

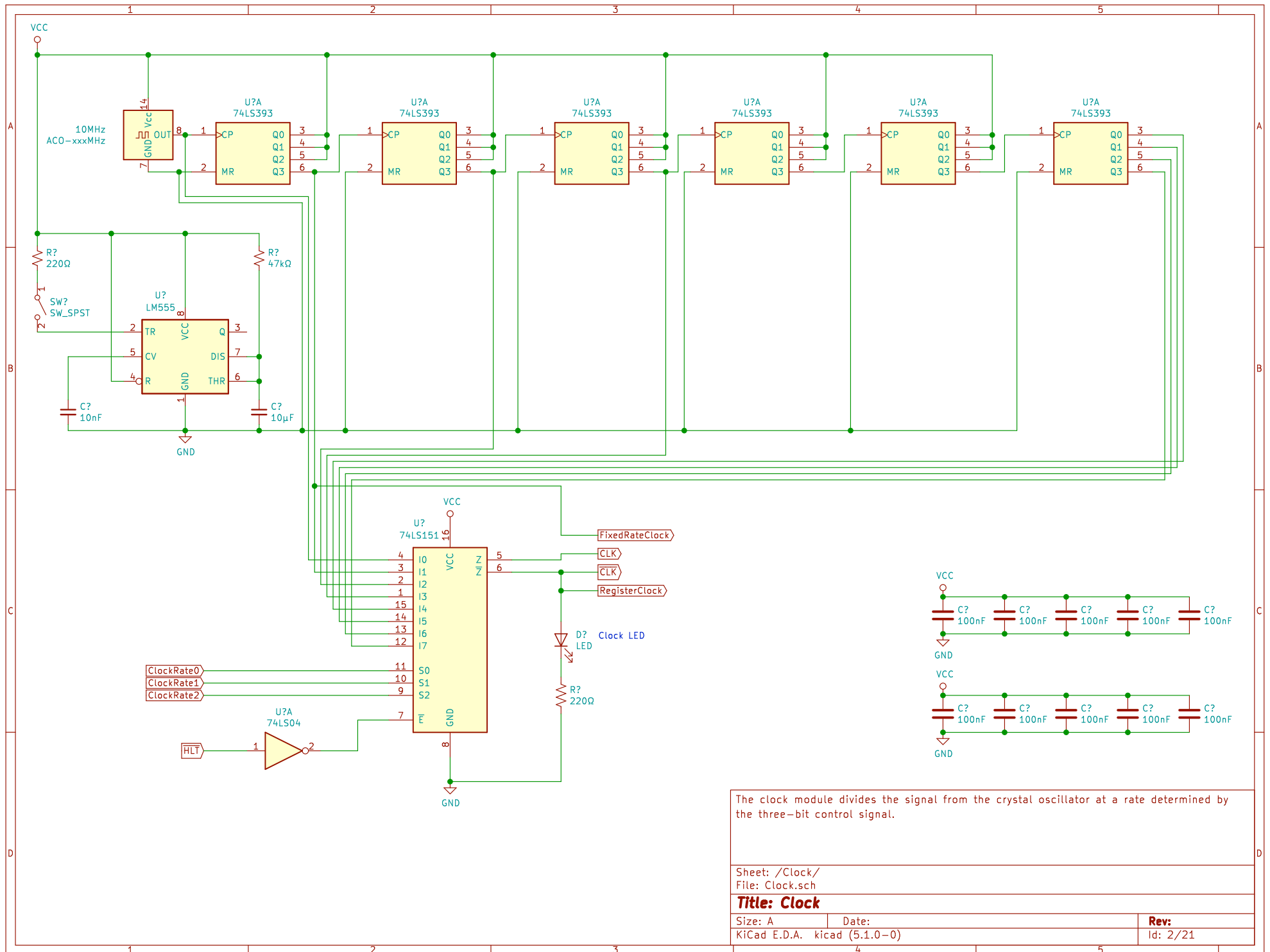
	1	2	3	4	5	
A		Sheet: Output Display File: Output Display.sch	Sheet: Register XY File: Register XY.sch Sheet: Program Counter	Sheet: Speed Control File: Speed Control.sch Sheet: Clock		A
			File: Program Counter.sch Sheet: PC/IF	File: Clock.sch Sheet: Power-on Reset		
B		Sheet: Instruction RAM File: Instruction RAM.sch Sheet: Data RAM	File: PC/IF.sch Sheet: Instruction ROM File: Instruction ROM.sch Sheet: Instruction Register	File: Power-on Reset.sch Sheet: Register A File: Register A.sch Sheet: Register B		B
		File: Data RAM.sch	File: Instruction Register.sch Sheet: Instruction Decoder	File: Register B.sch Sheet: ALU		
C		Sheet: Serial File: Serial.sch Sheet: Register D	File: Instruction Decoder.sch Sheet: Execute File: Execute.sch Sheet: Control Word Display	File: ALU.sch Sheet: Bus Display File: Bus Display.sch		C
		File: Register D.sch	File: Control Word Display.sch			
D						D
	1	2	3	4	5	

TTL microcomputer built from 74xx series logic chips.

Sheet: /  
File: TurtleTTL.sch

Title: Turtle TTL

Size: A	Date:	Rev:
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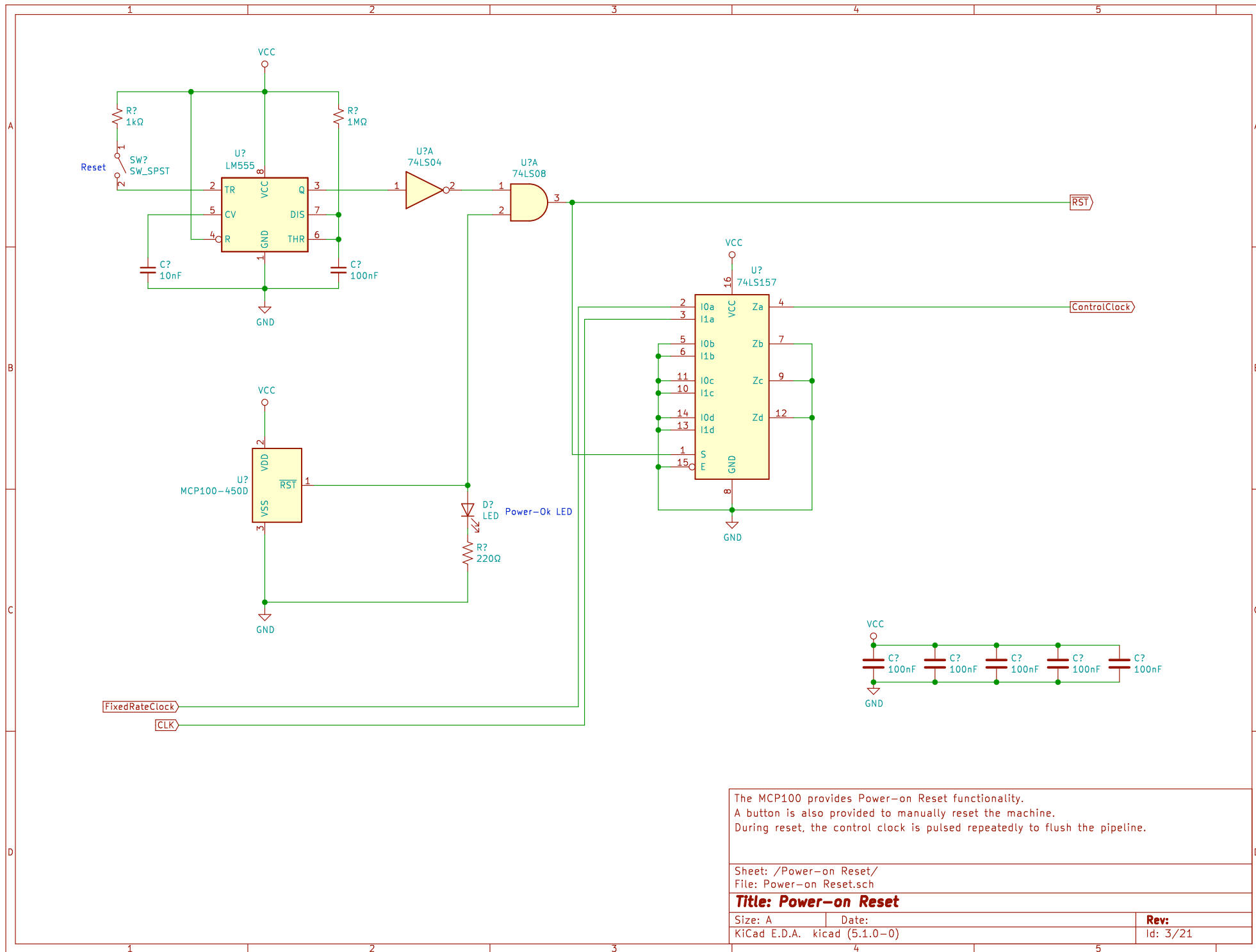
The clock module divides the signal from the crystal oscillator at a rate determined by the three-bit control signal.

Sheet: /Clock/  
File: Clock.sch

**Title: Clock**

Size: A Date:  
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Rev:  
Id: 2/21



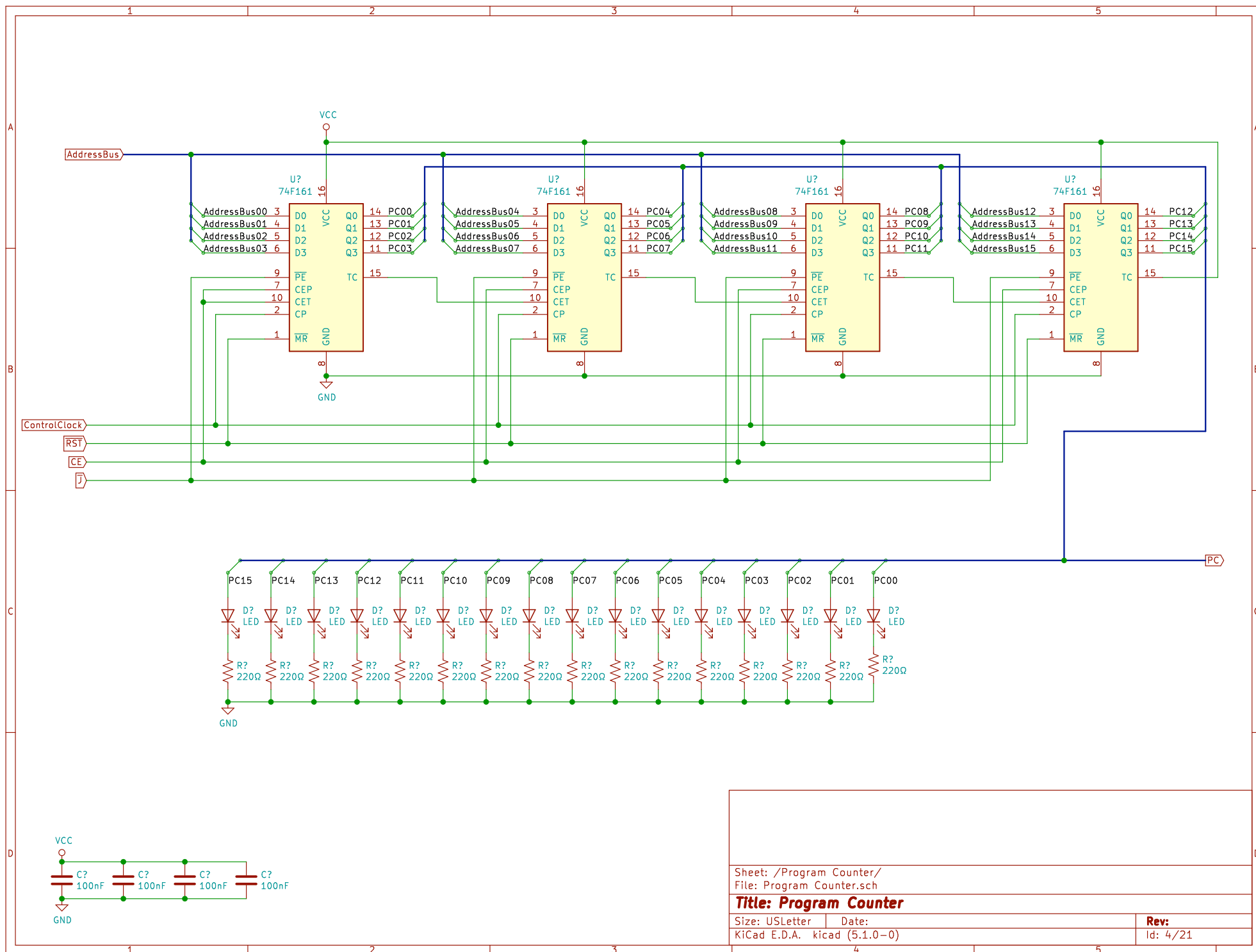
The MCP100 provides Power-on Reset functionality.  
A button is also provided to manually reset the machine.  
During reset, the control clock is pulsed repeatedly to flush the pipeline.

Sheet: /Power-on Reset/  
File: Power-on Reset.sch

**Title: Power-on Reset**

Size: A Date:  
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Id: 3/21

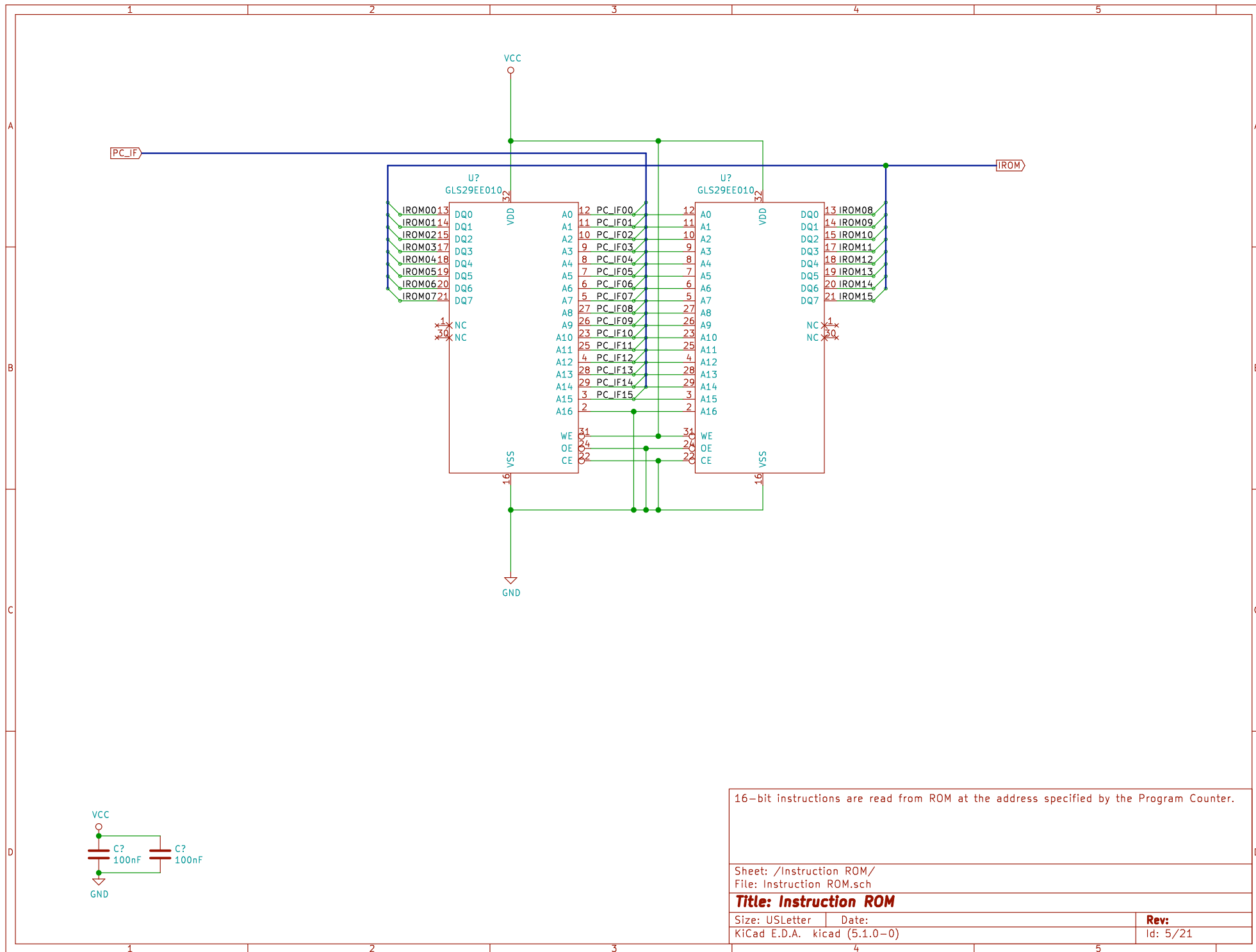


Sheet: /Program Counter/  
File: Program Counter.sch

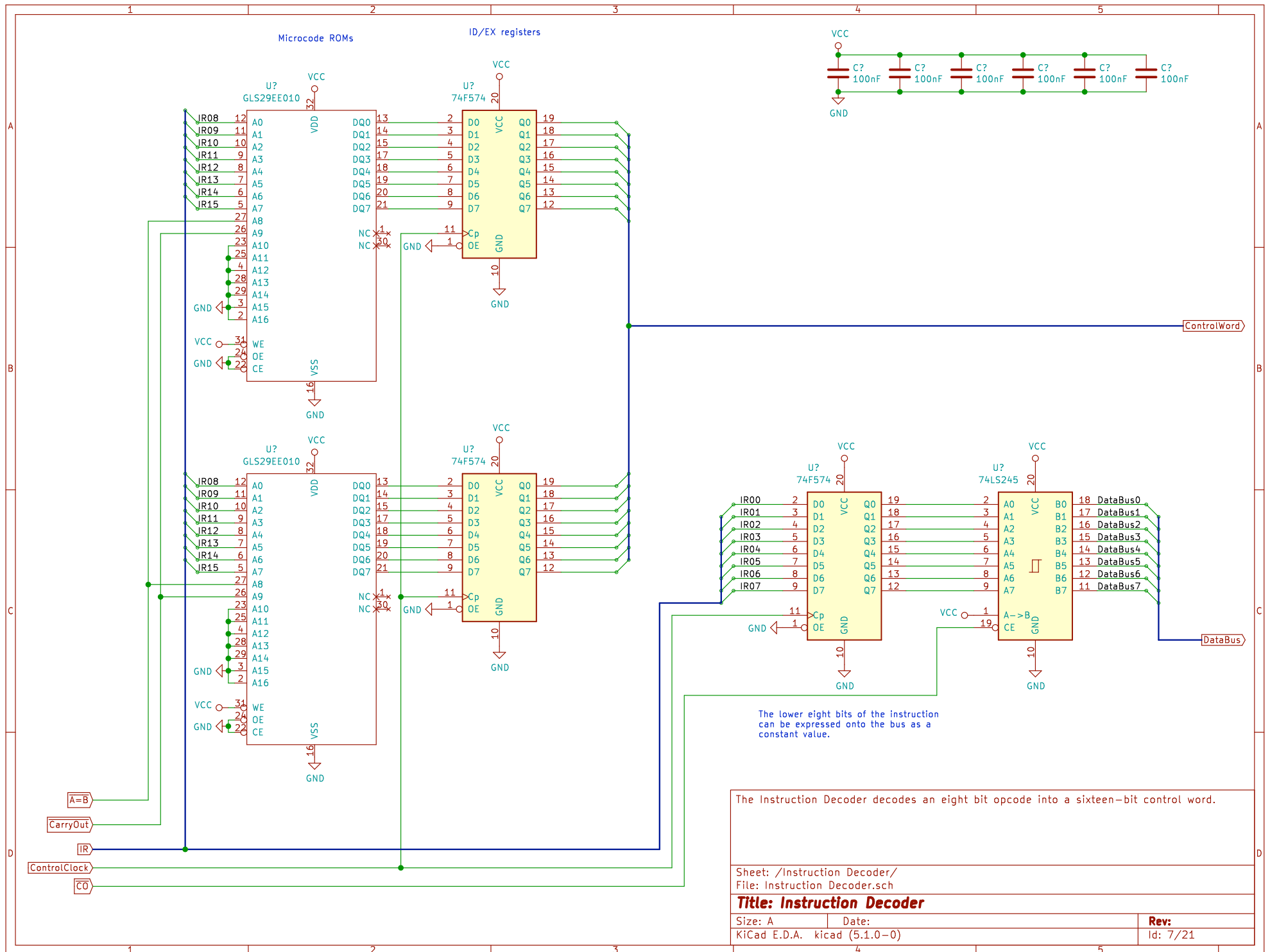
# **Title: Program Counter**

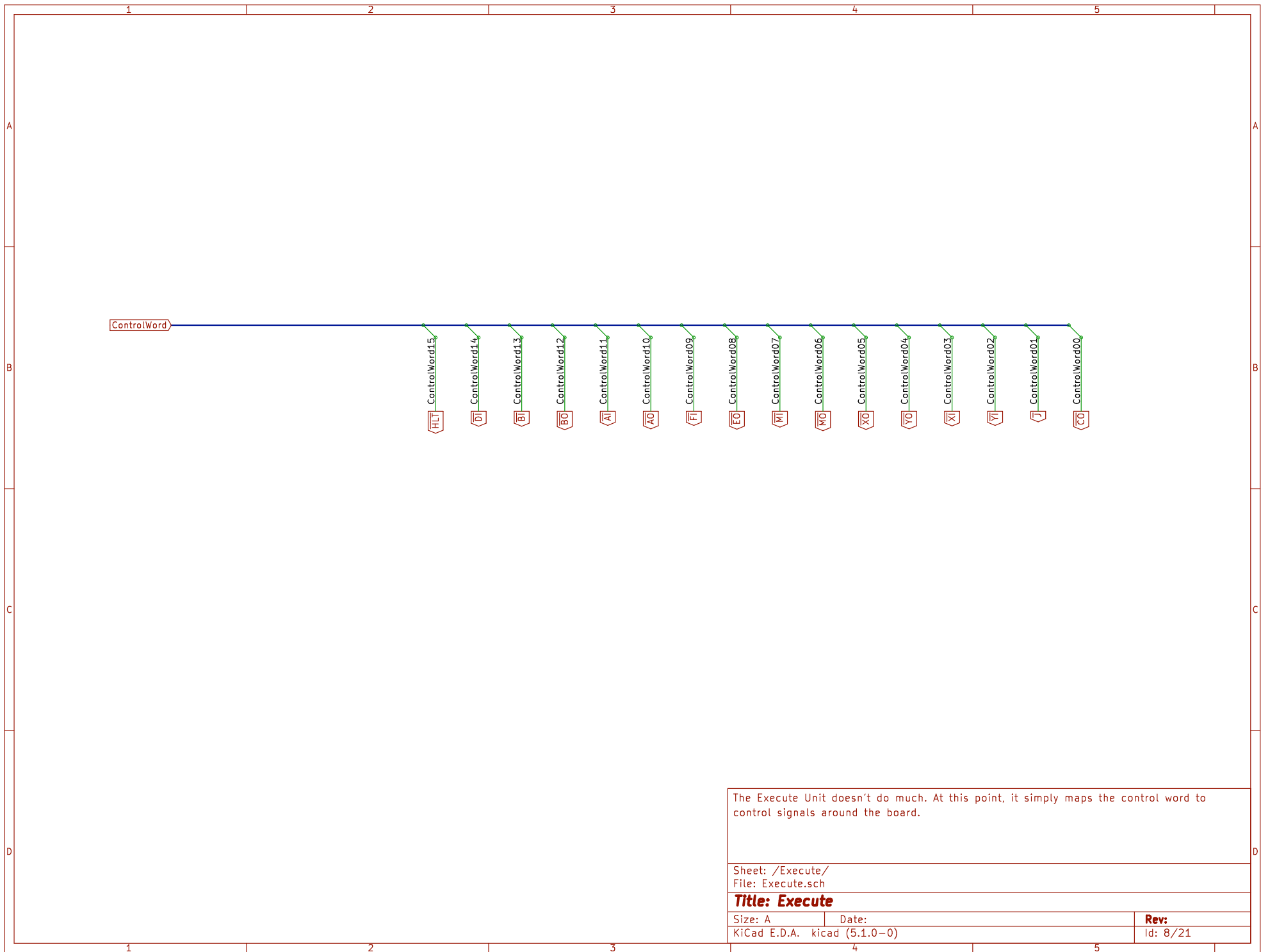
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The diagram area is a large rectangle defined by a grid. The horizontal axis is labeled 1, 2, 3, 4, 5 from left to right. The vertical axis is labeled A, B, C, D from top to bottom. The area is currently empty, intended for a schematic diagram.

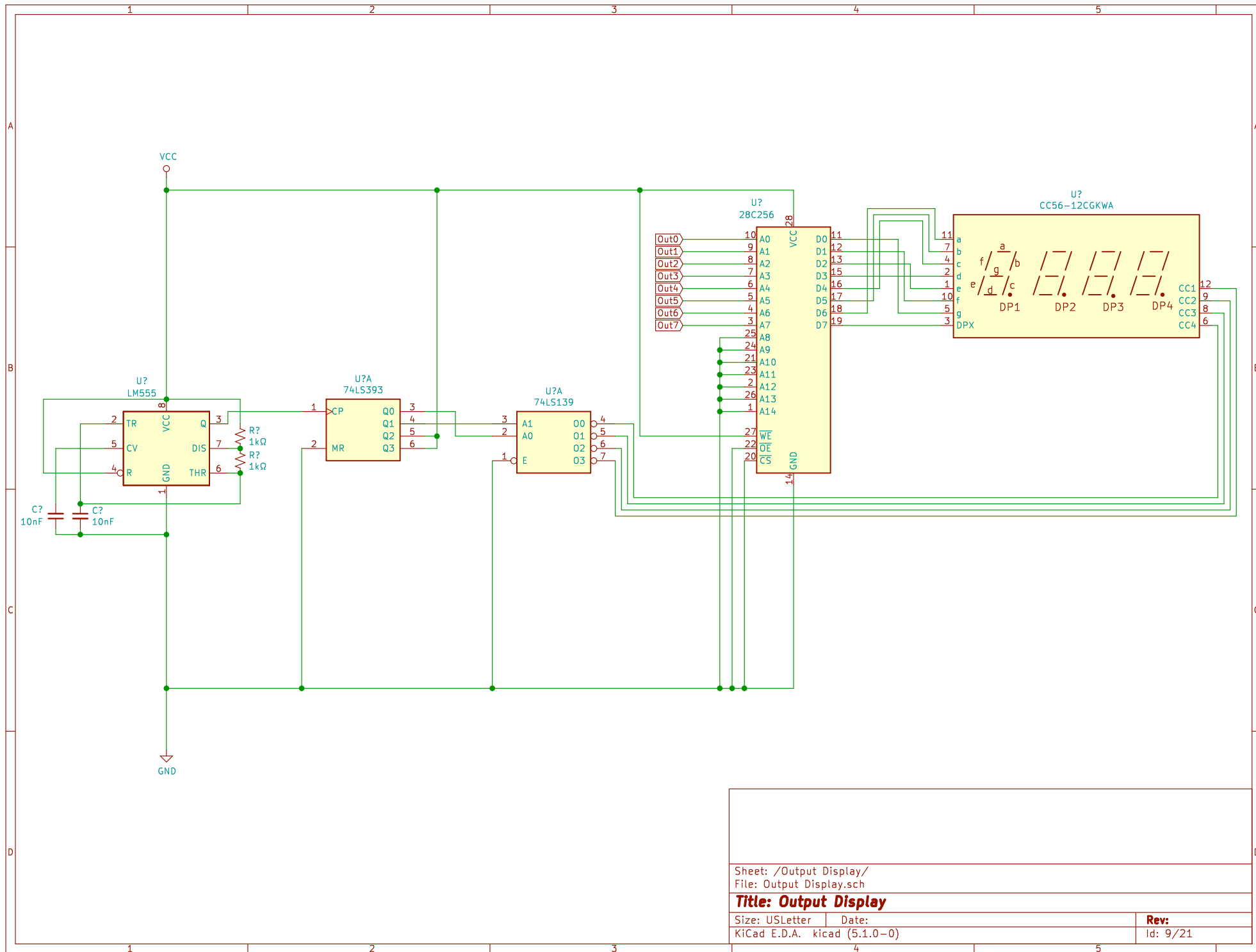


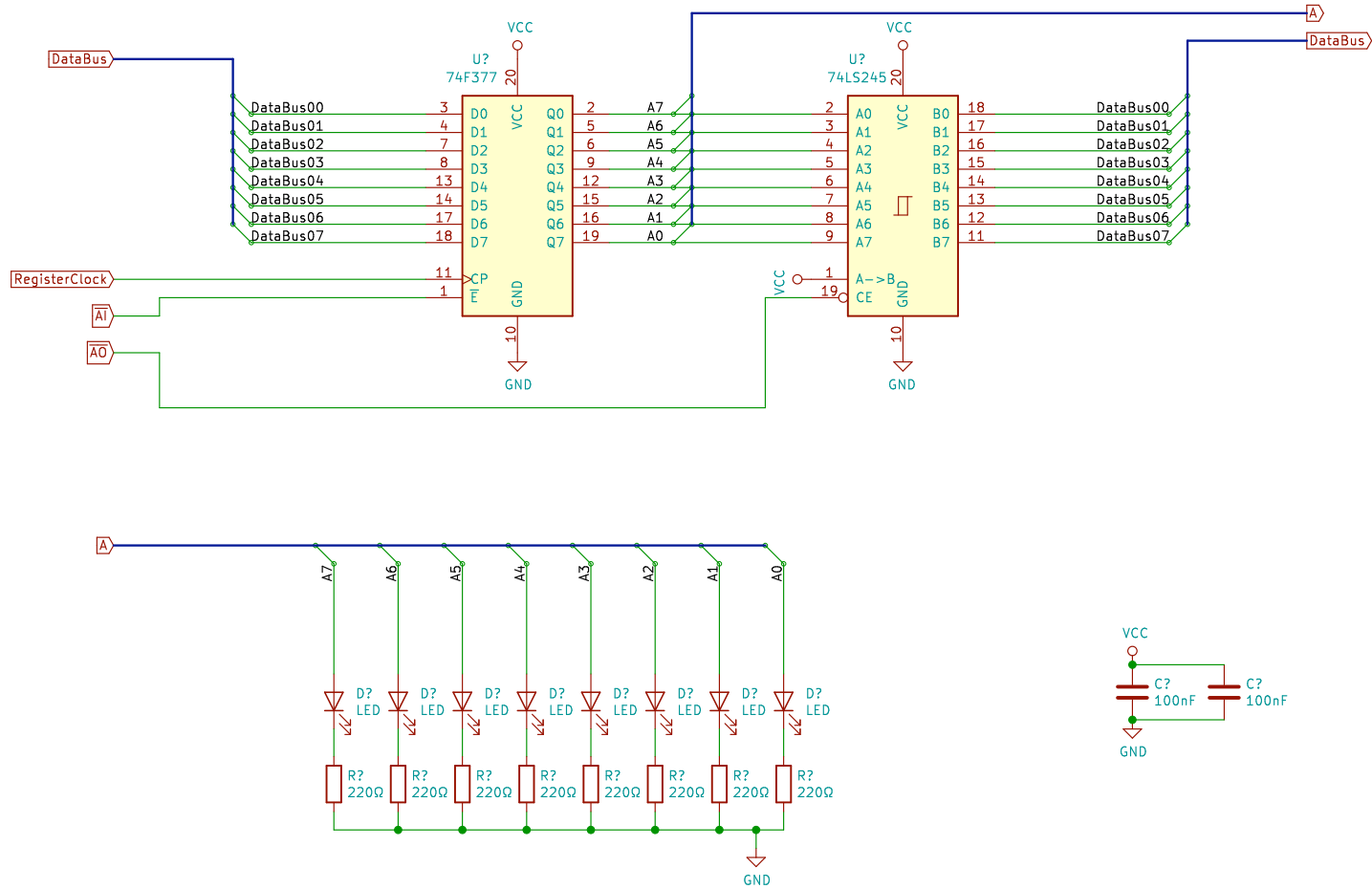


The Execute Unit doesn't do much. At this point, it simply maps the control word to control signals around the board.

Sheet: /Execute/ File: Execute.sch	
<b>Title: Execute</b>	
Size: A	Date:
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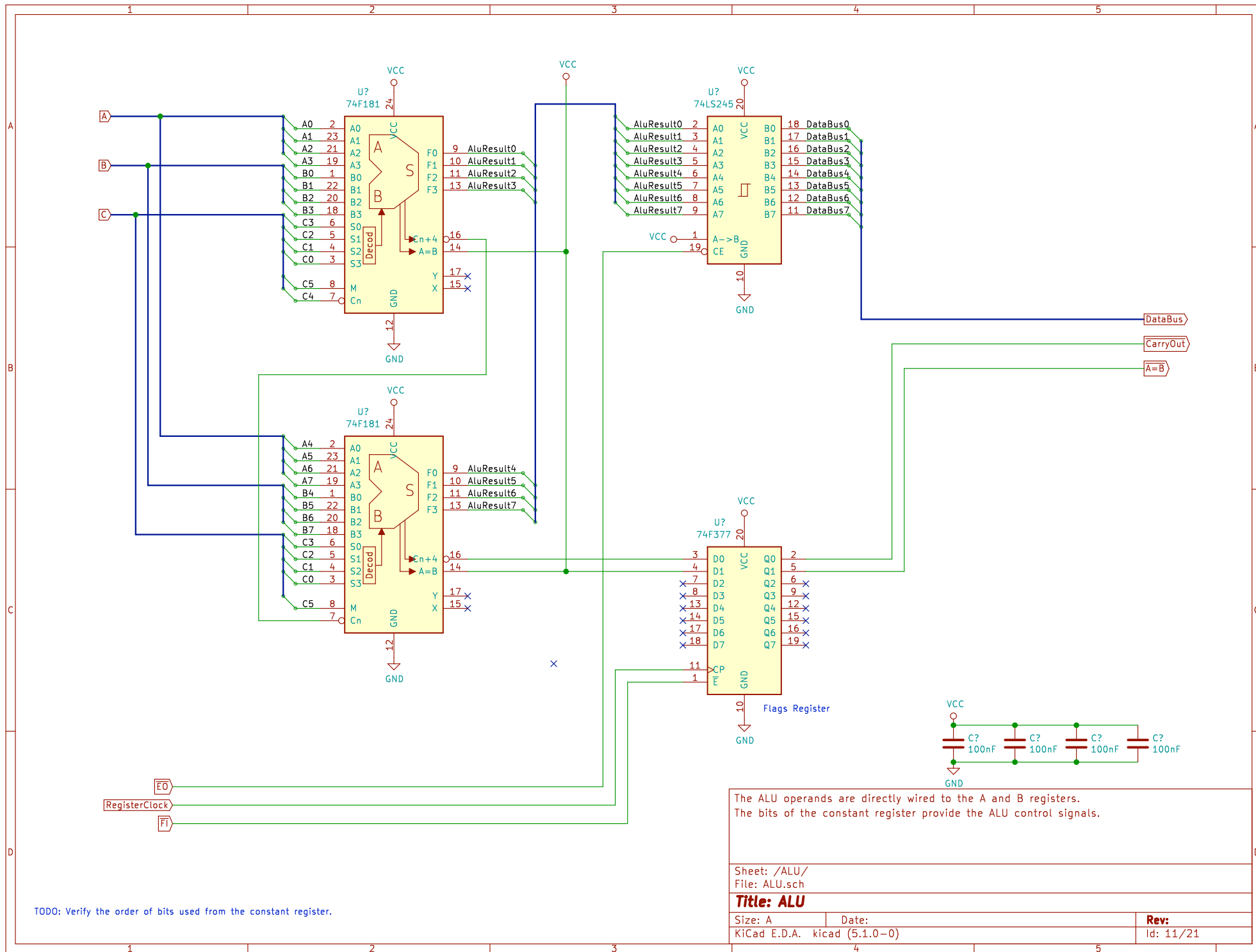
Register A is wired to the ALU's A operand.

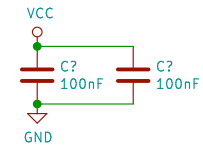
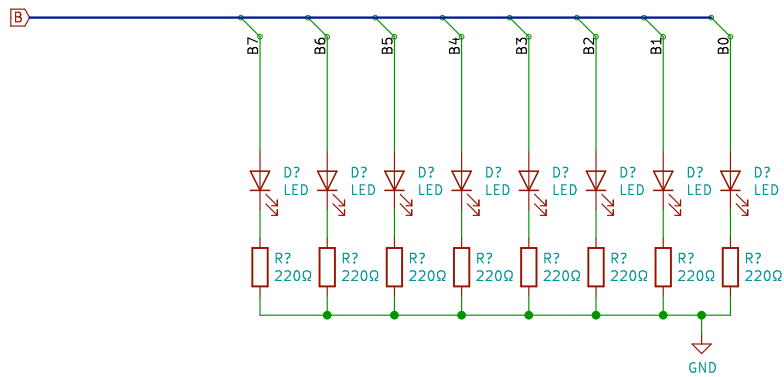
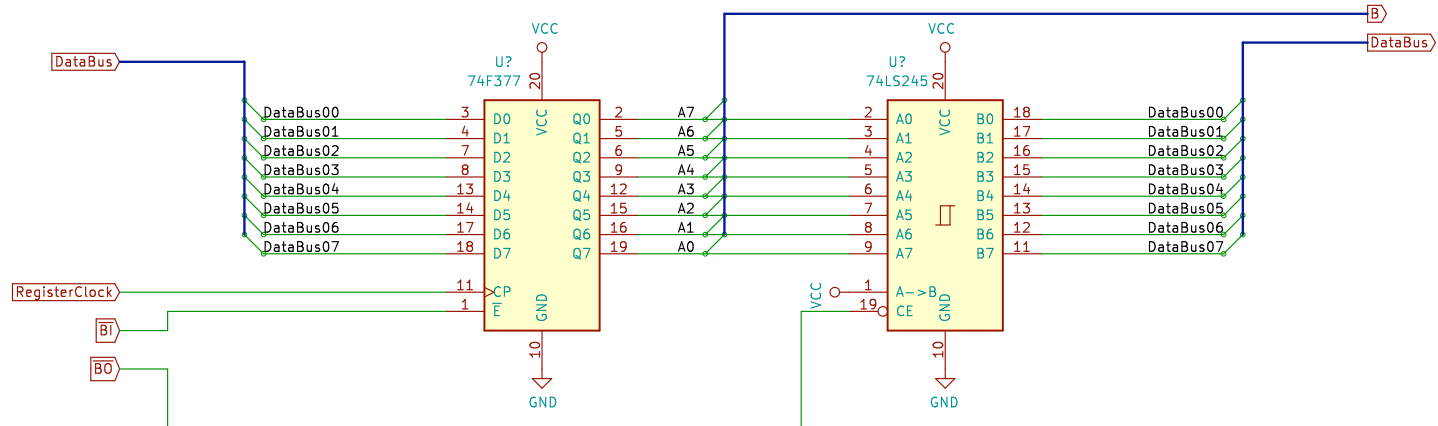
Sheet: /Register A/  
File: Register A.sch

**Title: Register A**

Size: A Date:  
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Register B is wired to the ALU's B operand.		
Sheet: /Register B/ File: Register B.sch		
<b>Title: Register B</b>		
Size: A	Date:	Rev:
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1					2					3					4					5					
A																									A
B																									B
C																									C
D																									D
1					2					3					4					5					

Sheet: /Data RAM/  
File: Data RAM.sch

**Title: Data RAM**

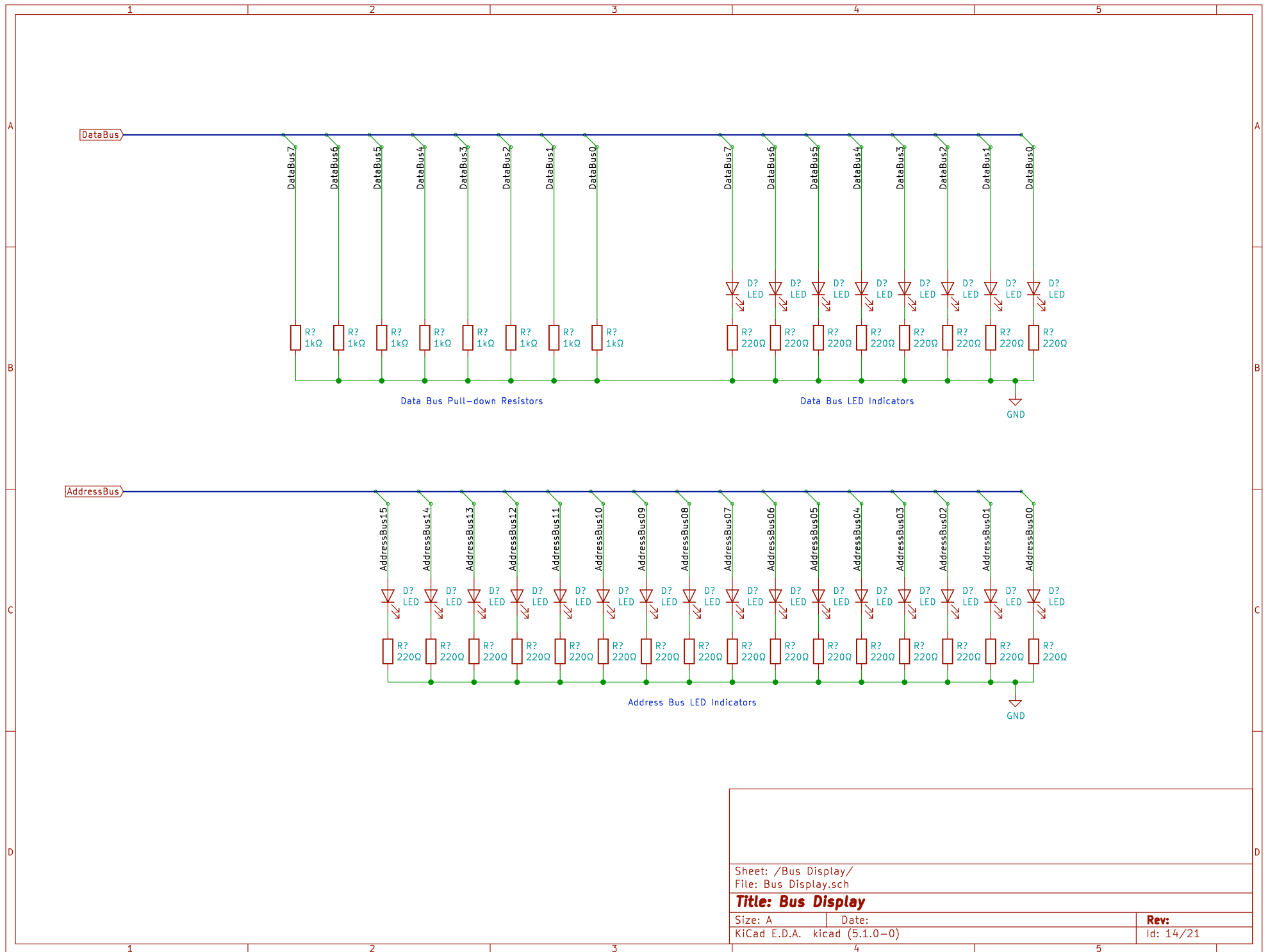
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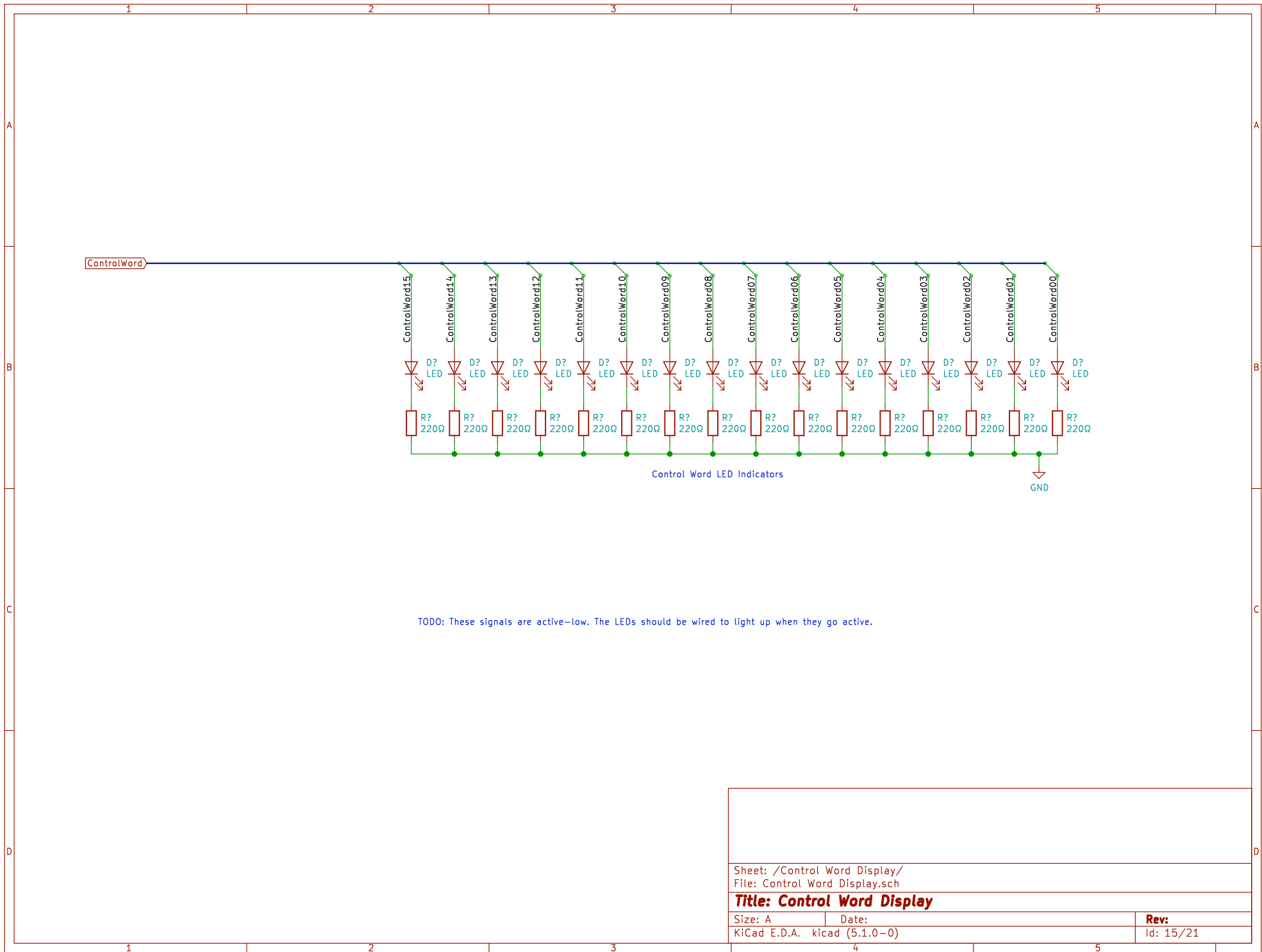
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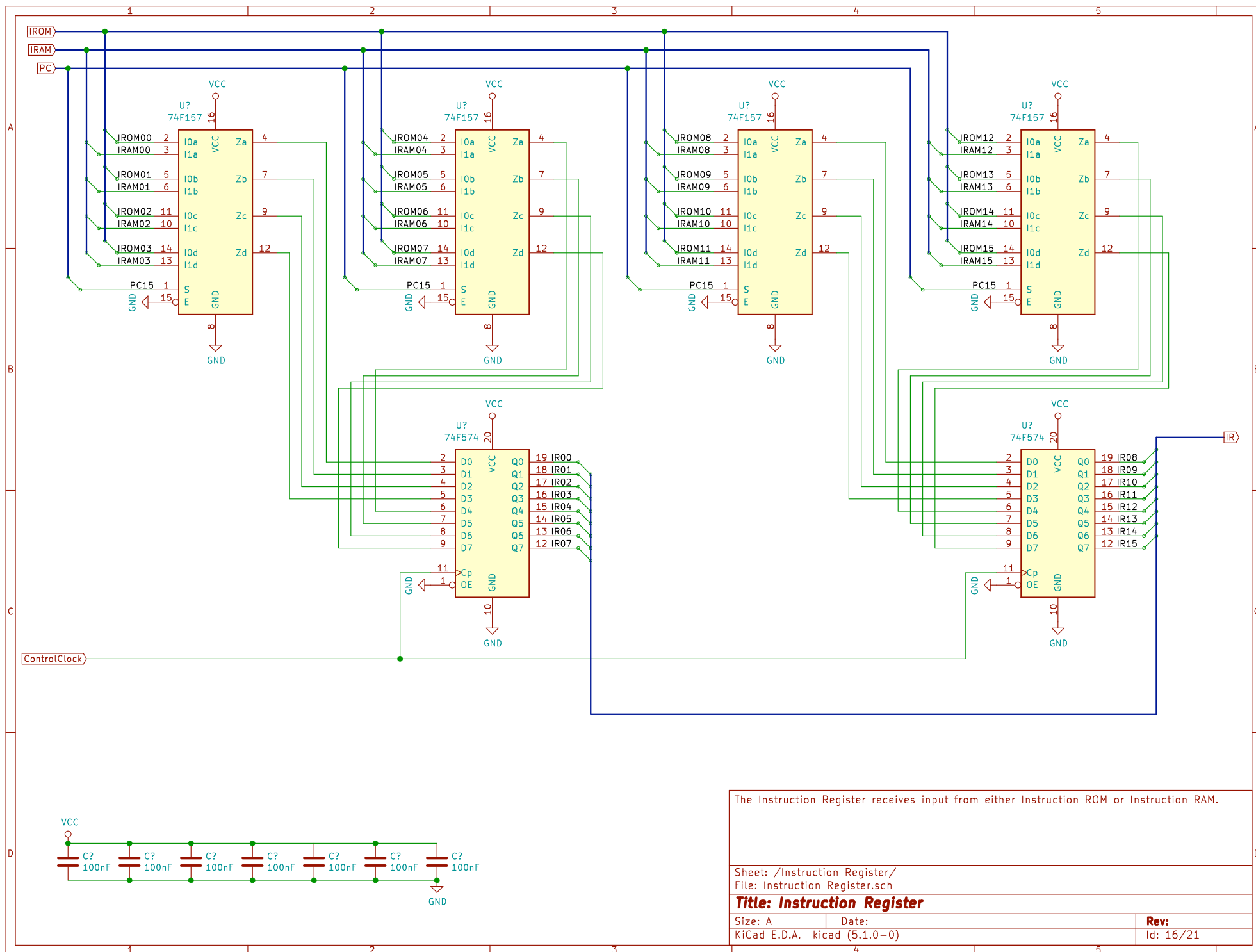
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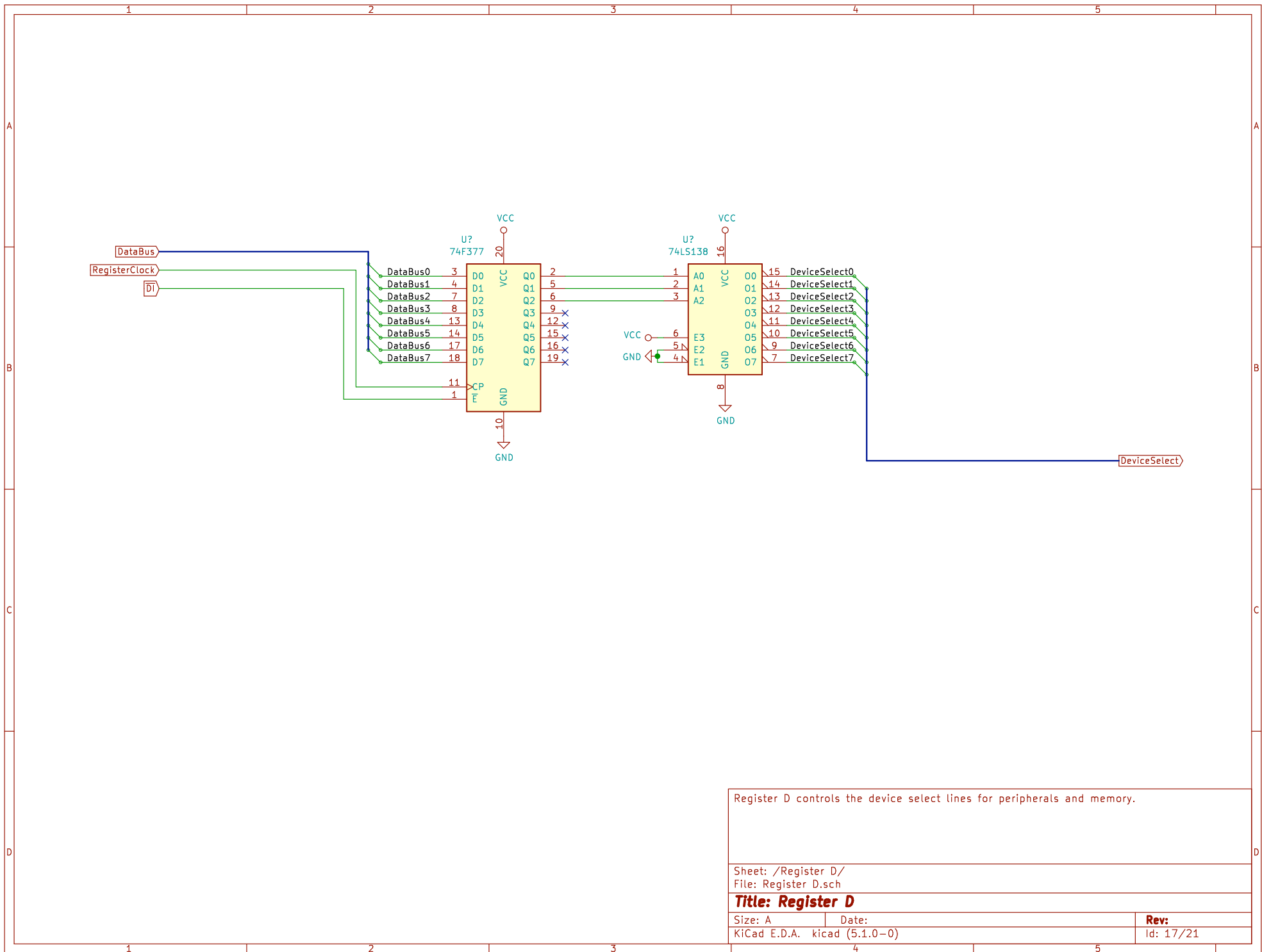
Sheet: /Data RAM/	
File: Data RAM.sch	
Title: Data RAM	
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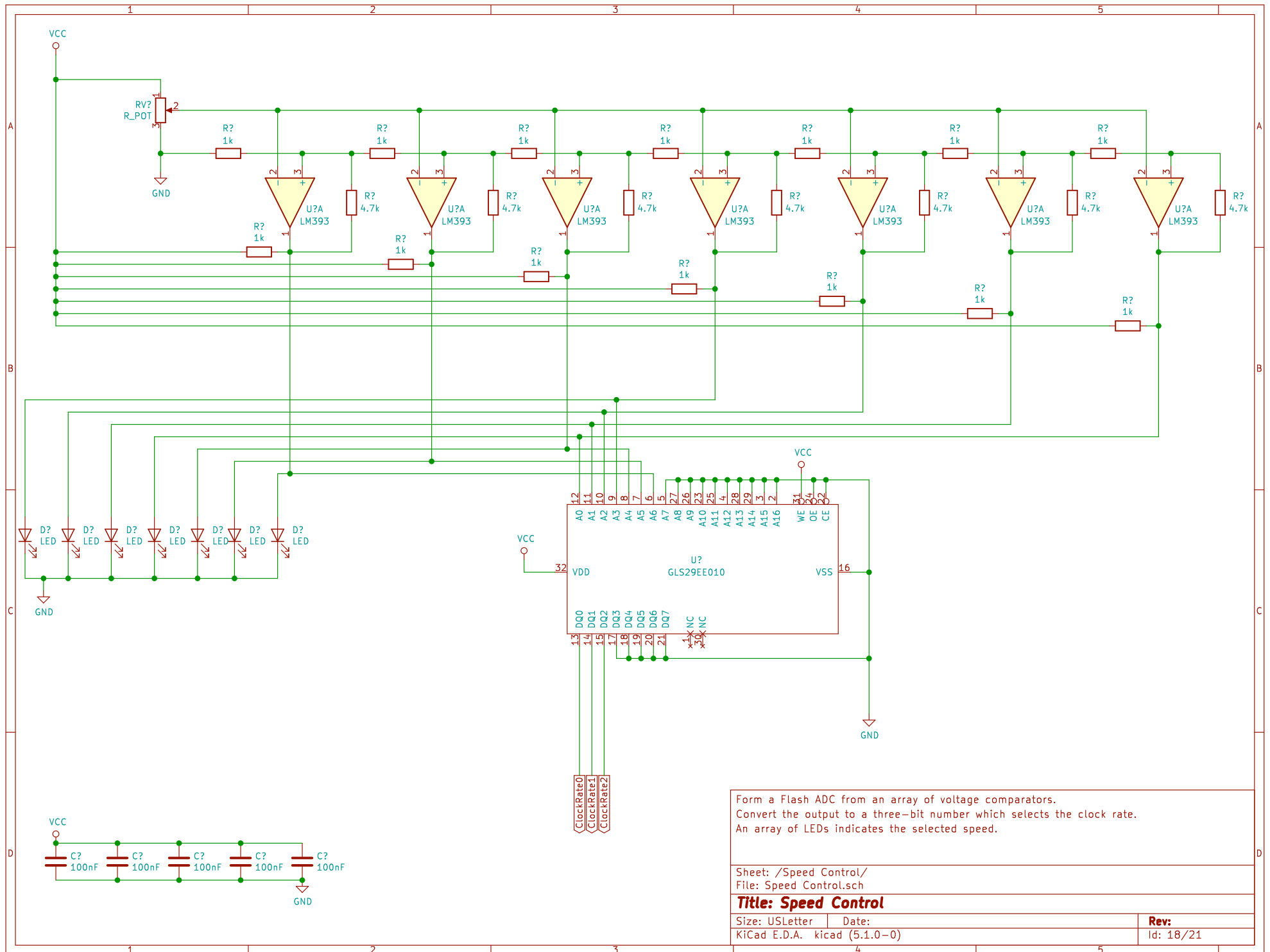








Register D controls the device select lines for peripherals and memory.		
Sheet: /Register D/ File: Register D.sch		
<b>Title: Register D</b>		
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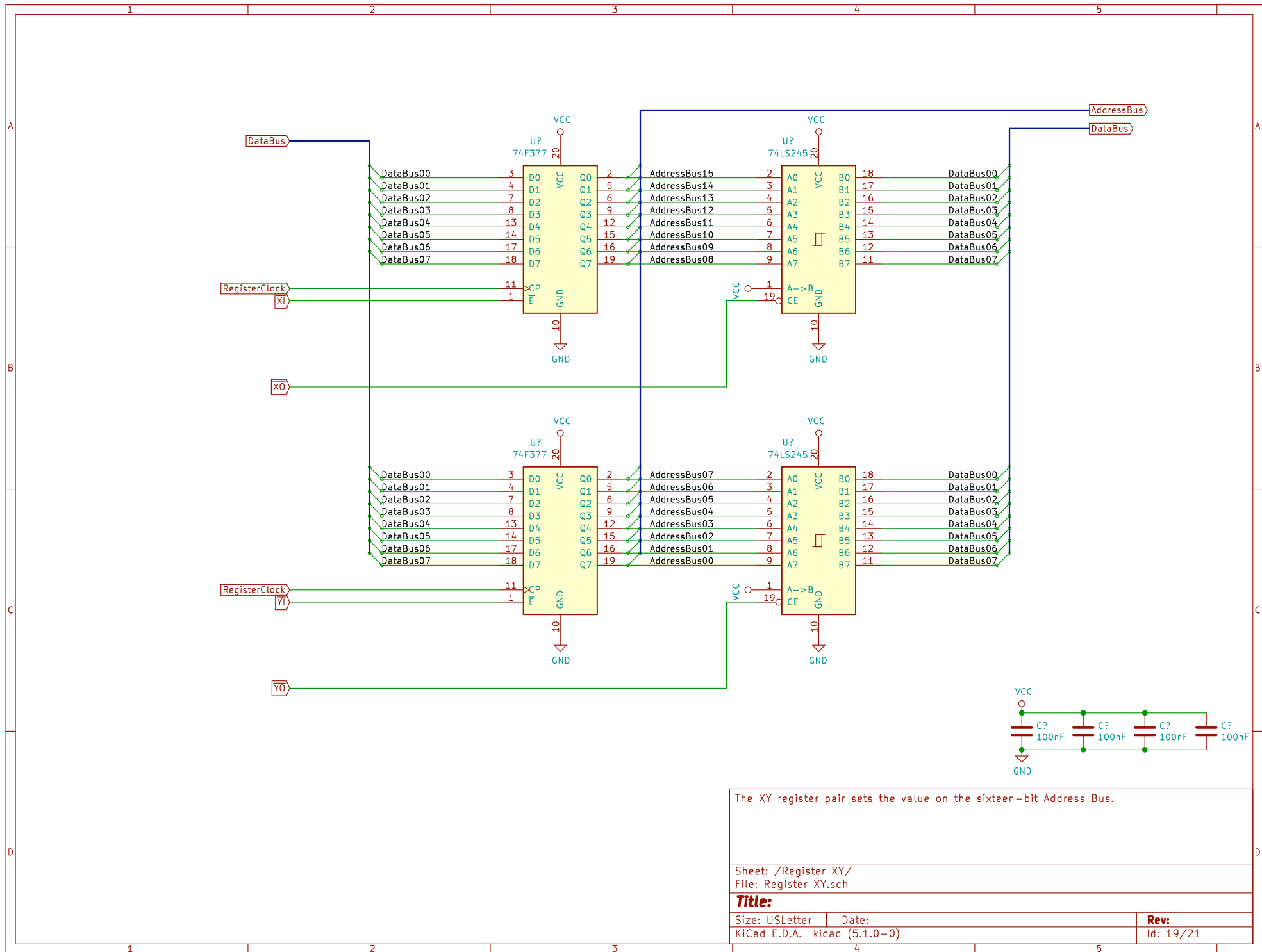
Form a Flash ADC from an array of voltage comparators.  
Convert the output to a three-bit number which selects the clock rate.  
An array of LEDs indicates the selected speed.

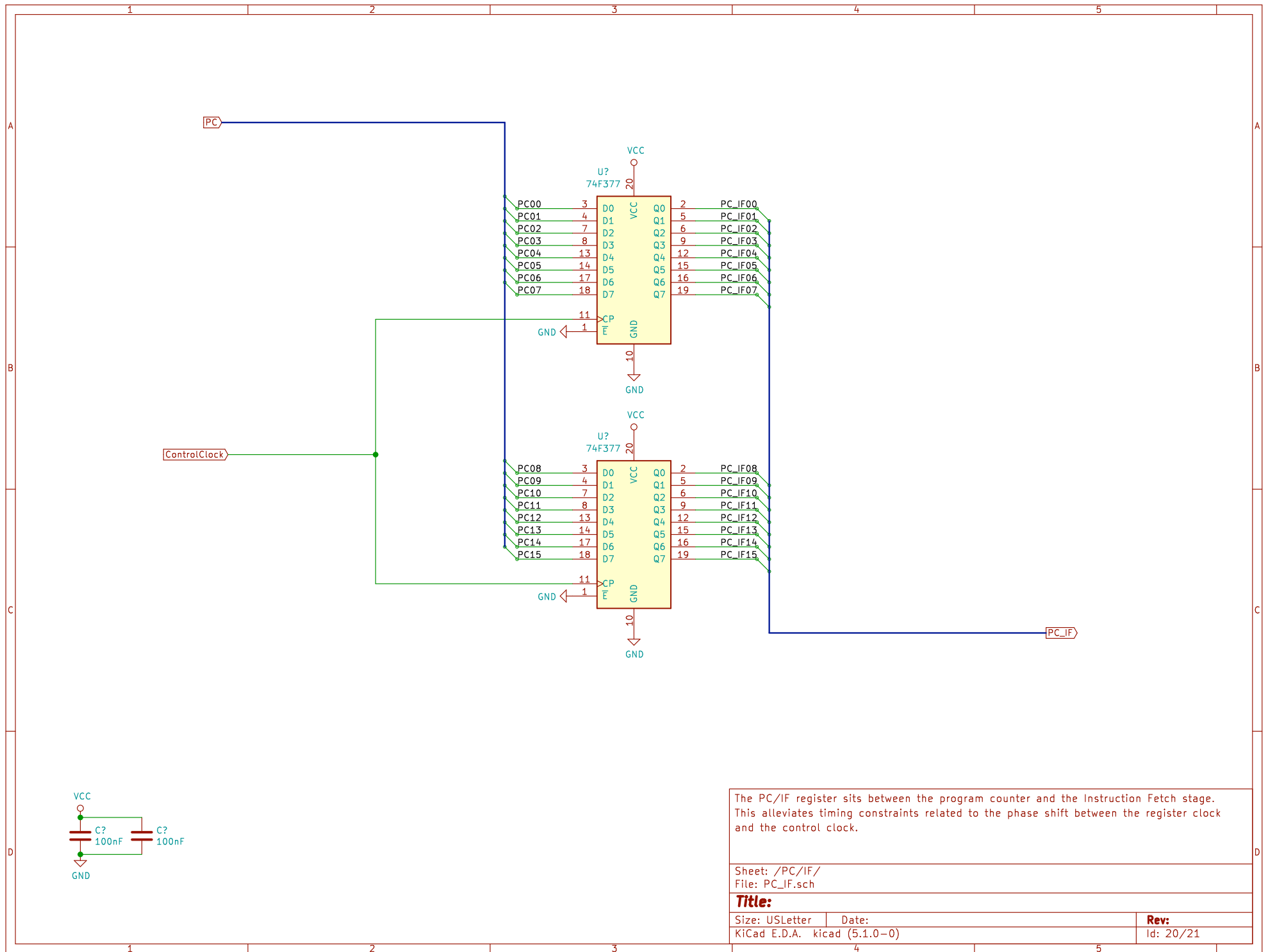
Sheet: /Speed Control/  
File: Speed Control.sch

**Title: Speed Control**

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Id: 18/21



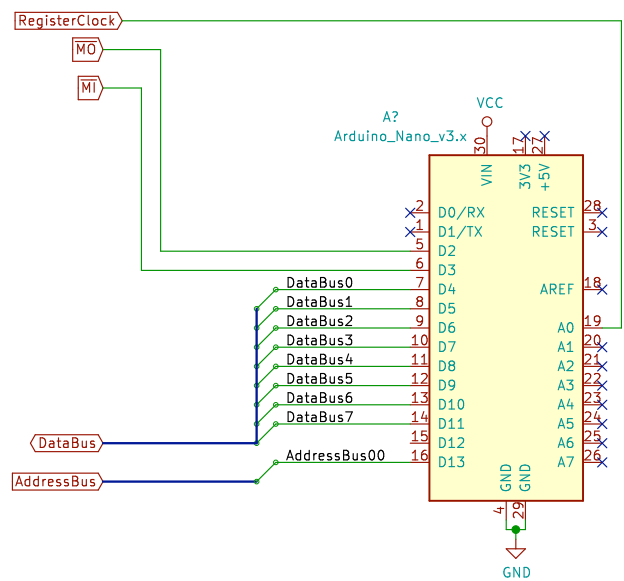


The PC/IF register sits between the program counter and the Instruction Fetch stage. This alleviates timing constraints related to the phase shift between the register clock and the control clock.

Sheet: /PC/IF/  
File: PC\_IF.sch

**Title:**

Size: USLetter	Date:	Rev:
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An Arduino Nano serves as a serial interface module.		
Sheet: /Serial/ File: Serial.sch		
Title:		
Size: USLetter	Date:	Rev:
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