Fletcher Porter

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University of California, Santa Barbara (UCSB) · Bachelors · Graduated August 2019

- Major in Mechanical Engineering
- Exchange study from Aug. 2017 to June 2018 at Lunds Tekniska Högskola (LTH) in Lund, Sweden
- Courses in robotic control at UCSB including physics-based modeling
- Courses in design with polymer composite materials, batteries, and fuel cells at LTH

Experience

- NASA Jet Propulsion Laboratory · Robotics Intern · 11 June 2018–7 Sep. 2018 Designed and led the fabrication and assembly of the mechanical and electrical systems for a gravity-offload system (GOS) used to study robotic mobility for future missions to icy moons
- Developed and implemented a control system for the GOS that uses computer vision
- Operated the disaster recovery robot RoboSimian to conduct tests
- Conceived novel robotic systems for a sampling system to study soil in Death Valley, California

Hawkes Group, UCSB · Undergraduate Researcher · March 2019—Sep. 2019

- Developed soft robots for application in aircraft wing inspection
- Designed magnetic tool mounts for soft, vine-like robots
- Developed models for jump height of a carbon fiber-bow jumping robot

NASA Jet Propulsion Laboratory · Robotics Intern · 14 June 2016–26 Aug. 2016 – Designed a level wind for the Deep Subsurface Access (DSA) probe

- Performed testing on DSA drivetrain to verify the design for the larger assembly
- Generated creative ideas for a sample transfer mechanism on the DSA probe
- Designed, built, and tested the actuation for an extensible arm for sampling on Europa

NASA Jet Propulsion Laboratory · Robotics Intern · June-Aug. 2014, Oct. 2015-May 2016

- Designed components for a novel robotic manipulator for RoboSimian
- Rapid prototyped components using a laser cutter and 3D printer to aid iterative design
- Developed roller skates for RoboSimian to significantly increase locomotive speed

Projects

Capstone Course Design Project (UCSB) · Automatic Stair Climbing Vehicle · Sep. 2018–June 2019 – Designed, built, and tested a motorized dolly that climbs stairs while carrying a heavy payload

- Machined most of the not-off-the shelf components by hand with a mill and lathe

Mechatronics Course Design Project (LTH) · Camera Cleaning System · Aug. 2017–May 2018 - Designed and built a lens cleaning system for Axis Communications security cameras

FIRST Tech Challenge · Student Robotics Mentor · June 2015–Present Teaching high school students engineering design

Publications	

B. H. Wilcox, J. A. Carlton, J. M. Jenkins, and F. Porter, "A deep subsurface ice probe for Europa," in 2017 IEEE Aerospace Conference, pp. 1–13, March 2017.

A portfolio of my work can be found at http://portfolium.com/fporter