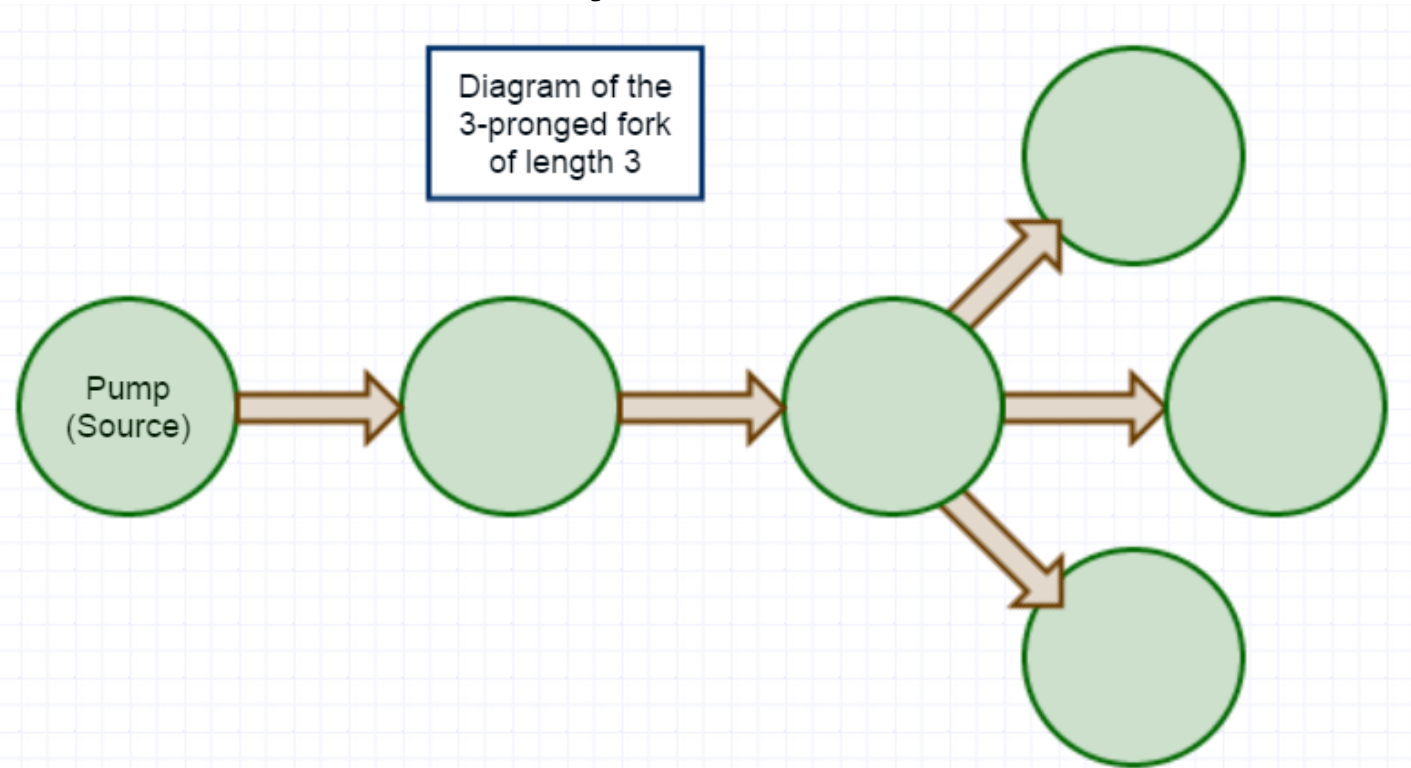


# A network model for multicellularity

Christopher Ebsch  
Francesco Pancaldi



# Outline

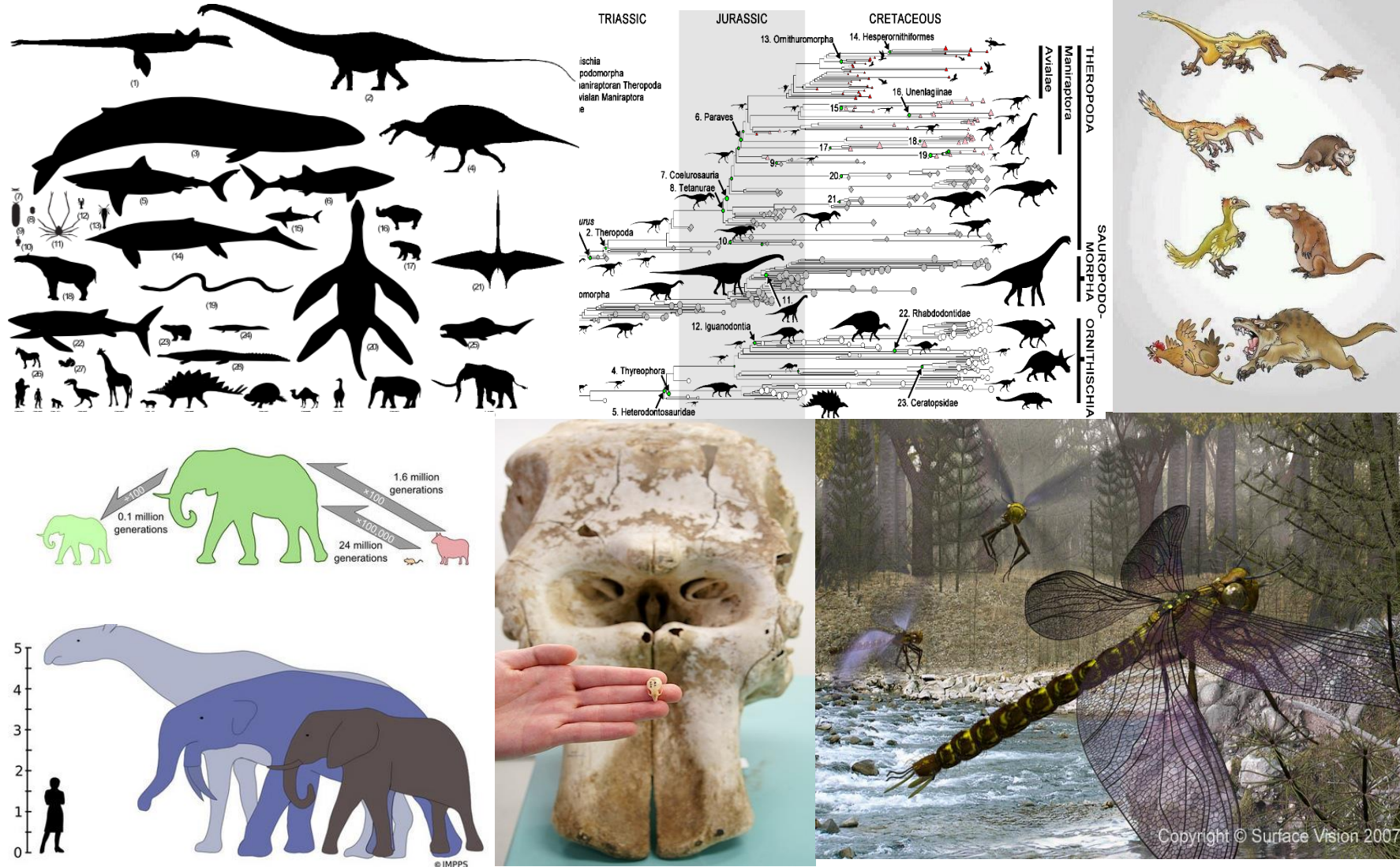
- Summary of previous direction
- Assumptions of the updated model
- Two canonical networks
- Critical energy
  - Example
- Extensions to other networks
- Robustness
  - Example
- Recursive formulation of critical energy (in progress)
- Future directions

# Summary of previous direction

Previous Goal: Model evolution of animal size.



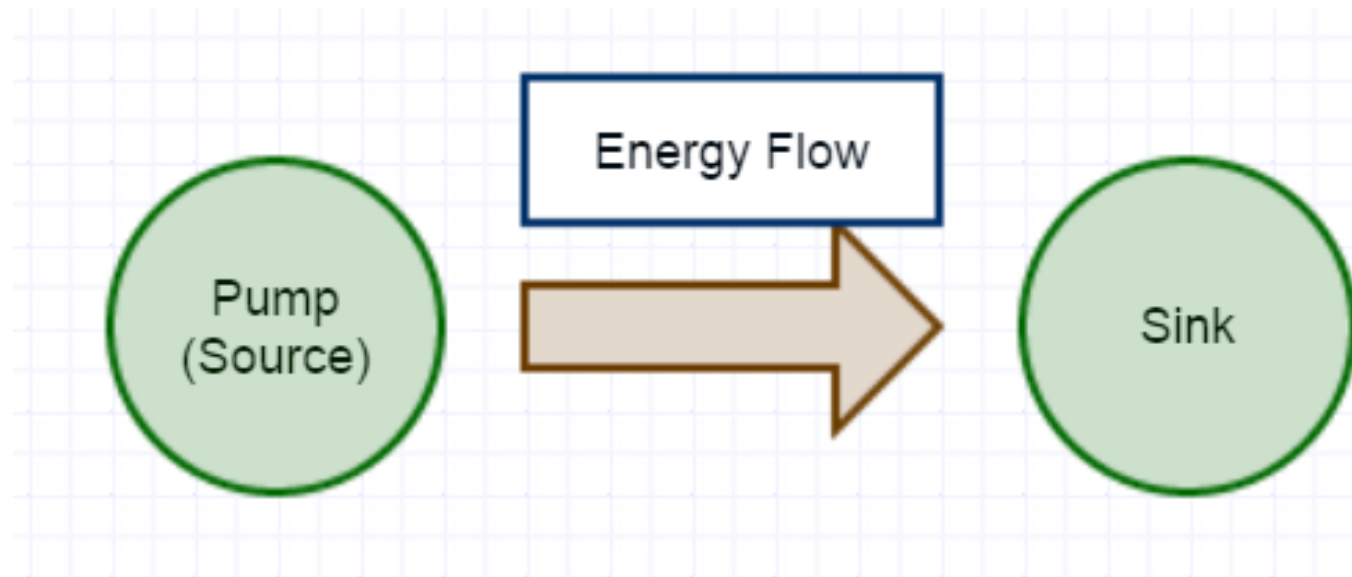
New Goal: Model of optimal sizes and structures for energy transport in biological networks.



# Basic network structure

- Begin with a connected, directed network of  $N$  nodes with energy source (pump).
- Energy,  $E(N)$ , is gathered by the pump
- Each node (including the pump) consumes a fixed amount of energy,  $C$ , that it receives.
- The remaining energy at that node,  $E(N)-C$ , is divided equally to its outgoing edges.
- A portion,  $1-p$ , of the energy being transported is lost to the environment (with  $0 < p \leq 1$ ).

Repeat until all nodes have consumed  $C$  energy or the energy remaining in the system is less than amount needed to sustain any unfed nodes. Unfed nodes at the end of a feeding cycle will be considered dead. A dead cell no longer consumes energy, but maintains connections.

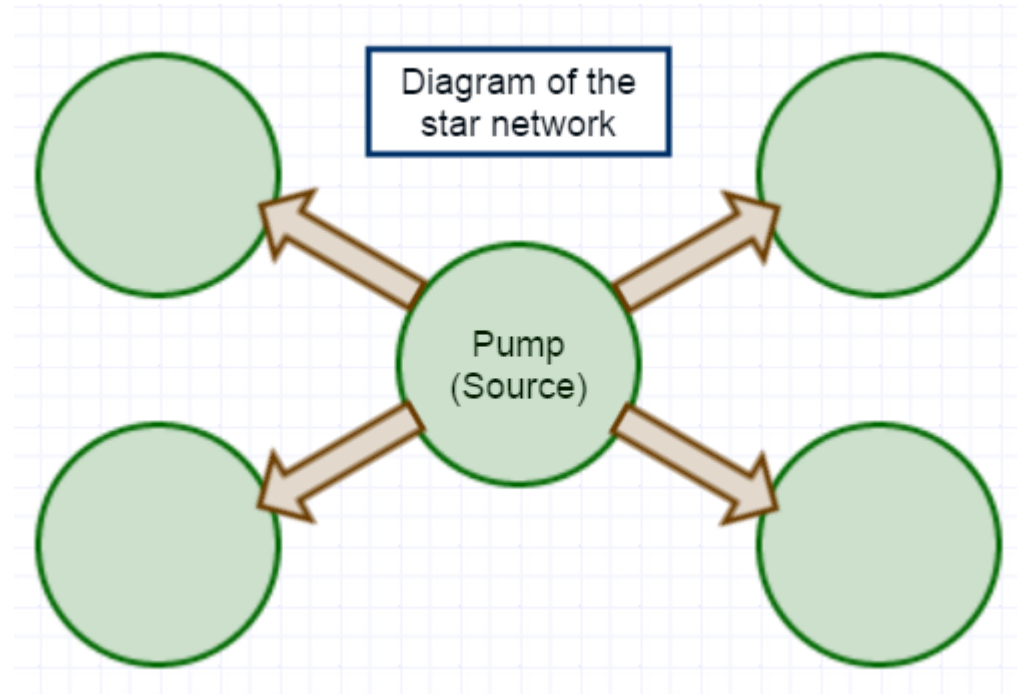


# Assumptions of the model

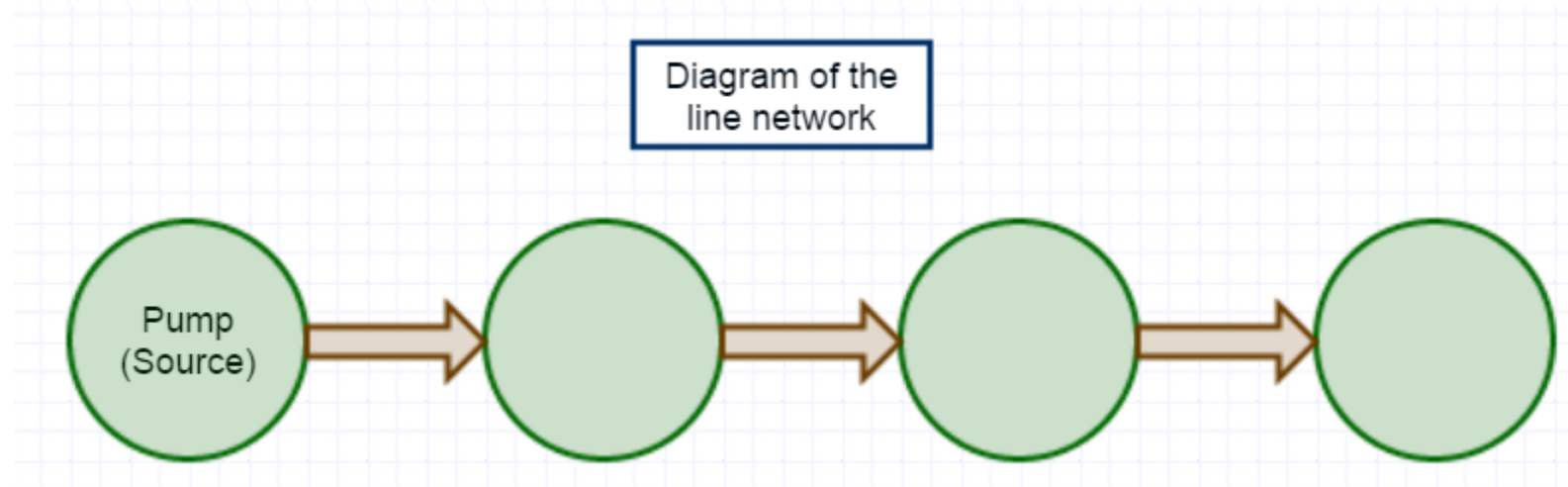
- Energy gathered at a given time step is monotonically increasing in the number of surviving nodes and is bounded by  $\bar{E}$ .
- The parameters of the energy function,  $E(\mathbf{N})$ , and the bound  $\bar{E}$  can fluctuate with a certain random distribution (ex: Gaussian)
- After  $N$  feeding cycles, the network can reproduce and mutate at random, then the process is repeated (in progress).

# Two canonical topologies

- The star connects the pump to all other nodes in the network and there are no other connections



- The line connects each node sequentially with the next one in a list.



# Critical energy

- The critical energy,  $E^*(N,T)$ , is defined as the minimum energy needed to keep all nodes in the network alive with  $T$  being the structure of the network.
- In general, we calculate the critical energy by taking the maximum value of the energies needed for survival along every path leaving the pump.

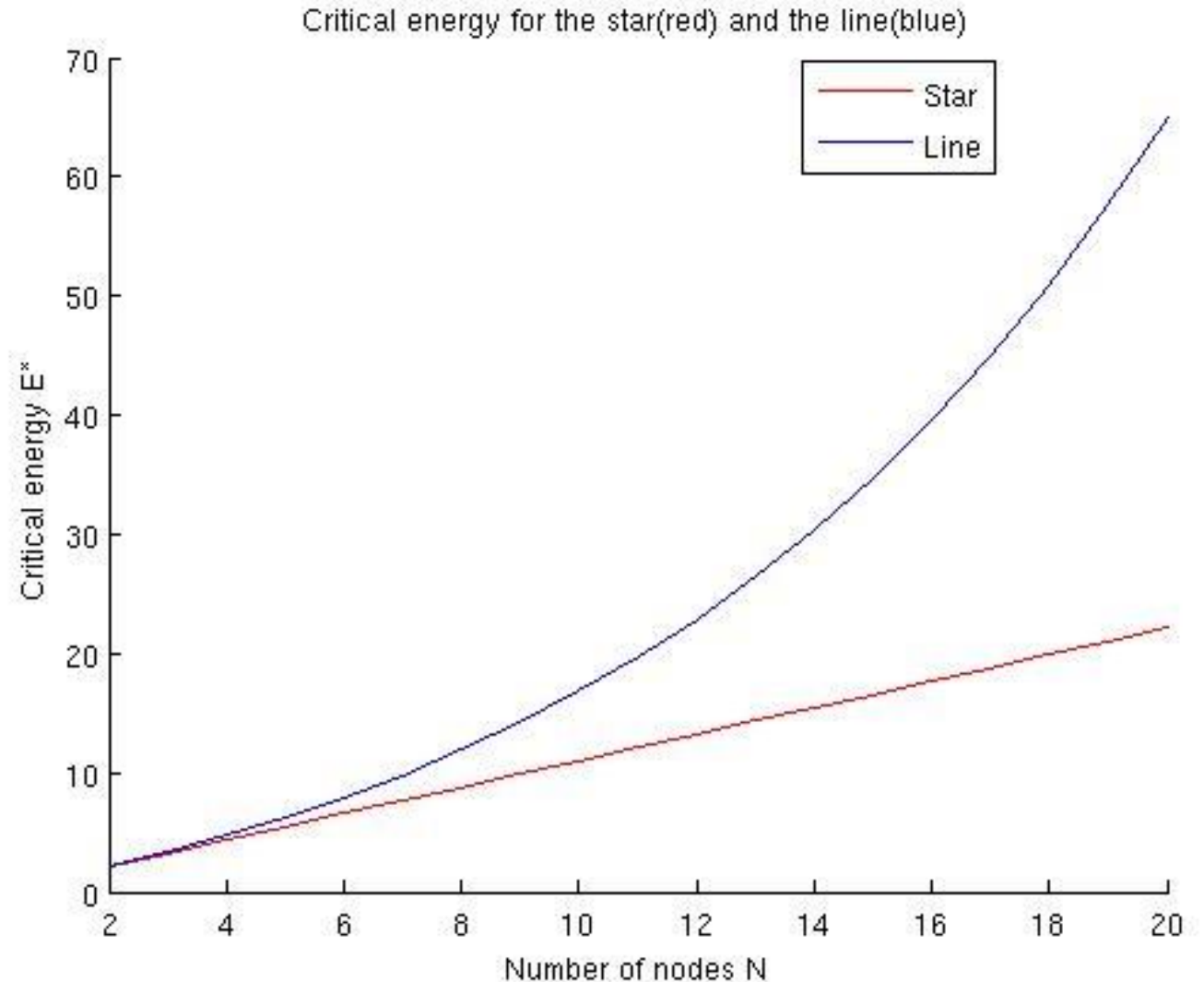
# Example: Calculating critical energy

- Let  $N=3$
- Then there are 2 topologies the line, say  $T_L$ , and the star,  $T_S$
- On the line there is only 1 path leaving the pump so we calculate  $[(E(3) - C) * p - C] * p - C > 0$ , then  $E^*(3, T_L) = \min(E(3))$  such that the inequality remains true.
- On the star there are 2 equal paths so it suffices to calculate along one of them so that:  $\left[ \frac{E(3) - C}{2} * p \right] - C > 0$ , then  $E^*(3, T_S) = \min(E(3))$ .



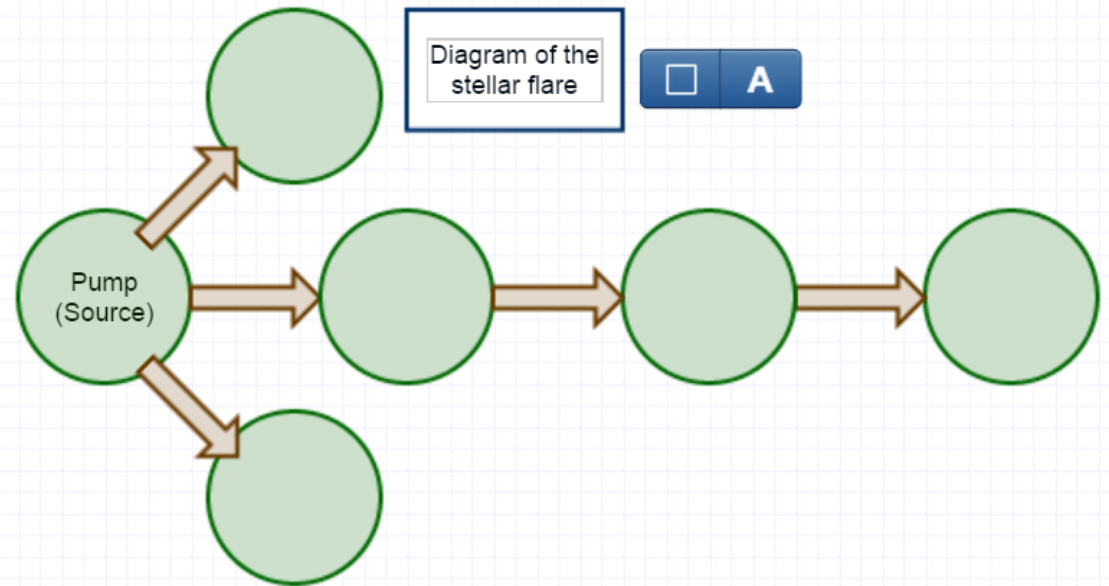
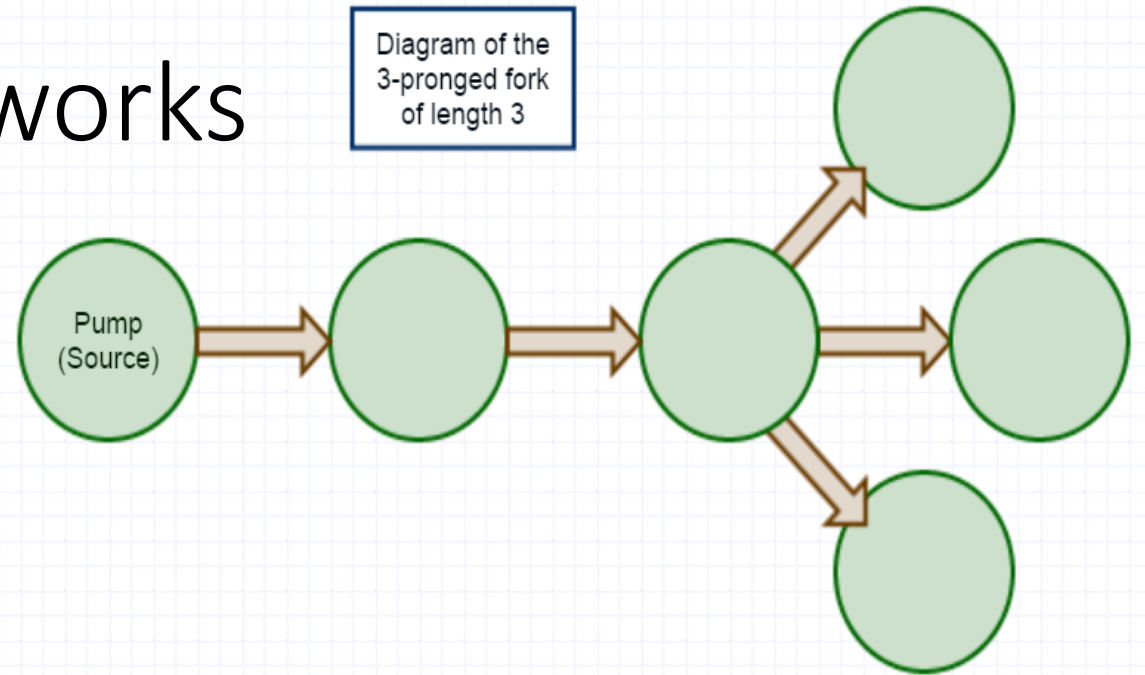
# Critical energies by varying N

In this graph we use  $C=1$   
and  $p=0.9$



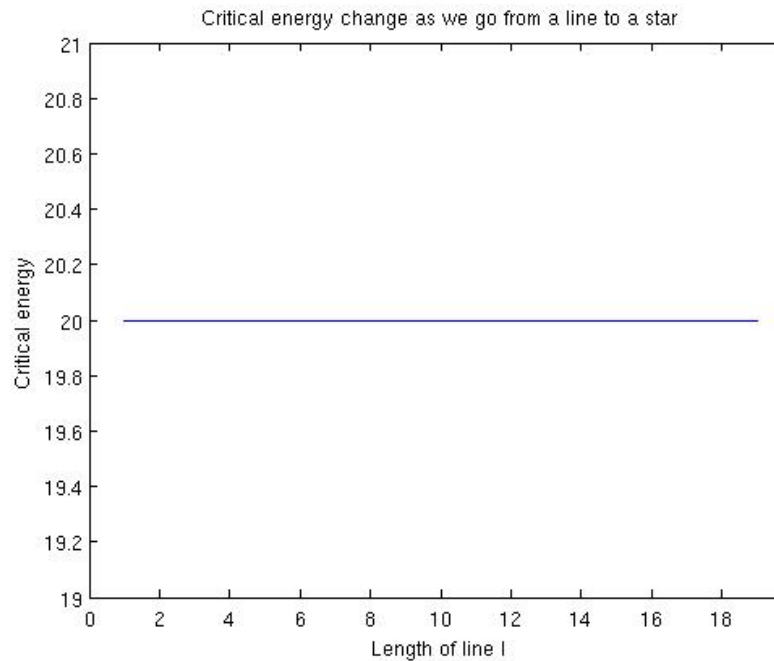
# Extending to other networks

We define two quantities,  $S$  and  $L$  with  $S+L=N$ , where  $S$  and  $L$  go from 1 to  $N-1$ .  $S$  is the number of points in the star-like part.  $L$  is the length of the longest path without counting the center of the star.

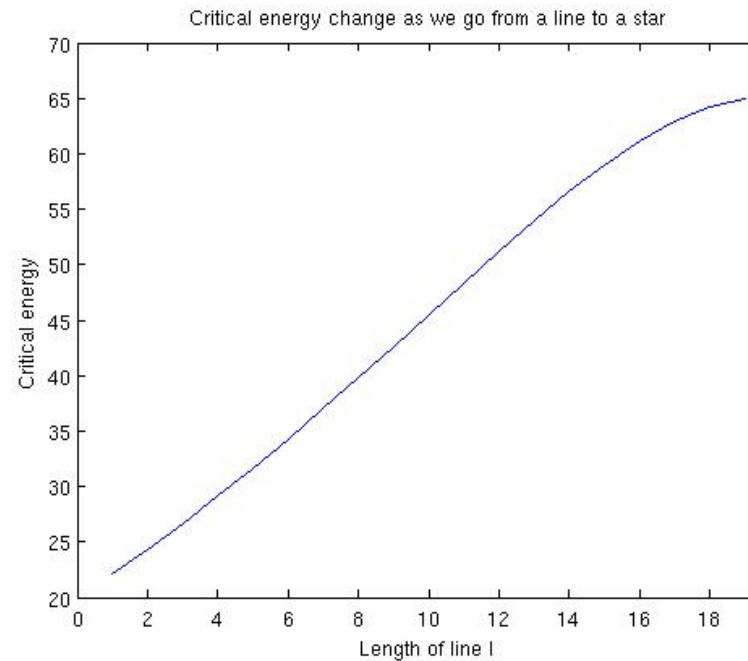


# Plot of critical energy for $N=20$ of the fork

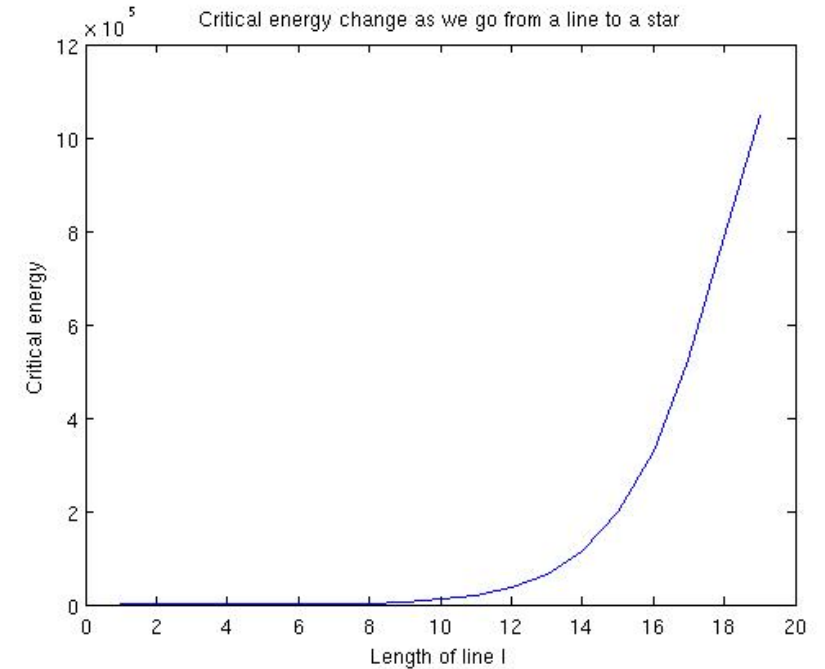
$p=1$



$p=0.9$

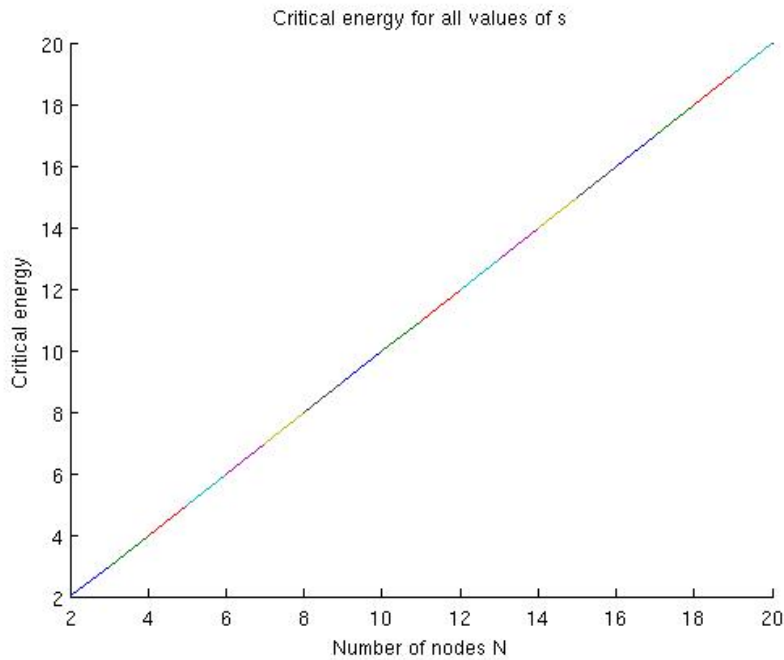


$p=0.5$

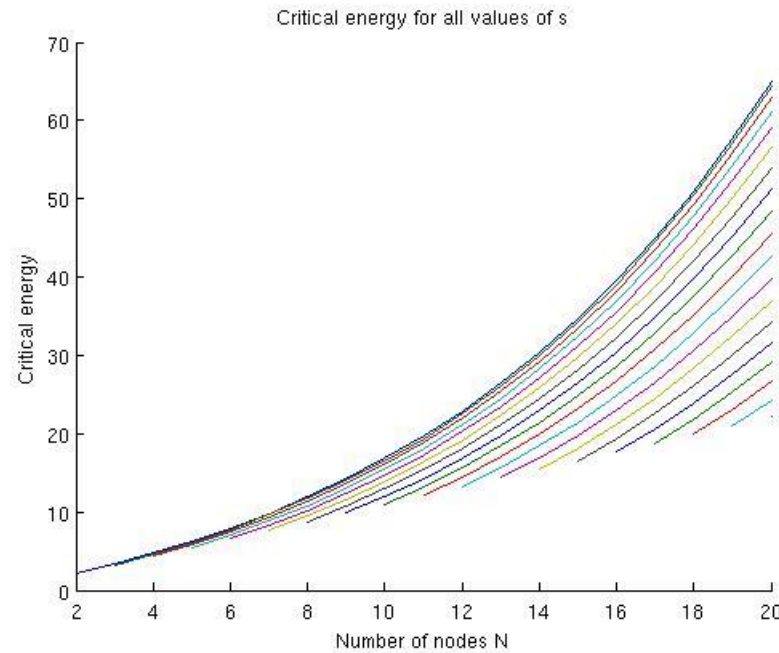


# Plots of critical energy for fork varying N plotting S in the range 1 to N-1

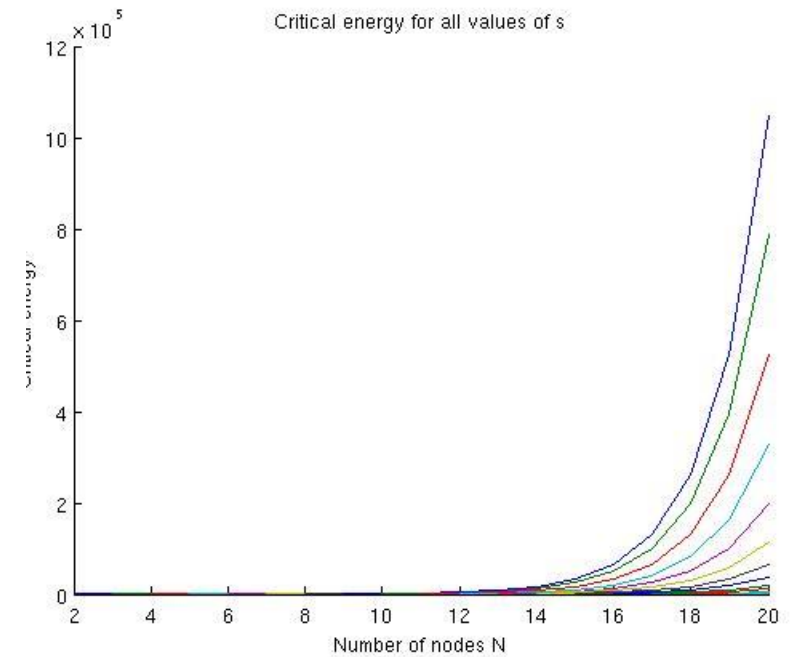
$p=1$



$p=0.9$

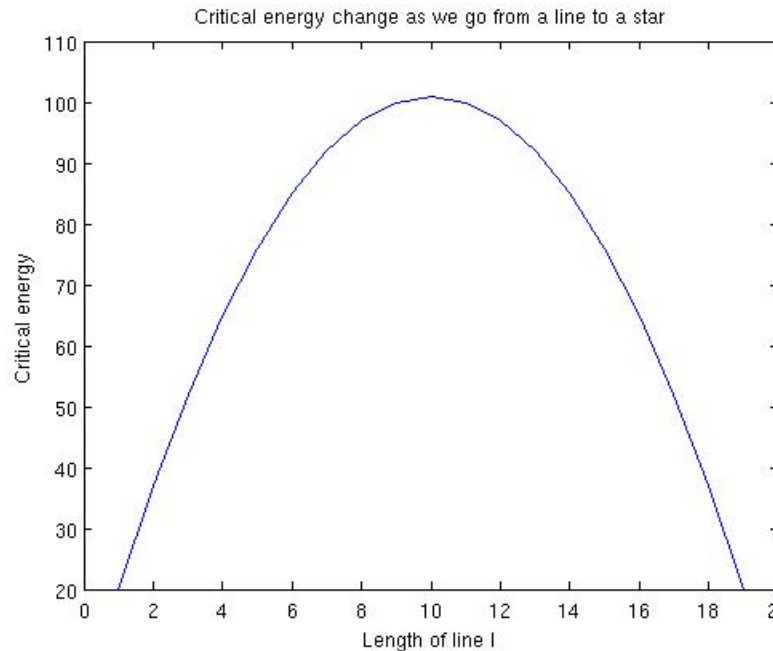


$p=0.5$

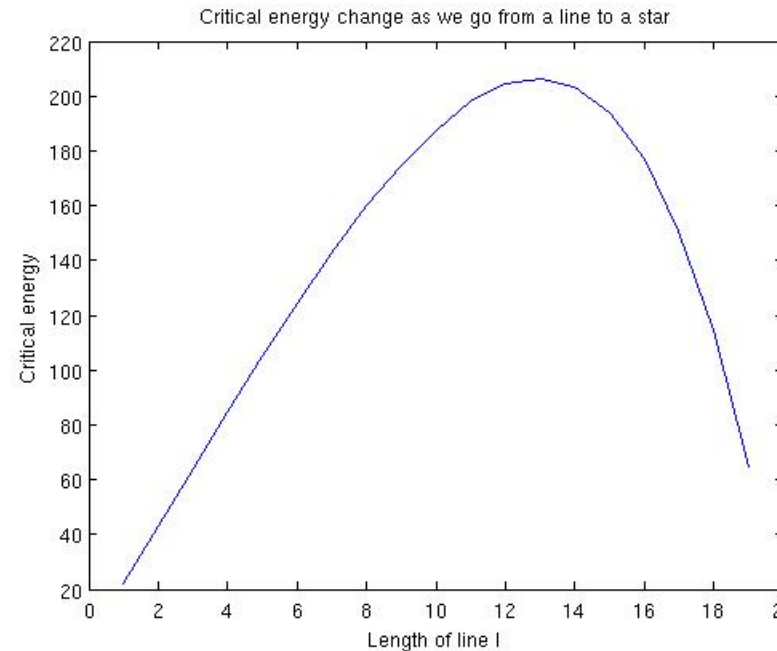


# Critical energy for the stellar flare with constant $N=20$

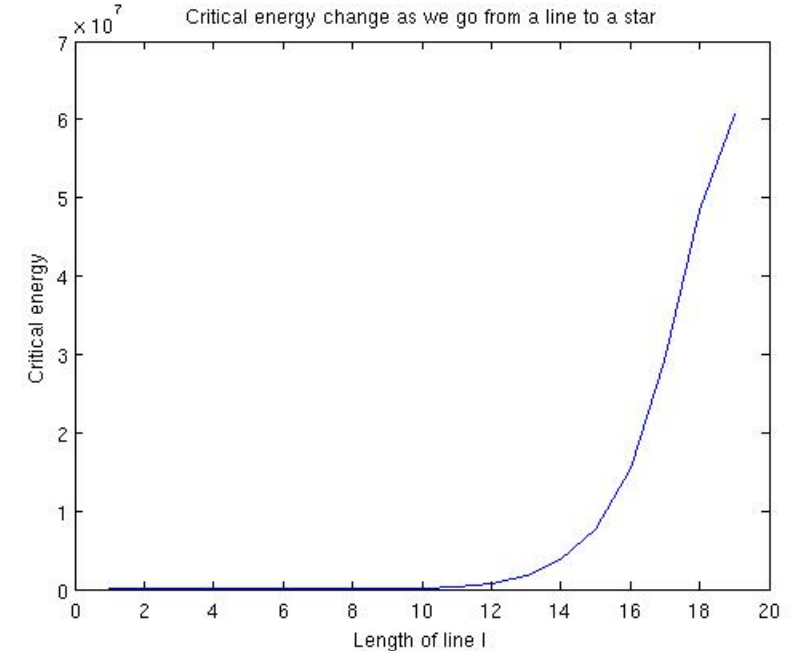
$p=1$



$p=0.9$

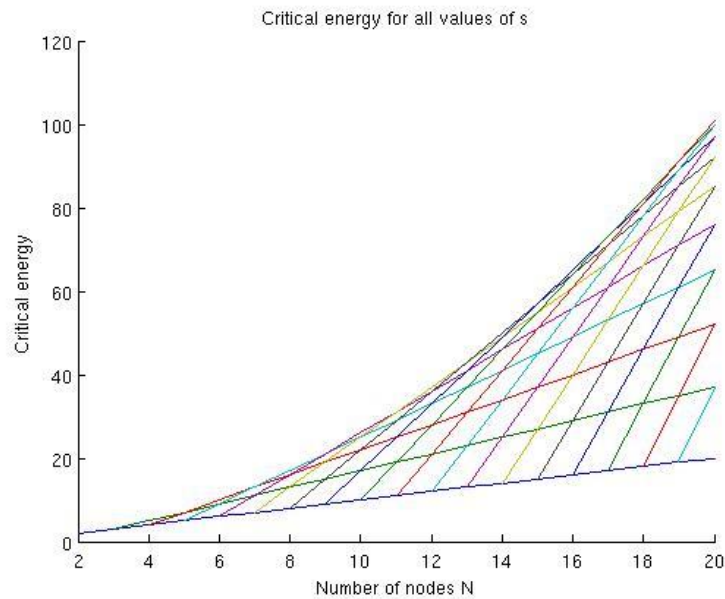


$p=0.4$

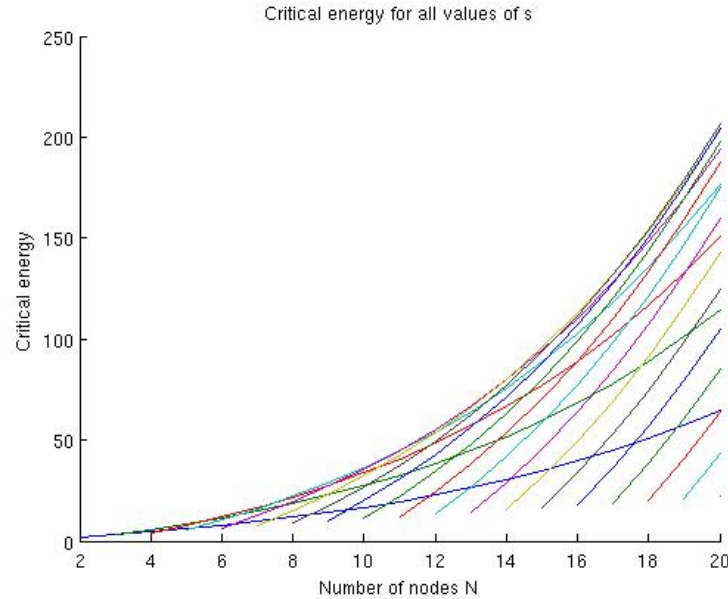


# Critical energy of the stellar flare varying $N$ and plotting $S$ in the range 1 to $N-1$

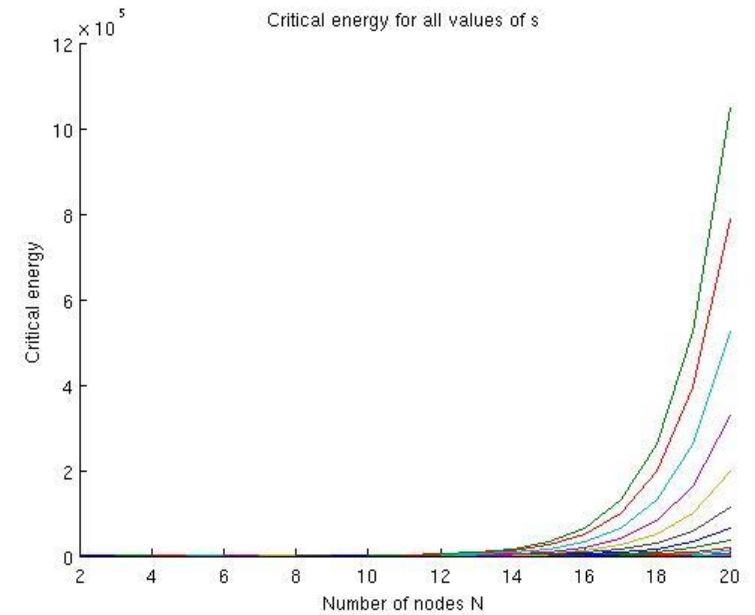
$p=1$



$p=0.9$



$p=0.5$



# Robustness

- A robust system is one that loses a small proportion of its total cells when it first drops below the critical energy.

More robust

Least robust

Diagram of the  
line network

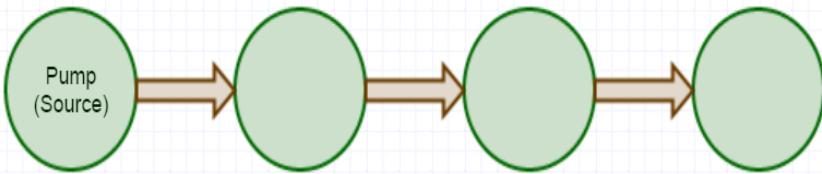


Diagram of the  
3-pronged fork  
of length 3

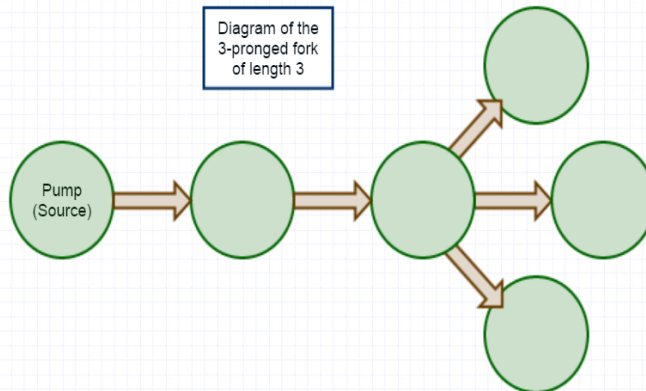
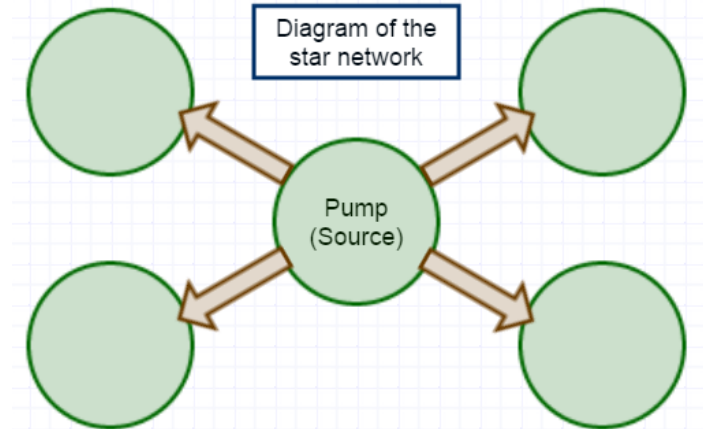


Diagram of the  
star network



# Recursive formula for critical energy (in progress)

- Idea: Develop a recursive formula dependent on the energy function and the branching factor at each node.



# Future directions

- Additional topologies analyzed
- Verification of simulation
- Exploring other possible fitness metrics
- **Evolutionary simulations**

# Thank you for your attention!

