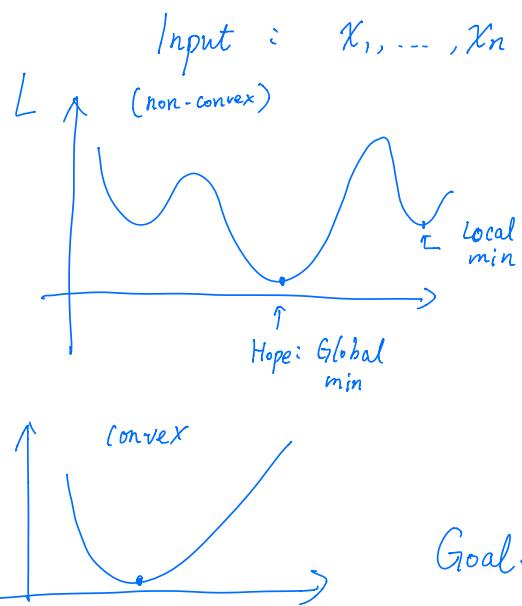


Private Gradient Descent

- Recap: Private ERM Problem
Exponential Mechanism
 - (Projected) Gradient Descent
Privacy , Convergence
-

HW2 Due on Weds

Formulation.



feasible set of models/parameters

$$\ell: C \times X \rightarrow \mathbb{R}$$

$\ell(w, x)$ measures "loss"

$$L: C \rightarrow \mathbb{R}$$

$$L(w) = \frac{1}{n} \sum_{i=1}^n \ell(w, x_i)$$

$$\Pi_C(w) = \arg \min_{w' \in C} \|w - w'\|_2$$

"Projection"

Goal: output \hat{w} s.t.

$$L(\hat{w}) \approx \min_{w \in C} L(w)$$

Projected Gradient Descent (PGD)

PGD (L, C, η) :

→ Init: $w_0 \in C$ arbitrary

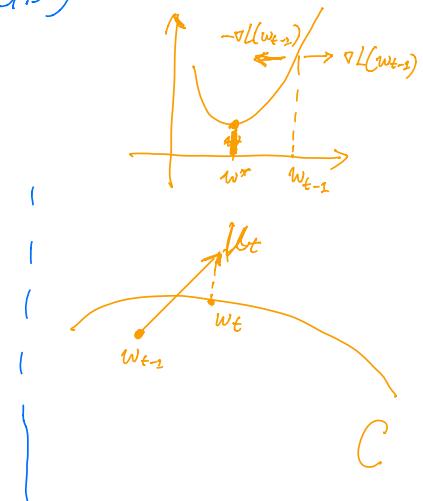
For $t = 1, \dots, T$:

$$g_t = \nabla L(w_{t-1}) \leftarrow \text{Gradient}$$

$$u_t \leftarrow w_{t-1} - \eta \cdot g_t$$

$$w_t \leftarrow \Pi_C(u_t).$$

→ Output $\hat{w} = \frac{1}{T} \sum_{t=1}^T w_t$



Robustness to noise in gradient estimation. (\hat{g}_t)

$$\rightarrow \text{For privacy: } \hat{g}_t = g_t + \underbrace{N(0, \delta^2 I_d)}_{\substack{\text{d-dim} \\ \text{i.i.d. Gaussian}}}$$

$$\mathbb{E}[\hat{g}_t] = g_t = \nabla L(w_{t-1})$$

$$\rightarrow \text{For efficiency: } \hat{g}_t = \nabla L(w_{t-1}, X_{I_t}), \quad I_t \leftarrow \text{unif}\{1, \dots, n\}$$

$$\mathbb{E}[\hat{g}_t] = g_t = \nabla L(w_{t-1})$$

"Unbiased"

Noisy/Private PGD (outputs $\hat{w} = \frac{1}{T} \sum_{t=1}^T w_t$).

- Proof idea for privacy: think of releasing w_1, \dots, w_T

Suffices to release $w_0 \xleftarrow{\text{diff}} w_1 \xrightarrow{\text{diff}} w_2 \dots$

Suffices to release $\underbrace{\tilde{g}_1, \tilde{g}_2, \dots, \tilde{g}_T}_{\text{Adaptive Composition of Gaussian Mechanism.}}$

Adaptive Composition of Gaussian Mechanism.

Lemma. If ℓ is G -Lipschitz for every x . ($\|\nabla \ell(w; x)\| \leq G$) on C ,
 $(|\ell(w, x) - \ell(w', x)| \leq G \|w - w'\|)$.

then Noisy PGD is (ϵ, δ) -DP when $\left[\delta \geq \frac{2G}{n} \cdot \frac{\sqrt{2T \ln(1/\delta)}}{\epsilon} \right]$.

Proof Ideas:

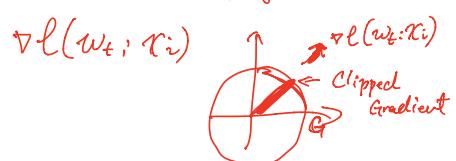
① Overall ℓ_2 -sensitivity of all T gradients: $\frac{2G}{n} \cdot \sqrt{T}$

$$\nabla L(w_t) = \frac{1}{n} \sum_{i=1}^n \nabla \ell(w_t; x_i)$$

② Apply Advanced Composition to T adaptive Gaussian Mech

Better techniques = $\begin{cases} \text{Renyi DP accountant} & (\text{Tensorflow}) \\ \text{Gaussian DP} & \text{---} \\ (\text{zero}) - \text{Concentrated DP} & \text{---} \end{cases}$

NB: Enforce low sensitivity by "Gradient Clipping" on



Private SGD.

Private SGD (L, C, η) :

→ Init: $w_0 \in C$ arbitrary

Also Subsampling
a minibatch → For $t = 1, \dots, T$:
 $I_t \leftarrow \text{unif}(\{1, \dots, n\})$; $g_t = \nabla \ell(w_{t-1}; X_{I_t})$
 $\tilde{g}_t = g_t + N(0, \delta^2 \text{Id})$

$$u_t \leftarrow w_{t-1} - \eta \cdot \tilde{g}_t$$

$$w_t \leftarrow \Pi_C(u_t)$$

$$\rightarrow \text{Output } \hat{w} = \frac{1}{T} \sum_{t=1}^T w_t$$

SG Langevin
Dynamics.

How to analyze Privacy?

SGD+ Gaussian
Noise.

Privacy Amplification

- Keep I_t secret
- Use their randomness.

In general: $A: \mathcal{X} \mapsto \mathcal{Y}$ is (ϵ, δ) -DP.
 $\underset{\mathcal{X}}{\text{take one data point}}$

- Consider: $A': \mathcal{X}^n \mapsto \mathcal{Y}$
 - $I \leftarrow \text{unif}(\{1, \dots, n\})$
 - Return $A(X_I)$
- A' is (ϵ', δ') -DP where
 $\epsilon' = \ln\left(1 + \frac{e^\epsilon - 1}{n}\right) \approx \frac{\epsilon}{n}$ for $\epsilon \leq 1$
 $\delta' = \frac{\delta}{n}$

Can generalize to subsample of size $\boxed{m \leq n}$.

$$\epsilon' \approx \frac{m}{n} \epsilon$$

$$\delta' \approx \frac{m}{n} \delta.$$

- Adding Gaussian noise w/ $\beta = \frac{2G}{\epsilon} \sqrt{2\ln(1/\delta)}$ is (ϵ, δ) -DP.

$$\underline{\left[\nabla l(w_{t+1}; x) + N(0, \beta^2 I) \right]}$$

- Subsampling + Gaussian is (ϵ', δ') -DP

$$\underline{\epsilon' = \frac{\epsilon}{n}, \quad \delta' = \frac{\delta}{n}.}$$

- Advanced Composition over T iterations.

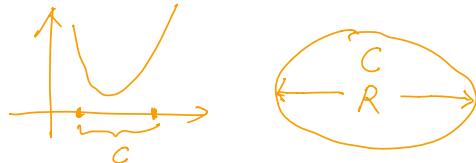
$$\left(\frac{\epsilon \sqrt{T}}{n}, \quad \frac{\delta \cdot T}{n} \right) - \text{DP}$$

(ignoring constants).

Set δ to be smaller than
 $\frac{1}{n}$.
 Can $\delta = \frac{1}{n^5}$

Can Run $T = n^2$ iterations!

Convergence / Optimality.



Theorem. Let $L: C \rightarrow \mathbb{R}$ be convex and G -Lipschitz
 $C \subseteq \mathbb{R}^d$ be a closed and convex set

(Part a)



$$w^* \in \arg \min_{w \in C} L(w)$$

with diameter R

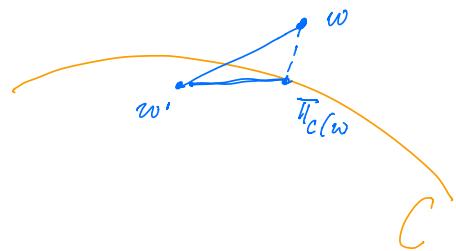
- For regular PGD, set $\eta = \frac{R}{G\sqrt{T}}$, then $\underbrace{L(\hat{w}) - L(w^*)}_{\downarrow_0} \leq \frac{RG}{\sqrt{T}}$
- For noisy PGD, set η, T, δ^2 so that, $\mathbb{E}[L(\hat{w}) - L(w^*)] \leq O\left(\frac{RG\sqrt{nd} \ln(1/\delta)}{n\epsilon}\right)$
 "Cost of privacy" Gap: $\frac{\sqrt{d}}{n\epsilon}$ ← "tight" in the worst-case
 Gap for EM: $\frac{d}{n\epsilon}$

Projection Lemma

Lemma If $C \subseteq \mathbb{R}^d$ is closed and convex.

Then for any $w \in \mathbb{R}^d$, $w' \in C$

$$\| \pi_C(w) - w' \| \leq \| w - w' \|$$



Proof (for regular PGD).

$$w^* = \underset{w \in C}{\operatorname{argmin}} L(w)$$

Claim. (Measure of Progress).

$$\underbrace{L(w_t) - L(w^*)}_{\text{Excess Risk}} \leq \frac{\eta \cdot \|g_t\|^2}{2} + \frac{1}{2\eta} \left(\|w_t - w^*\|^2 - \|w_{t+1} - w^*\|^2 \right)$$

2 Key Quantities

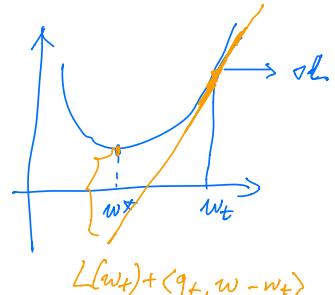
↓ Excess Risk ↓ Distance to w^*

↓ Squared distances.

Proof. $L(w^*) \geq L(w_t) + \langle g_t, w^* - w_t \rangle$

$$L(w_t) - L(w^*) \leq \underbrace{\frac{1}{\eta} \langle \eta g_t, w_t - w^* \rangle}_{\text{Excess Risk}}$$

$$\boxed{\forall a, b \in \mathbb{R}^d \quad \langle a, b \rangle = \frac{1}{2} (\|a\|^2 + \|b\|^2 - \|a-b\|^2)}$$



$$\begin{aligned} L(w_t) - L(w^*) &\leq \frac{1}{2\eta} \left(\|\eta g_t\|^2 + \|w_t - w^*\|^2 - \|w_t - w^* - \eta g_t\|^2 \right) \\ &= \frac{\eta \cdot \|g_t\|^2}{2} + \frac{1}{2\eta} \left(\|w_t - w^*\|^2 - \|w_t - w^*\|^2 \right) \\ &\leq \frac{\eta \cdot \|g_t\|^2}{2} + \frac{1}{2\eta} \left(\|w_t - w^*\|^2 - \|w_{t+1} - w^*\|^2 \right) \quad (\text{Projection}) \end{aligned}$$

Noisy / Private PGD.