

# Fletcher Porter

+358 41 476 3167 · [me@fletcherporter.com](mailto:me@fletcherporter.com) · <http://fletcherporter.com>

I'm a jack-of-all-trades engineer with particular skill in software development and mechanical design. I love to get my hands dirty in every piece of a system. I find joy in having a broad understanding of everything and intimate knowledge of a few things I get to own.

## Education

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**Aalto University** · MS Mechanical Engineering · Expected June 2024  
– Specializing in Mechatronics

**University of California, Santa Barbara (UCSB)** · BS Mechanical Engineering · Sept. 2019  
– Exchange study in 2017-2018 at Lunds Tekniska Högskola (LTH) in Lund, Sweden  
– Courses in robotics, design with polymer composite materials, batteries, and fuel cells

**English Speaking** · Native speaker

**Certified SolidWorks Associate (CSWA)** · Jan. 2020

## Experience

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**Oblong Inc.** · Software Developer · Dec. 2020 – March 2022  
– Qualified new hardware for a complex, embedded, multimedia, hardware/software device  
– Collaborated on a hybrid remote/in-person team in the midst of the COVID-19 pandemic  
– Improved logging on products to quicken Oblong's response to customer issues  
– Debugged audio issue involving Linux, PulseAudio, Cisco hardware, and Oblong's hardware  
– Took on maintainance and development of Oblong's legacy products and software tools  
– Developed polyglot software in Python, Go, Bash, C++, C, Ruby, JavaScript, and TypeScript

**Tetra Bio Distributed** · Software Engineer, Board Secretary · April 2020 – Jan. 2021  
– Developed a **software display** to show respiration descriptors of COVID-19 patients to doctors  
– Designed a web server to send patient data to a browser front end using Python and Go  
– Developed a Continuous Integration system to automatically test the software as it's checked in  
– Wrote drivers for a pressure and a flow sensor for an embedded Linux system  
– Made signal processing tools to turn sensor data into patient state descriptors useful to doctors

**NASA Jet Propulsion Laboratory** · Robotics Intern · Summers 2018, 2016, and 2014  
– Developed a system to study robotic mobility for missions to icy moons  
– Designed in CAD a mechanical system to offload gravity with minimal lateral forces  
– Prepared engineering drawings of mechanical components to send to vendors to machine  
– Designed an electrical system to distribute power to microprocessors that control the system  
– Wrote automatic control programs and documentation in Python and Arduino C  
– Developed a proposal for a **probe to bore ~20 km into Europa's icy crust**  
– Designed and executed a test to demonstrate the feasibility of the proposed system  
– Co-authored "**A deep subsurface ice probe for Europa**" in IEEE Aerospace Conference 2017

**Hawkes Group, UCSB** · Undergraduate Researcher · March 2019 – Sept. 2019  
– Iteratively designed in CAD a fixture to hold tools on the end of a **soft, vine-like robot**  
– Built these fixtures by making them on a 3D printer and assembling them

**Capstone Course Design Project, UCSB** · Student Engineer · Sept. 2018 – June 2019  
– Designed in SolidWorks from requirements a **stair-climbing dolly** that carries heavy payloads  
– Machined most custom components by hand on a mill and lathe from drawings I made

A portfolio of my work can be found at <http://portfolium.com/fporter/portfolio>