# CS 113: Mathematical Structures for Computer Science

Dr. Francis Parisi

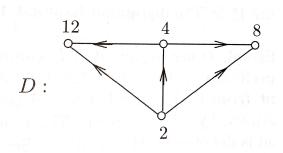
Pace University

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## **Directed Graphs**

Chapter 15

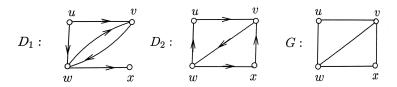
- A directed graph or digraph is a common modeling tool when the ordering of the vertices of a graph are important
- Suppose for vertex set  $V = \{2, 4, 8, 12\}$  there is a directed line segment from vertex i to vertex j, and  $i \neq j$ , if  $i \mid j$ .



#### Definition

A digraph or directed graph D is a finite nonempty set of V(D) of vertices and set E(D) of ordered pairs of distinct vertices of D, each ordered pair of which is called a **directed edge** or an **arc**.

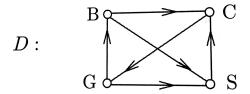
- ► A directed edge (*u*, *v*) is drawn as a directed line segment (arrow)
- For a directed edge e = (u, v) u is the **initial vertex**
- v is the terminal vertex
- ▶ In a graph (u, v) and (v, u) represent the same edge
- ► In a digraph (u, v) and (v, u) represent different directed edges
- ▶ If for each pair u, v at most one of (u, v) and (v, u) is a directed edge, then the graph is an **oriented graph**



- ▶ *D*<sub>1</sub> is not oriented, but *D*<sub>2</sub> is oriented
- $ightharpoonup D_2$  is and orientation of graph G

## Example

Soccer teams from Brazil, China, Germany, and Spain play one another. Brazil beats China and Spain, Germany beats Brazil and Spain, Spain beats China, and China defeats Germany. How do we model this as a digraph?



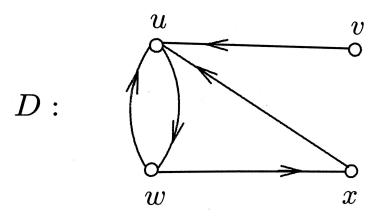
- ► Two vertices u and v in a digraph D are **adjacent** if there is at least one directed edge (u, v) or (v, u)
- If (u, v) is a directed edge we say u is adjacent to v and v is adjacent from u
- ► The number of vertices to which a vertex v is adjacent is the outdegree of v denoted by od v or od(v)
- ► The number of vertices from which a vertex v is adjacent is the indegree of v denoted by id v or id(v)

Theorem (The First Theorem of Digraph Theory)

If D is a digraph of size m, then

$$\sum_{v \in V(D)} \operatorname{od} v = \sum_{v \in V(D)} \operatorname{id} v = m.$$

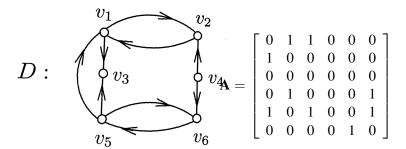
This is illustrated in the following figure



#### **Definition**

The **adjacency matrix**  $\mathbf{A} = [a_{ij}]$  of a digraph D with  $V(D) = \{v_1, v_2, \dots, v_n\}$  is defined as expected just like for a graph,

$$a_{ij} = \begin{cases} 1 \text{ if } (v_i, v_j) \in E(G) \\ 0 \text{ otherwise.} \end{cases}$$



- Finite state machines describe and increasing number of input-output devices – some examples
  - pushing a sequence of buttons on your phone followed by the talk button connects to another person's phone
  - entering information at a web site and clicking "complete order" places an online order
  - placing coins in a vending machine and pushing a button to make a selection for a candy bar
  - and of course a computer is an input-output device
- A finite state machine is also know as a sequential circuit

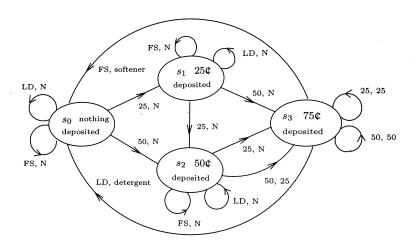
## Example

Consider a laundromat that has a machine to dispense laundry detergent and fabric softener. It costs  $75 \diamondsuit$  to purchase laundry detergent or fabric softener. This can be modeled as a finite state machine.

| Time   | $t_0$       | $t_1$       | $t_2$       | $t_3$      | $t_4$ |
|--------|-------------|-------------|-------------|------------|-------|
| State  | $s_0$       | $s_1$       | $s_2$       | <i>S</i> 3 | $s_0$ |
| Input  | <b>25</b> ¢ | <b>25</b> ¢ | <b>25</b> ¢ | LD         |       |
| Output | nothing     | nothing     | nothing     | detergent  |       |

#### A finite-state machine consists of:

- 1. a finite set S of internal states
- 2. a finite input set I
- 3. a finite output set O
- 4. a next-state (or transition) function  $f: S \times I \rightarrow S$
- 5. an **output function**  $g: S \times I \rightarrow O$



**Finite-State Automata** Finite-State Machines that produce no output

A finite-state automaton (singular for automata) consists of:

- 1. a finite set S of states
- 2. a finite set I of input values
- 3. a **transition function** *f* that associates a next step with each state-input pair

An example is the network of roads in a town; the inputs are directions (right turn, left turn, go straight) and each new intersection (location) is a state.

## Graphs - Key Results

► The First Theorem of Digraph Theory: If *D* is a digraph of size *m*, then

$$\sum_{v \in V(D)} \operatorname{od} v = \sum_{v \in V(D)} \operatorname{id} v = m.$$

- Finite-State Machine: A structure consisting of
  - 1. a finite set S of internal states
  - 2. a finite input set I
  - 3. a finite output set O
  - 4. a next-state (or transition) function  $f: S \times I \rightarrow S$
  - 5. an **output function**  $g: S \times I \rightarrow OS$
- Finite-State Automaton: A structure consisting of
  - 1. a finite set S of states
  - 2. a finite set I of input values
  - 3. a **transition function** *f* that associates a next step with each state-input pair