

	1	2	3	4	5	
A		Sheet: Output Display File: Output Display.sch	Sheet: Register XY File: Register XY.sch Sheet: Program Counter	Sheet: Speed Control File: Speed Control.sch Sheet: Clock		A
B		Sheet: Instruction RAM File: Instruction RAM.sch Sheet: Data RAM	File: Program Counter.sch Sheet: PC/IF	File: Clock.sch Sheet: Power-on Reset		B
C		File: Data RAM.sch Sheet: Serial	File: PC_IF.sch Sheet: Instruction ROM	File: Power-on Reset.sch Sheet: Register A		C
D		File: Serial.sch Sheet: Register D	File: Instruction ROM.sch Sheet: Instruction Register	File: Register A.sch Sheet: Register B		D
	1	2	3	4	5	

TTL microcomputer built from 74xx series logic chips.

Sheet: /
File: TurtleTTL.sch

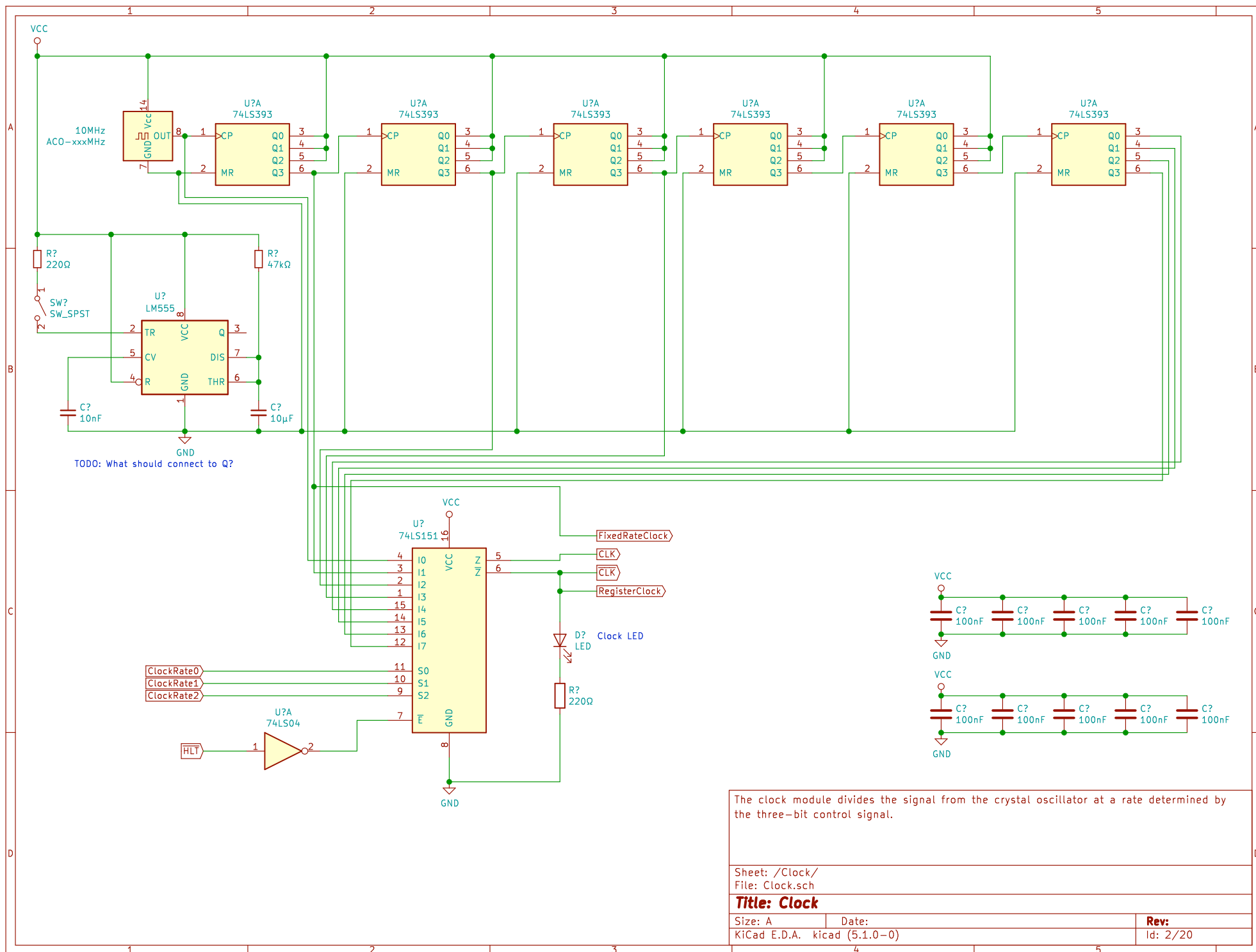
Title: Turtle TTL

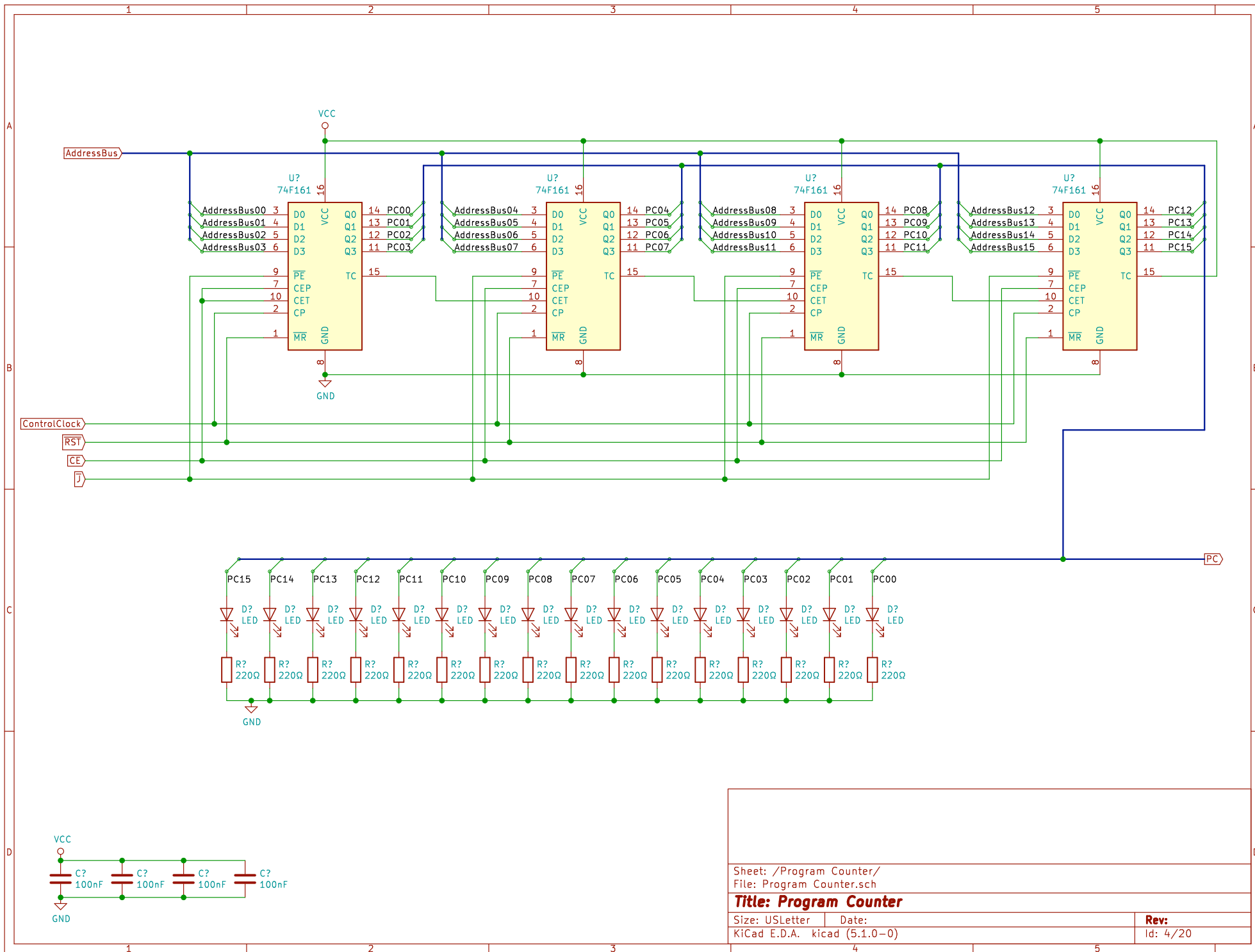
Size: A

Date:

KiCad E.D.A. kicad (5.1.0-0)

Rev:
Id: 1/20



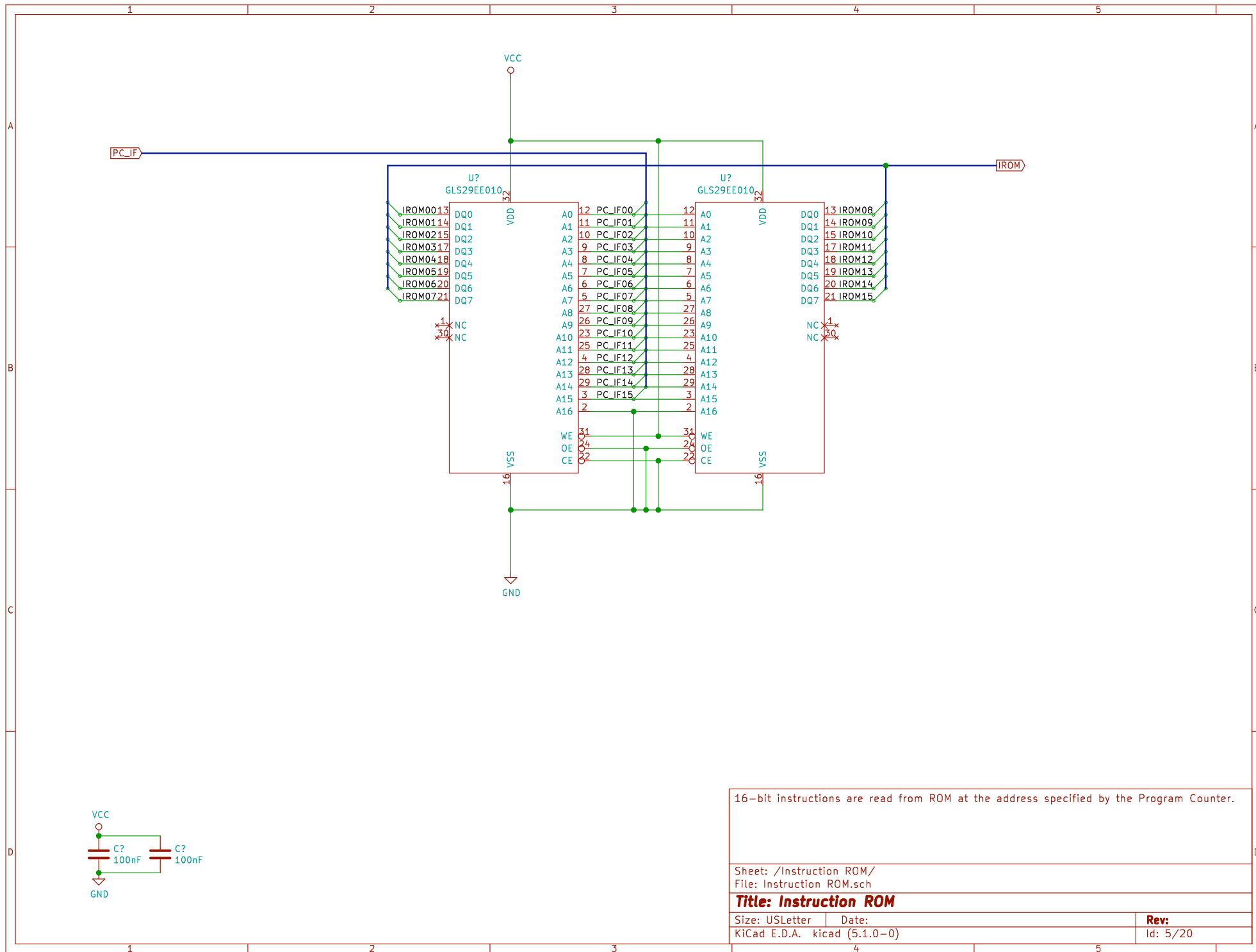


Sheet: /Program Counter/
File: Program Counter.sch

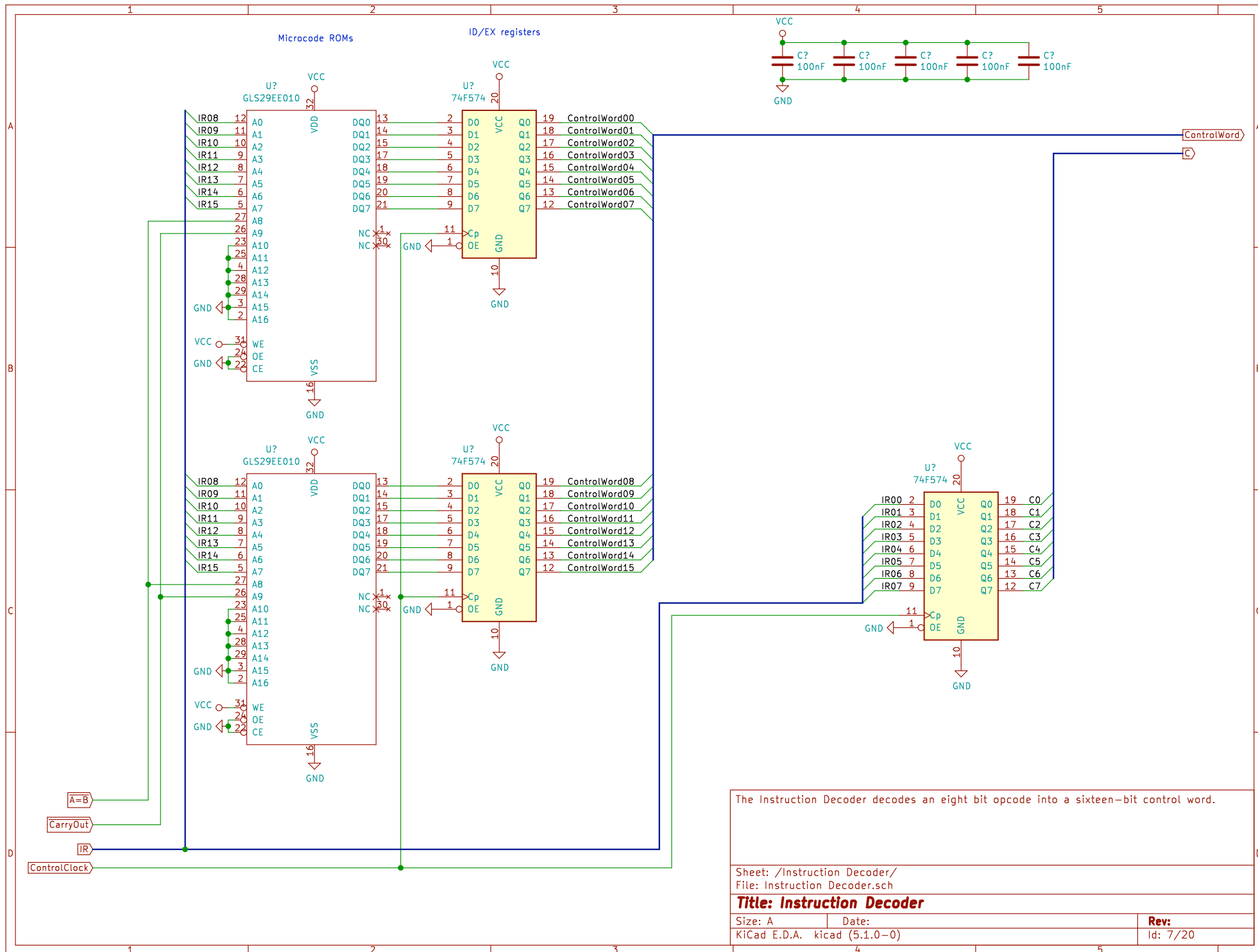
Title: Program Counter

Size: USLetter Date:
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Rev:
Id: 4/20



[illegible]

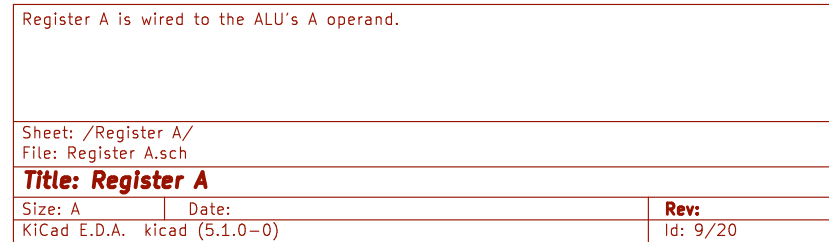


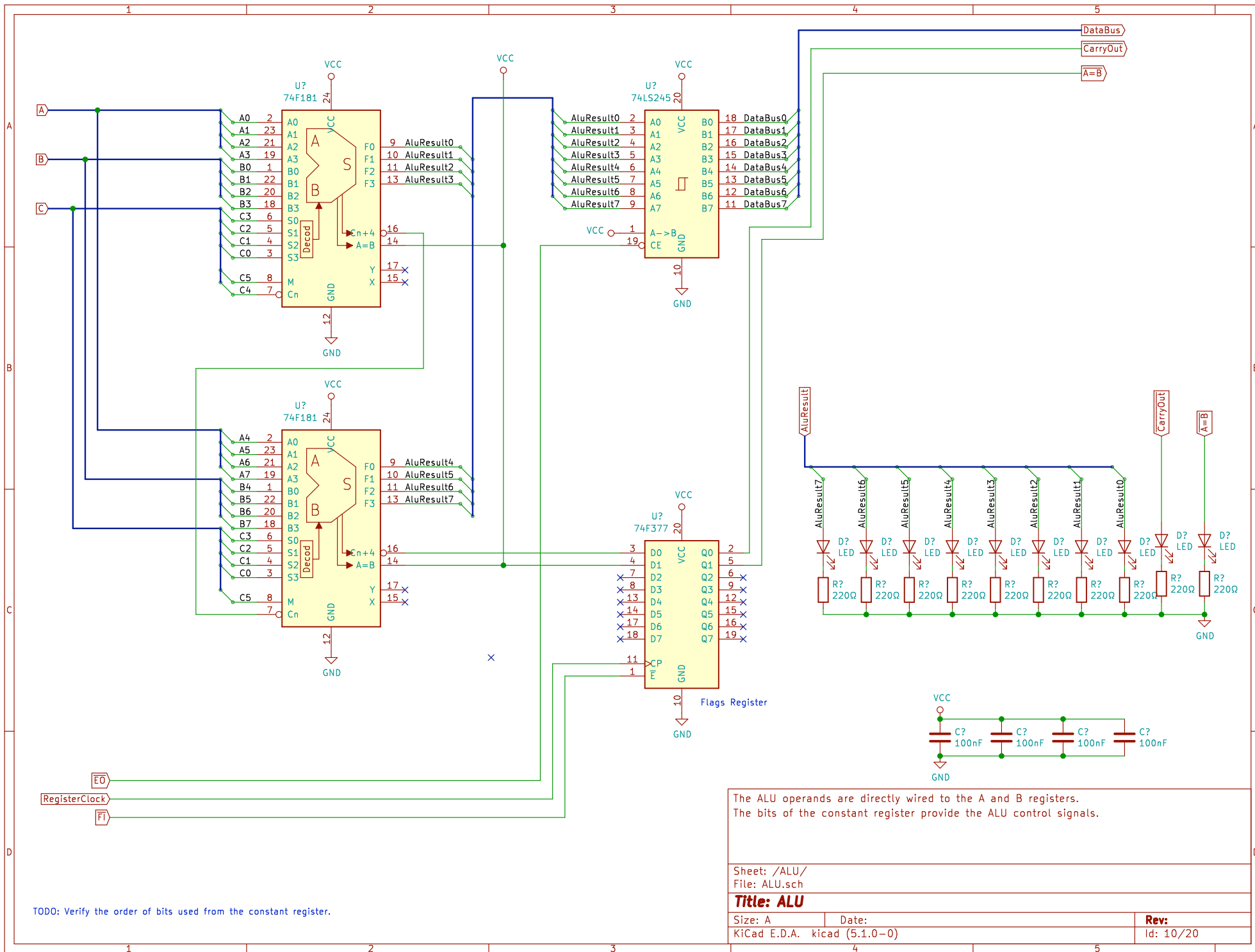
The Instruction Decoder decodes an eight bit opcode into a sixteen-bit control word.

Sheet: /Instruction Decoder/
File: Instruction Decoder.sch

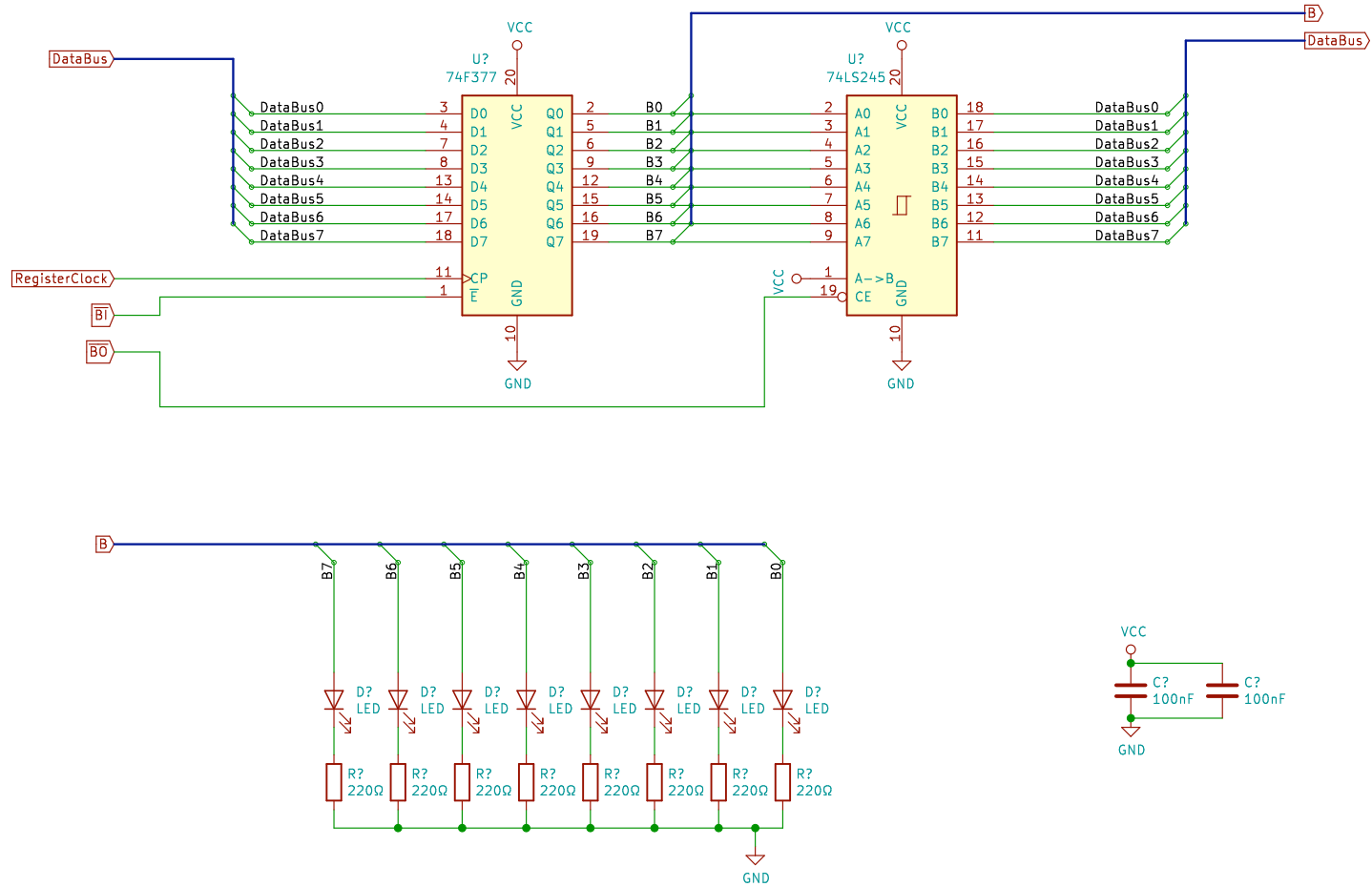
Title: Instruction Decoder

Size: A	Date:	Rev:
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TODO: Verify the order of bits used from the constant register.



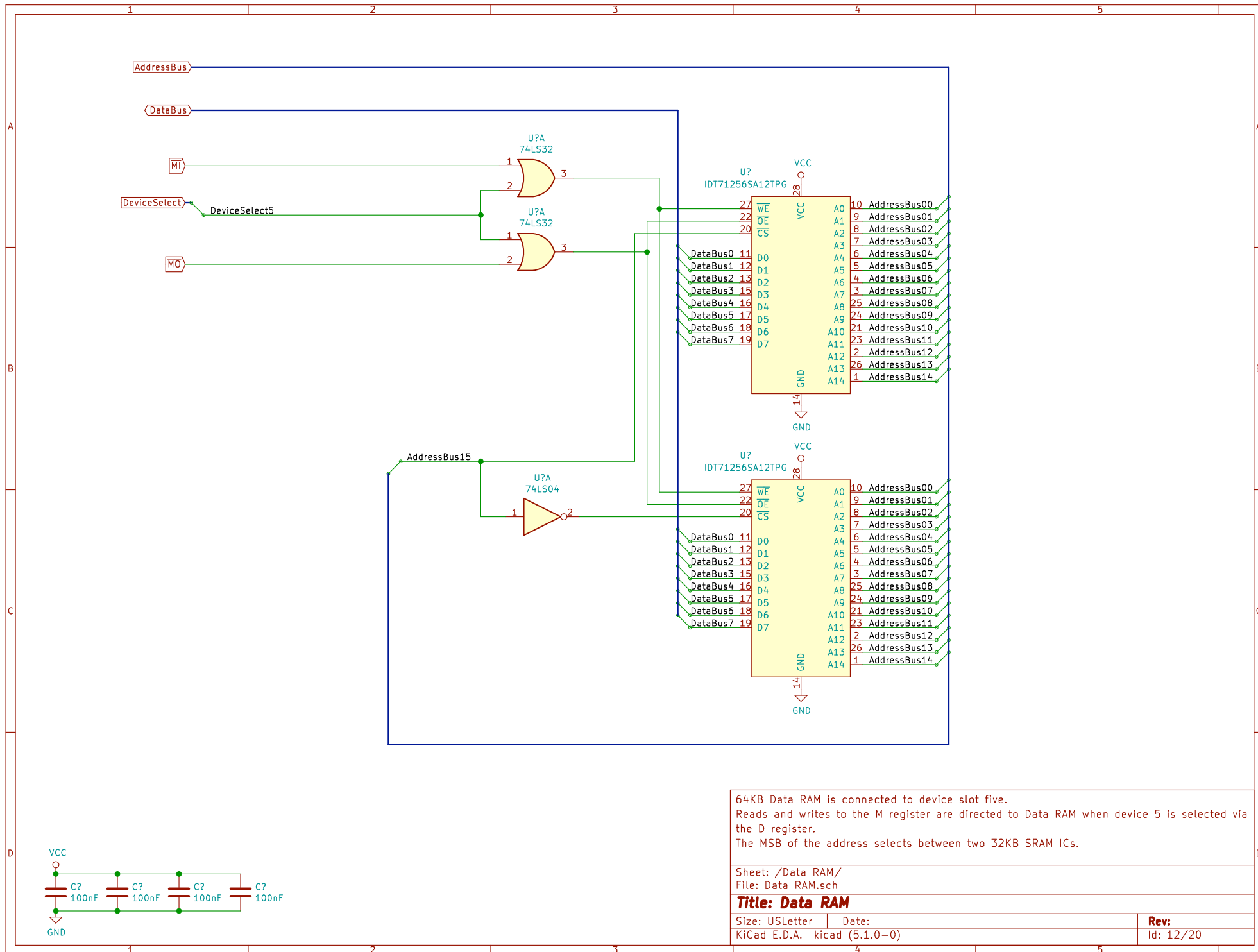
Register B is wired to the ALU's B operand.

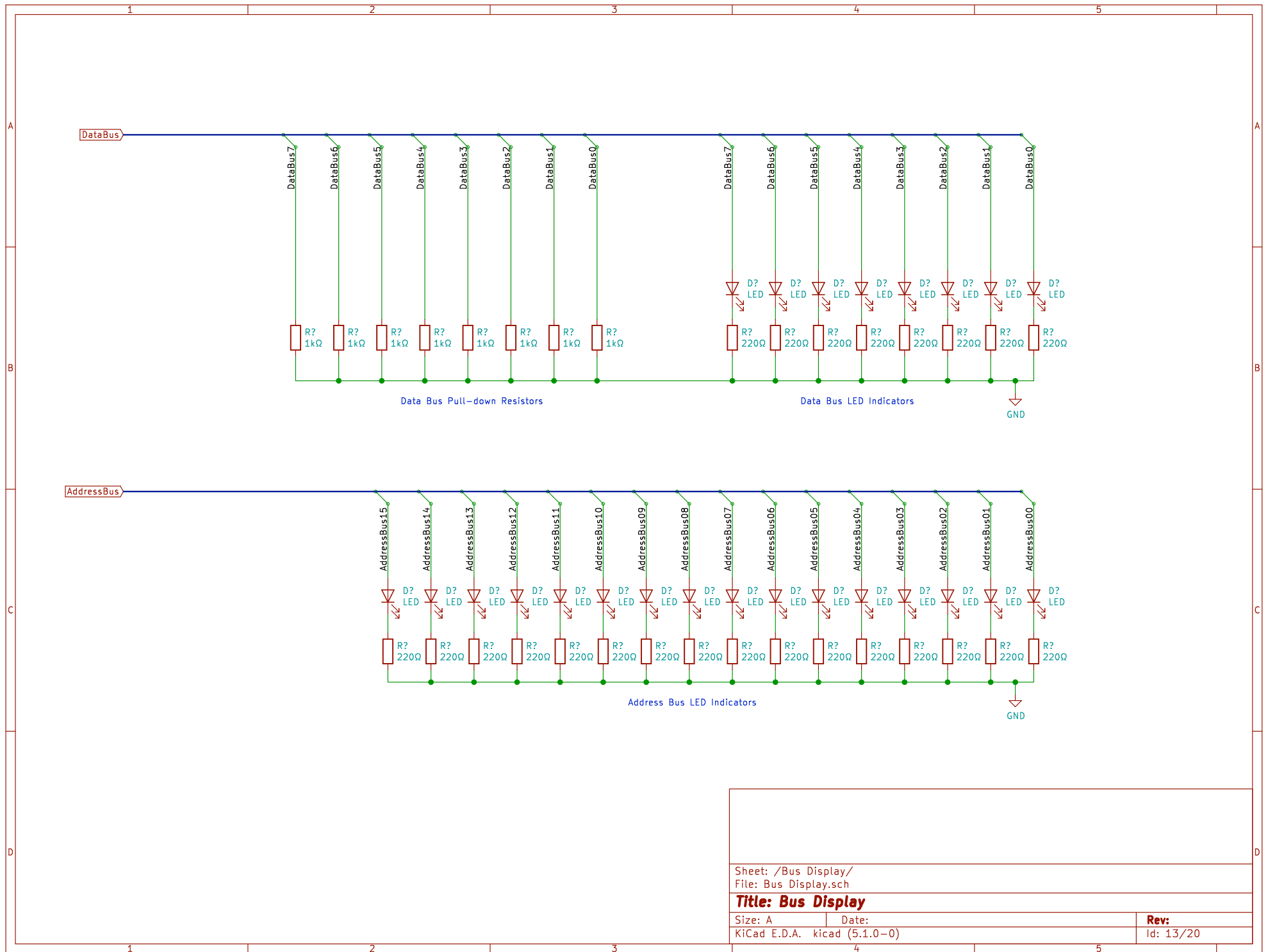
Sheet: /Register B/
File: Register B.sch

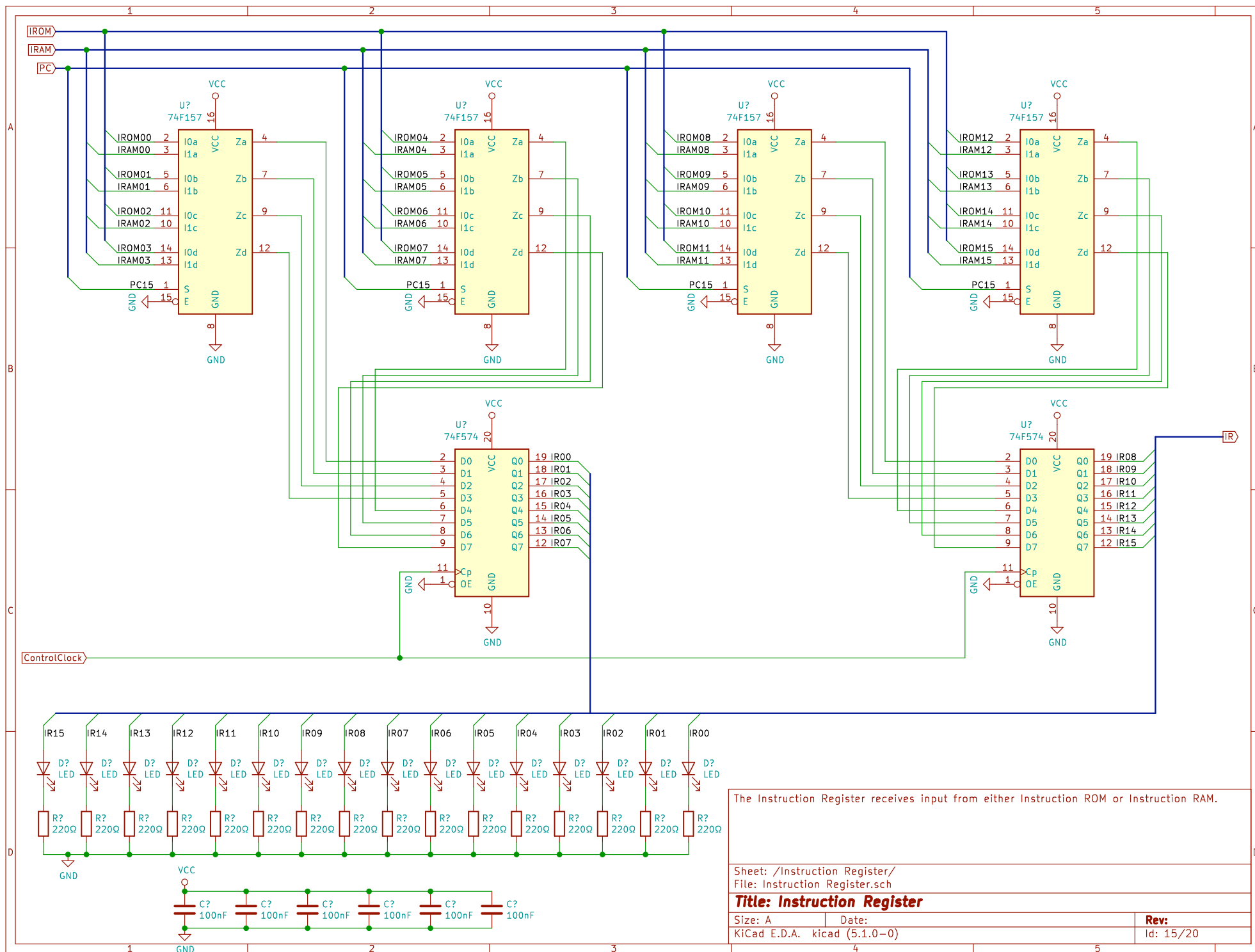
Title: Register B

Size: A Date:
KiCad E.D.A. kicad (5.1.0-0)

Rev:
Id: 11/20







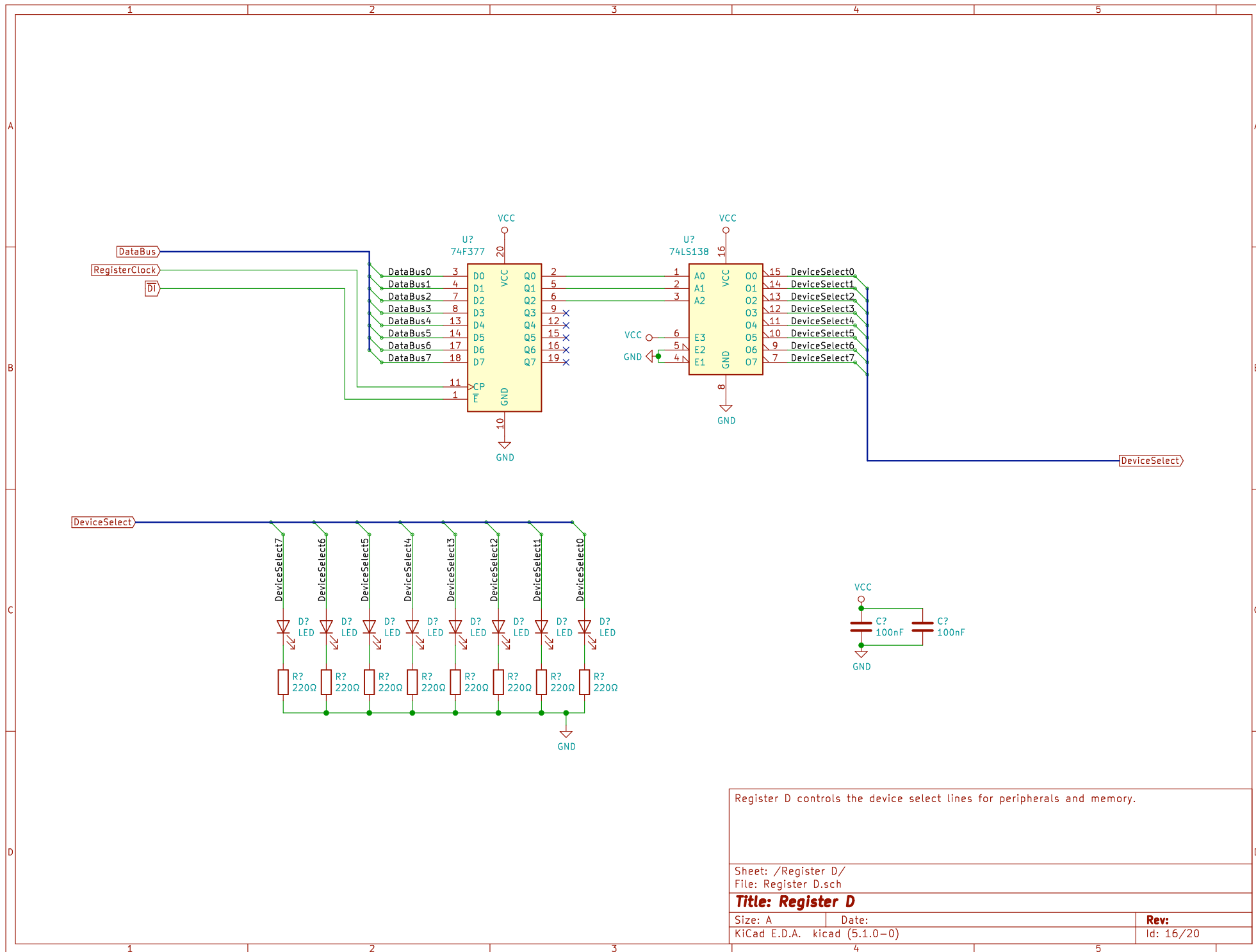
The Instruction Register receives input from either Instruction ROM or Instruction RAM.

Sheet: /Instruction Register/
File: Instruction Register.sch

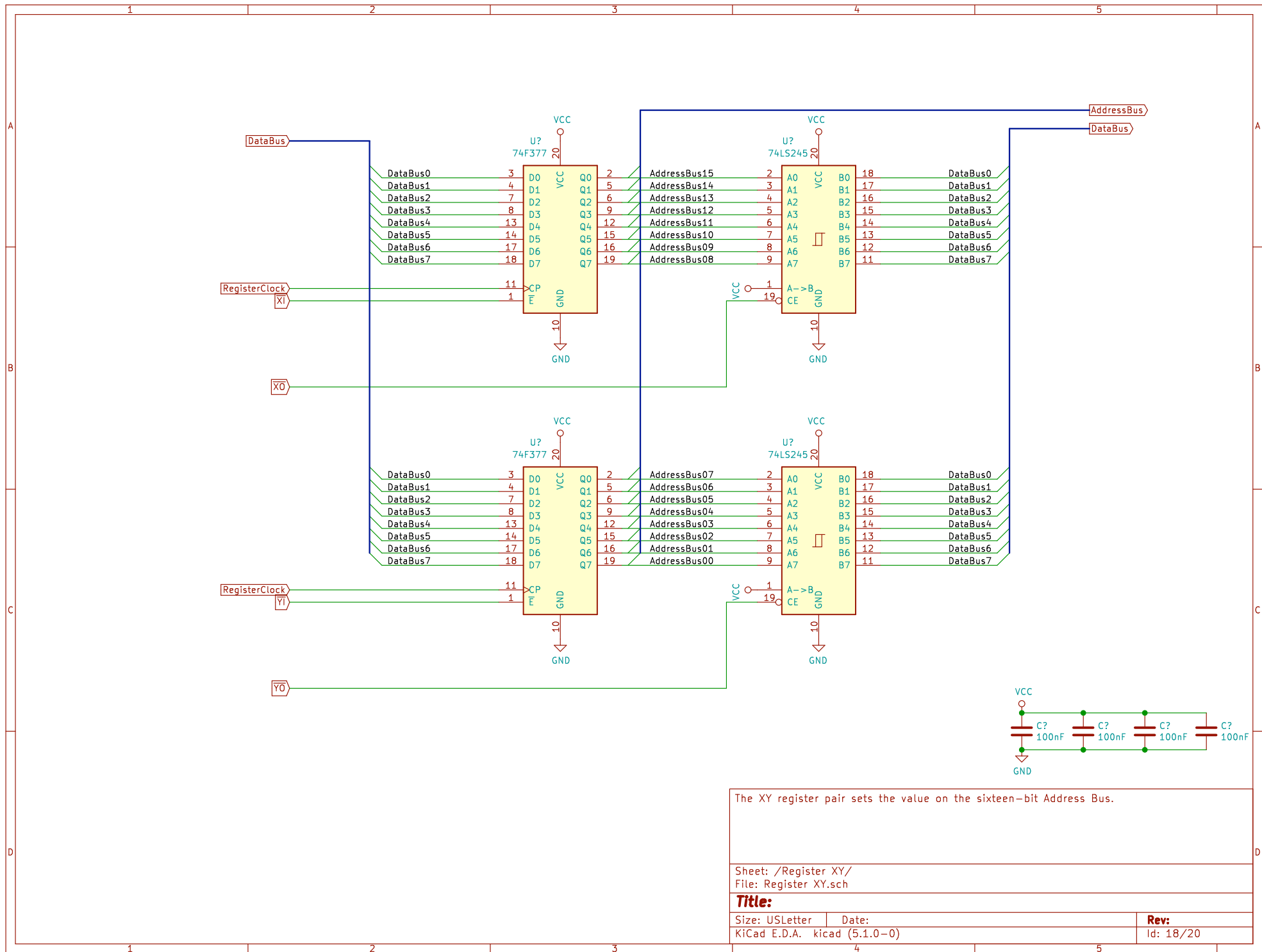
Title: Instruction Register

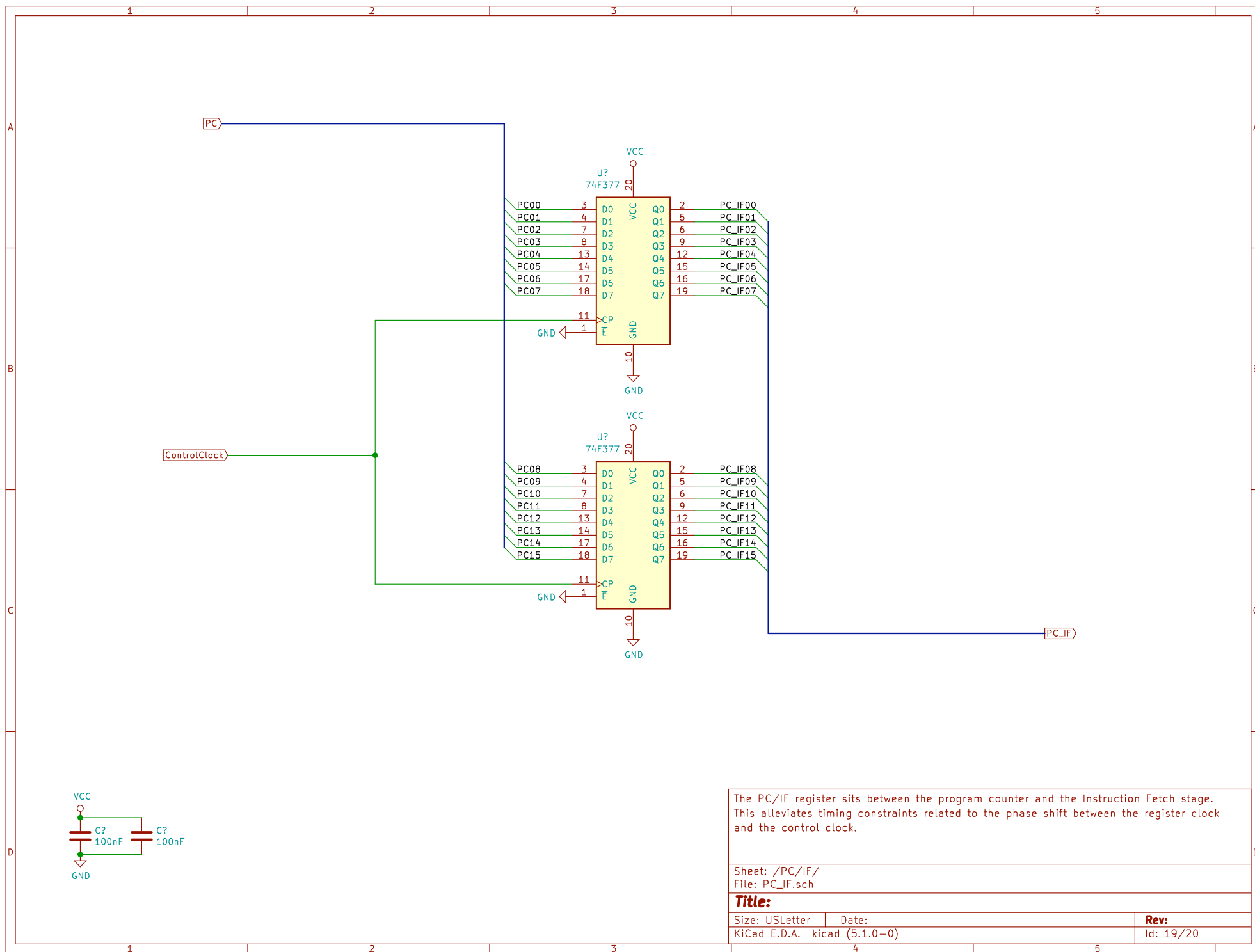
Size: A Date:
KiCad E.D.A. kicad (5.1.0-0)

Rev:
Id: 15/20

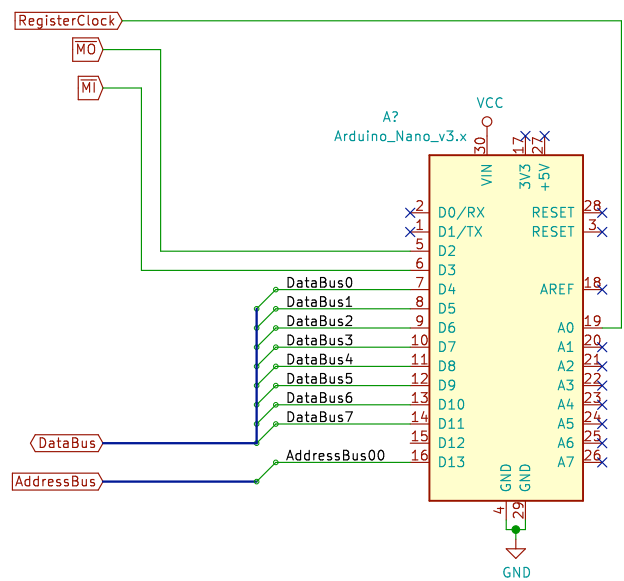


Register D controls the device select lines for peripherals and memory.		
Sheet: /Register D/ File: Register D.sch		
Title: Register D		
Size: A	Date:	Rev:
KiCad E.D.A. kicad (5.1.0-0)		Id: 16/20





The PC/IF register sits between the program counter and the Instruction Fetch stage. This alleviates timing constraints related to the phase shift between the register clock and the control clock.		
Sheet: /PC/IF/ File: PC_IF.sch		
Title:		
Size: USLetter	Date:	Rev:
KiCad E.D.A. kicad (5.1.0-0)		Id: 19/20



An Arduino Nano serves as a serial interface module.		
Sheet: /Serial/ File: Serial.sch		
Title:		
Size: USLetter	Date:	Rev:
KiCad E.D.A. kicad (5.1.0-0)		Id: 20/20