Lab 9: SLAM

VNAV 2020

ORB-SLAM: https://github.com/raulmur/ORB_SLAM2

Kimera: https://github.com/MIT-SPARK/Kimera-VIO

(optionally) LDSO: https://github.com/tum-vision/LDSO

EVO for evaluation: https://github.com/MichaelGrupp/evo

Exercises

https://mit-spark.github.io/VNAV2020-handouts/lab9/exercises
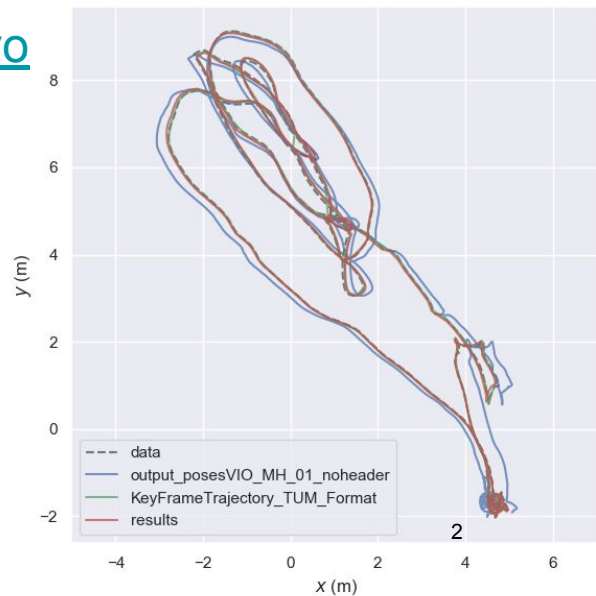
16.485 Visual Navigation for Autonomous Vehicles (VNAV)
Fall 2020