

Mini-Project (ML for Time Series) - MVA 2025/2026

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1 Introduction and contributions

In the rapidly evolving field of sports analytics, understanding team tactics is crucial for performance analysis. In fluid team sports like soccer, analyzing team formation is one of the most intuitive methods to interpret tactics from the perspective of domain participants. However, extracting these insights from spatiotemporal tracking data presents significant challenges. Players frequently switch positions temporarily or engage in abnormal situations like set-pieces, making it difficult to distinguish between a genuine tactical change instructed by a coach and a transient movement noise. Existing approaches often fail to address this dynamic, either assuming formations remain constant throughout a match or reacting too sensitively to frame-by-frame changes [1, 3, 4].

To address these limitations, this project studies the framework proposed by Kim et al. in [2]. The article introduces a novel, unsupervised change-point detection (CPD) framework designed to distinguish tactically intended formation changes from temporary role swaps. The methodology consists of two distinct phases: Formation Change-Point Detection (FormCPD), which identifies shifts in the global spatial configuration of the team, and Role Change-Point Detection (RoleCPD), which detects long-term tactical changes in individual player roles within a specific formation period. By utilizing graph-based statistics and Delaunay triangulation, the method aims to provide a robust timeline of tactical instructions.

Contributions and Work Repartition In alignment with the course requirements, this report details our reproduction and extension of the SoccerCPD framework. The organization of the project is as follows:

- **Work Repartition:** The workload was divided based on the two-step nature of the pipeline. Fotios Kapotos focused on the first stage, FormCPD, analyzing the generation of role-adjacency matrices and the segmentation of formation periods. Adonis Jamal concentrated on the second stage, RoleCPD, investigating the sequence of role permutations and the detection of intra-formation tactical shifts.
- **Source Code:** We utilized the open-source Python implementation provided by the authors to run the core algorithms. However, we performed a deep-dive analysis into the code to understand the underlying mechanics of the discrete g-segmentation and re-implemented specific analytical components to verify limitations.
- **Experiments:** Beyond verifying the results on sample data, we conducted a novel experiment titled the "Messi Effect". This analysis aims to compare formation structural differ-

ences and player stationarity in matches involving Lionel Messi versus those without him, testing the model’s ability to capture player-centric tactical gravity. Moreover, we explored the stationarity of players across different formations and roles, providing insights into individual player behavior within team tactics. Finally, we address a limitation of the original method by providing offensive and defensive formation change-point detection, enhancing the interpretability of tactical shifts.

2 Methodology

2.1 Formation Change-Point Detection (FormCPD)

FormCPD converts raw player trajectories $X(t) \in \mathbb{R}^{N \times 2}$ into a temporal sequence of role-based formation graphs $\{A(t)\}_{t \in T}$. Discrete g-segmentation is then applied to detect change-points $T_1 < \dots < T_m$ such that formations are stationary within each segment. Finally, formation segments are aligned and clustered to extract canonical formation types.

2.1.1 Role Assignment

Players are assigned to latent spatial roles following [1], modeling stable positional zones rather than player identities. Each role k is represented by a Gaussian component (μ_k, Σ_k) with the constraint that each role is occupied by exactly one player per frame.

Parameters are estimated via a constrained EM algorithm: the E-step solves a one-to-one assignment using Hungarian matching on negative log-likelihoods, while the M-step updates role parameters from all assigned positions across time.

2.1.2 Change-Point Detection on Graphs via Delaunay Triangulation

Given role locations $V(t) = \{v_1(t), \dots, v_N(t)\}$, each frame is encoded as a role-adjacency graph using Delaunay triangulation. Two roles are connected if they share an edge in the triangulation, producing a binary adjacency matrix $A(t) \in \{0, 1\}^{N \times N}$. Formation changes are detected on the sequence $\{A(t)\}$ using discrete g-segmentation [5]. Dissimilarity between frames is measured by the Manhattan distance

$$d_M(A(t), A(t')) = \|A(t) - A(t')\|_{1,1}.$$

Frames with excessive role switching (rate > 0.7) are discarded. Candidate change-points are retained if they satisfy constraints on statistical significance ($p < 0.01$), minimum segment duration (5 minutes), and inter-segment dissimilarity. A recursive procedure recovers multiple change-points, partitioning the match into formation intervals.

2.1.3 Formation Clustering

Each segment T_i is summarized by a formation graph $F(T_i) = (V(T_i), A(T_i))$, obtained by averaging role positions and adjacency matrices over stable frames. Since role labels are arbitrary across segments, formations are aligned using Hungarian matching on Euclidean distances between $V(T_i)$ and $V(T_j)$, yielding a permutation matrix Q .

Formation similarity is defined as

$$d(F_i, F_j) = \|QA(T_i)Q^\top - A(T_j)\|_{1,1},$$

capturing differences in topological structure. Agglomerative hierarchical clustering on these distances produces a small set of canonical formation types.

2.2 Role CPD

The goal of RoleCPD [2] is to detect long-term tactical changes in player roles (e.g., a winger swapping sides with another winger permanently) while ignoring temporary switches (e.g., overlapping runs or covering defensive duties). This process operates within a single Formation Period (T_i) identified in the previous step. Figure 7 in Appendix B illustrates the ground truth of such role assignments with simulated tactical switches.

2.2.1 Formal Representation

We define the inputs and mathematical framework based on the SoccerCPD protocol:

- **Input:** A sequence of "Temporary Role Permutations" $\{\pi_t\}_{t=1}^{|T_i|}$.
- **Role Permutation (π_t):** At every frame t , the Role Representation step assigns a role X_p to every player p . Since roles are distinct, this assignment is a permutation of the initial canonical role:

$$\beta_t(p) = \pi_t(X_p)$$

Where β_t is the player-to-temporary-role mapping at time t .

2.2.2 The Distance Metric

To detect a change, we must quantify the difference between the team's configuration at time t and time t' . Since the data consists of permutations (non-Euclidean), we cannot use standard Euclidean distance. We use the Hamming Distance normalized by the number of roles ($N = 10$ outfield players):

$$d(\pi_t, \pi_{t'}) = \frac{1}{N} \sum_{p \in P} \mathbb{1}_{\pi_t(X_p) \neq \pi_{t'}(X_p)}$$

This metric represents the "Switch Rate" or the proportion of players whose roles differ between two frames. Figure 8 plots this switch rate over time, showing it fluctuates relative to a dominant permutation.

2.2.3 Change-Point Detection Algorithm

The paper utilizes Discrete g-segmentation, a graph-based change-point detection method effective for repeated observations in non-Euclidean space. The procedure is as follows:

1. **Preprocessing:** Calculate the Switch Rate relative to the dominant permutation. Exclude frames with a switch rate > 0.7 (likely temporary switches during set-pieces or abnormal situations).
2. **Segmentation:** Apply the detection algorithm recursively on the sequence of permutations using the Hamming distance. Figure 9 shows the result of a single segmentation step, while Figure 10 demonstrates the final output after recursive segmentation captures all tactical phases, accurately recovering the ground truth on the synthetic example.
3. **Significance Test:** A change point τ is significant if:

- The p-value of the scan statistic is < 0.01 .
- The segmentation duration is sufficient (robustness against noise).
- The most frequent permutations (Instructed Roles) in the segments before and after τ must be distinct.

3 Data

Our study utilizes two distinct types of spatiotemporal datasets to evaluate the SoccerCPD framework: high-frequency GPS tracking data used in the original SoccerCPD study, and event-stream data for our novel "Messi Effect" experiment. This section analyzes the properties, quality, and preprocessing requirements of these signals.

3.1 Fitogether Tracking Data

For the reproduction of the core algorithm and methods, we utilized the sample dataset provided by the authors.

- **Source & Format:** The data originates from the K-League (South Korea) and consists of player trajectories recorded at 10 Hz. The raw input is a sequence of 2D coordinates $x_{i,t} \in \mathbb{R}^2$ representing the position of player i at frame t .
- **Data Diagnosis & Quality:** We performed a preliminary diagnosis of the signal stationarity and completeness. The tracking data is relatively clean, with practically no gaps (missing values $< 1\%$). However, we observed high-frequency jitter in the raw trajectories, consistent with GPS measurement noise.
- **Preprocessing:** To satisfy the model's assumption that role centers follow a Gaussian distribution, we normalized the pitch coordinates to a centered metric system (meters relative to the pitch center).

3.2 StatsBomb Event Data

To investigate the structural impact of Lionel Messi on team dynamics and formations (what we term the "Messi Effect"), we utilized the StatsBomb Open Data repository. This dataset differs fundamentally from the Fitogether data, presenting unique challenges for the SoccerCPD pipeline. High-frequency GPS tracking data is not publicly available for matches involving Messi, so we relied on event-stream data.

3.2.1 Signal Characteristics and Challenges

Unlike the continuous 10 Hz GPS signal, StatsBomb data is event-based, recording location (x, y) only when an on-ball action occurs (e.g., pass, shot, dribble).

- **Sparsity:** The primary diagnosis reveals extreme sparsity. While GPS data provides ≈ 600 points per minute per player, event data provides fewer than 10 points per minute on average. This challenges the EM algorithm used in the Role Assignment step, which relies on dense spatial clusters to estimate role means μ_k and covariances Σ_k .

- **Spatial Bias:** Event data is inherently biased towards the ball’s location. Defenders engaging in off-ball marking are often unrecorded in the event stream.

3.2.2 Adaptation and Preprocessing

To adapt this data for the SoccerCPD framework, we applied the following transformations:

1. **Coordinate Transformation:** StatsBomb coordinates are given in a $[0, 120] \times [0, 80]$ system with the origin at the top-left corner. We projected these to the centered metric system used by the Fitogether model to ensure consistency.
2. **Pseudo-Trajectory Generation:** To mitigate sparsity, we aggregated events over temporal windows. Instead of instantaneous frame-by-frame analysis, we treated the collection of event locations within a time window as a sampling of the underlying spatial distribution \mathcal{F}_i .
3. **Role Proxy:** Since we lack continuous tracks for all 10 players simultaneously, we modified the input feature matrix $A(t)$. Instead of a frame-wise Delaunay graph, we constructed aggregate adjacency matrices based on average positions of players over 5-minute segments, serving as a proxy for the mean role-adjacency matrix.

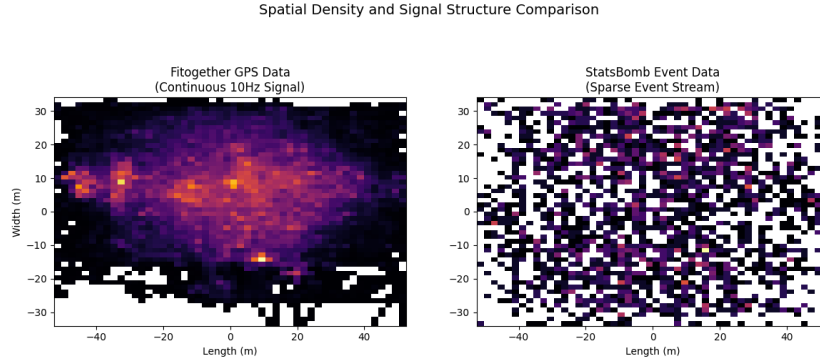


Figure 1: Spatial density comparison between continuous Fitogether GPS tracking data and StatsBomb event-based data (right). The GPS data shows continuous coverage of player positions, while the event data is sparse and concentrated around ball actions.

3.3 Statistical Properties and Gaussian Assumptions

A key hypothesis of the FormCPD method is that player positions within a role follow a Gaussian distribution $x_{i,t} \sim \mathcal{N}(\mu_k, \Sigma_k)$. We diagnosed the validity of this assumption on our datasets.

- **Fitogether Data:** Shapiro-Wilk tests on the specific role clusters (e.g., Center Back) showed deviations from normality, likely due to behaviours such as tactical pressing or zonal marking which create skewed distributions. However, the clusters remain sufficiently separable for the EM algorithm to converge.
- **StatsBomb Data:** The distributions are highly multi-modal due to players switching flanks (e.g., Messi drifting from Right Wing to Center). This multimodal nature supports the use of

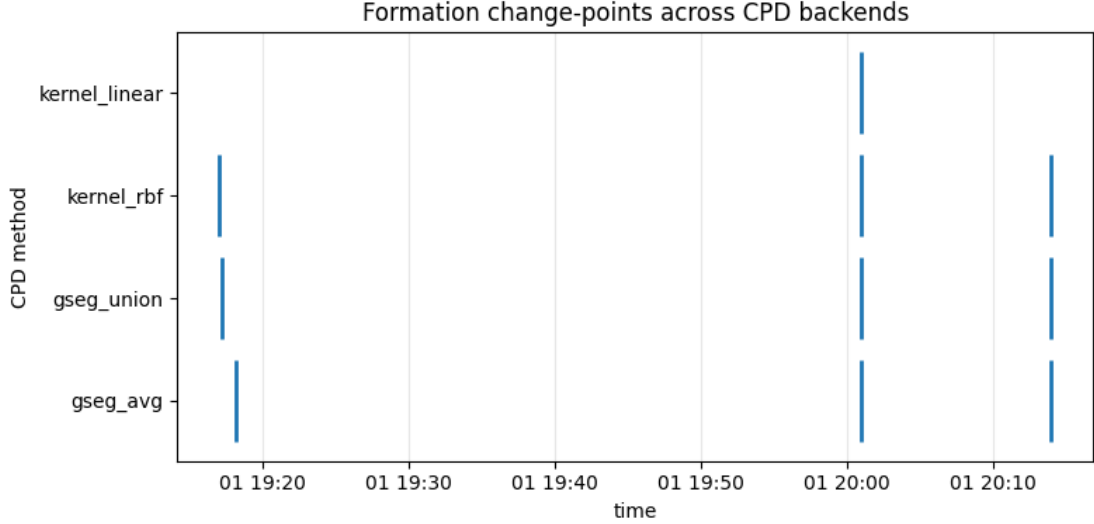


Figure 2: Formation change-points detected by different CPD backends on a common timeline.

the Role Permutation analysis in RoleCPD, as it effectively captures these discrete switches that simple Gaussian averages might obscure.

4 Results

Comparison across CPD backends (single match). We compare several formation CPD backends (`gseg_avg`, `gseg_union`, `kernel_rbf`, `kernel_linear`) on a single reference match, using identical preprocessing and hyperparameters. The goal is not to rank methods, but to assess whether different CPD formulations yield compatible formation change-point timelines.

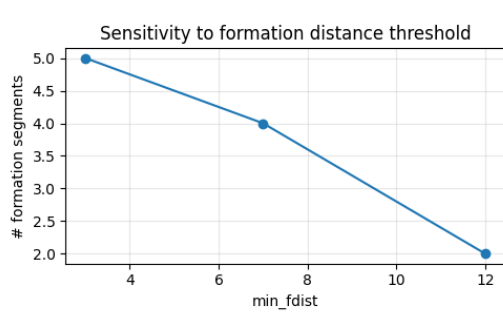
Figure 2 shows the detected formation change-points for each backend on a common timeline. Despite differences in underlying detection principles, most methods identify change-points at similar temporal locations, indicating a shared high-level segmentation of the match. Minor discrepancies mainly correspond to additional or missing change-points rather than large temporal shifts, suggesting differences in sensitivity rather than fundamentally different interpretations of the match dynamics.

Overall, this experiment indicates that formation change-points are largely consistent across CPD backends for this match. Since the analysis is restricted to a single game, these observations should be interpreted qualitatively and primarily serve to illustrate methodological robustness rather than general performance.

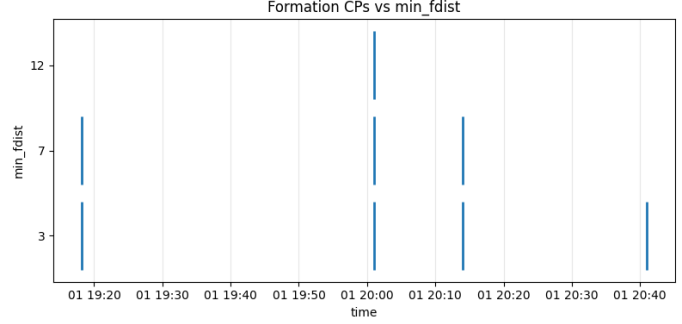
4.1 Experiments using SoccerCPD

Sensitivity analysis of formation CPD (single match). We evaluate the sensitivity of the formation change-point detection (CPD) pipeline to its main hyperparameters on a single reference match. All experiments use the same CPD backend (`gseg_avg`), and one parameter is varied at a time while keeping the others fixed.

We first study the impact of the formation distance threshold `min_fdist`, which controls the min-



(a) Number of formation segments



(b) Formation change-point timeline

Figure 3: Sensitivity of formation change-point detection to the formation distance threshold `min_fdist`. Increasing the threshold reduces the number of detected segments while preserving the temporal locations of the most salient change-points.

imum Manhattan distance between mean formation graphs required to validate a change-point. As `min_fdist` increases, the number of detected formation segments decreases monotonically, indicating that higher thresholds progressively filter out minor structural variations. Importantly, the remaining change-points occur at consistent temporal locations, suggesting that `min_fdist` mainly acts as a pruning mechanism rather than inducing temporal instability.

We then analyze sensitivity to the minimum period duration `min_pdur`, which enforces a lower bound on segment length. Over the tested range, both the number and locations of detected change-points remain unchanged, indicating that the formation changes identified in this match are temporally well separated and not driven by short-lived fluctuations.

Overall, these results suggest that, for this match, formation change-points are robust to reasonable variations in temporal resolution and structural significance thresholds. Since the analysis is conducted on a single match, these findings should be interpreted as illustrative rather than representative, motivating a broader multi-match evaluation.

References

- [1] Alina Bialkowski, Patrick Lucey, Peter Carr, Yisong Yue, Sridha Sridharan, and Iain Matthews. Large-scale analysis of soccer matches using spatiotemporal tracking data. In *Proceedings of the IEEE International Conference on Data Mining (ICDM)*, pages 725–730. IEEE, 2014.
- [2] Hyunsung Kim, Bit Kim, Dongwook Chung, Jinsung Yoon, and Sang-Ki Ko. Soccercpd: Formation and role change-point detection in soccer matches using spatiotemporal tracking data. In *The 28th ACM SIGKDD Conference on Knowledge Discovery and Data Mining*, pages 3146–3156. ACM, 2022.
- [3] Takuma Narizuka and Yoshihiro Yamazaki. Characterization of the formation structure in team sports, 2018.
- [4] Takuma Narizuka and Yoshihiro Yamazaki. Clustering algorithm for formations in football games. *Scientific Reports*, 9(1), September 2019.

- [5] Jingru Zhang and Hao Chen. Graph-based two-sample tests for data with repeated observations, 2019.

A Appendix: Visual Examples for FormCPD

This appendix gathers all visual material related to the FormCPD pipeline (Role assignment, Delaunay encoding, and adjacency representations) referenced in Section 2.1.

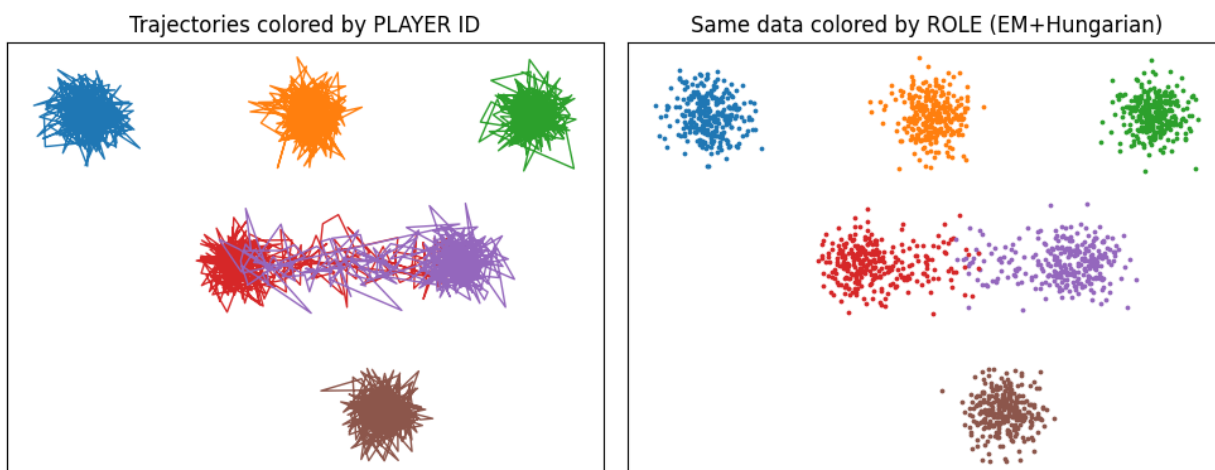


Figure 4: Player versus role-based coloring of trajectories during a simulated position swap.

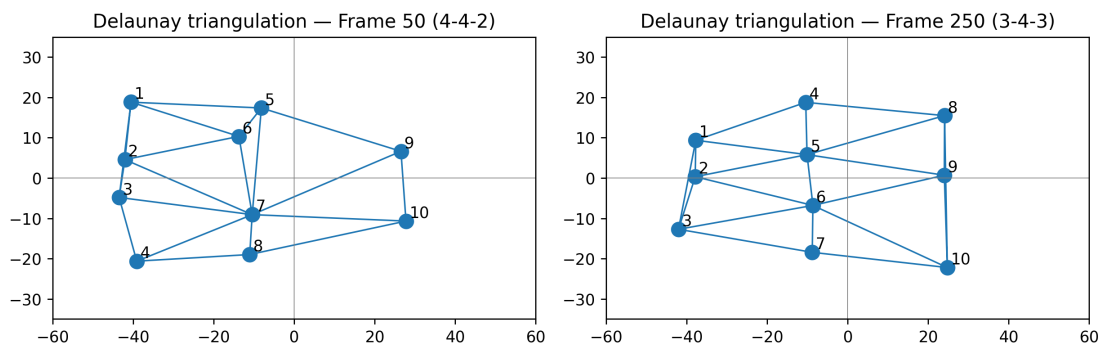
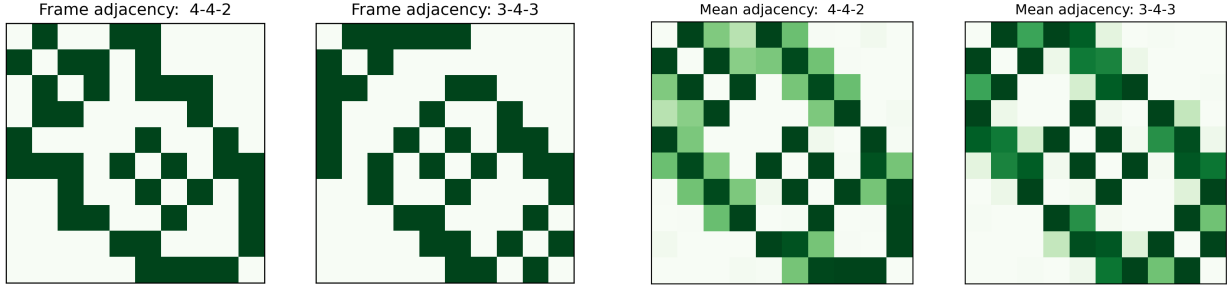


Figure 5: Delaunay triangulations of role locations at two frames before and after a synthetic formation change (4-4-2 \rightarrow 3-4-3).



(a) Single-frame binary adjacency matrices before and after the simulated formation change (4-4-2 → 3-4-3) (Green = 1).

(b) Mean role-adjacency matrices averaged over each formation period (Green = 1).

Figure 6: Delaunay-based adjacency representation on a synthetic formation change.

B Appendix: Visual Examples for RoleCPD

This appendix gathers all visual material related to the RoleCPD pipeline (Hamming distance, Change Point Detection, and Segmentation) referenced in Section 2.2.

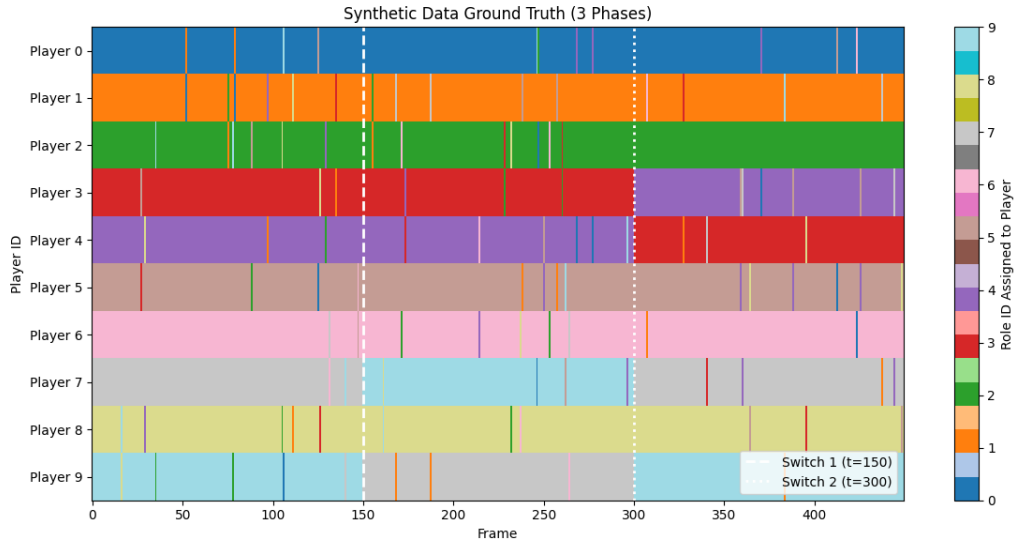


Figure 7: Ground truth role assignments over time with two tactical switches at frames 150 and 300.

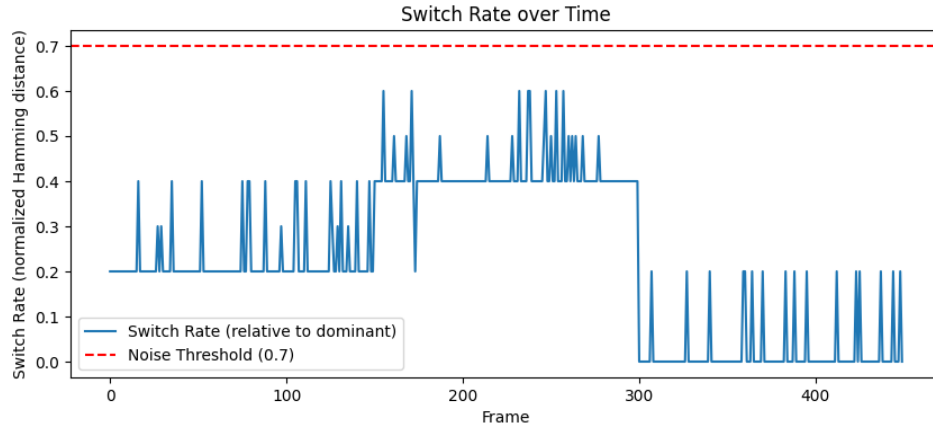


Figure 8: Hamming distance-based switch rate time series used for change point detection.

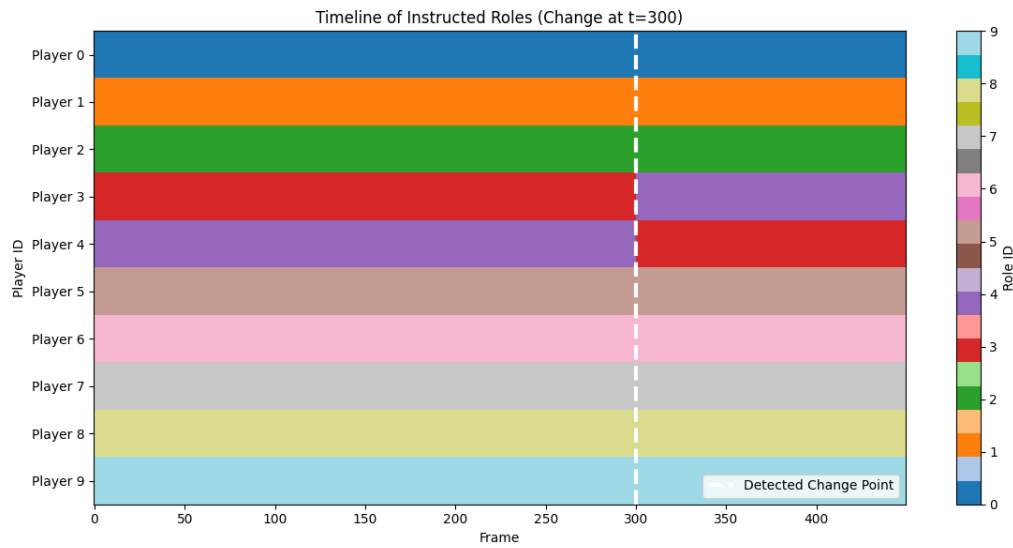


Figure 9: Visualization of one detected tactical phase with dominant role assignments. This shows the need for recursive segmentation to capture multiple phases.

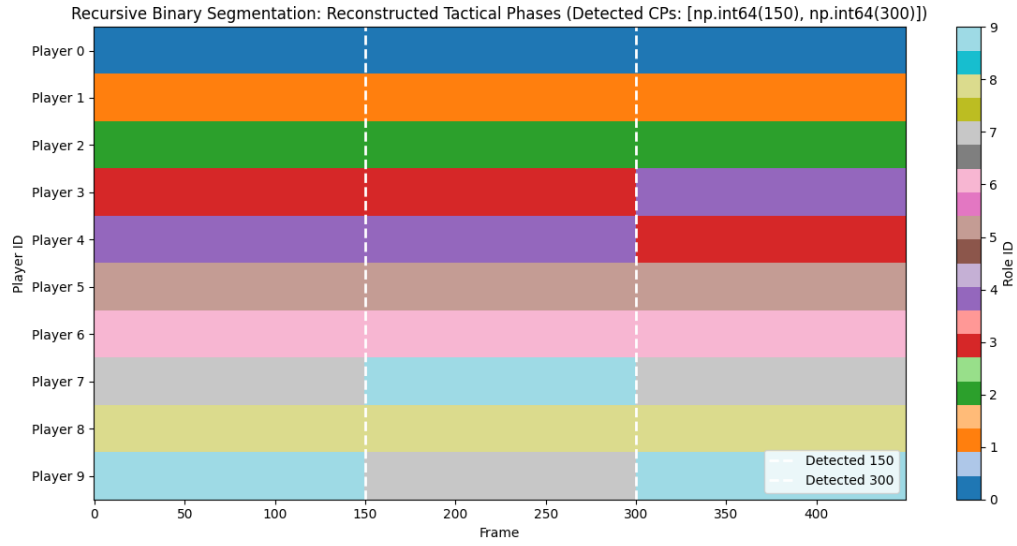


Figure 10: Visualization of all detected tactical phases after recursive binary segmentation, showing accurate recovery of the ground truth phases.