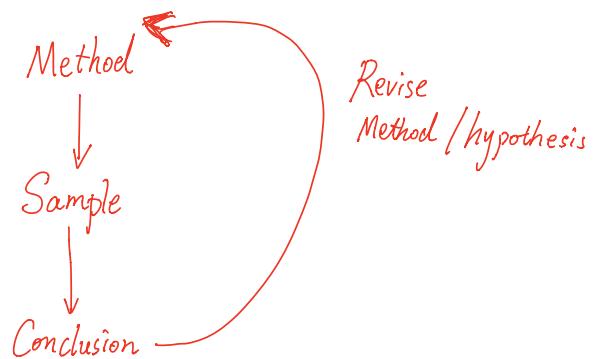


Lecture 23

Adaptive Data Analysis.



Logistics:

Project Presentation (May 3 & 5)

Schedule announced this week

20 mins.

No more HW.

Model for Adaptive Data Analysis

Statistical / Linear Queries

$$\phi: \mathcal{X} \rightarrow [0,1] \quad \text{"predicate"}$$

$$q_\phi(p) = \underset{\substack{\uparrow \\ \text{population}}}{\mathbb{E}} [\phi(x)] \quad \text{"Population value"}$$

$$q_\phi(D) = \underset{\substack{\wedge \\ d_i \in D}}{\mathbb{E}} [\phi(d_i)] = \frac{1}{n} \sum_{i=1}^n [\phi(d_i)] \quad \text{"Empirical Average"}$$

$$D = (d_1, \dots, d_n) \in \mathcal{X}^n$$

Example: mean, correlation, variance, error/risk, gradient

Extension:

① Low-Sensitive Queries

$$\forall \text{ neighbors } D \& D', \quad |f(D) - f(D')| \leq \Delta$$

② Minimization Queries

Query is given by some loss function $L: \mathcal{X}^n \times \Theta \rightarrow [0,1]$

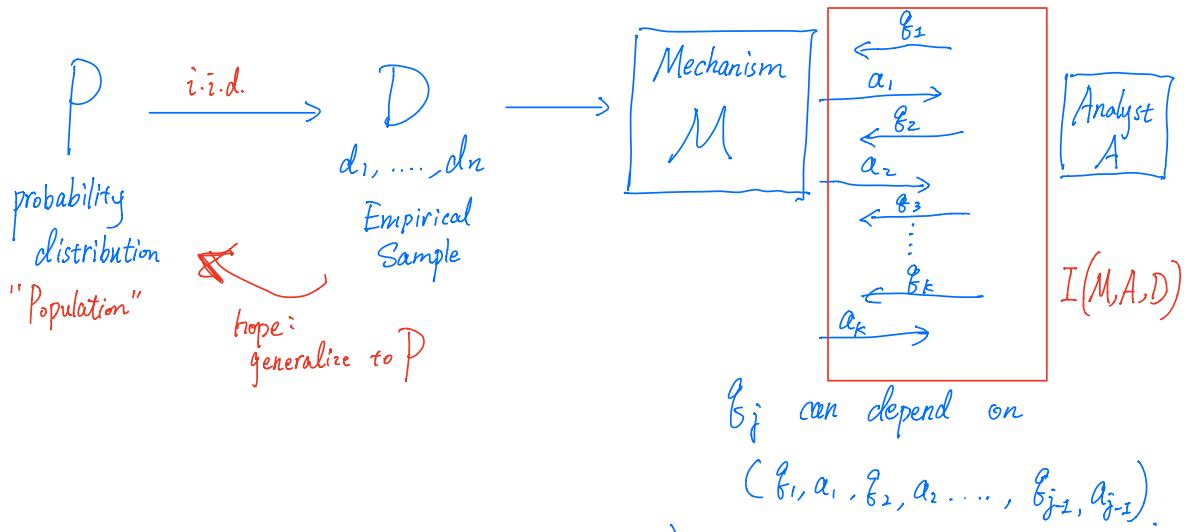
Answer $\theta \in \Theta$

\uparrow Dataset \sqsubset Parameter Space.

$$\forall \text{ neighbors } D \& D' \quad |L(D, \theta) - L(D', \theta)| \leq \Delta.$$

$$\forall \theta \in \Theta$$

Interaction of Adaptive Data Analysis.



Transcript $\bar{T} = (\langle f_1, a_1 \rangle, \dots, \langle f_k, a_k \rangle) \leftarrow I(M, A, D)$

"Goal" : $\forall j, \quad$

$$|a_j - g_j(P)| \leq \text{small.}$$

↑ Population Value.

Not just empirical averages

Avoid : queries g s.t.

$$|g(P) - g(D)| \geq \text{Large}$$

D is not representative.

DP \implies Generalization in ADA

(α, β) - sample accuracy

$$\mathbb{P}_{D \sim P^n, T} \left[\max_j |g_j(D) - a_j| \geq \alpha \right] \leq \beta$$

(α, β) - distributional accuracy

$$\mathbb{P}_{D \sim P^n, T} \left[\max_j |g_j(P) - a_j| \geq \alpha \right] \leq \beta$$

Sample Complexity / Accuracy.

Non-adaptive Queries.

- Take empirical averages: $\alpha_j = \hat{f}_j(D)$

$$\max_j |\alpha_j - f_j(P)| \lesssim \sqrt{\frac{\log(k)}{n}}$$

Adaptive Queries

- Sample Splitting Method: $D_1, \dots, D_k, \alpha_j = g_j(D_j)$

$$\max_j |\alpha_j - g_j(P)| \leq \sqrt{\frac{k}{n}}$$

- Differential Privacy, Gaussian Mechanism

$$\alpha_j = \hat{f}_j(D) + N(0, \sigma^2).$$

$$\max_j |\alpha_j - \hat{f}_j(P)| \leq \underbrace{\frac{k^{1/4}}{\sqrt{n}}}_{\mathcal{O}(\alpha + \epsilon)}$$

Adding Noise Reduces Error.

$$\frac{\sqrt{k}}{n\beta} + \delta$$

ϵ $\xrightarrow{\text{privacy/gen}} \text{Bound}$ δ $\xrightarrow{\text{sample accuracy bound}}$

Transfer Theorem . (ϵ, δ) -version [JLN RSS 20]

Suppose $I(M, A, D)$ is (α, β) -sample accurate \leftarrow
 $\& (\epsilon, \delta)$ -DP. \leftarrow

Then for every $c, d > 0$, $I(M, A, D)$ is (α', β') \leftarrow
 distributionally accurate, for

$$\alpha' = \alpha + (e^\epsilon - 1) + c + 2d, \quad \beta' = \frac{\beta}{c} + \frac{\delta}{d}$$

$\approx \epsilon$ α ϵ

$$\alpha' = O(\alpha + \epsilon) \quad \beta' = \left(\frac{\beta}{\alpha} + \frac{\delta}{\epsilon} \right)$$

Simpler version $(\epsilon, 0)$ -DP

(α, β) - sample accuracy

$(\epsilon, 0)$ - DP.

$\Rightarrow (\alpha', \beta')$ - distributionally accurate.

$$\alpha' = \alpha + (e^\epsilon - 1) + \sqrt{\frac{2 \ln(1/\eta)}{n}}, \quad \beta' = \beta + \eta, \text{ for all } \eta > 0.$$

$$\approx \alpha + \epsilon + \tilde{O}\left(\frac{1}{\sqrt{n}}\right)$$

\tilde{O} Sampling error bound

Proof Sketch.

$$D \xleftarrow{i.i.d.} P^n$$

Transcript: $\pi = (f_1, a_1, \dots, f_k, a_k) \leftarrow I(M, A, D)$

$$Q_\pi = P^n | \pi$$

"Posterior distribution over D conditioned on π "

- Suppose M is (α, β) -sample accurate.

$$\underbrace{P\left[\max_j |a_j - f_j(D)| \geq \alpha\right]}_{\text{Event } E \text{ about } (D, \pi)} \leq \beta$$

Lemma (Bayesian Resampling)

$$\underset{\substack{D \sim P^n \\ \pi \leftarrow I(M, A, D)}}{P}\left[(D, \pi) \in E\right] = \underset{\substack{D \sim P^n \\ \pi \sim I(M, A, D) \\ D' \sim Q_\pi}}{P}\left[(D', \pi) \in E\right]$$

- Generic: Nothing to do w/ DP.
- Sample accuracy w.r.t. D
 \Rightarrow Sample accuracy w.r.t. $D' \sim Q_\pi$
- $f(D) \approx f(Q_\pi) = \underset{D' \sim Q_\pi}{E}[f(D')]$
- Goal: $\underset{\alpha}{f(D)} \approx \underset{\alpha}{f(P)}$ ↪
 Missing Step: $f(Q_\pi) \approx f(P)$

Do you want to see the proof?

Bayesian Resampling
Lemma

Proof. $\mathbb{P}_{\substack{D \sim P^n \\ \pi \leftarrow I(M, A, D) \\ D' \sim Q_\pi}} \left[(D', \pi) \in E \right]$

$$\begin{aligned}
 &= \sum_{D=x} \sum_{\pi=\pi} \sum_{D'=x'} \mathbb{1}[(x', \pi) \in E] \cdot \mathbb{P}[D=x] \cdot \mathbb{P}[\pi|x] \cdot \mathbb{P}[x'|x] \\
 &= \sum_{D=x} \sum_{\pi=\pi} \sum_{D'=x'} \mathbb{1}[(x', \pi) \in E] \cdot \mathbb{P}[D=x, \pi=\pi] \mathbb{P}[D'=x' | \pi=\pi] \\
 &\quad \text{D}' \sim P^n \\
 &= \sum_{\pi=\pi} \sum_{D'=x'} \mathbb{1}[(x', \pi) \in E] \cdot \mathbb{P}[\pi=\pi] \cdot \mathbb{P}[D'=x' | \pi=\pi] \\
 &\quad \text{D}' \sim P^n \\
 &\quad \pi \leftarrow I(M, A, D) \\
 &= \sum_{\pi=\pi} \sum_{D'=x'} \mathbb{1}[(x', \pi) \in E] \cdot \mathbb{P}[\pi=\pi] \cdot \mathbb{P}[D'=x' | \pi=\pi] \\
 &\quad \text{D}' \sim P^n \\
 &\quad \pi \leftarrow I \\
 &= \mathbb{P}_{\substack{\pi \leftarrow I \\ D' \sim P^n}} \left[(D, \pi) \in E \right]
 \end{aligned}$$

Differential Privacy $\Rightarrow f(Q_\pi) \approx f(P)$

Proof (Sketch).

$$\begin{aligned}
f(Q_\pi) &= \underset{D' \sim Q_\pi}{\mathbb{E}} [f(D')] \\
&= \underset{\substack{D' \sim Q_\pi \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{E}} [f(d'_i)] = \underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{E}} [f(d_i)] \quad \text{Conditionally} \\
&= \int_{x \in X} f(x) \cdot \underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[d_i = x \mid \pi]} \quad \text{Bayes Rule} \\
&= \int_{x \in X} f(x) \cdot \frac{\underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[\pi \mid d_i = x]} \cdot \underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[d_i = x]}}{\underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[\pi]}} \quad \text{Approximate Cancellation?} \\
&\leq \int_{x \in X} f(x) \cdot \frac{e^\epsilon \underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[\pi]} \cdot \underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[d_i = x]}}{\underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[\pi]}} \quad \pi \leftarrow I(M, A, D) \\
&= e^\epsilon \int_{x \in X} f(x) \cdot \underset{\substack{D \sim P^n \\ i \leftarrow \text{unif}\{1, \dots, n\}}}{\mathbb{P}[d_i = x]} = f(P).
\end{aligned}$$

$$f(Q_\pi) \lesssim e^\epsilon f(P)$$

$$f(Q_\pi) \geq e^{-\epsilon} f(P).$$

Putting Together

- $f(Q_n) \in [e^{-\varepsilon} f(P), e^{\varepsilon} f(P)]$

Due to (ε, δ) -DP.

- " $f(D) \approx f(Q_n)$ "

$$\underset{\substack{D \leftarrow P^n \\ x \leftarrow I}}{P} \left[|f(Q_n) - f(D)| \geq C_\eta \right] = \underset{\substack{D \leftarrow P^n \\ x \leftarrow I \\ D' \leftarrow Q_n}}{P} \left[|f(Q_n) - f(D')| \geq C_\eta \right] \leq \eta$$

$C_\eta = \sqrt{\frac{2 \ln(\eta)}{n}}$

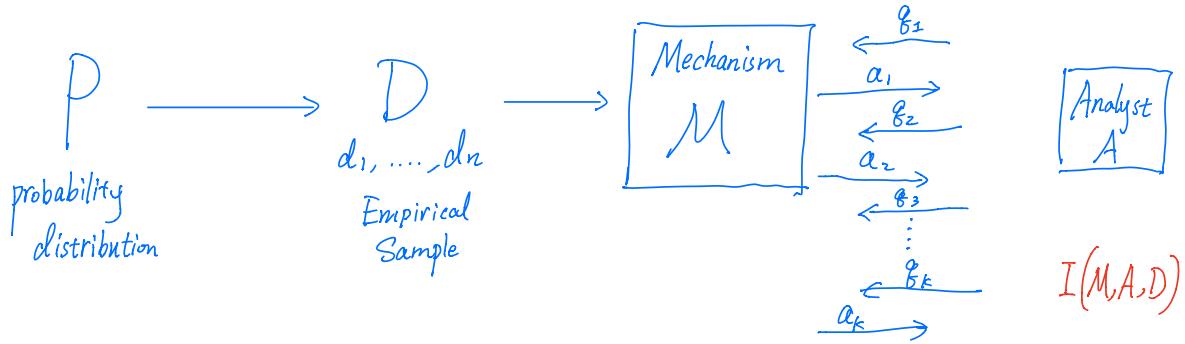
Azuma
Ineq.

- Sample accuracy, w.p. $1-\beta$.

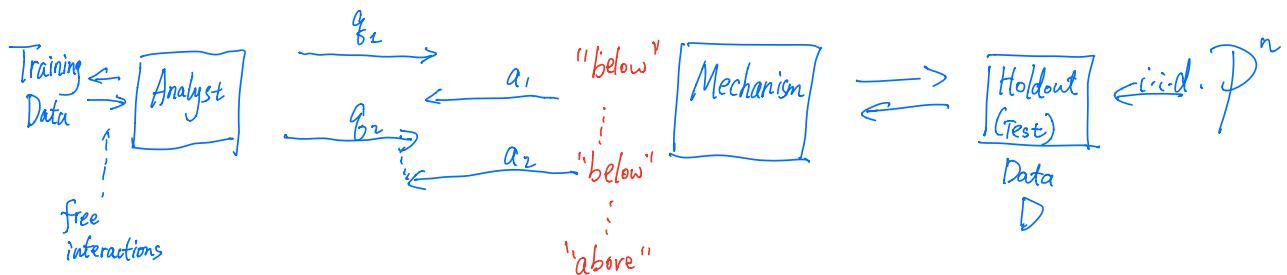
$$|\alpha - f(D)| \leq \delta \quad \text{for all queries. } f = f_j.$$

Add 3 sources of error \square

Mental Model of ADA.



θ_j can depend on
 $(\theta_1, a_1, \theta_2, a_2, \dots, \theta_{j-1}, a_{j-1})$.



Example : $f_1(D) = \frac{1}{n} \sum_{i=1}^n \left[\mathbb{I}[h(x_i) = y_i] \right]$

\uparrow
 error
 accuracy

Reusable Holdout.

Sparse Vector or Thresholdout

Dwork et al.
Science '2016

Algorithm 2: SparseVector($\mathbf{s}, T, \Delta, \epsilon, q_1, q_2, \dots$):

Input: q_1, q_2, \dots is a stream of Δ -sensitive queries

1 **AllDone** $\leftarrow \text{FALSE}$; \tilde{T} : threshold Stop when
2 $\tilde{T} = T + Z_0$ where $Z_0 \sim \text{Lap}(2\Delta/\epsilon)$; $g(\mathbf{s})$ is above T .
3 **while** not **AllDone** **do**
4 Accept the next query q_i ;
5 $a_i \leftarrow q_i(\mathbf{s})$;
6 $\tilde{a}_i \leftarrow a_i + Z_i$ where $Z_i \sim \text{Lap}(4\Delta/\epsilon)$;
7 **if** $\tilde{a}_i < \tilde{T}$ **then**
8 **return** $b_j = \perp$;
9 **else**
10 **return** $b_j = \top$;
11 **AllDone** $\leftarrow \text{TRUE}$;

- Only Noise T once.
- Could release " \perp " many times.