

# Fletcher Porter

+1 (626) 321-6687 · [me@fletcherporter.com](mailto:me@fletcherporter.com) · <http://fletcherporter.com> · Class of 2019

## Education

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**University of California, Santa Barbara (UCSB)** · BS Mechanical Engineering · Graduated 2019-08

- Exchange study from 2017-08 to 2018-06 at Lunds Tekniska Högskola (LTH) in Lund, Sweden
- Courses in design with polymer composite materials, batteries, and fuel cells at LTH

## Experience

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**NASA Jet Propulsion Laboratory** · Gravity-Offload System · 2018-06-11 – 2018-09-07

- Developed a system to study robotic mobility for missions to icy moons
- Designed in CAD a mechanical system to offload gravity with minimal lateral forces
- Made engineering drawings of mechanical components to send to vendors to machine
- Designed an electrical system to distribute power to microprocessors that control the system
- Assembled the mechanical and electrical systems by hand
- Wrote automatic control programs with documentation in Python and Arduino C

**Hawkes Group, UCSB** · Vine Robots · 2019-03 – 2019-09

- Iteratively designed in SolidWorks a fixture to hold tools on the end of a **soft, vine-like robot**
- Built these fixtures by making them on a 3D printer and assembling them
- Documented design process and results

**Capstone Course Design Project (UCSB)** · Automatic Stair Climbing Vehicle · 2018-09 – 2019-06

- Designed in SolidWorks a **dolly that climbs stairs** while carrying a heavy payload
- Created manufacturing drawing of all custom components in the system
- Machined most custom components by hand on a mill and lathe
- Reported the design process and results

**NASA Jet Propulsion Laboratory** · Ocean Worlds Mobility and Sensing · 2016-06-14 – 2016-08-26

- Developed a proposal for a **probe to bore ~20 km into Europa's icy crust**
- Designed components to demonstrate the feasibility of the proposed system
- Performed a test with a robot arm to demonstrate the proposed boring method
- Created drawings for parts to manufacture and to get ROM quotes

**Mechatronics Course Design Project (LTH)** · Camera Cleaning System · 2017-08-28 – 2018-05-15

- Designed and built a **mechanical system for cleaning security cameras**
- Documented the design process and results in a report

**NASA Jet Propulsion Laboratory** · RoboSimian Cam Hand · 2014-06-09 – 2014-08-12

- Designed components of a **robot manipulator** in SolidWorks and iterated on the design

**Robotic Planning and Kinematics Class** · UCSB ME 179P · 2019-01-07 – 2018-03-19

- Wrote **planning and kinematics programs** in Python
- Documented code with Python docstrings

**Robotic Controls Class** · UCSB ME 179D · 2018-09-27 – 2018-12-11

- Wrote control programs for robot arms in Matlab and Simulink

## Publications

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B. H. Wilcox, J. A. Carlton, J. M. Jenkins, and F. Porter, "A deep subsurface ice probe for Europa," in 2017 IEEE Aerospace Conference, pp. 1–13, March 2017.

A portfolio of my work can be found at <http://portfolium.com/fporter/portfolio>