) , where $\alpha, \beta \in \Gamma$ & $\gamma \in \{L, R\}$. When there is a directed edge from q_i to q_j with label (α, β, γ) , it means that if

$$\delta(q_i, \alpha) = (q_j, \beta, \gamma)$$

every edge in the transition
slm can be represented by a 3-tuple
 $(\alpha_i, \alpha_1, \beta, \gamma, q_j)$

α/β	α	γ	β	q_j
$\rightarrow q_1$			$\alpha R q_2$	
q_2		$\gamma R q_2$	$\gamma L q_3$	
q_3				



language acceptability By TM

Let us consider the TM

$M = (\mathcal{Q}, \Sigma^*, \Gamma, \delta, q_0, b, f)$ A string w in Σ^* is said to be accepted by M if $q_0 \xrightarrow{\text{TM}} q_f$ for some $q_f \in F$ and $w \in L(M)$

M does not accept w if the M/G

M either halts in a non-accepting state or does not halt (M can enter in an infinite loop & never halts).

e.g:- $\alpha = \{q_0, q_1\}$, $\Sigma = \{a, b\}$
 $F = \emptyset$ & δ as follows.

$$\delta(q_0, a) = (q_1, a, R)$$

$$\delta(q_0, b) = (q_1, b, R)$$

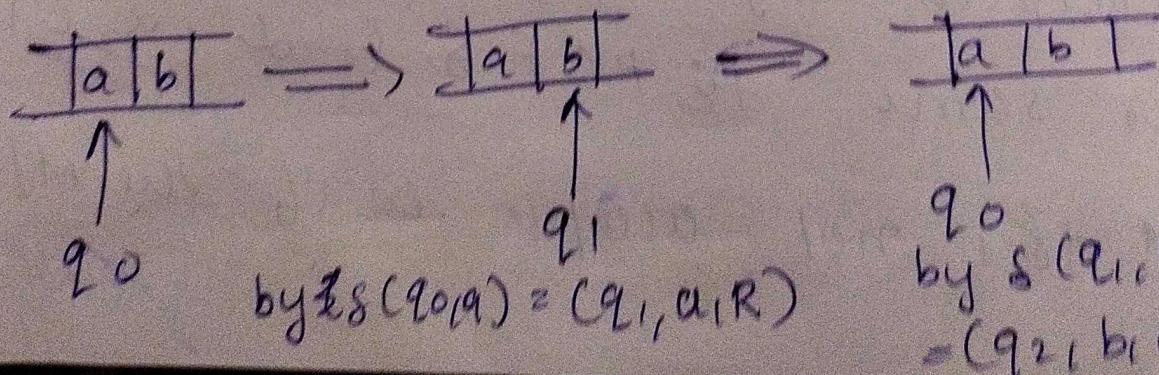
$$\delta(q_0, B) = (q_1, B, R)$$

$$\delta(q_1, a) = (q_0, a, L)$$

$$\delta(q_1, b) = (q_0, b, L)$$

$$\delta(q_1, B) = (q_0, B, L)$$

Suppose that the tape initially contains 'ab' with the R/W head is on the symbol 'a'.



Here in 3rd step, mlc goes back to state q0. Again it is the original state & the sequence of moves starts again. Here TM will run forever with the R/w head moving alternately right then left, but making no modifications to the tape. This is an instance of a TM that does not halt, i.e. TM is in infinite loop. This situation can be represented by $x_1 q x_2 \xrightarrow{*} x_1 q x_2$. This indicates that starting from initial ϵ , the mlc never halts.

e.g.: Consider the TM 'M' described by the transition table given in the following table. Describe the processing of strings a) 011 b) 0011 c) 001 d) using 10s
which of the following strings are accepted by M?

δ/Γ	0	1	x	y	B
$\rightarrow q_1$	xRq_2				BRq_5
q_2	$0Rq_2$	yLq_3		yRq_2	
q_3	$0Lq_4$		xRq_3	yLq_3	
q_4	$0Lq_2$		xRq_1		
q_5				yRq_5	BRq_6
(q_6)					

a) 011

$q_1, 011 \xrightarrow{x} q_2 11 \xrightarrow{y} q_3 xy 1 \xleftarrow{x}$

$xq_5 y 1 \xleftarrow{y} xyq_5 1$

$\delta(q_5, 1)$ is not defined so the
input string 011 is not accepted.

b) 0011

$q_1, 0011 \xrightarrow{x} q_2 011 \xrightarrow{y} x0q_2 11$

$x q_3^0 y_1 \leftarrow q_4^0 x q_4^0 y_1$

$x q_4^0 y_1 \leftarrow x x q_2 y_1 \leftarrow$

$x x y q_2 \leftarrow x x q_3 y y \leftarrow$

$x q_3 x y y \leftarrow x x q_5 y y \leftarrow$

$x x y q_5 y \leftarrow x x y y q_5 B \leftarrow$

$x x y y B \underline{q_6}$

001 is accepted.

001

$q_1 001 \leftarrow x q_2 01 \leftarrow x 0 q_2 \rightarrow$

$x q_3^0 y \leftarrow q_4 x 0 y \leftarrow x q_4^0 y$

$\leftarrow x x q_2 y \leftarrow x x y q_2 B \leftarrow$

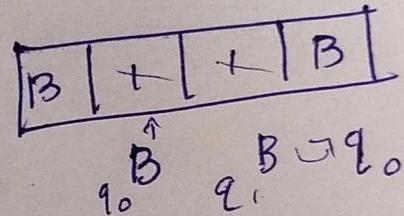
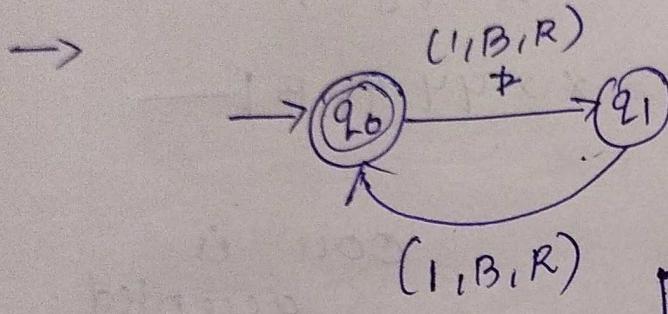
M halts as q_2 is not an

accepting state 001 is not accepted

by M

Designing a Turing M/c

- Design a turing machine to recognize all strings consisting of even no. of '1's.



$$M = (\{q_0, q_1\}, \{1\}, \{1, B\}, \delta, q_0, B, \text{Final})$$

$$\delta(q_0, 1) = (q_1, B, R)$$

$$\delta(q_1, 1) = (q_0, B, R)$$

Consider the string $w = \cancel{1} \cancel{1} 1 1$

~~q0, 11 + Bq1, B R~~

~~Bq0, 11 + Bq1, 1 + BBq0~~ GF

As q_0 is the final stage i.e.
the w is accepted by M .

$$N = 111$$

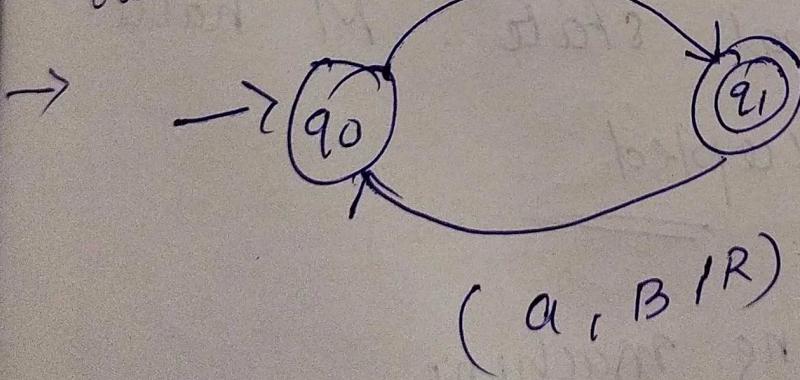
$$q_0, 111 \xrightarrow{B} q_1, 111 \xrightarrow{B} Bq_0, 1$$

$$\xrightarrow{B} Bq_1, \cancel{\text{111}} \quad \cancel{\text{111}}$$

The machine halts

As q_1 is not accepting state,
 111 is not accepted by M .

To design a Turing machine to
accept the language $L = \{a^n b^n\}$ is
odd no's (a, B, R)



{ [B] a | a | a | B] }

δ M- { $\{q_0, q_1\}$, {a, y, $q_0, B\gamma$,
 $s, q_0, B, q_1\}$ }

$$\delta(q_0, a) = (q_1, B, R)$$

$$\delta(q_1, a) = (q_0, B, R)$$

$$w = aaa$$

$$q_0, aaa \xrightarrow{B} q_1, aa \xrightarrow{BB} q_0, a \\ \xrightarrow{BBB} q_1, F$$

String accepted.

$$w = aa$$

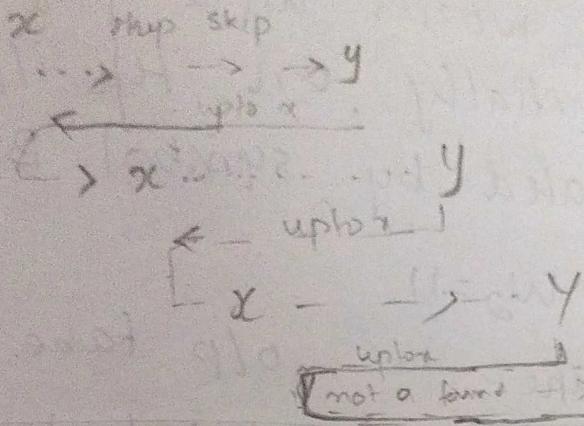
$$q_0, aa \xrightarrow{B} q_1, a \xrightarrow{BB} q_0, F$$

q_0 is not final state. M halts
String not accepted

Q Design a turing machine

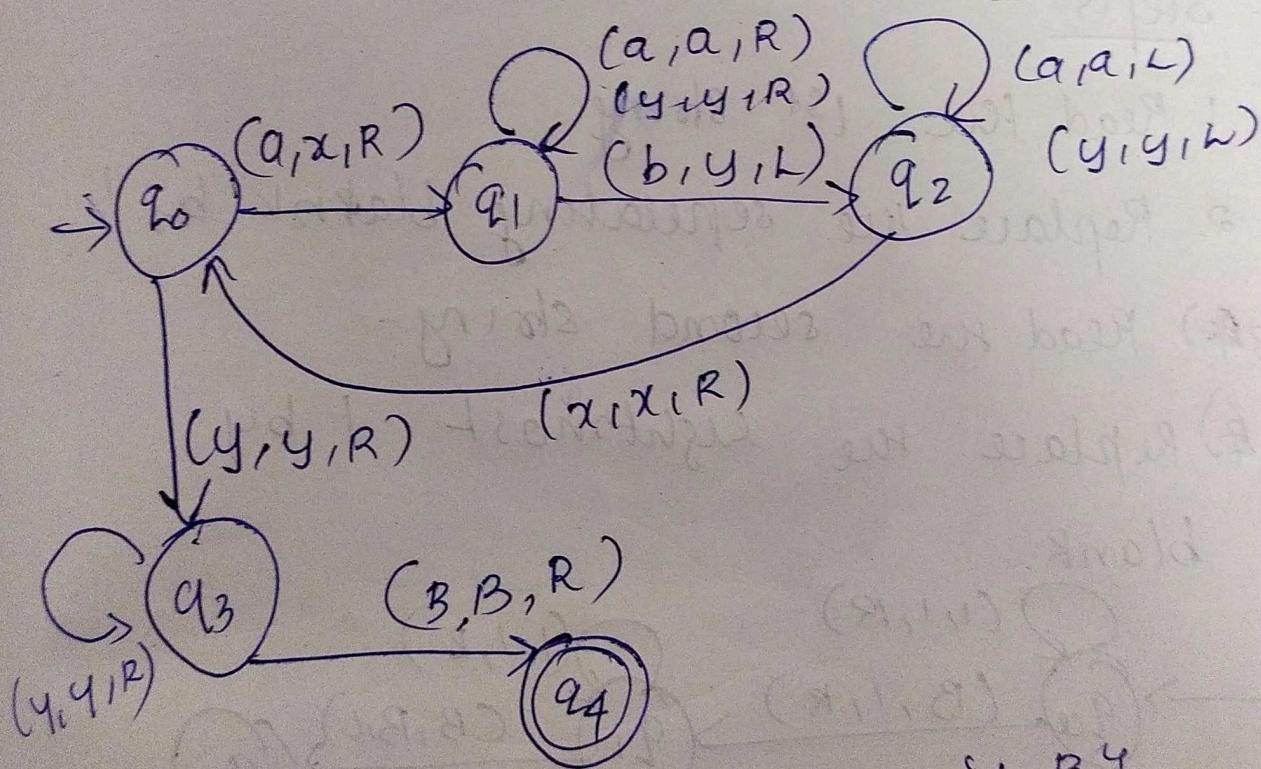
$$L = \{a^n b^n \mid n \geq 1\}$$

$\Rightarrow \{B|a|a|a|b|b|b|B\}^*$



If one 'a' is there then find out whether a matching 'b' can be found

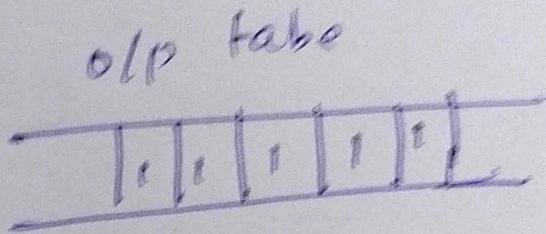
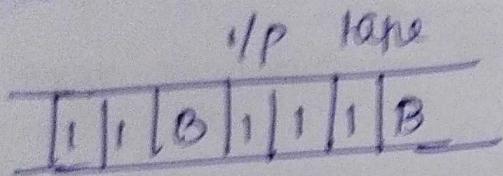
If y comes after x, then move to B, skip
ie move to final



Q. Design a TM over $\{1, B\}^*$ which can compute concatenation fn over $\Sigma = \{1\}^*$.

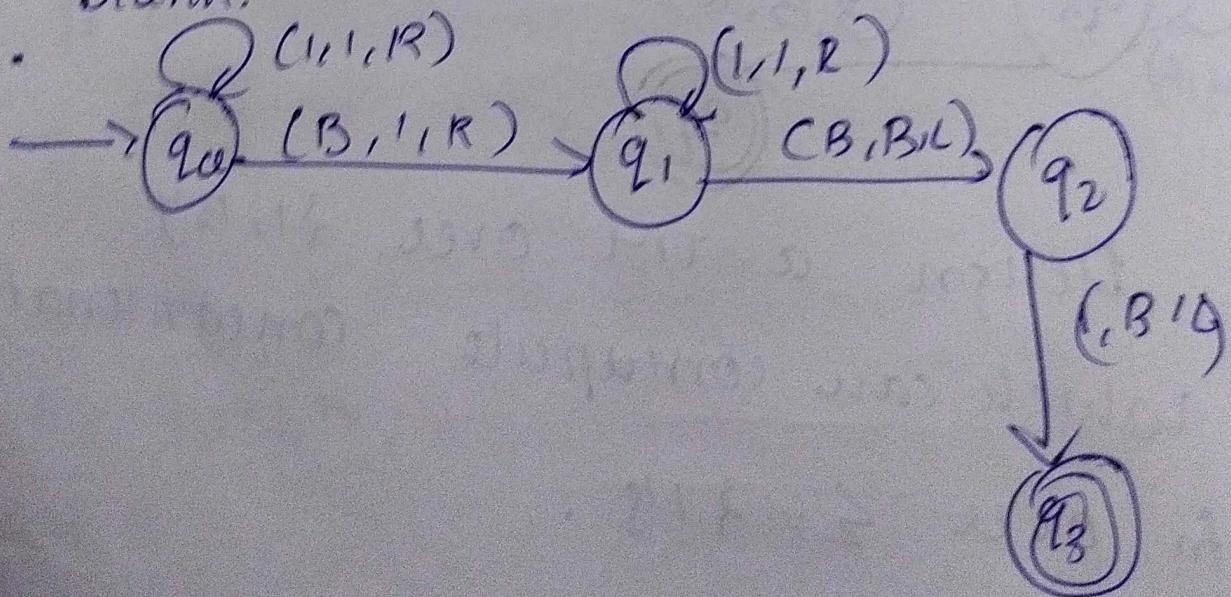
soln: let us assume that the two words w_1 & w_2 are written initially on the I/P tape separated by symbol B.

eg: $w_1 = 11 \quad w_2 = 11$



steps

1. Read the 1st string
2. Replace the separating blank by 1
3. Read the second string
4. Replace the eightmost 1 by blank.



$$M = (\{q_0, q_1, q_2, q_3\}, \{1, 4, 5, 13\}, \\ \{s, q_0, B, \{q_3\}\})$$

s is given in the following table.

O/F	1	B
$\rightarrow q_0$	IRq_0	IRq_1
q_1	IRq_1	$B \sqsubset q_2$
q_2	BLq_3	
(q_3)		

$$w = 1B1, \quad w_1 = 1, \quad w_2 = 1$$

$$q_0, 1B1 \leftarrow 1q_0 B 11 \leftarrow 11q_0 B \cancel{B} \leftarrow 11$$

$$11q_0 B \leftarrow 11q_2 B \leftarrow 1q_3 B B$$

$$11$$

$$w_1 = 11, \quad w_2 = 111$$

$$q_0 11B111 \leftarrow 1q_0 B 111 \leftarrow 11q_0 B 111 \leftarrow$$

$$111q_1 111 \leftarrow 111q_2 1q_1 111 \leftarrow 1111q_1 111 \leftarrow$$

~~1111111q₁B~~ — 11111q₂'B ←

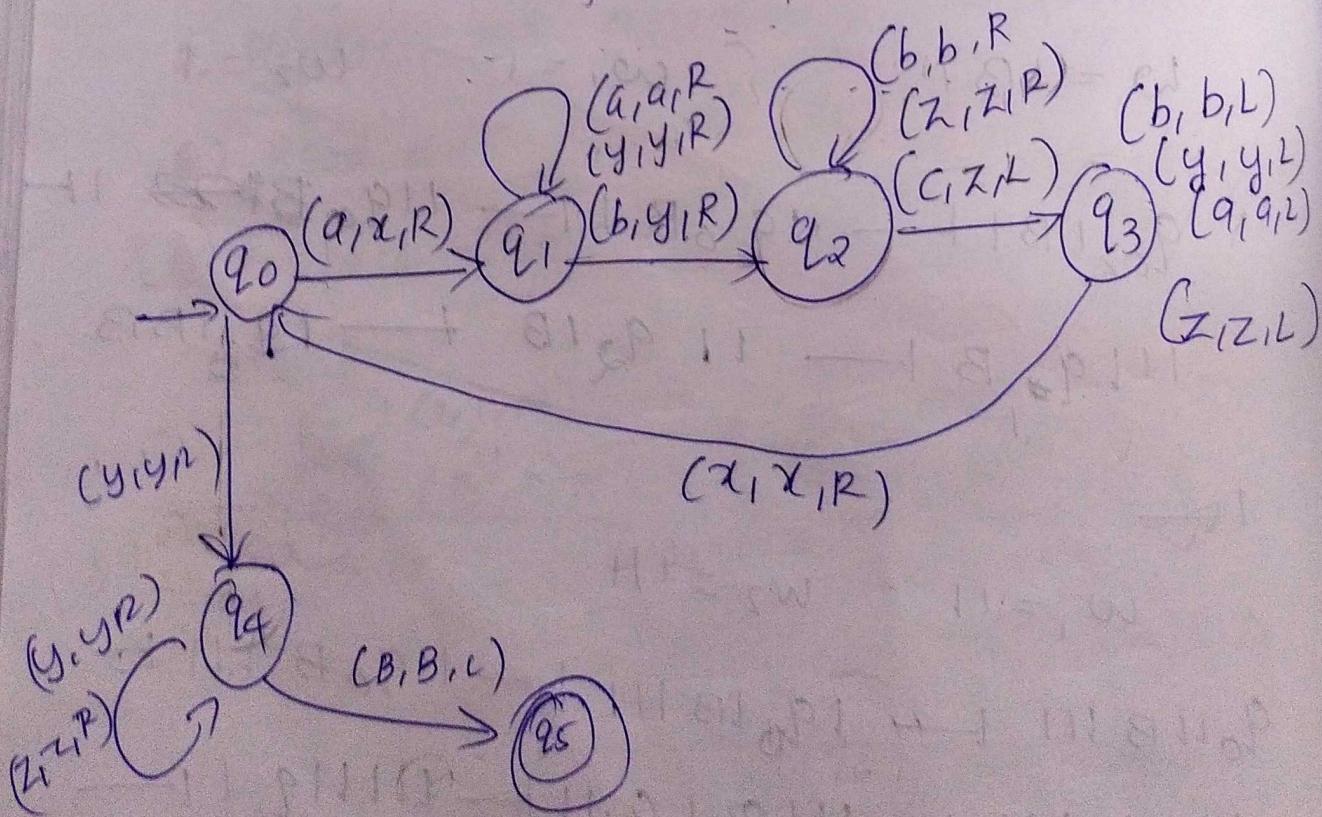
11111q₃'B

- Q Design a turing machine for
the language $L = \{a^n b^n c^n\}$

$\Sigma = \{B, a, b, b, c, c, C\}$

x, y, z, \dots

$\dots x \dots y \dots z \dots$



$$s(q_0, a) = (q_1, x, !^2)$$

$$\{ s(q_1, a) = (q_1, a, R)$$

$$s(q_1, y) = (q_1, y, !^2)$$

$$s(q_1, b) = (q_2, b, R)$$

$$s(q_2, b) = (q_2, b, R)$$

$$s(q_2, z) = (q_3, z, !^2)$$

$$s(q_2, c) = (q_3, b, L)$$

$$s(q_3, b) = (q_3, y, L)$$

$$s(q_3, y) = (q_3, a, L)$$

$$s(q_3, a) = (q_0, x, !^2)$$

$$s(q_3, x) = (q_0, x, !^2)$$

$$s(q_0, y) = (q_0, y, R)$$

$$s(q_0, y) = (q_4, y, R)$$

$$s(q_4, y) = (q_4, z, R)$$

$$s(q_4, z) = (q_5, B, L)$$

$$s(q_4, B) = (q_5, B, L)$$

z

~~$q_0, 000111222$~~ ←
 ~~$xq_1, 00111222$~~ ← ~~$x0q_1, 0111222$~~
 ~~$x00q_1, 111222$~~ ←
 $q_0 aaabbccc$ ← $xq_1 aabbccc$
← $xq_1 abbbccc$ ← $xaaq_1 bbbccc$
← $xaaayq_2 bbbccc$ ← $xaaaybq_2 ccc$
← ~~$xaaay bbq_2 ccc$~~ ← ~~$xaaay$~~
 $xaaqbq_3 bzbcc$

$q_0 aabbcc$ ← $xq_1 aabbcc$ ←
 $xq_1 bbbc$ ← $xay q_2 bcc$ ←
 $xayb q_2 cc$ ← $xay q_3 bzc$
← $xaq_3 y bzc$ ← $xq_3 ay bzc$
← $q_3 xaybz$ ← $xq_0 aybzc$
← $xq_1 y bzc$ ← $xxq_1 bzc$

$\overline{xxyyq_2zc} \vdash \overline{xxyyq_3yz}$
 $\overline{xxyyq_2zc} \vdash \overline{xxyyq_3zz} \vdash$

$\overline{xxyyq_2zc} \vdash \overline{xxyyzq_2c}$

$\vdash \overline{xxyyq_3z} \vdash \overline{xq_4y_3q_2z}$

$\vdash \overline{xxq_3yyz} \vdash \overline{xq_3xyyz}$

$\vdash \overline{xxq_0yyz} \vdash \overline{xxq_4yq_4yzz}$

$\vdash \overline{xxyyq_4zz} \vdash \overline{xxyyzq_4z}$

$\vdash \overline{xxyyzq_4B} \vdash \overline{xxyyzzBq_5} =$

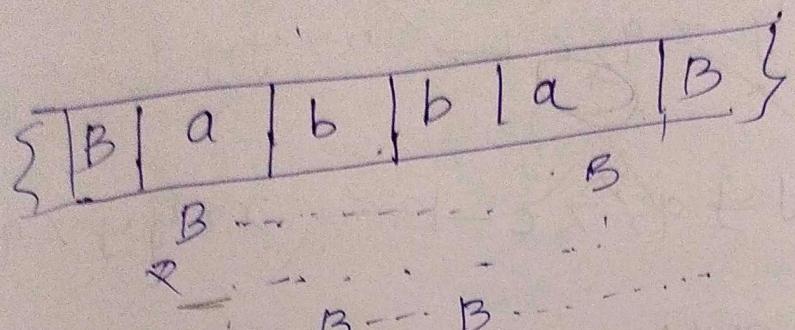
~~String~~ String accepted q_{5CF}

Q. 1) Construct a turing machine that
 L = {ww^R / w ∈ (a|b)*}

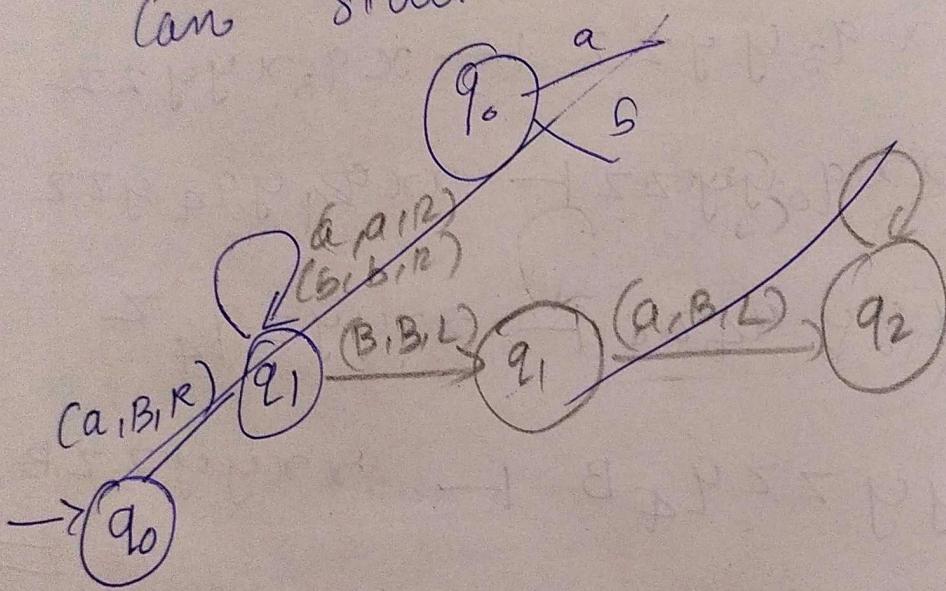
Q. 2) Construct a TM that displays the
 language L = {w ∈ (0,1)* / w has equal no. of 0's & 1's}

Language L = {w ∈ (0,1)* / w has equal no. of 0's & 1's}

$$D \quad L = \{ w w^R / w \in (a+b)^* \}$$



Can start with a or b



B a b b a a b b a B

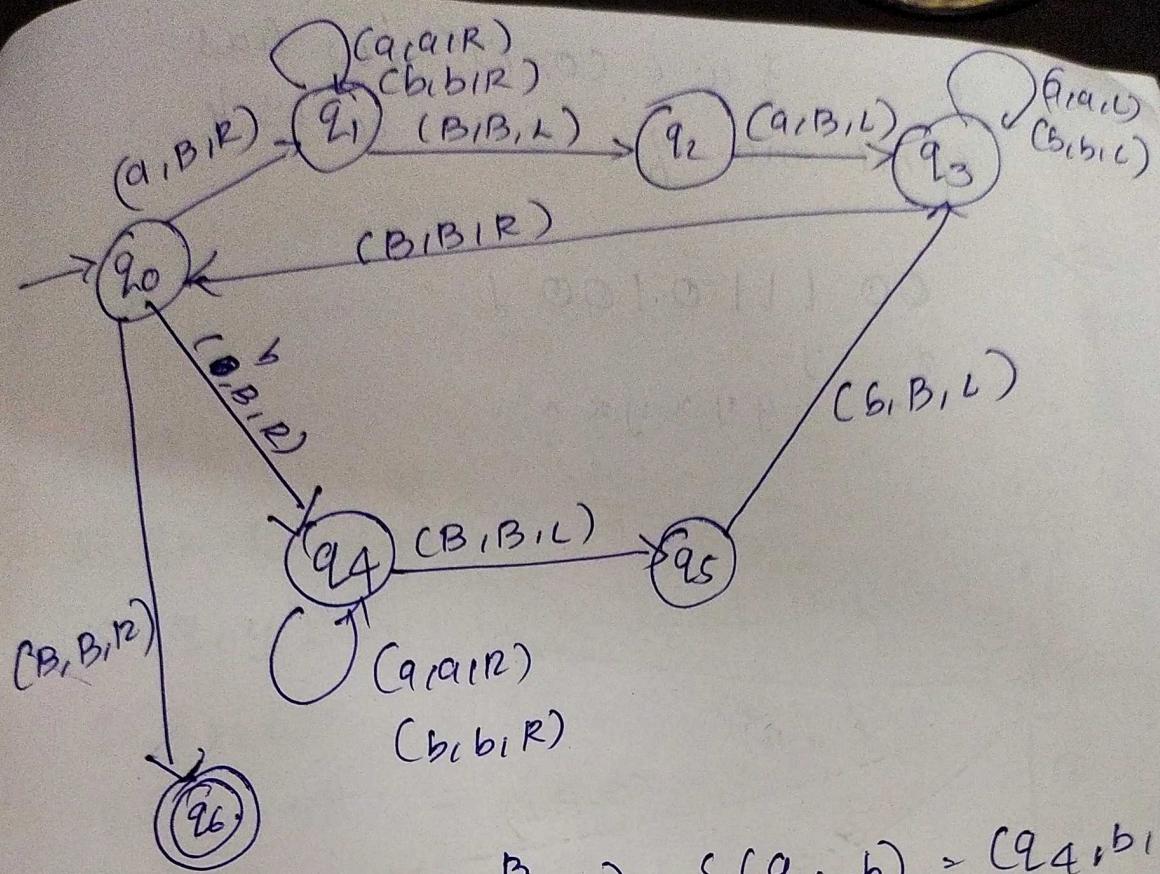
B - - - - - - - - B -

-- B - - - - - - - -

- - B - - - - - - - - B -

- B - - - - - - - - B -

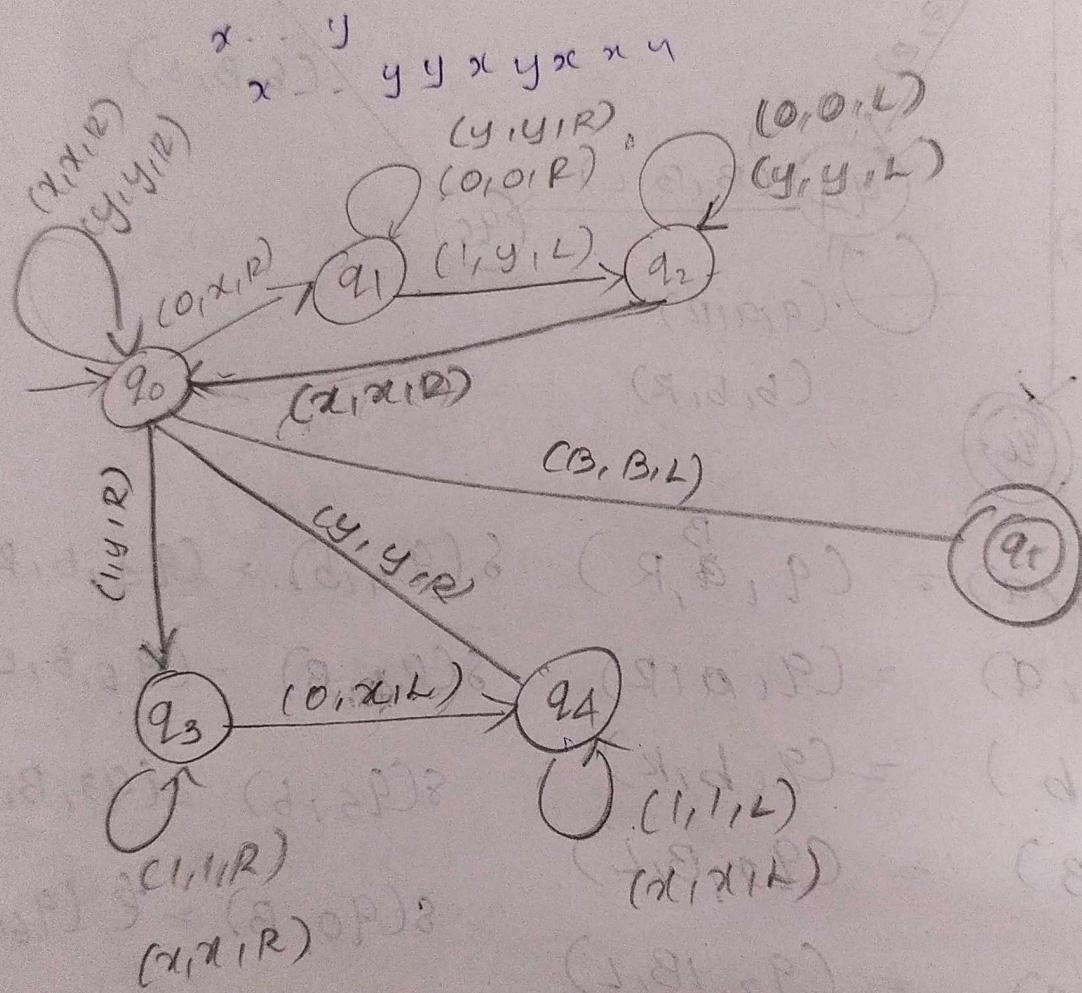
- - - - - - - - - -



$$\begin{aligned}
 s(q_0, a) &= (q_1, a, R) & s(q_4, b) &= (q_4, b, R) \\
 s(q_1, a) &= (q_1, a, R) & s(q_4, B) &= (q_5, B, L) \\
 s(q_1, b) &= (q_1, b, R) & s(q_5, b) &= (q_3, B, L) \\
 s(q_1, B) &= (q_2, B, L) & s(q_0, B) &= \text{f} (q_6, B, R) \\
 s(q_2, a) &= (q_3, B, L) & & \\
 s(q_2, b) &= (q_3, a, L) & & \\
 s(q_2, B) &= (q_3, b, L) & & \\
 s(q_3, a) &= (q_3, a, L) & & \\
 s(q_3, b) &= (q_3, b, L) & & \\
 s(q_3, B) &= (q_0, B, R) & & \\
 s(q_0, b) &= (q_4, B, R) & & \\
 s(q_4, a) &= (q_4, a, R) & &
 \end{aligned}$$

$\Rightarrow L = \{w \in \{0,1\}^* \mid w \text{ has equal no. of } 0's \text{ & } 1's\}$

$\rightarrow 0011101001$



~~0001~~ 0011101001B

x - y

x - y

y - x

x - y B - →

$$s(q_0, \alpha) = (q_1, x_{12})$$

$$s(q_0, y) = (q_0, y_{12})$$

$$s(q_0, x) = (q_0, x_{12})$$

$$s(q_0, \beta) = (q_{\cancel{0}}, y_{12})$$

$$s(q_1, \gamma) = (q_2, y_{12})$$

$$s(q_1, \alpha) = (q_1, x_{12})$$

$$s(q_1, y) = (q_1, y_{12})$$

$$s(q_2, \alpha) = (q_2, x_{12})$$

$$s(q_2, y) = (q_2, y_{12})$$

$$s(q_2, x) = (q_0, x_{12})$$

$$s(q_3, \gamma) = (q_3, x_{12})$$

$$s(q_3, \alpha) = (q_4, x_{12})$$

$$s(q_3, y) = (q_4, y_{12})$$

$$s(q_4, \alpha) = (q_4, x_{12})$$

$$s(q_4, y) = (q_0, y_{12})$$

$$s(q_4, \beta)$$

$$s(q_0, \beta) \quad \cancel{\text{S}}$$

$q_0 00010111 \leftarrow x q_0, 0010111$
 $\rightarrow x 0 q_1, 010111 \rightarrow x 00 q_1, 10111$
 $\rightarrow x 0 \cdot q_2, 0 y 0111 \rightarrow x q_2 00 y 0111$
 $\rightarrow q_2 x 00 y 0111 \leftarrow x q_2 00 y 0111$
 $\rightarrow x x q_0, 0 y 0111 \rightarrow x x 0 q_0, 0 y 0111$
 $\rightarrow x x 0 y q_0, 0111 \leftarrow x x 0 y q_0, 1111$
 $\rightarrow x x 0 y 0 q_1, 1111 \leftarrow x x * 0 y q_2 0 y 1111$
 ~~$\rightarrow x x * 0 q_2 y 0 y 1111 \leftarrow x x q_2$~~
 $x x q_2 0 y 0 y 1111 \leftarrow x q_2 x 0 y 0 y 1111$
 $\rightarrow x x q_0 0 y 0 y 1111 \leftarrow x x x q_0, 0 y 0 y 1111$
 $\rightarrow x x x y q_0, 0 y 1111 \leftarrow x x x y 0 q_1, 0 y 1111$
 $\rightarrow x x x y 0 y q_1, 1111 \leftarrow x x x y 0 q_2, 0 y 1111$
 $\rightarrow x x x y q_2 0 y y 1111 \leftarrow x x x q_2 0 y 0 y 1111$
 ~~$\rightarrow x x x q_2 x 0 y y 1111 \rightarrow x x x q_2 x 0 y 0 y 1111$~~
 $\rightarrow x x x y q_0 0 y y 1111 \rightarrow x x x y x q_0, y y 1111$

$\xrightarrow{\quad} \text{xxxxyxq}_1y_1y_1 \leftarrow$
 ~~$\text{xxxxyxq}_1y_1y_1 \leftarrow \text{xxxxyxq}_1y_1y_1$~~
 $\text{xxxxyxq}_1y_1y_1 \leftarrow \text{xxxxyxq}_1y_1y_1$
 $\xrightarrow{\quad} \text{xxxxyxq}_2x_1y_1y_1 \leftarrow \cancel{\text{xxxxyxq}_2x_1y_1y_1}$
 $\xrightarrow{\quad} \text{xxxxyxq}_2x_1y_1y_1 \leftarrow \cancel{\text{xxxxyxq}_2x_1y_1y_1}$
 $\xrightarrow{\quad} \text{xxxxyxq}_2x_1y_1y_1 \leftarrow \cancel{\text{xxxxyxq}_2x_1y_1y_1}$
 $\xrightarrow{\quad} \text{xxxxyxq}_2x_1y_1y_1 \leftarrow \cancel{\text{xxxxyxq}_2x_1y_1y_1}$
 $\xrightarrow{\quad} \text{xxxxyxq}_2x_1y_1y_1 \leftarrow \cancel{\text{xxxxyxq}_2x_1y_1y_1}$

Turing machine as Transducer.

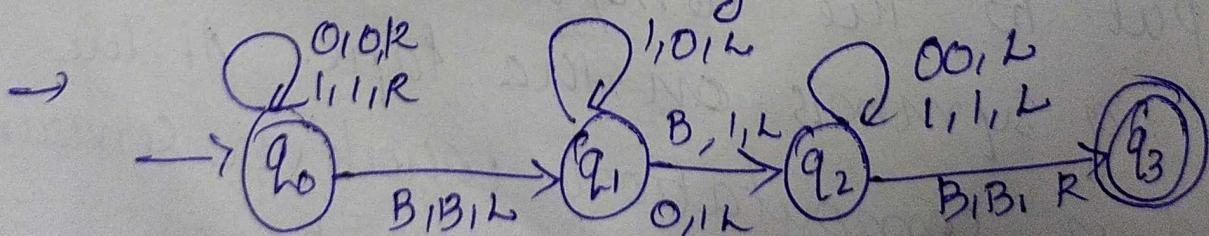
A turing machine can function as a transducer i.e., when a string is given as input to turing machine it produces some output.

Input to the computation is a set of symbols on the tape. At the end of computation whatever remains on the tape is the output.

A function f is said to be computable or turing computable if

There exists a turing machine M
 $\Leftrightarrow M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$
 such that $q_0 w \xrightarrow{*} q_f f(w)$,
 where w is the domain of f .
 All common mathematical functions
 are turing computable basic operations
 like addition, subtraction, multipli-
 cation, division can be performed
 on it. This means that a
 turing machine is an abstract
 model of modern computer system.

Q2 Construct a turing machine that
 increments a binary no.



Q2 Design a turing machine that computes the function

$$f(m, n) = (m+n)$$

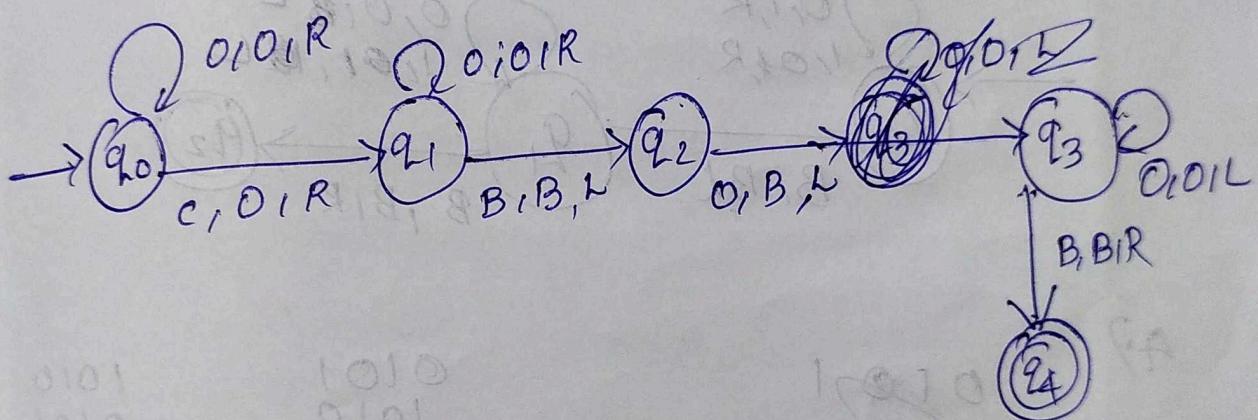
2 + 3

2 represented as 00

1B|0|0|1|c|0|0|1|0|B|1|1
B 0 0 ↓ 0 0 0 B -

3 cc 000

cc c is used
to differentiate



Q3 Construct a turing machine that computes the complement of given binary number.

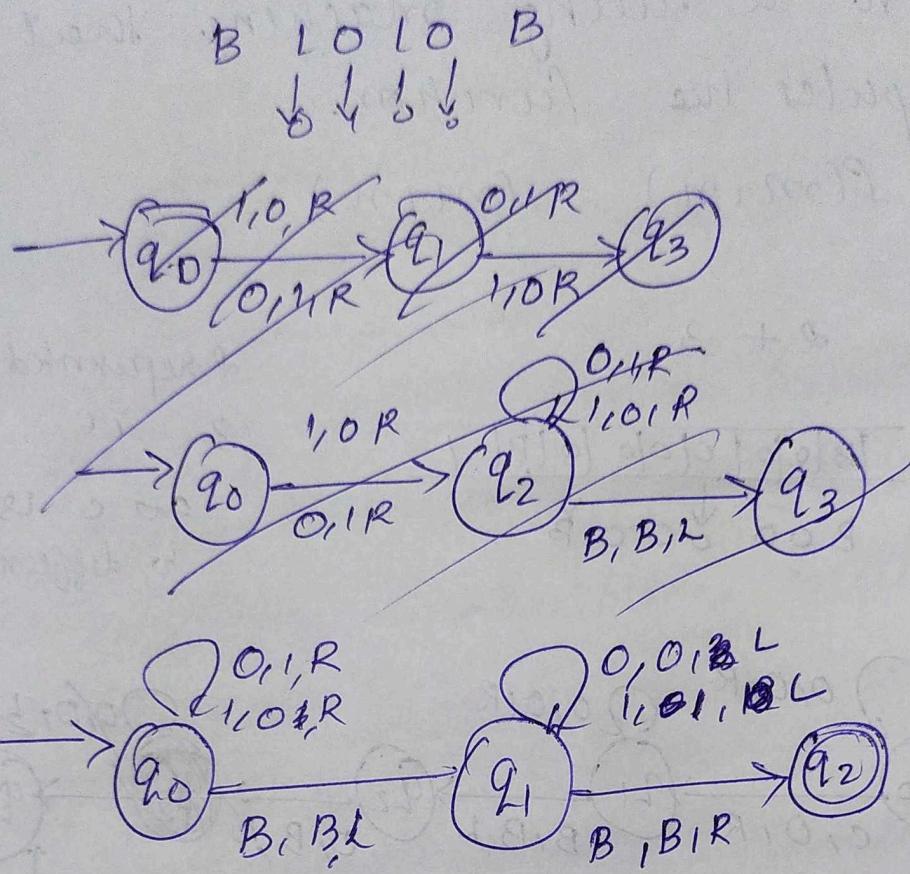
Q4 2's complement

Q5 Design a turing machine that performs the computation

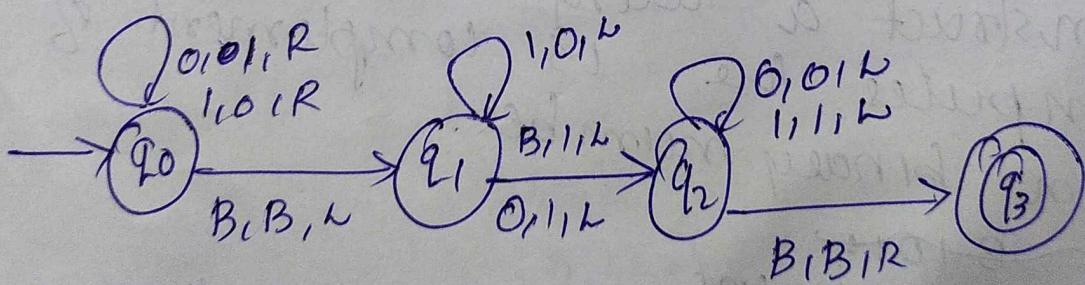
$q_0 w + * q_1 w$

Q6 Design a turing machine that

32



4.7



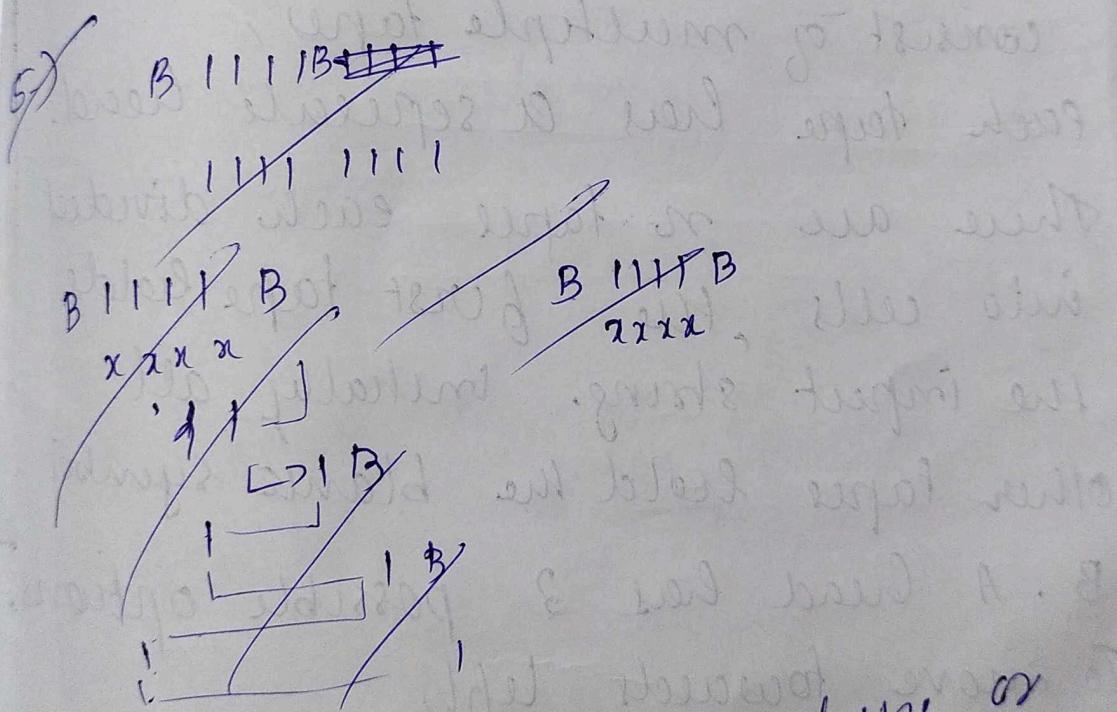
$$\begin{array}{r}
 1000 \\
 0111 \\
 \hline
 0
 \end{array}
 \quad
 \begin{array}{r}
 1000 \\
 0111 \\
 + 1 \\
 \hline
 1000
 \end{array}$$

$$\begin{array}{r}
 0101 \\
 1010 \\
 \hline
 1011
 \end{array}$$

$$\begin{array}{r}
 1010 \\
 0101 \\
 \hline
 0
 \end{array}$$

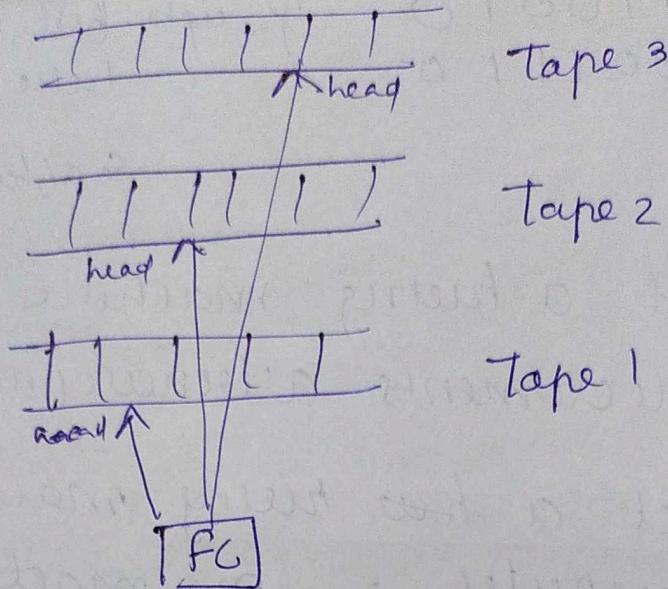
$(\begin{array}{l} 110010 \\ 001110 \end{array})$ upto first 4,
 take ones
 complement
 & after same.

- 6) construct a turing machine
 that decrements a binary no.
 7) construct a turing machine
 that computes n^m mode 2



Types of Turing machine or
Variants of Turing machine.

1) Multitape tape turing machine :-



A multitape turing machine consists of multiple tapes, each tape has a separate head.

There are n tapes each divided into cells. The first tape holds the input string. Initially all other tapes hold the blank symbol.

- B. A head has 3 possible options
- 1) To move towards left,
- 2) To move " right
- 3) To remain stationary.

All the heads are ~~not~~ connected to a finite control. Finite control

is in a state at an instant
when a transition occurs,

finite control may change its state.

Head reads the symbol from the current
cell on each tape and writes a
symbol on it.

Each head can move towards
left, right or stay stationary

for multitape turing defined
as ~~QXF^K~~

$$Q \times \Gamma^K \rightarrow Q \times F^K \times S_{n,R}, S^{\gamma^K}$$

A move depends on the current
state and K tape symbols under

K tape heads.

e.g.: A transition function for a

4 tape turing machine is

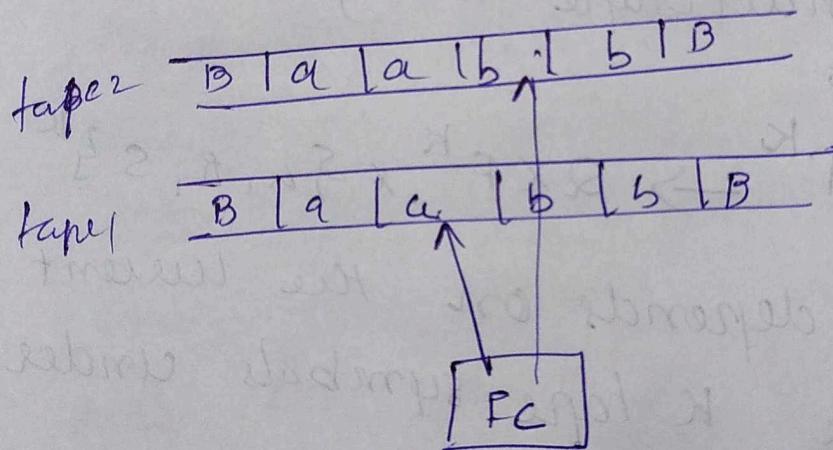
$$\delta(q_0, a_1 a_2 a_3 a_4) = (q_1, \{b_1 b_2 b_3 b_4\}, \{R, L, S\})$$

consider the language

$$L = \{a^n b^n / n \geq 1\}$$

→ In a normal Turing machine head has to move back and forth to match each pair of symbols $a \neq b$. On a multitape Turing machine, no such moves are required. This is done by making a copy of input string on another ϵ string.

Let I/P string be aabb



Head of tape 1 is positioned on first a of I/P string, head of tape 2 is positioned on first b of I/P string. Now the heads advance on both tapes simultaneously towards right. ϵ

The string is accepted if there are equal no. of a's & b's in the string. This will happen if head on tape 1 encounters the first b & head on tape 2 encounters first B simultaneously.

- Q. Design a multtape turing machine that determines the ones complement of given binary no.

$\Rightarrow q_0 \xrightarrow{0} q_0, 01$ 0110
 Tape 4 symbol - {0, 1}
 Tape 2 ϵ = 2B4 initially

$$\delta(q_0, 0B) = \delta(q_0, 01, RR)$$

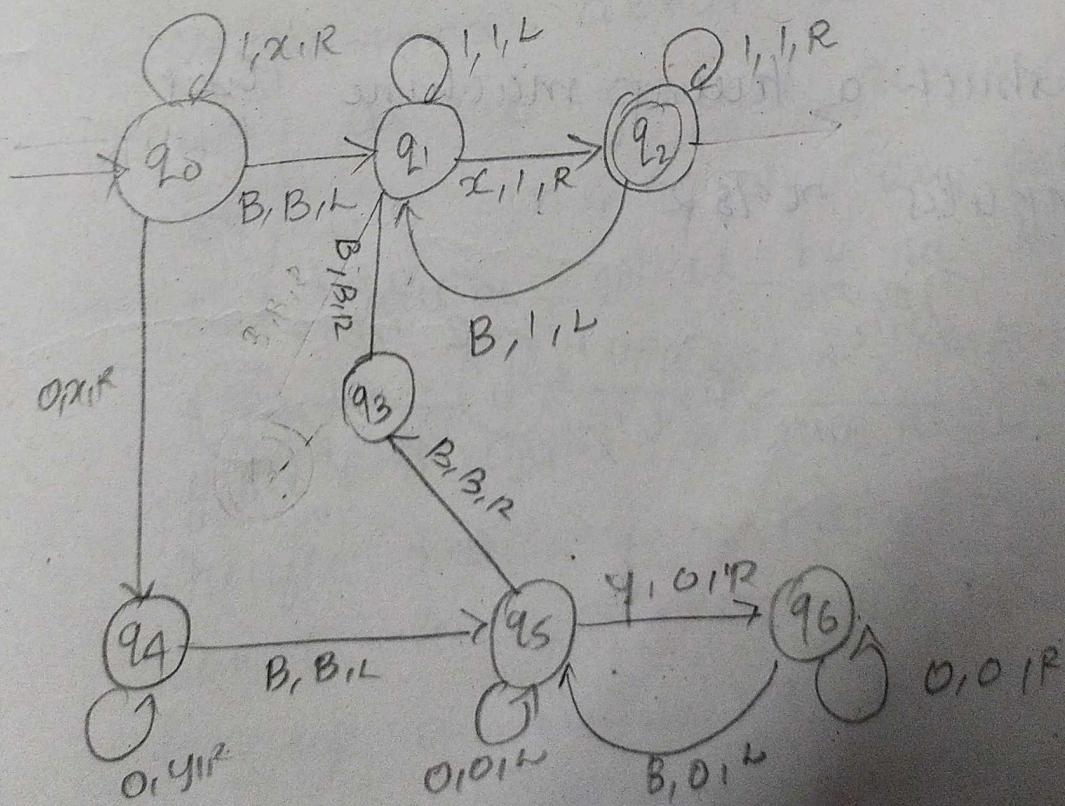
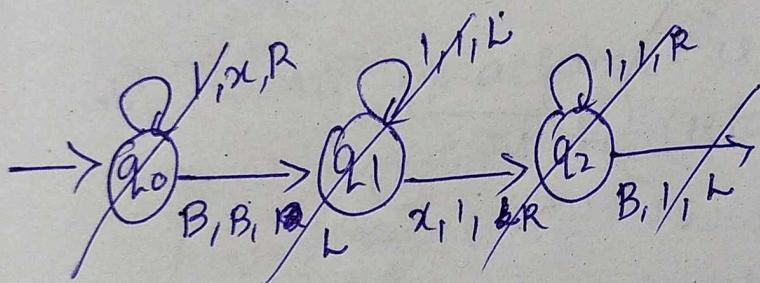
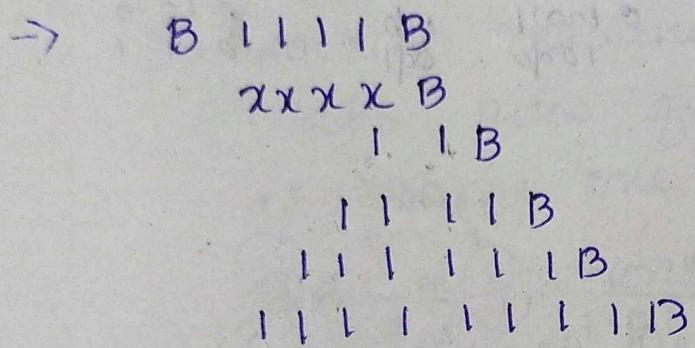
$$\delta(q_0, 1B) = \delta(q_1, 10, RR)$$

$$\delta(q_0, BB) = \delta(q_1, BB, SS)$$

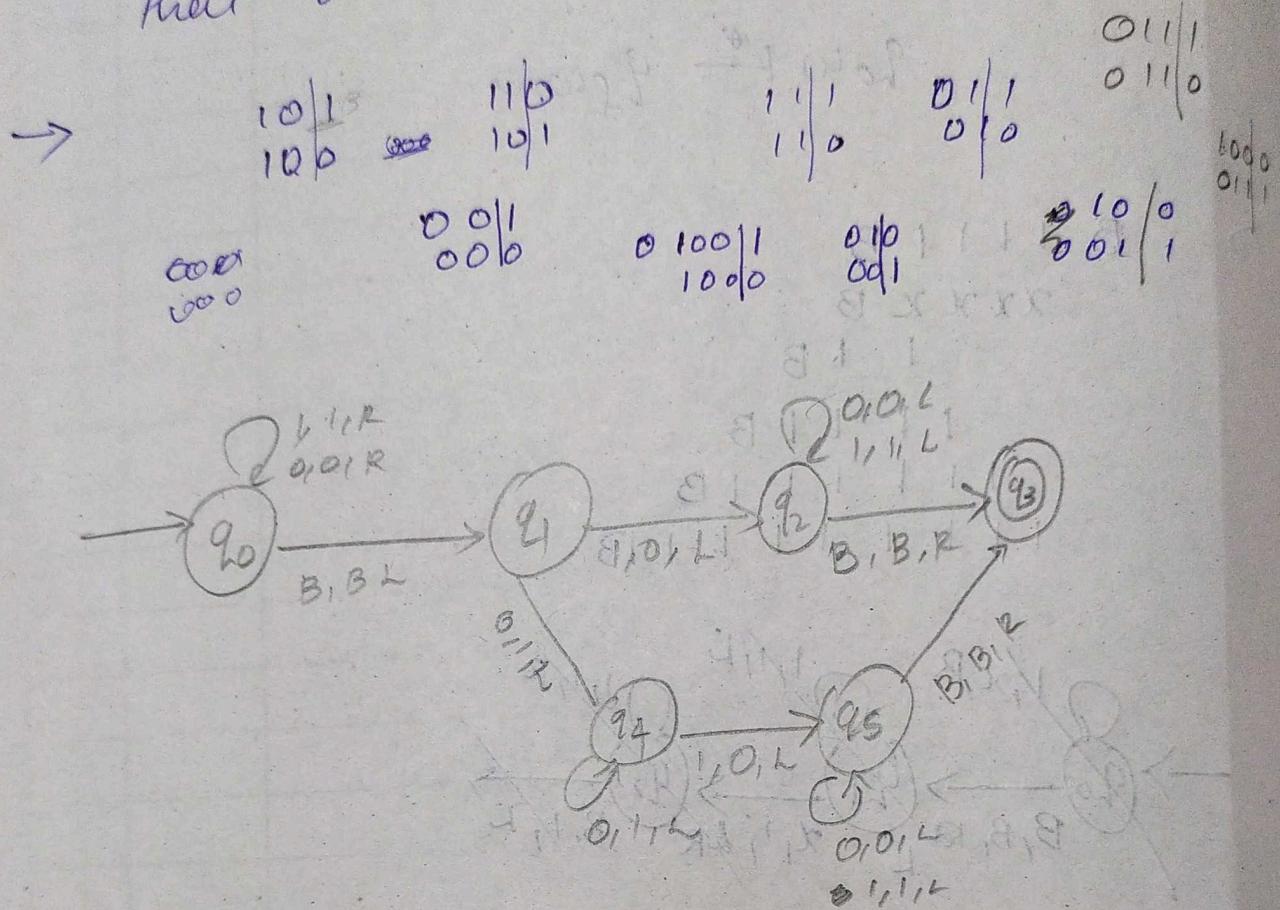
\equiv

Q.3) Construct a Turing machine ~~such~~
to perform the computation

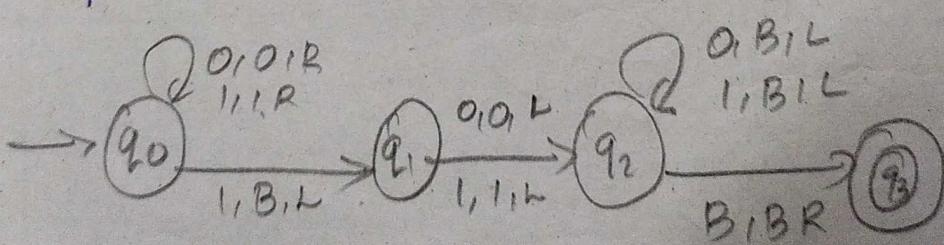
$$q_{\text{start}} \xrightarrow{*} q_{\text{final}}$$



6. Construct a turing machine
that decodes a binary no.



7. Construct a turing machine that
computes $n \otimes_2 2$.



Universal Turing Machine

Turing machine can be thought of in 2 ways

- ① Turing machine gives an unprogrammable piece of hardware specialised at solving one particular problem with instructions that are fixed handwired at the factory.
- ② Turing machine is a software i.e. there is a certain generic turing machine that can be programmed about the same way as the general purpose computers can, to solve any problem that can be solved by the turing + machine. The program makes the generic machine behave like a specific machine. i.e. turing machine can be thought of as programming language on which we can write programs. Programs written in this

language can be interpreted
by some universal machine.

Universal Turing machine or takes
of arguments, a description of machine
(binary encoded) say m . & input
string say ' w '.

$$U(\star^M, w) = m(w)$$

It is the functional notation of
universal \oplus TM.

U code halts on \star^P w if & only
if TM halts on \star^P w .

Consider a TM which is defined

$$\text{as } M = (\Sigma, \Gamma, \delta, q_0, B, F)$$

$$\Sigma = \{q_0, q_f\}, \{q, b\}, \{q, b, B\}, \\ \delta, q_0, B, q_f$$

$$\delta(q_0, q) = (q_0, q, R)$$

$$\delta(q_0, b) = (q_0, b, L)$$

$$\delta(q_0, B) = (q_f, B, L)$$

First we encode all the components
of this TM using binary coding.

In binary coding, only symbols 0 & 1 are available. Here 0 is used to quote all the transitions function and 1 is used as separator between states of TM.

$$\alpha = \{ q_0^0, q_f^0 \} = 0100$$

$$\beta = \{ a, b \} = 0100$$

$$F = \{ q_0, q_1, B \} = 01001000$$

$$S(q_0, a) = (q_0, a, R) = 010101010$$

$$S(q_0, b) = (q_0, b, L) = 01010100100$$

$$S(q_0, B) = (q_f, B, L) = 01001001000100$$

(500)

Let $w = ab$ be the string to be
checked on turing machine M
the input to universal turing
machine is encoded as,

Q:
010011

$$q_0 = 0$$

$$q_f = 00$$

X:
a = 0
b = 00
B = 000

T

a = 0
b = 00
B = 000

$$S(q_0, q) = (q_0, a, R) - 010101010$$

$$S(q_0, b) = (q_0, b, L) - 010010100100$$

$$S(q_0, B) = (q_f, B, L) : 010001001000100$$

Let $w = 01010011010001000110101010101$
be string to be checked
on the TM. M. The L.P to universal TM
will be,

(010011010011010001000110101010101
0100101001010100010010001001
0110001100)

Universal turing machine used binary code of turing machine M on string AB & will check if AB is recognised by M..

If true, universal turing machine will halt to say 'Yes'.

If false, UTM will stop to say 'No'.

Non-Deterministic Turing Machine

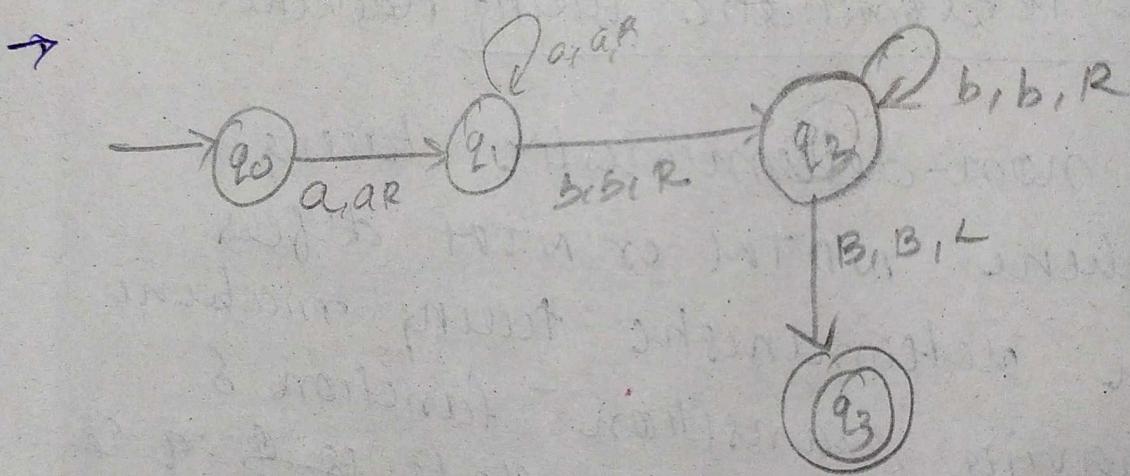
A non-deterministic turing machine NDTM or NTM differs from deterministic turing machine by having transition function δ such that for a st. state $q \in Q$ & a tape symbol $s(q, x)$ is a set of triples $\{ (q_1, y_1, L), (q_2, y_2, R), (q_3, y_3, R) \}$

NDTM can choose, at each step, any of the triples to be the next move, the transition function for NDTM is given as

$$\delta: Q \times \Gamma \rightarrow Q \times \{L, R\}$$

A string $w \in \Sigma^*$ is said to -
 & be accepted by NDTM if there exist
 sequence of moves starting from initial
 id to an accepting ~~or~~ condition.

- a) Construct a NDTM which accepts
 the language $L = \{a^n b^m / n \geq 1, m \geq 1\}$



Enumeration Machine

An enumeration machine is a turing machine with a pointer & it has infinite tape & finite state control as a turing machine plus a pointer is used to generate

strings of the language.

Recursive Enumerable Language (REL)

A language L is recursively enumerable if it is possible to design a turing machine for the language L such that for any string $w \in L$, turing machine accepts w by entering into final state. and for any string $w \notin L$ turing machine rejects w by halt-ing in a non final stage or by looping forever. i.e.,
if $w \in L \Rightarrow M$ accepts by reaching final state. if $w \notin L \Rightarrow M$ halts at non final state or M enters infinite loop.

Recursive language

A language L is recursive language, if it is design possible to design the turing machine for the language L such that for any string $w \in L$,

Turing machine accepts w by entering into final state. For any string $w' \in L$, Turing machine rejects w' by halting in a non final state. i.e., if M accepts w by entering final state. If M halts by entering non-final state.

Properties of Recursively Enumerable & Recursive language

1) Union :-

If L_1 & L_2 are 2 recursive language, then their union $L_1 \cup L_2$ is also will also be recursive. This is because TM halts for x_1 & halts for x_2 , it will also halt for $L_1 \cup L_2$.

2) Concatenation :-

If L_1 & L_2 are 2 recursive language, then their concatenation $L_1 \cdot L_2$ will also be recursive.

eg: $L_1 = \{a^n b^n ; n \geq 0\}$ is recursive

$L_2 = \{a^m c^m / m \geq 0\}$ "

$L_1 L_2 = \{a^n b^n a^m c^m ; (n \geq 0, m \geq 0)\}$

is also recursive

3) Kleen Closure :-

If L_1 is recursive, then its Kleen closure L_1^* will also be recursive.

eg: $L_1 = \{a^n b^n ; n \geq 0\}$

$L_1^* = \{a^n b^n ; n \geq 0\}^*$

4) Intersection :-

If L_1 & L_2 are 2 recursive languages, then their intersection $L_1 \cap L_2$ will also be recursive.

eg:- $L_1 = \{a^n b^n d^{n+m} ; n \geq 0 \text{ & } m \geq 0\}$

$L_2 = \{a^n b^n d^n ; n \geq 0\}$

$L_1 \cap L_2 = \{a^n b^n d^n ; n \geq 0\}$

is also recursive.

3) Complement of recursive language is recursive.

6) If $L_1 \cup L_2$ are & recursively enumerable languages, then

1) $L_1 \cup L_2$ is RE.

2) $L_1 \cap L_2$ is RE.

3) If L is a RCL & its complement \bar{L} is also RE;

Then L is recursive language.

7) Complement of RE need not be recursively enumerable.

Decidability

The Problem solved by TM can be categorised into 2 categories

1) The Problems in which TM can both halt in the accepting or rejecting state are called decidable problems. In other words, a problem

is said to be decidable. If it is
so solvable.

A language L is decidable, if there
exists a turing machine M such that
for all strings w if $w \in L$, M enters
 Q_{accept} . If $w \notin L$, ~~M~~ M enters Q_{reject} .

The problems in which TM may
not halt at all if they do not
accept its input \Leftrightarrow the problems that
do not have ~~see the p.~~ algorithms
are called ~~see~~ undecidable problems.

A problem is said to be undecidable
if it is unsolvable

* Halting Problem

- 7) If L is a Recursively Enumerable language and its complement L' is also Recursively Enumerable, then L is Recursive language.
- 8) Complement of Recursively Enumerable Language L need not be Recursively Enumerable.

Decidability

The problems solved by Turing Machine can be categorized into two categories:

- 1) The problems in which TM can halt in the accepting or rejecting state are called decidable problems.
 In other words, a problem is said to be decidable if it is solvable. A Language L is decidable, if there exists a TM, M such that for all strings w :
 If $w \in L$, M enters q_{accept} .
 If $w \notin L$, M enters q_{reject} .
- 2) The problems in which TM may not halt at all if they do not accept its input is the problem that do not have algorithm, are called undecidable problems.
 A problem is said to be undecidable if it is unsolvable.

A Recursively Enumerable Language is also known as Turing Recognisable (or partially decidable), while a Recursive language is known as Turing Decidable.

So deciders always terminates, while recognizers can run forever without deciding.

Halting Problem

⇒ Halting problem is the problem of determining, from a description of a machine and an input, whether the program or machine will halt (ie finish running) or continue to run forever.

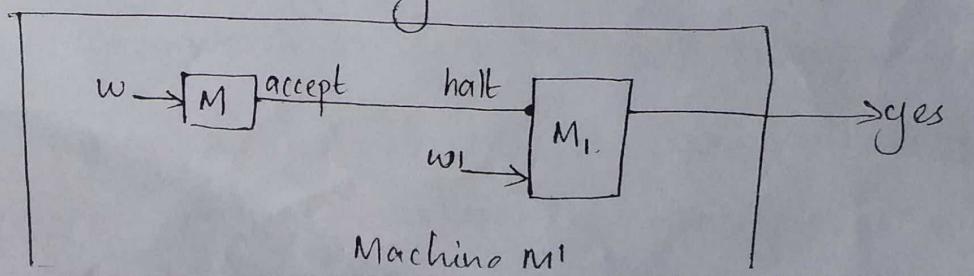
⇒ Halting problem is an undecidable problem.

⇒ Alan Turing proved in 1936 that a general algorithm to solve the halting problem for all possible program-input pairs cannot exist.

Theorem : Halting problem of a Turing Machine is undecidable.

Proof: To show this we reduce problem of halting to a problem of acceptance.

Consider the following TM.



Here we take an instance (M, w) and construct another instance (M_1, w_1)

It is taken such that M_1 halts on input w_1 , if and only if M accepts w .

The machine M' stops when M_1 halts.

Initially, the string w is fed to the TM, M and w_1 is fed to the TM, M_1 .

If M accepts w , then it sends a halt signal to M_1 .

Then TM, M_1 halts on input w_1 .

If M rejects w , then M_1 does not halt on w_1 .

Thus halting of M_1 depends on the acceptance behaviour of M . Acceptance behaviour of TM is undecidable, Hence halting of M_1 or M' is undecidable.

Chomsky Hierarchy

A number of language families are present.

Noam Chomsky, a founder of Formal Language Theory provided an initial classification into 4 language types:

Type 0, Type 1, Type 2, Type 3

→ Four types of languages and their associated grammars are defined in Chomsky Hierarchy.

The Languages are:

Type 0 Languages or Unrestricted Languages.

Type 1 Languages or Context sensitive Languages.

(2)

CLOSURE PROPERTIES OF RECURSIVE & RECURSIVELY ENUMERABLE LANGUAGE

PROPERTY 1

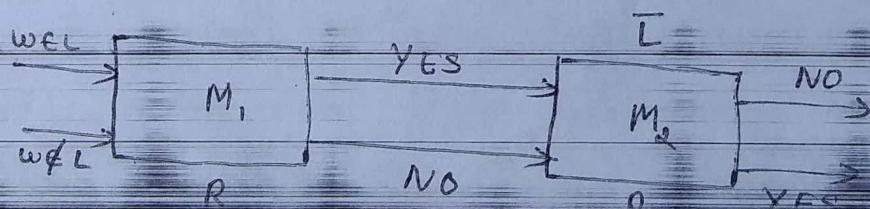
The complement of a recursive language is also recursive, ie, recursive languages are closed under complementation.

Proof.

Let ' L ' be a recursive language accepted by the Turing m/c M_1 where 'YES' is an accepting state & 'NO' is a non-accepting state.

Let ' \bar{L} ' be a recursive language accepted by the TM M_2 where 'NO' is an accepting state & 'YES' is a non-accepting state.

The construction of M_1 & M_2 are given as follows,



Let $w \in L$, then M_1 accepts w & halts with 'YES'. M_1 rejects w if $w \notin L$ & halts with 'NO'. M_2 is activated once M_1 halts. M_2 marks on \bar{L} & hence if M_1 returns 'YES', M_2 halts with 'NO'. If M_1 returns 'NO', M_2 halts with 'YES'.

Thus for all w , where $w \in L$ or $w \notin L$, M_2 halts with either 'Yes' or 'No'. Hence the complement of a recursive lang is

(3)

Property 2

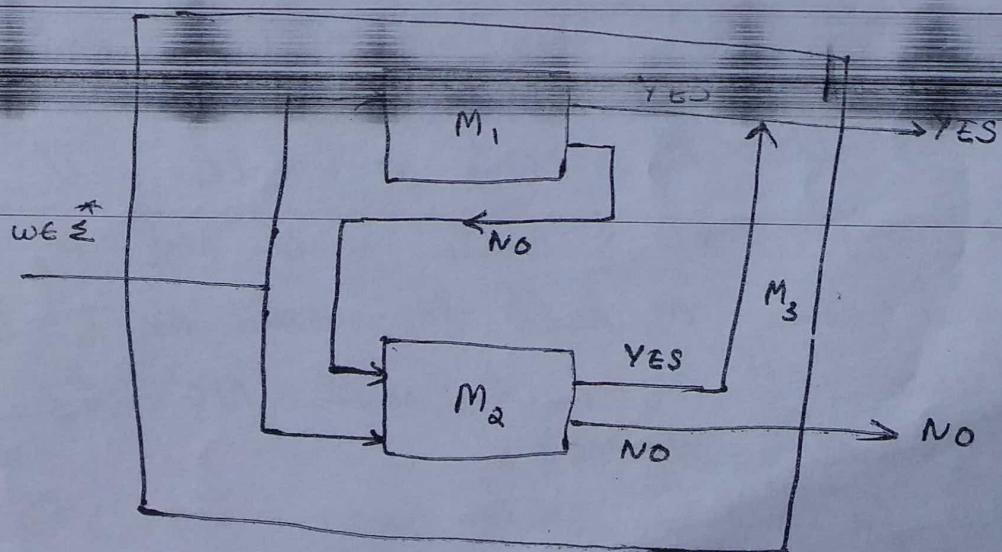
The union of two recursive language is also recursive, ie, recursive languages are closed under union.

Proof

Let L_1, L_2 are two recursive languages (ie $L_1, L_2 \in R$) then there exist two TMs M_1, M_2 that compute L_1, L_2 respectively, because recursive languages are decided by TM.

For deciding $L_1 \cup L_2$, construct a TM M_3 which can simulate M_1 & M_2 parallel to each other one step at a time. It first stimulates M_1 , that is starts M_1 on w first. If it decides on the given i/p w , ie M_1 outputs YES, then M_3 also o/p's YES & terminates.

On the other hand, if M_1 o/p's NO, M_3 starts M_2 on i/p ' w ' & o/p's whatever M_2 o/p's. It is clear that M_3 decides $L_1 \cup L_2$ as shown in fig. below



Since both M_1 & M_2 are algorithms, M_3 is guaranteed to halt. This simulation causes M_3 to decide if and only if at least one of the two m/c's M_1 & M_2 decide.

Thus we can conclude that M_3 decides or computes $L_1 \cup L_2$, ie $L_1, L_2 \in R$.

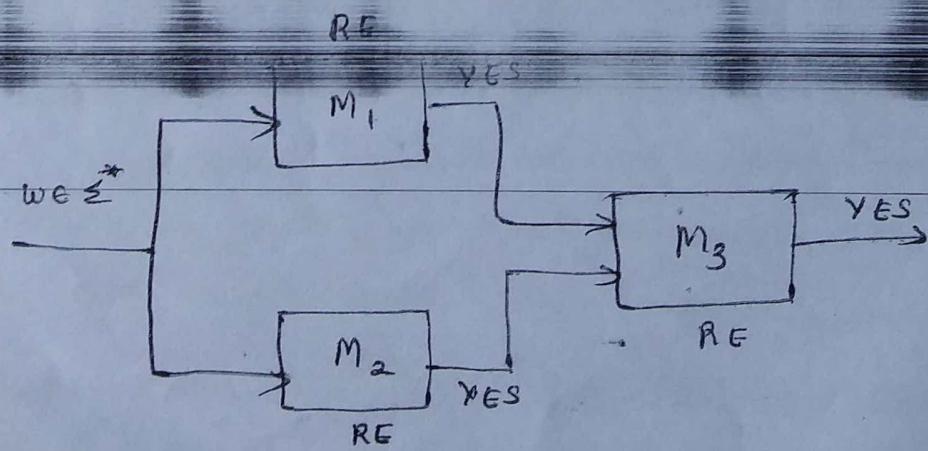
\rightarrow Property 3

The union of two recursively enumerable language is also recursively enumerable, ie RE lang's are closed under union.

Proof

Suppose L_1 & L_2 are two recursively enumerable lang's (ie $L_1, L_2 \in R_E$) then there exist two TM's M_1 & M_2 corresponding to L_1 & L_2 respectively, because RE lang's are accepted by TM.

$\therefore M_1$ will accept any string w if $w \in L_1$ & similarly M_2 will accept w , if $w \in L_2$.



(u)

Now, we can form the m/c M_3 which can simulate M_1 & M_2 parallel to each other one step at a time. If either accepts, then M_3 accepts & recognizes $L_1 \cup L_2$, as in the fig.

The m/c can choose whether to simulate M_1 or M_2 first so it is a NDIM, however it will not make any difference in computation because NDIM & DTM's have the same expressive power.

The possible outcomes are,

- 1) If M_1 & M_2 both reject, the string simultaneously only then M_3 rejects.
- 2) If M_1 accepts the string, then M_3 accepts
- 3) If M_2 accepts the string, then M_3 accepts.

This simulation causes M_3 to accept iff at least one of the two m/c's M_1 & M_2 accepts. So we can conclude that M_3 recognizes $L_1 \cup L_2$, i.e. $L_1, L_2 \in RE$

→ Property 4

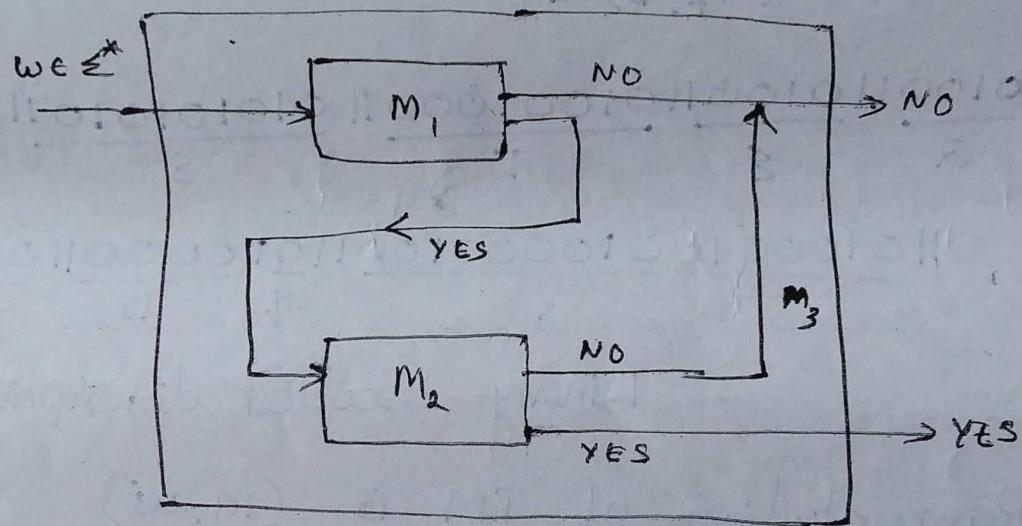
The intersection of two recursive language is also recursive. i.e. recursive languages are closed under intersection.

Proof

Let $L_1 \& L_2$ are two recursive languages (ie $L_1, L_2 \in R$) then there exist two TM's $M_1 \& M_2$ that compute $L_1 \& L_2$ respectively, because recursive languages are decided by TM.

$$L(M_1) = L_1 \& L(M_2) = L_2$$

Let M_3 be the TM, ie constructed by the intersection of $M_1 \& M_2$. M_3 is constructed as follows,



The TM M_3 simulates M_1 with i/p string w . If $w \notin L_1$, then M_1 halts along with M_3 with answer 'NO' since $L(M_3) = L(M_1) + L(M_2)$. If then M_1 accepts with the answer 'YES' &

If M_2 accepts the string, then the answer of $M_2 \& M_3$ are 'YES' & halts. Else $M_2 \& M_3$ halts with answer 'NO'.

Thus the intersection of two recursive lang. is recursive.