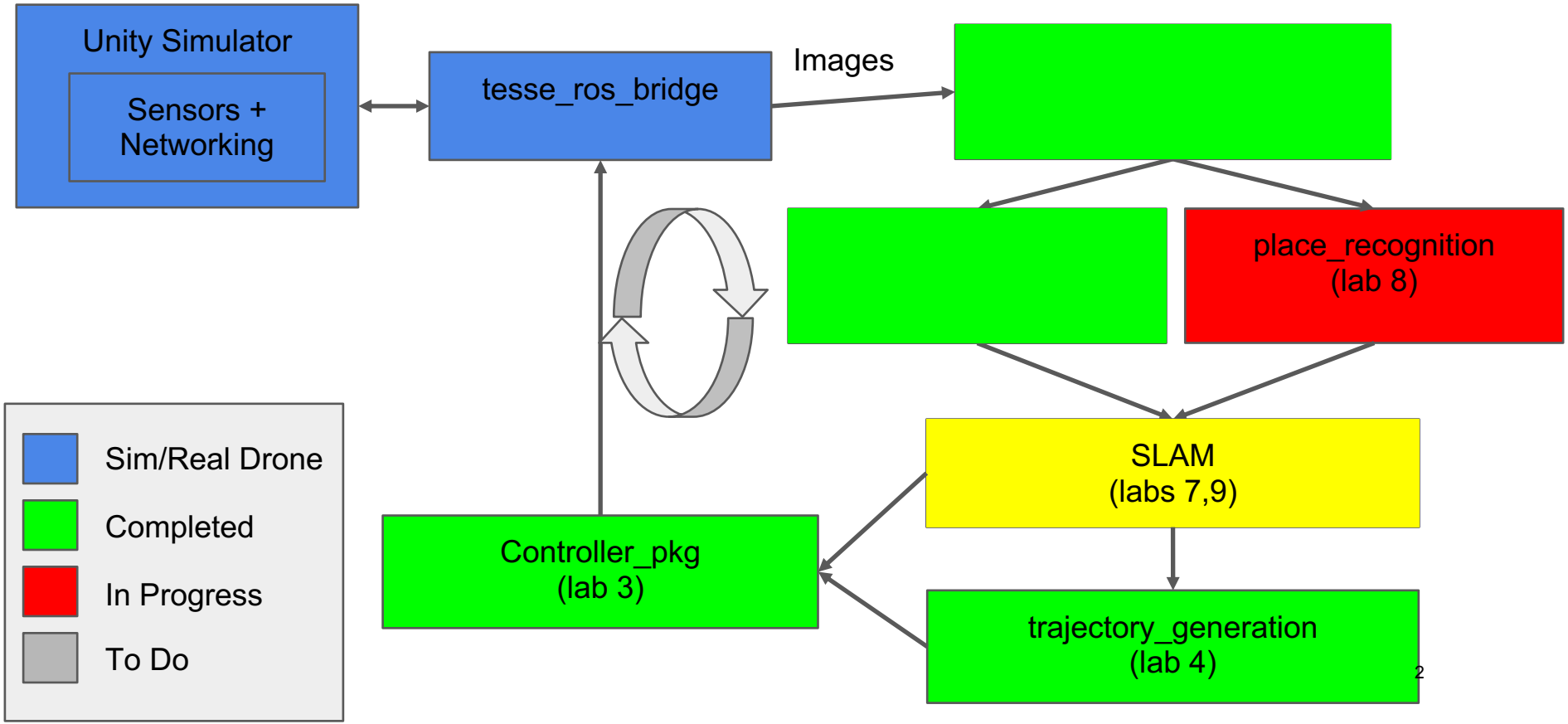
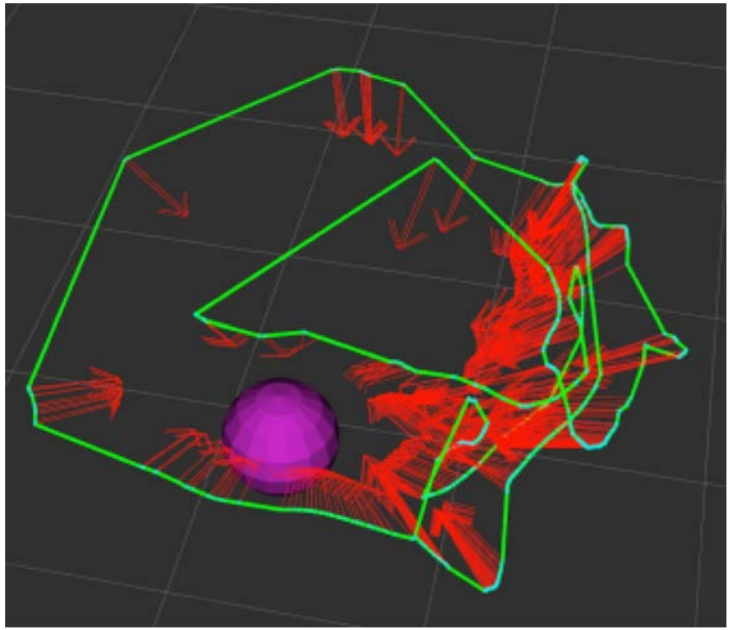
Lab 8: Object Tracking and Place Recognition

VNAV 2020

Where we're headed -- we're almost there!



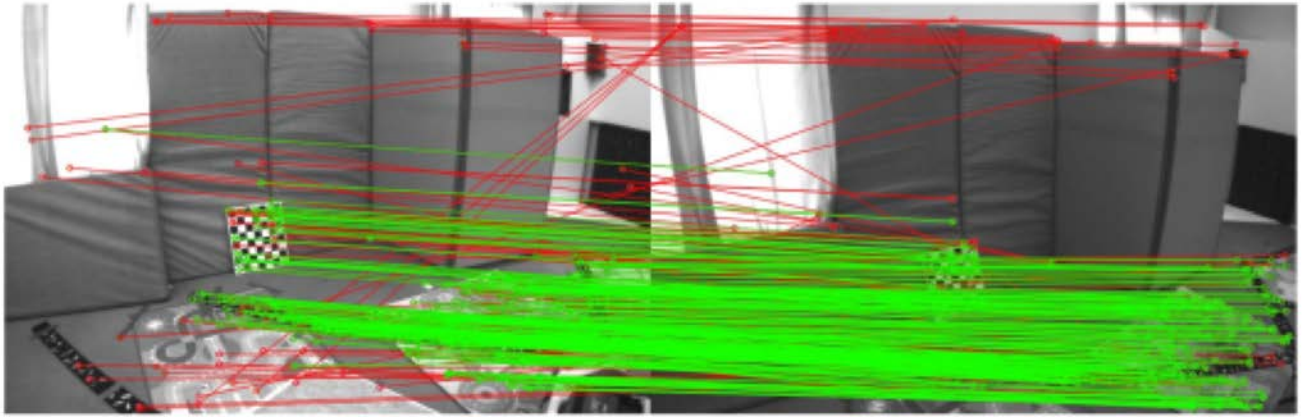
Object Localization



Loop Closure Detection in ORB-SLAM 2

Example Loop Closure

SIFT features



https://mit-spark.github.io/VNAV2020-handouts/lab8/

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