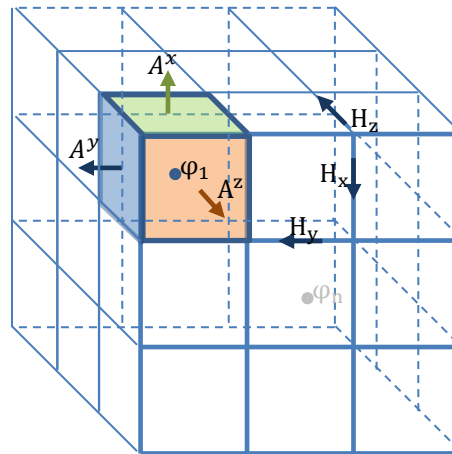


Model Parameters

Cell-center discretization



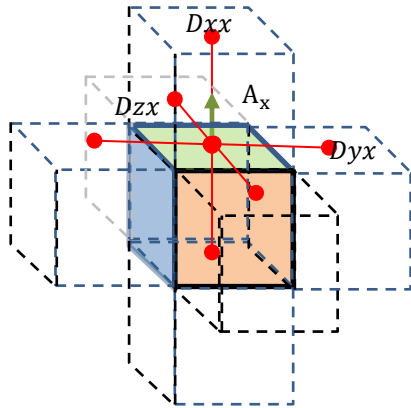
Vector Laplacian

$$\Delta A_x = \frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_x}{\partial y^2} + \frac{\partial^2 A_x}{\partial z^2}$$

$$\frac{\partial^2 A_x}{\partial x^2} = \frac{(A_{n+1}^x - A^x)_{h_{n-1}} - (A^x - A_{n-1}^x)_{h_n}}{h_{mid}}$$

$$\frac{\partial^2 A_x}{\partial y^2} = \frac{(A_{n+1}^x - A^x)_{h_{mid}} - (A^x - A_{n-1}^x)_{h_{mid}}}{h}$$

$$\frac{\partial^2 A_x}{\partial z^2} = \dots$$



In Matlab form...

$$\frac{\partial}{\partial x} = \begin{bmatrix} 1/\sqrt{h_1} & \dots & 0 \\ -1/\sqrt{h_2} & 1/\sqrt{h_2} & \vdots \\ 0 & \dots & -1/\sqrt{h_{end}} \end{bmatrix}$$

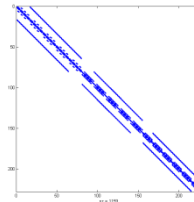
$$\frac{\partial^2}{\partial x^2} = H_{mid} \left(\frac{\partial}{\partial x} \right)^T \frac{\partial}{\partial x}$$

$$\frac{\partial^2 A_x}{\partial x^2} = \text{kron}(\text{kron}(\text{speye}(nz), \text{speye}(ny)), \frac{\partial^2}{\partial x^2})$$

Same idea for the 8 other partial derivatives yielding...

Laplacian Operator

$$L = \begin{bmatrix} \frac{\partial^2 A_x}{\partial x^2} + \frac{\partial^2 A_x}{\partial y^2} + \frac{\partial^2 A_x}{\partial z^2} & 0 & 0 \\ 0 & \frac{\partial^2 A_y}{\partial x^2} + \frac{\partial^2 A_y}{\partial y^2} + \frac{\partial^2 A_y}{\partial z^2} & 0 \\ 0 & 0 & \frac{\partial^2 A_z}{\partial x^2} + \frac{\partial^2 A_z}{\partial y^2} + \frac{\partial^2 A_z}{\partial z^2} \end{bmatrix}$$



Boundary Conditions (Primary Field) x-y polarized

$$\frac{\partial A^x}{\partial x} \text{ and } \frac{\partial A^y}{\partial x} \Big|_{\partial \Omega} = 0$$

$$\frac{\partial A^x}{\partial y} \text{ and } \frac{\partial A^y}{\partial y} \Big|_{\partial \Omega} = 0 \quad \Delta A^z \Big|_{\partial \Omega} = 0$$

$$\frac{\partial A^x}{\partial z} \text{ and } \frac{\partial A^y}{\partial z} \Big|_{\partial \Omega} = g(x, y, z)$$

Defining $g(x, y, z)$ as the 1D problem for the x and y components:

$$A^x(z) = e^{i\sqrt{i\omega\mu\sigma}z}$$

