

Propositional Satisfiability: Unit Propagation and DPLL



Empirical analysis
slides draw upon
material from:
Prof. Bart Selman
Cornell University

Brian C. Williams
16.410/413
November 9th, 2015

Assignments

- Assignment:
 - Problem Set #7: Due Wednesday.
- Reading:
 - Today: *[AIMA] Ch. 7, 8.*

Monday:

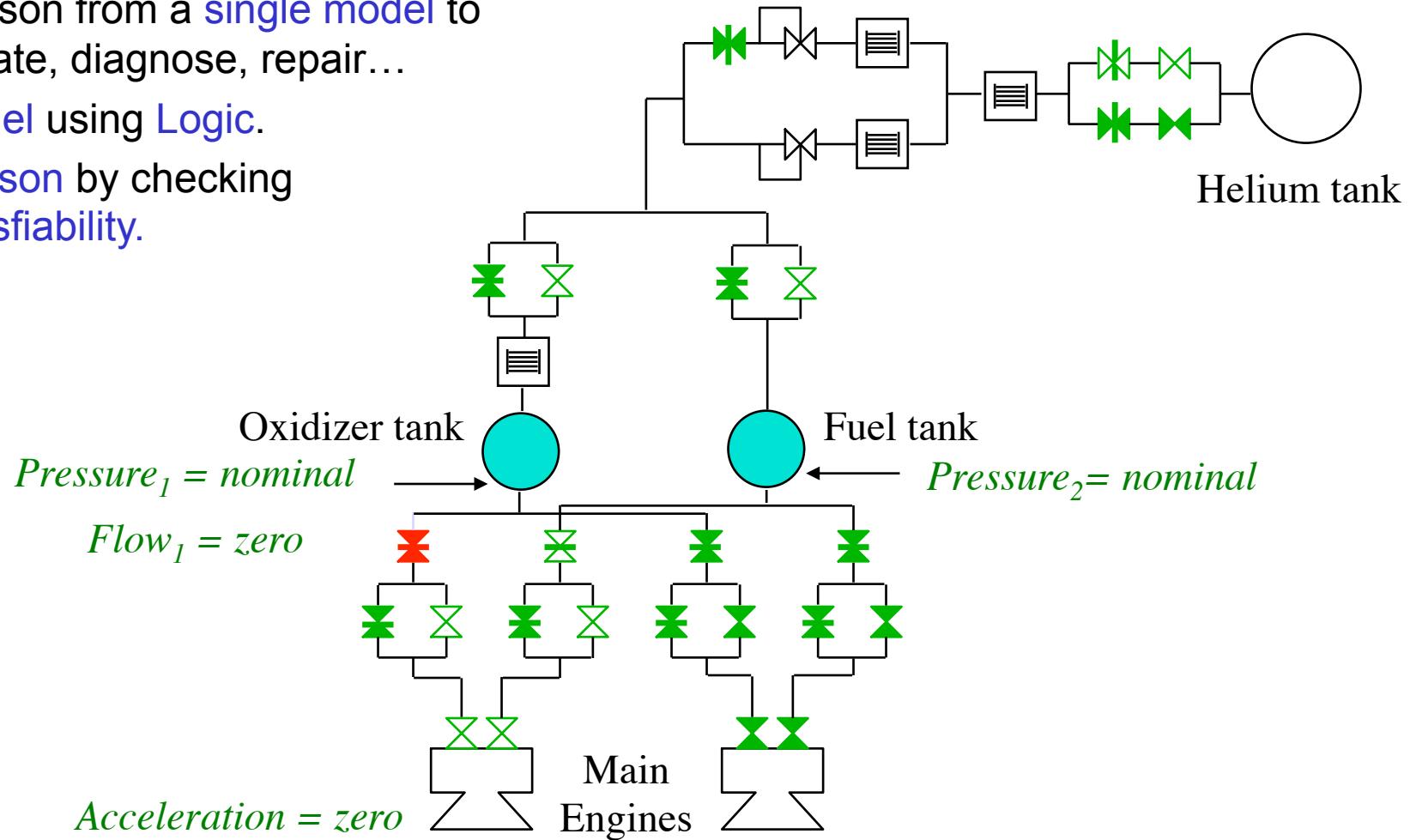
- J. de Kleer and B. C. Williams, "Diagnosing Multiple Faults," *Artificial Intelligence*, 32:100-117, 1987.
- Wednesday: B. C. Williams, and R. Ragno, "Conflict-directed A*" and its Role in Model-based Embedded Systems," Special Issue on Theory and Applications of Satisfiability Testing, *Journal of Discrete Applied Math*, January 2003.

Outline

- Review
- Propositional Satisfiability with Inference
- Empirical, Average Case Analysis
- Model-based Diagnosis (separate slide packet).

Model-based Reasoning

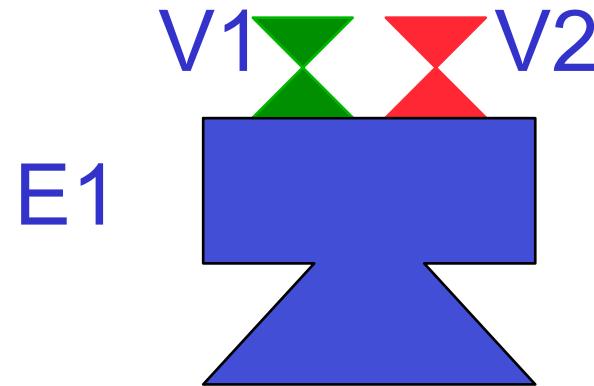
- Reason from a **single model** to operate, diagnose, repair...
- Model using **Logic**.
- Reason by checking **Satisfiability**.



Engine Model in Propositional Logic

“An Engine E1 can either be **okay**, or broken in some unknown way.

When **E1 is okay**, it will **thrust** when there is a **flow through V1 and V2**.”



($\text{mode}(E1) = \text{ok}$ **or** $\text{mode}(E1) = \text{unknown}$) **and**
not ($\text{mode}(E1) = \text{ok}$ **and** $\text{mode}(E1) = \text{unknown}$) **and**

($\text{mode}(E1) = \text{ok}$ **implies**
 ($\text{thrust}(E1) = \text{on}$ **if and only if** $\text{flow}(V1) = \text{on}$ **and** $\text{flow}(V2) = \text{on}$))

Propositional Satisfiability

Given: a logical sentence S

Find: a truth assignment (true / false) that satisfies S :

1. Reduce S to *clausal form*.
2. Perform search + inference
 - similar to MAC = Backtrack + Constraint Propagation [Davis, Logmann & Loveland, 1962].

Propositional Satisfiability as Backtrack Search

Procedure: BT(Φ , A)

Input: A *cnf theory* Φ ,
An assignment A to some propositions in Φ .

Output: true if Φ is satisfiable; false otherwise.

If a clause in Φ is violated, Return false;

Else If all propositions in Φ are assigned by A , Return true;

Else Q = some proposition in Φ that is unassigned by A ;

Return (BT(Φ , $A[Q = \text{True}]$) or

BT(Φ , $A[Q = \text{False}]$))

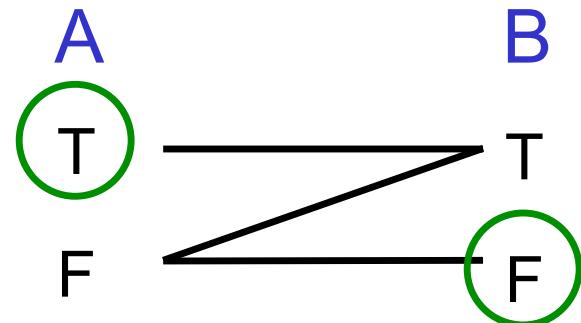
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Unit Clause Resolution

Idea: Apply arc consistency (AC-3) to binary clauses.

Clause: (not A or B)



Unit clause resolution (aka unit propagation rule):

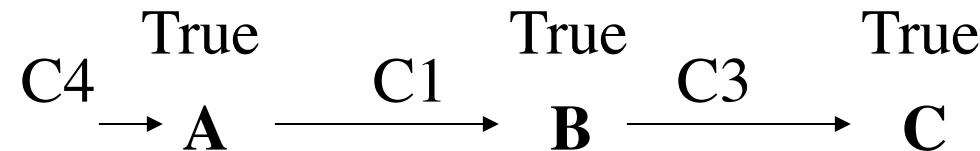
If all literals are false save L, then L must be true:

- $\frac{(\text{not } A) \quad (\text{not } B) \quad (\text{A or B or C})}{C}$
- Unit propagation = repeated application of unit clause resolution rule.

Unit Propagation Examples

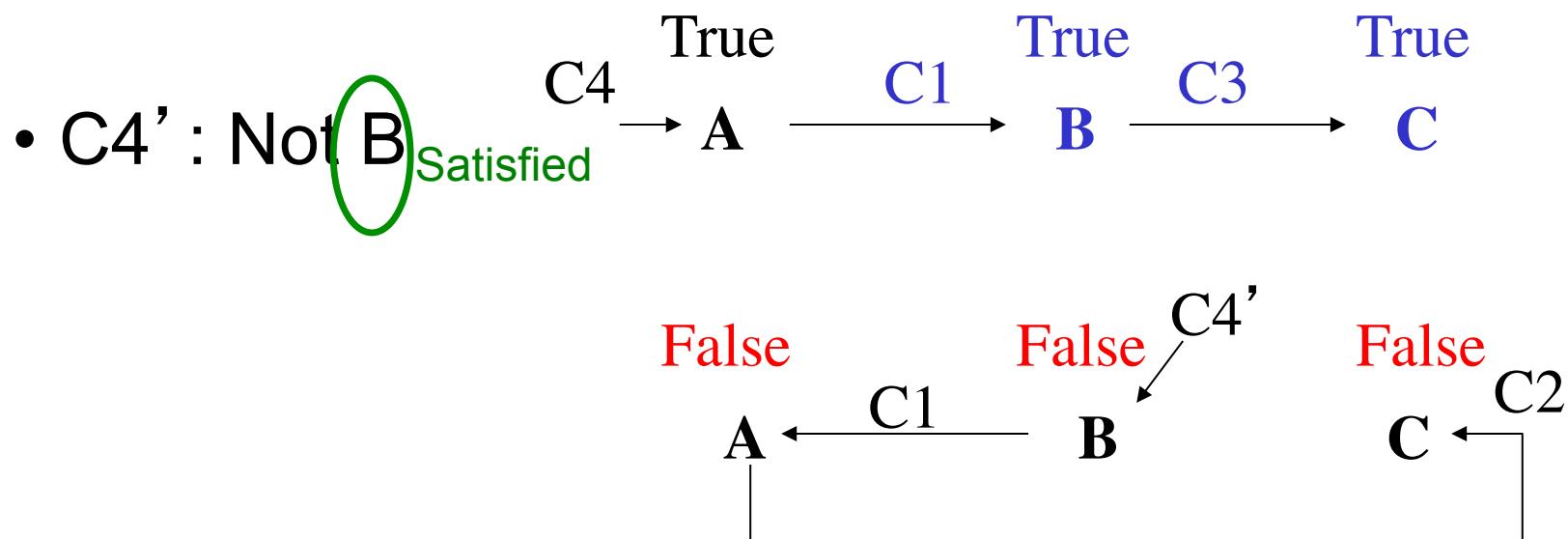
- C1: Not A or B Satisfied
- C2: Not C or A Satisfied
- C3: Not B or C Satisfied
- C4: A Satisfied

Support

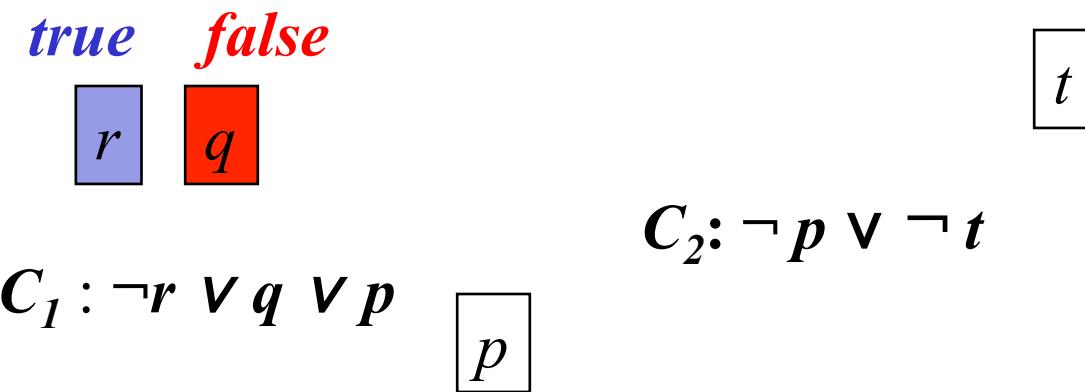


Unit Propagation Examples

- C1: Not A or B Satisfied
- C2: Not C or A Satisfied
- C3: Not B or C Satisfied
- C4: A

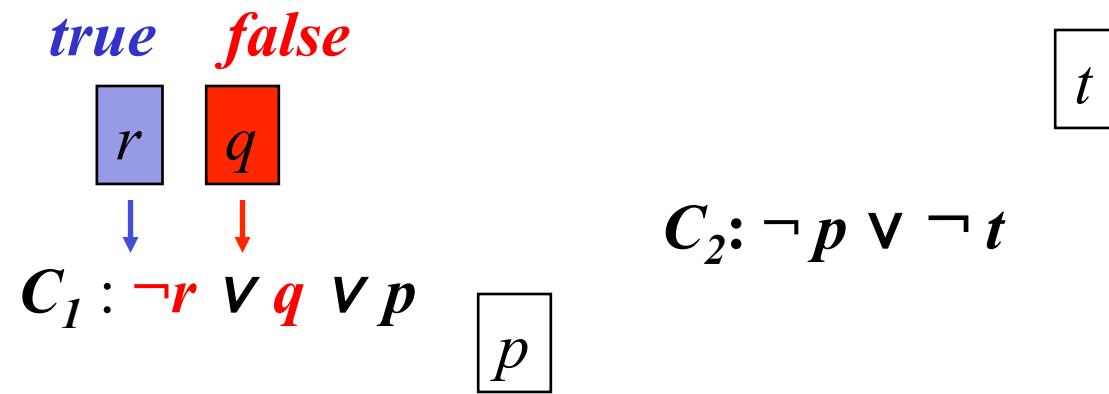


Unit Propagation



```
Procedure: propagate(C) // C is a clause
  if all literals in C are false except L, and L is unassigned
  then assign true to L and
        record C as a support for L and
        for each clause C' mentioning “not L”,
          propagate(C')
end propagate
```

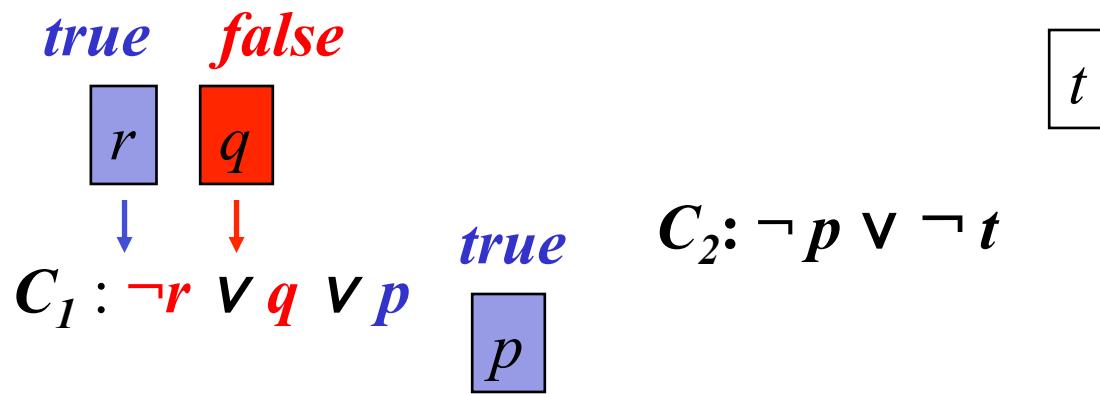
Unit Propagation



Procedure: *propagate(C)* // C is a clause

- if all literals in C are false except L , and L is unassigned
then assign true to L and
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 - for each clause C' mentioning “not L ”,
 - propagate(C')

Unit Propagation

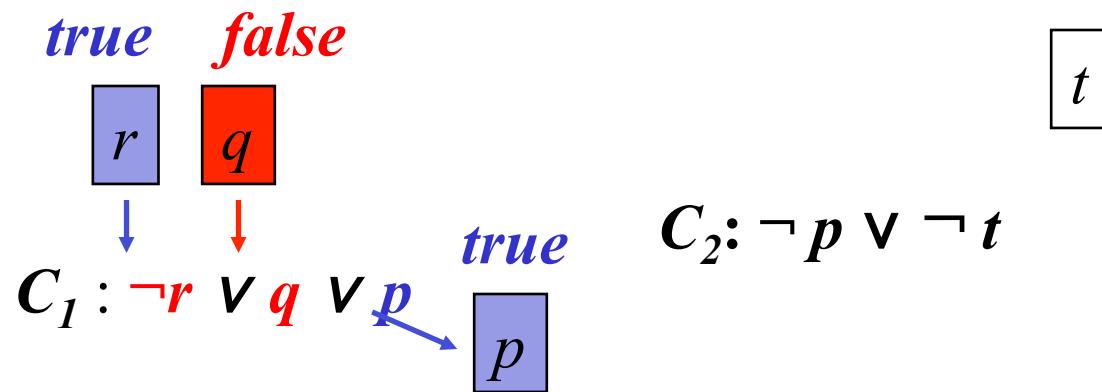


Procedure: $propagate(\mathbf{C})$ // \mathbf{C} is a clause

if all literals in \mathbf{C} are false except \mathbf{L} , and \mathbf{L} is unassigned
→ then assign true to \mathbf{L} and
record \mathbf{C} as a support for \mathbf{L} and
for each clause \mathbf{C}' mentioning “not \mathbf{L} ”,
 $propagate(\mathbf{C}')$

end $propagate$

Unit Propagation



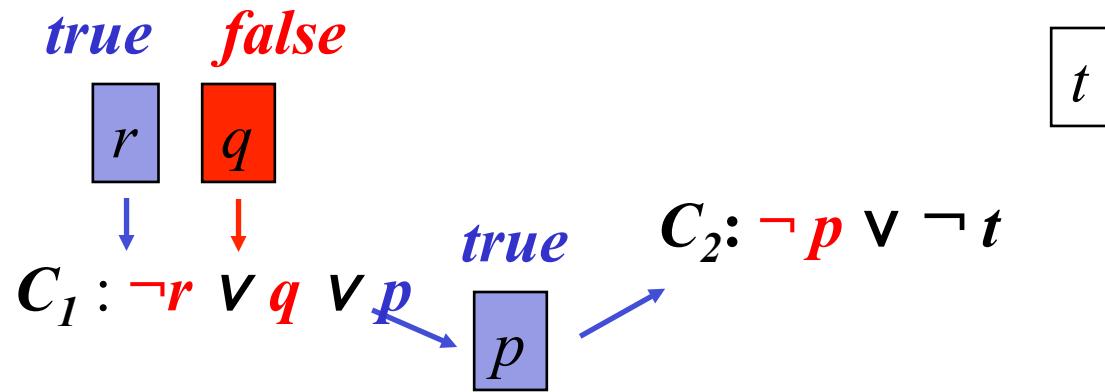
Procedure: $\text{propagate}(\mathbf{C})$ // \mathbf{C} is a clause

if all literals in \mathbf{C} are false except \mathbf{L} , and \mathbf{L} is unassigned
then assign true to \mathbf{L} and

- record \mathbf{C} as a support for \mathbf{L} and
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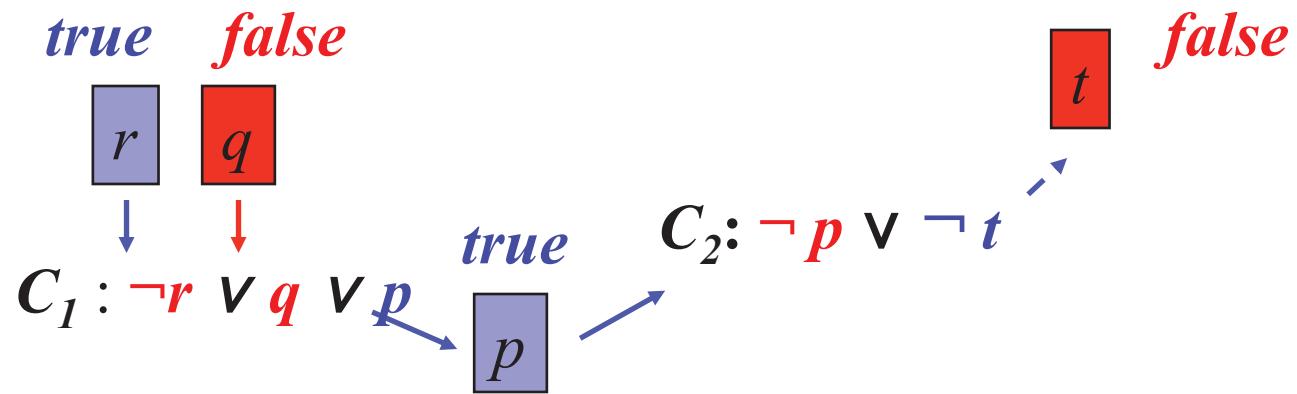
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Unit Propagation



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Propositional Satisfiability using DPLL

[Davis, Logmann, Loveland, 1962]

Initially:

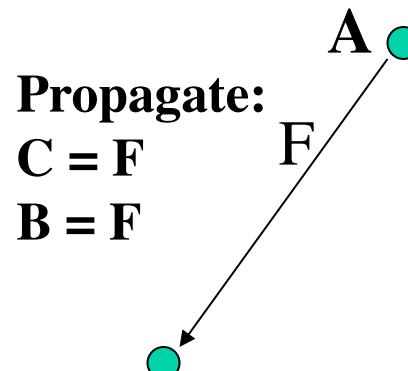
- Unit propagate.

Repeat:

1. Assign **true** or **false** to unassigned proposition.
2. Unit propagate.
3. Backtrack when clause violated.
4. Satisfiable if assignment complete.

Example:

- C1: Not A or B satisfied
- C2: Not C or ~~A~~ satisfied
- C3: Not B or ~~C~~ satisfied



Propositional Satisfiability using DPLL

[Davis, Logmann, Loveland, 1962]

Initially:

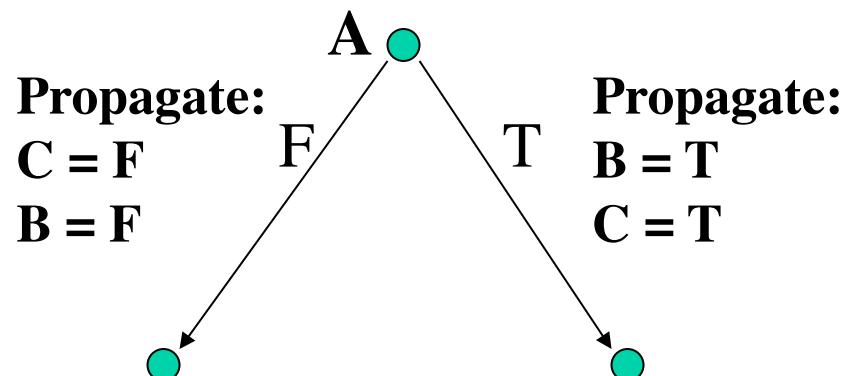
- Unit propagate.

Repeat:

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3. Backtrack when clause violated.
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Example:

- C1: ~~Not A or B~~ satisfied
- C2: ~~Not C or A~~ satisfied
- C3: ~~Not B or C~~ satisfied



How Do We Fold Unit Propagation into Backtracking?

Procedure: $\text{BT}(\Phi, A)$

Input: A *cnf* theory Φ ,
An assignment A to some propositions in Φ .

Output: A decision of whether Φ is satisfiable.

If a clause in Φ is violated, Return false;

Else If all propositions of Φ are assigned in A , Return true;

Else $Q = \text{some unassigned proposition in } \Phi$;

Return ($\text{BT}(\Phi, A[Q = \text{True}])$ or

$\text{BT}(\Phi, A[Q = \text{False}]))$

Hint: Like MAC and Forward Checking:

- limited inference
- apply inference after assigning each variable.

D(P)LL Procedure

[Davis, Logmann, Loveland, 1961]

Procedure: DPLL(Φ , A)

Input: A cnf theory Φ ,
An assignment A to propositions in Φ

Output: A decision of whether Φ is satisfiable.

→ A' = propagate(Φ);

If a clause in Φ is violated, given A' Return false;

Else If all propositions of Φ are assigned in A', Return true;

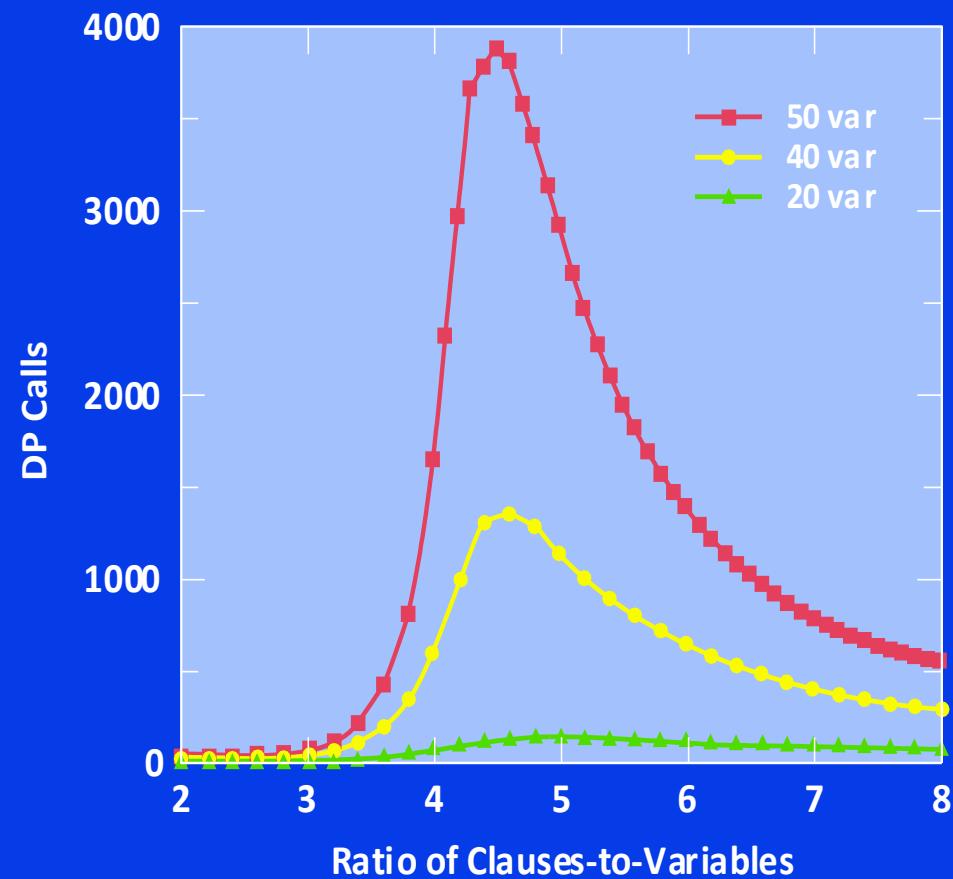
Else Q = some unassigned proposition in Φ ;

Return (DPLL(Φ , A' [Q = True]) or
DPLL(Φ , A' [Q = False]))

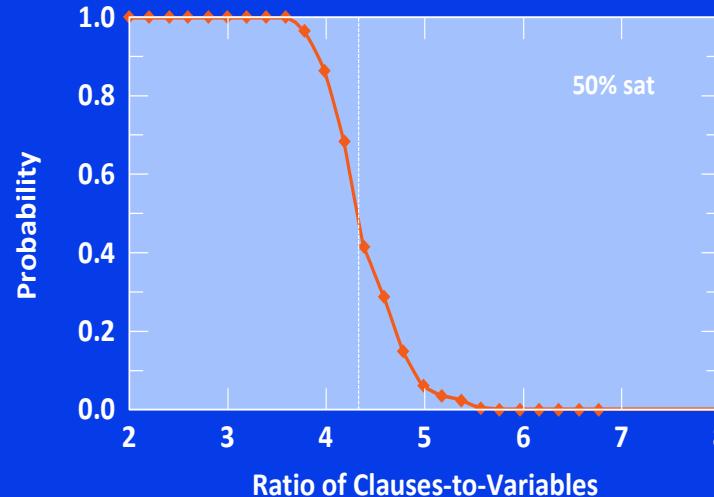
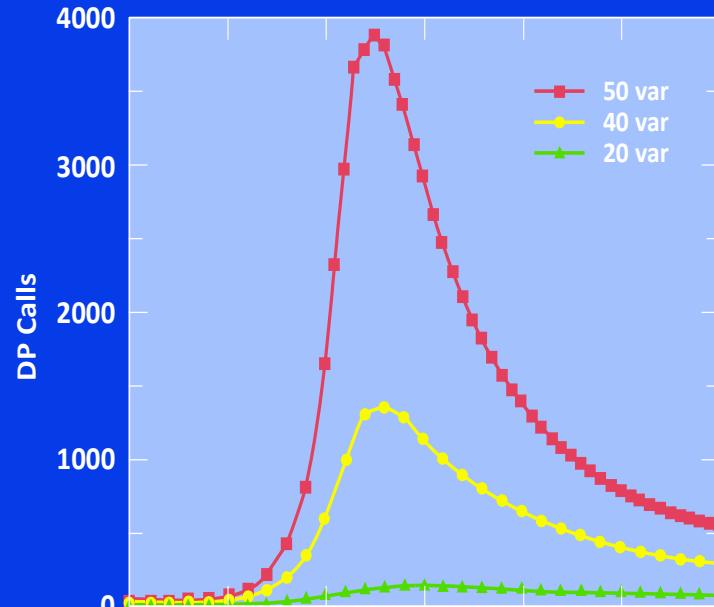
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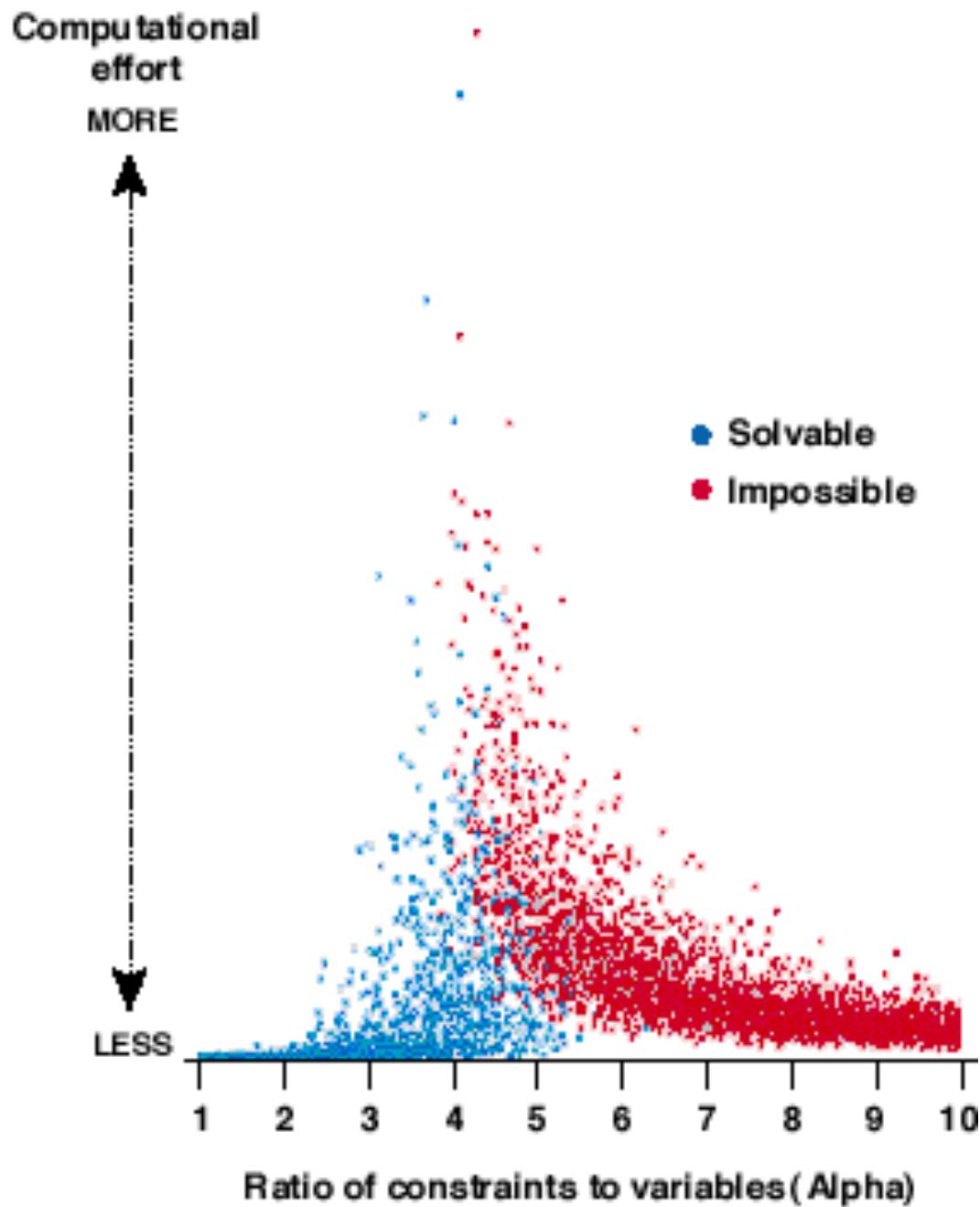
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Hardness of 3SAT



The 4.3 Point

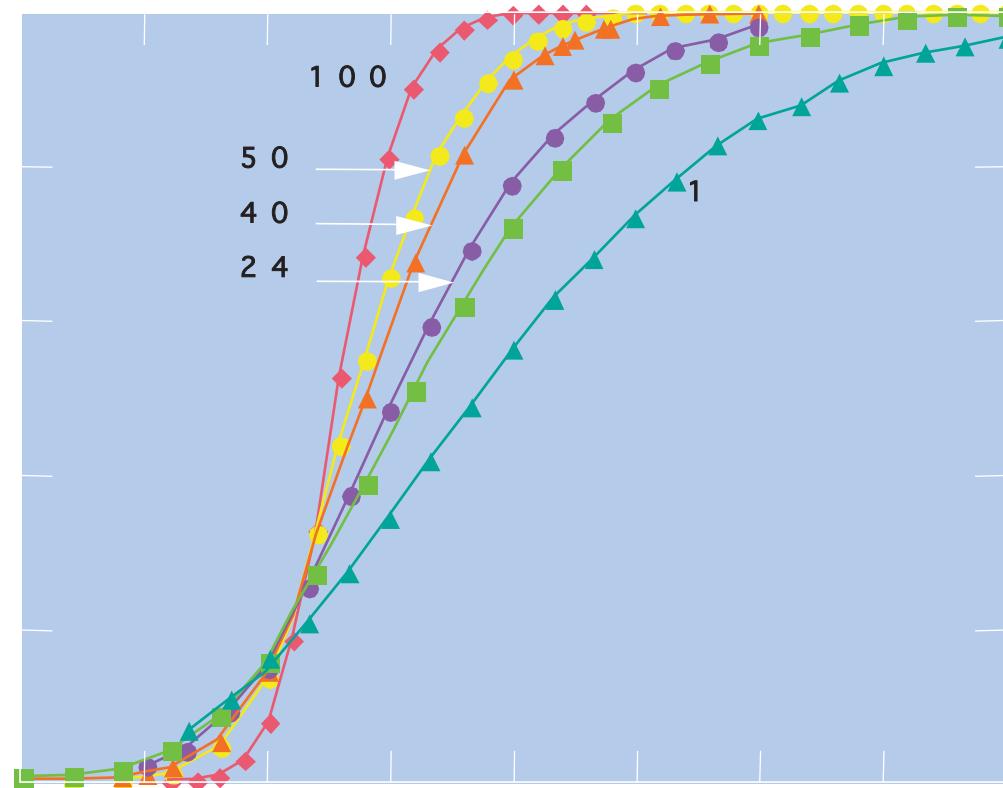




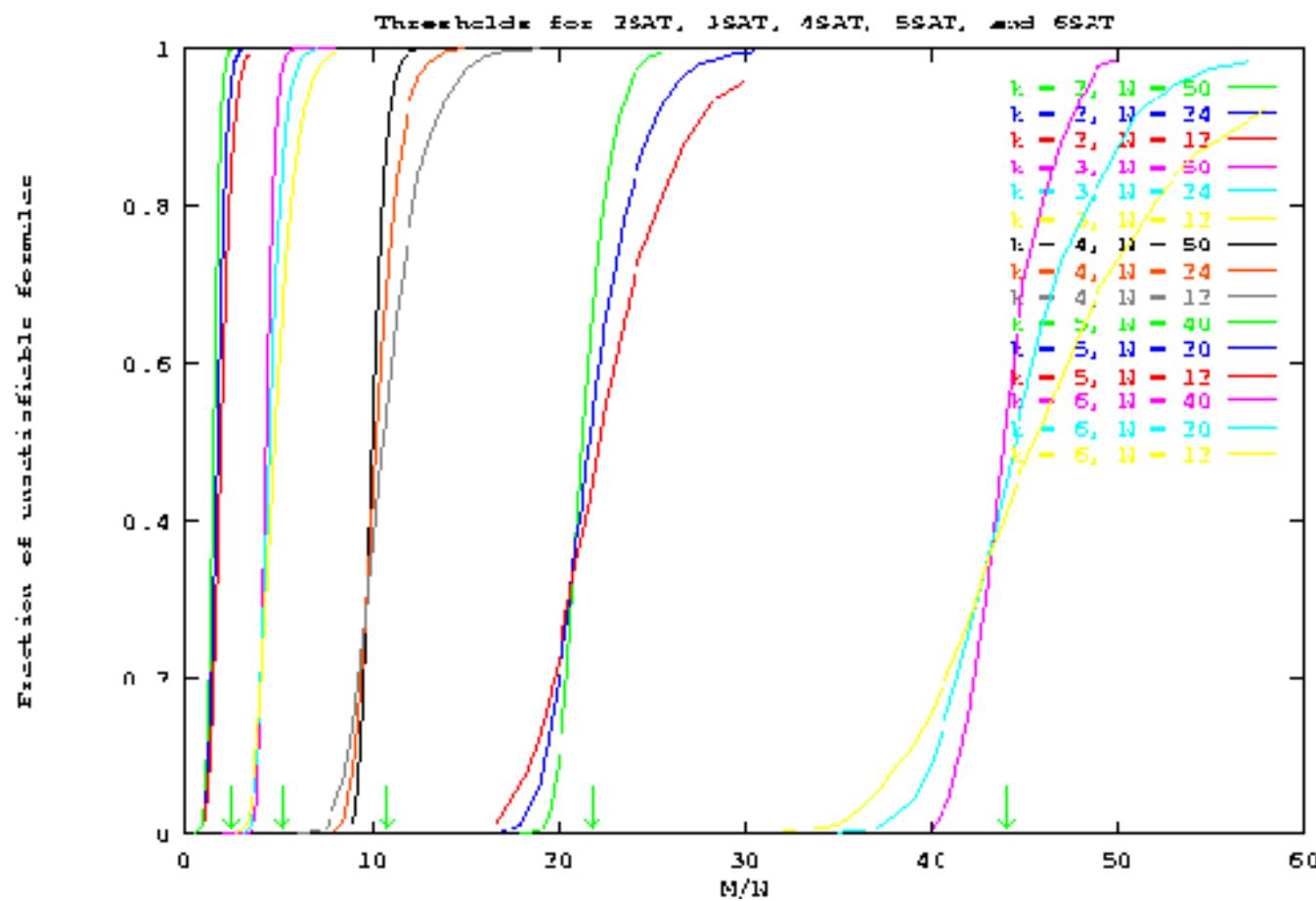
Intuition

- At low ratios:
 - few clauses (constraints),
 - many assignments,
 - easily found.
- At high ratios:
 - many clauses,
 - inconsistencies easily detected.

Phase Transitions for Different Numbers of Variables



Phase Transitions: 2, 3 4, 5 and 6-SAT



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16.412J / 6.834J Cognitive Robotics

Spring 2016

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