# Fletcher Porter

+1 (626) 321-6687 · me@fletcherporter.com · http://fletcherporter.com

#### Education

University of California, Santa Barbara (UCSB) · BS Mechanical Engineering · Sept. 2019

- Exchange study from 2017-08 to 2018-06 at Lunds Tekniska Högskola (LTH) in Lund, Sweden
- Courses in robotics, design with polymer composite materials, batteries, and fuel cells

Certified SolidWorks Associate (CSWA) · Jan. 2020

## Experience \_

Oblong Inc. · Software Developer · December 2020 – March 2022

- Qualified new hardware for a complex, embedded, multimedia, hardware/software device
- Collaborated on a hybrid remote/in-person team in the midst of the COVID-19 pandemic
- Improved logging on products to quicken Oblong's response to customer issues
- Debugged audio issue involving Linux, PulseAudio, Cisco hardware, and Oblong's hardware
- Took on maintainance and development of Oblong's legacy products and software tools
- Developed polyglot software in Python, Go, Bash, C++, C, Ruby, JavaScript, and TypeScript

Tetra Bio Distributed · Engineer, Board Secretary · April 2020 – January 2021

- Developed a software display to show respiration descriptors of COVID-19 patients to doctors
- Designed a web server to send patient data to a browser front end using Python and Go
- Developed a Continuous Integration system to automatically test the software as it's checked in
- Wrote drivers for a pressure and a flow sensor for an embedded Linux system
- Made signal processing tools to turn sensor data into patient state descriptors useful to doctors
- Prepared IRS Form 1023-EZ to successfully get the organization 501(c)(3) non-profit status

### NASA Jet Propulsion Laboratory · Robotics Intern · June 2018 – Sept. 2018

- Developed a system to study robotic mobility for missions to icy moons
- Designed in CAD a mechanical system to offload gravity with minimal lateral forces
- Prepared engineering drawings of mechanical components to send to vendors to machine
- Designed an electrical system to distribute power to microprocessors that control the system
- Wrote automatic control programs and documentation in Python and Arduino C

## Hawkes Group, UCSB · Undergraduate Researcher · March 2019 – Sept. 2019

- Iteratively designed in CAD a fixture to hold tools on the end of a soft, vine-like robot
- $\,-\,$  Built these fixtures by making them on a 3D printer and assembling them
- Documented the design process and results

## Capstone Course Design Project (UCSB) · Student Engineer · Sept. 2018 – June 2019

- Designed in CAD a dolly that climbs stairs while carrying a heavy payload
- Created manufacturing drawing of all custom components in the system
- Machined most custom components by hand on a mill and lathe
- Reported the design process and results

## NASA Jet Propulsion Laboratory · Robotics Intern · June 2016 – Aug. 2016

- Developed a proposal for a probe to bore ~20 km into Europa's icy crust
- Designed and executed a test to demonstrate the feasibility of the proposed system
- Created drawings for parts to manufacture and to get ROM quotes
- Coauthored "A deep subsurface ice probe for Europa" in IEEE Aerospace Conference 2017

A portfolio of my work can be found at http://portfolium.com/fporter/portfolio