

Joint Name	World Coordinates (m)			Relative to last joint Coordinates (m)		
	X	Y	Z	X	Y	Z
Base	0	0	0	0	0	0
Base_Shoulder1	0	0	0.156	0	0	0.156
Shoulder1_Halfarm1	0	-0.005	0.285	0	-0.005	0.129
Halfarm1_Halfarm2	0	-0.012	0.495	0	-0.007	0.21
Halfarm2_Forearm1	0	-0.018	0.706	0	-0.006	0.211
Forearm1_Sphericalwrist1	0	-0.025	0.914	0	-0.007	0.208
Sphericalwrist1_Sphericalwrist2	0	-0.025	1.02	0	0	0.106
Sphericalwrist2_EECoupler	0	-0.025	1.126	0	0	0.106