



SofameH@CK 1

Overview of the data repository

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November 2018



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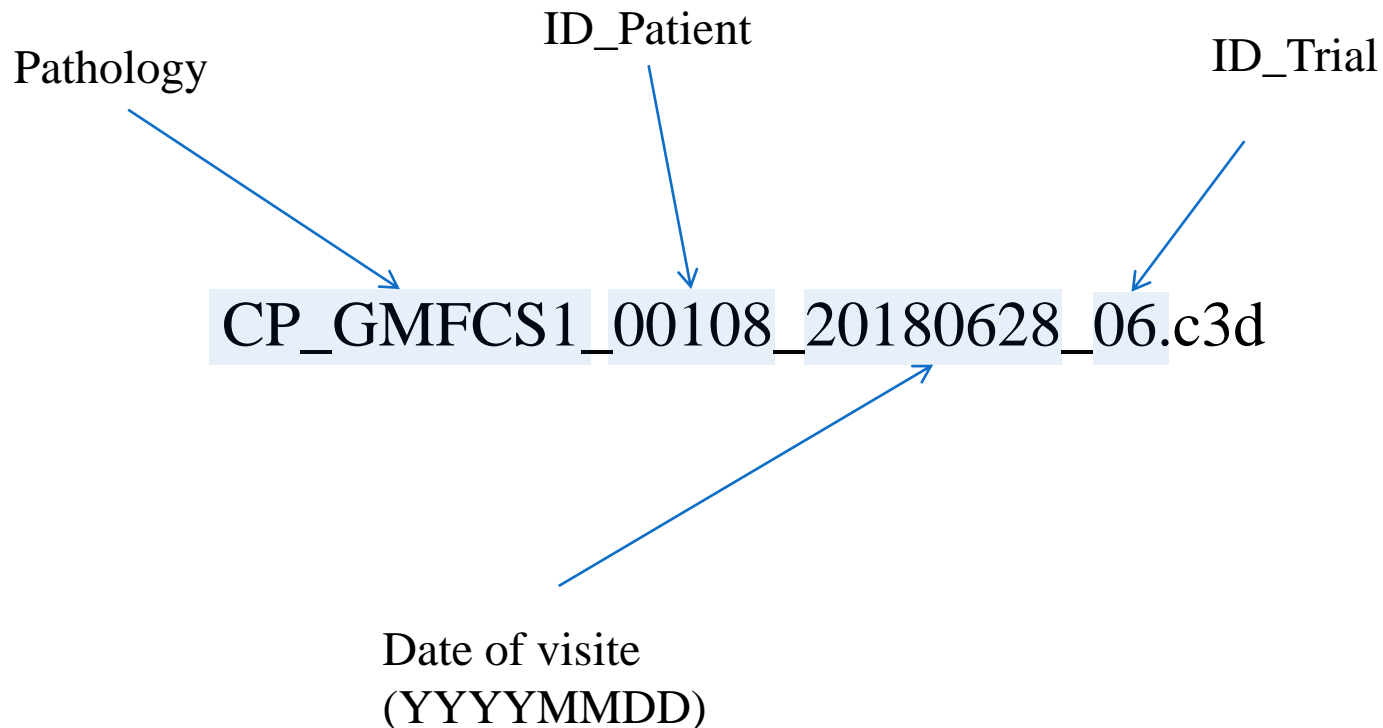


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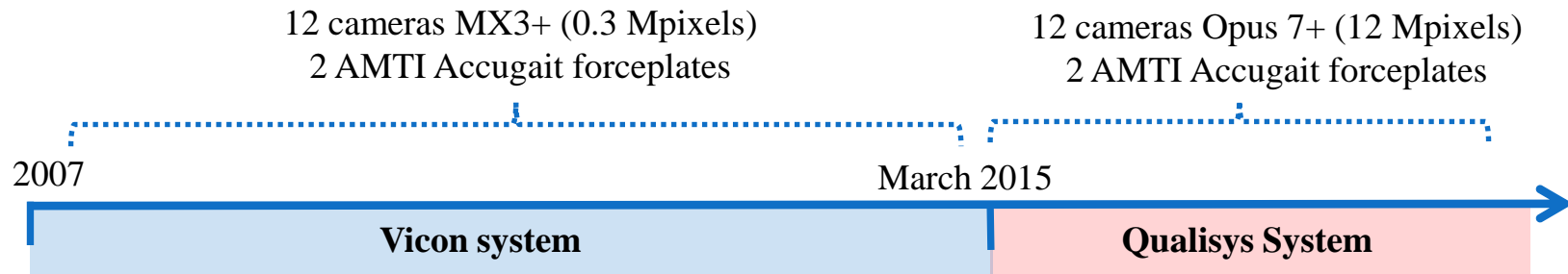


C3D Filename Convention

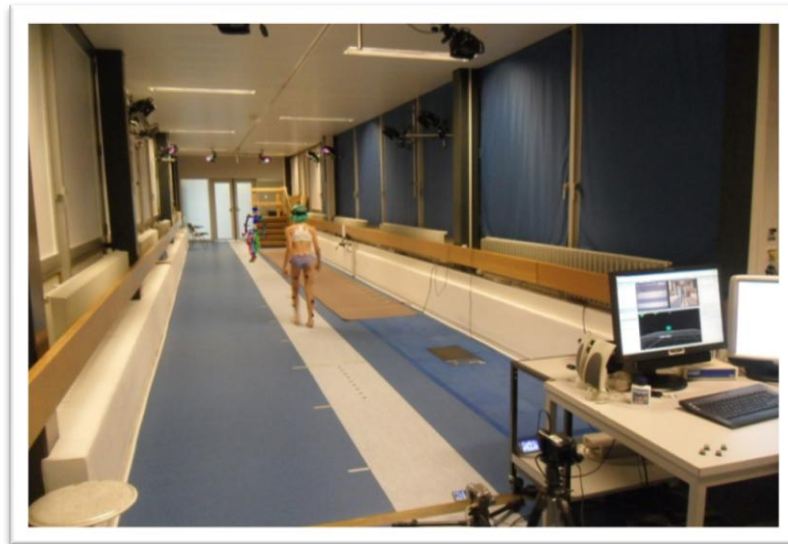




Material and gait conditions



- 10m walkway
- Gait condition:
 - Barefoot
 - Without external help
 - Self-selected speed
- Sample frequency : 100Hz





Overview of the population

	CP GMFCS I	CP GMFCS II	CP GMFCS III	Idiopathic Toe-Walker	Foot Deformity
N	20	20	5	20	23
Age (years)	12.4 (4.0)	15.9 (8.5)	11.4 (4.0)	9.3 (3.0)	19.2 (13.3)
GPS	6.7 (1.7)	9.9 (3.2)	10.4 (1.7)	6.9 (2.1)	5.1 (1.2)

Results are presented as mean (standard deviation)

CP is Cerebral palsy

GMFCS is Gross Motor Function Classification System ¹

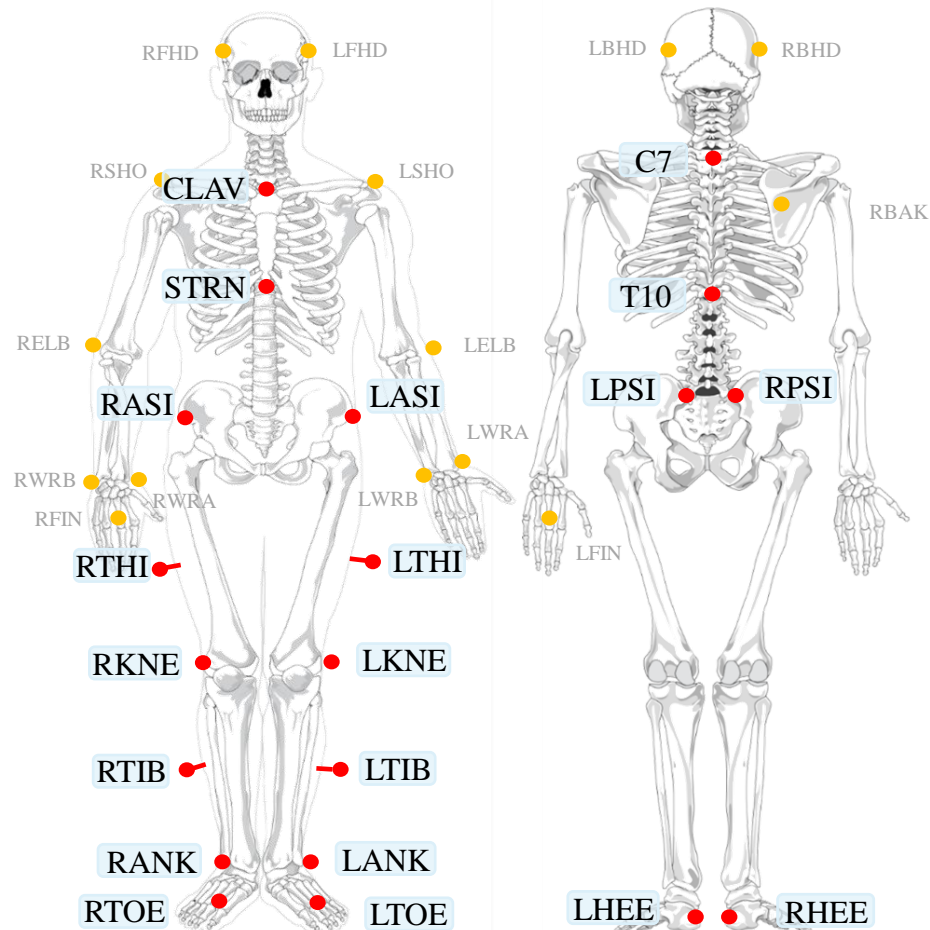
GPS is Gait Profile Score² with mean value of right and left side



Minimal MarkerSet: Lower Limb Conventional Gait Model

Segment	Marker Name	Marker Description
Trunk	C7	Spinal Process of the 7 th cervical vertebra
	T10	Spinal Process of the 10 th thoracic vertebra
	STRN	Processus Xyphoideus
	CLAV	Incisura Jugularis
Pelvis	R/LASI	Right/Left Anterior Superior Iliac Spines
	R/LPSI	Right/Left Posterior Superior Iliac Spines
R/L Thigh	R/LTHI	Right/Left Mid-Thigh Wand
	R/LKNE	Right/Left Lateral Femoral Epicondyle
R/L Shank	R/LTIB	Right/Left Mid-Tibia Wand
	R/LANK	Right/Left Lateral Malleolus
R/L Foot	R/LHEE	R/L Posterior Calcaneus
	R/LTOE	R/L 2 nd Metatarso-Cuneiform Joint

Note: All the C3D file contain this minimal markerset (●) and most files also contains optional markers (●) on the upper limbs & hands (right and left) and four markers on the head.





Event Detection with forceplates: Step 1

Input: Raw vertical Ground Reaction Force

Step 1: 4th order Low-Pass Butterworth (10Hz)

Step 2: Identify Max of GRF

Step 3: Set threshold (10N)

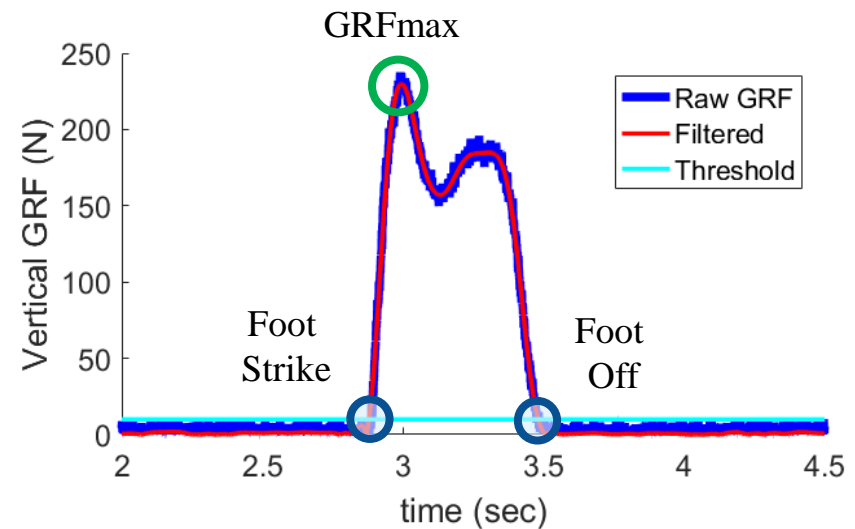
Step 4: Identify events

- **Foot Strike** is the first frame **before** GRFmax that is below the threshold
- **Foot Off** is the first frame **after** GRFmax that is below the threshold

Step 5: Right or Left foot?

- Compute the midpoints of the right and left foot markers.
- Compute dR & dL the distance between the midpoints and the centre of the forceplate
- If $dR > dL$ then the event are associated to the left foot and conversely

Output: Time of Foot Strike and Foot Off associated with Right or Left foot



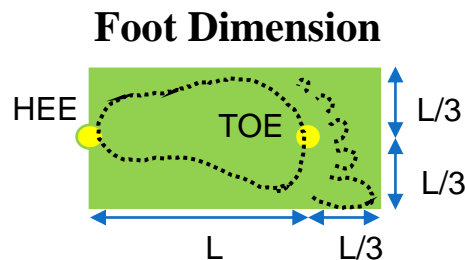


Event Detection with forceplates: Step 2

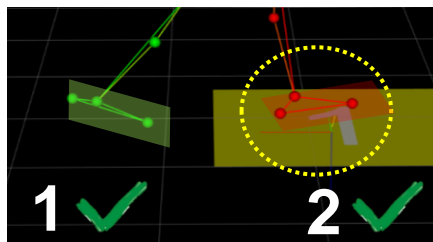
After the identification, two checks need to be done before validation of the event:

1. Is the ipsilateral foot fully on the forceplate?
2. Is the contralateral foot outside of the forceplate?

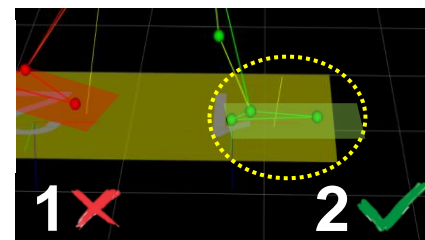
The two markers on the foot are used to define a rectangle representing the foot dimension



Event validated



Event removed: Case 1



Event removed: Case 2

