

Reputation and the Credibility of Inflation Plans

Rumen Kostadinov
McMaster

Francisco Roldán
IMF

IMF Western Hemisphere Department seminar
March 2024

The views expressed herein are those of the authors and should not be attributed to the IMF,
its Executive Board, or its management.

What is credibility?

- Macro models: **expectations** of future policy determine current outcomes
- Policy typically set assuming **commitment** or **discretion**
- Governments actively attempt to influence **beliefs** about future policy
 - Forward guidance, inflation targets, fiscal rules...
- This paper Rational-expectations theory of government **credibility**
... borrowing insights from game-theory literature on **reputation**
- Application in a (modernized) Barro-Gordon setup

What is credibility?

- Macro models: **expectations** of future policy determine current outcomes
- Policy typically set assuming **commitment** or **discretion**
- Governments actively attempt to influence **beliefs** about future policy
 - Forward guidance, inflation targets, fiscal rules...
- This paper Rational-expectations theory of government **credibility**
... borrowing insights from game-theory literature on **reputation**
- Application in a (modernized) Barro-Gordon setup

Our approach

- Reputation is other agents' **belief** about my commitments
 - ... conceptualize commitment with private-information behavioral types
- Discipline (rational expectations)
 - ... can only have reputation for **possible** things
 - ... reputation changes through Bayes' rule after actions and announcements
- Setup
 - Initial **announcement** of inflation targets
 - ... collapses the set of reputations
 - Continuation equilibrium *given a plan*
 - ... Crucial assumption: government action observed **imperfectly**
 - ... Dynamics of reputation

Our approach

- Reputation is other agents' **belief** about my commitments
 - ... conceptualize commitment with private-information behavioral types
- Discipline (rational expectations)
 - ... can only have reputation for **possible** things
 - ... reputation changes through Bayes' rule after actions and announcements
- Setup
 - Initial **announcement** of inflation targets
 - ... collapses the set of reputations
 - Continuation equilibrium *given a plan*
 - ... Crucial assumption: government action observed **imperfectly**
 - ... Dynamics of reputation

Our approach

- Reputation is other agents' **belief** about my commitments
 - ... conceptualize commitment with private-information behavioral types
- Discipline (rational expectations)
 - ... can only have reputation for **possible** things
 - ... reputation changes through Bayes' rule after actions and announcements
- Setup
 - Initial **announcement** of inflation targets
 - ... collapses the set of reputations
 - Continuation equilibrium *given a plan*
 - ... Crucial assumption: government action observed **imperfectly**
 - ... Dynamics of reputation

Main results

1. Compare continuation equilibria of different **plans**
 - ... Larger deviations are easier to detect
 - ... 'More time-inconsistent' plans have a more negative average drift of reputation
 - ... Tradeoff between **credibility** and promised **outcomes**
2. Main result choose a back-loaded plan with **gradual** disinflation
 - ... Gradualism helps incentives and slows down reputation losses
 - ... despite no inertia or other *real* reasons for gradualism
3. Take the limit as *initial reputation* vanishes to **zero**
 - ... Gradualism result is preserved

- **Sustainable plans – anything goes**

from Kydland and Prescott (1977), Chari and Kehoe (1990), Abreu, Pearce, and Stacchetti (1990), Phelan and Stacchetti (2001)

- **Reputation without noise – zero inflation at onset**

Milgrom and Roberts (1982), Kreps and Wilson (1982), Barro (1986), Backus and Driffill (1985), Barro and Gordon (1986), Sleet and Yeltekin (2007)

Dovis and Kirpalani (2019) – constant but more than zero

- **Reputation with noise**

Commitment: Lu (2013), Lu, King, and Pastén (2008, 2016)

Static plans: Faingold and Sannikov (2011)

- **Preference uncertainty with noise – announcements irrelevant**

Cukierman and Meltzer (1986), Faust and Svensson (2001), Phelan (2006), etc

Roadmap

- Model
- Continuation equilibria
- Plans
- Initial announcement
- Concluding remarks

Model

- A government dislikes inflation and output away from a target $y^* > 0$

$$L_t = \mathbb{E}_t \left[\sum_{s=0}^{\infty} \beta^s \left((y^* - y_{t+s})^2 + \gamma \pi_{t+s}^2 \right) \right]$$

- A Phillips curve relates output to current and expected future inflation

$$\pi_t = \kappa y_t + \beta \mathbb{E}_t [\pi_{t+1}]$$

- The government controls inflation only imperfectly (through g_t)

$$\pi_t = g_t + \epsilon_t$$

with $\epsilon_t \stackrel{iid}{\sim} F_\epsilon$

Reputation

- The government can be **rational** or one of many *behavioral* types
 - Behavioral types $c \in \mathcal{C}$
 - Type c is **committed** to an inflation plan $\{a_t\}_{t=0}^{\infty}$
 - For simplicity let all plans have $a_{t+1} = \phi_c(a_t)$ [Finding the state is an art]
- Behavioral types have (total) probability **z** (initial reputation)
 - Conditional on behavioral, probability ν over \mathcal{C}
- Private sector knows z and ν
 - Does *inference* over the government's type
 - Uses **announcements** and inflation **observations**

Reputation

- The government can be **rational** or one of many *behavioral* types
 - Behavioral types $c \in \mathcal{C}$
 - Type c is **committed** to an inflation plan $\{a_t\}_{t=0}^{\infty}$
 - For simplicity let all plans have $a_{t+1} = \phi_c(a_t)$ [Finding the state is an art]
- Behavioral types have (total) probability **z** (initial reputation)
 - Conditional on behavioral, probability ν over \mathcal{C}
- Private sector knows z and ν
 - Does *inference* over the government's type
 - Uses **announcements** and inflation **observations**

Behavioral types

- What is the set \mathcal{C} ?
 - ... and associated possible ϕ_c functions
- Consider $\{a_t\}_t$ paths characterized by
 - Starting point a_0
 - Decay rate ω
 - Asymptote χ

$$a_t = \chi + (a_0 - \chi)e^{-\omega t}$$

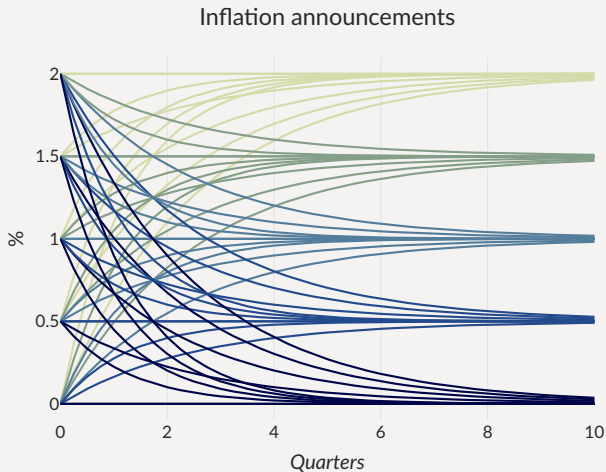
$$\phi(a) = \chi + e^{-\omega}(a - \chi)$$

Behavioral types

- What is the set \mathcal{C} ?
 - ... and associated possible ϕ_c functions
- Consider $\{a_t\}_t$ paths characterized by
 - Starting point a_0
 - Decay rate ω
 - Asymptote χ

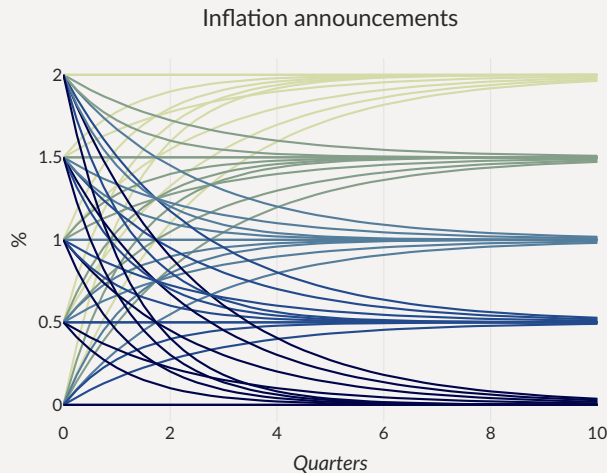
$$a_t = \chi + (a_0 - \chi)e^{-\omega t}$$

$$\phi(a) = \chi + e^{-\omega}(a - \chi)$$



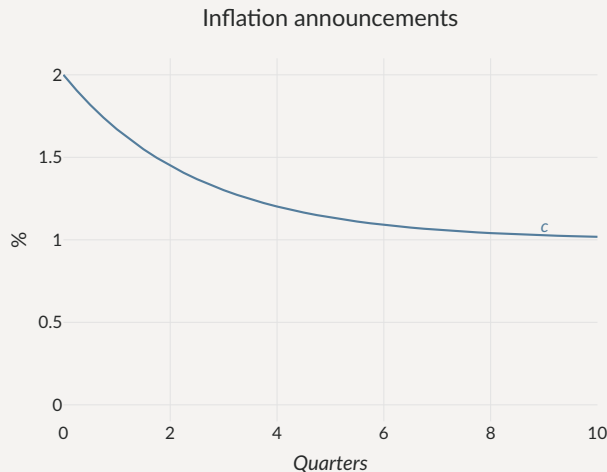
Gameplay

- At $t = 0$, inflation **targets** are announced
 - Type $c \in \mathcal{C}$ says c
 - Rational type **strategizes** announces r possibly $\in \mathcal{C}$
- At time $t \geq 0$, the government sets inflation
 - Behavioral type $c \in \mathcal{C}$ implements $g_t = a_t^c$
 - Rational type acts **strategically** chooses $g_t \leq a_t^c$



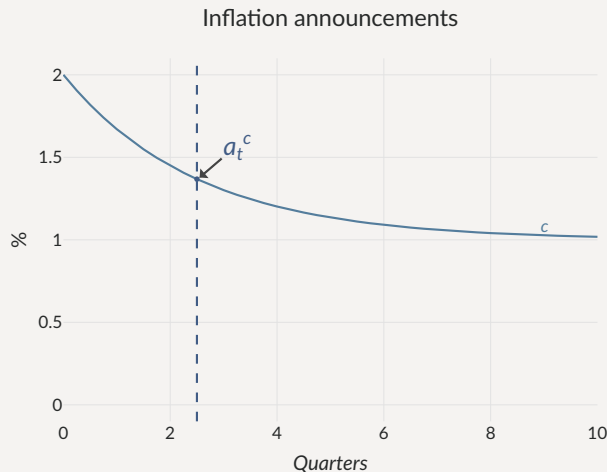
Gameplay

- At $t = 0$, inflation **targets** are announced
 - Type $c \in \mathcal{C}$ says c
 - Rational type **strategizes** announces r possibly $\in \mathcal{C}$
- At time $t \geq 0$, the government sets inflation
 - Behavioral type $c \in \mathcal{C}$ implements $g_t = a_t^c$
 - Rational type acts **strategically** chooses $g_t \lesseqgtr a_t^c$



Gameplay

- At $t = 0$, inflation **targets** are announced
 - Type $c \in \mathcal{C}$ says c
 - Rational type **strategizes** announces r possibly $\in \mathcal{C}$
- At time $t \geq 0$, the government sets inflation
 - Behavioral type $c \in \mathcal{C}$ implements $g_t = a_t^c$
 - Rational type acts **strategically** chooses $g_t \lessgtr a_t^c$



Continuation equilibria

Reputation and Outcomes

- Output is determined by **beliefs** $\mathbb{E}_t [\pi_{t+1}]$ and **actual inflation** $\pi_t = g_t + \epsilon_t$

$$\pi_t = \kappa y_t + \beta \mathbb{E}_t [\pi_{t+1}] = \kappa y_t + \beta \mathbb{E}_t [\mathbb{1}_c a_{t+1}^c + (1 - \mathbb{1}_c) g_{t+1}^*]$$

- Private sector solves a **signal extraction problem** to update beliefs

$$\mathbb{P}(c \mid \pi_t, \mathcal{F}_{t-1}) = \frac{\mathbb{P}(c \mid \mathcal{F}_{t-1}) \cdot f_\epsilon(\epsilon_t | c)}{\mathbb{P}(c \mid \mathcal{F}_{t-1}) \cdot f_\epsilon(\epsilon_t | c) + (1 - \mathbb{P}(c \mid \mathcal{F}_{t-1})) \cdot f_\epsilon(\epsilon_t | r)}$$

Reputation and Outcomes

- Output is determined by **beliefs** $\mathbb{E}_t [\pi_{t+1}]$ and **actual inflation** $\pi_t = g_t + \epsilon_t$

$$\pi_t = \kappa y_t + \beta \mathbb{E}_t [\pi_{t+1}] = \kappa y_t + \beta \mathbb{E}_t [\mathbb{1}_c a_{t+1}^c + (1 - \mathbb{1}_c) g_{t+1}^*]$$

- Private sector solves a **signal extraction problem** to update beliefs

$$\mathbb{P}(c \mid \pi_t, \mathcal{F}_{t-1}) = \frac{\mathbb{P}(c \mid \mathcal{F}_{t-1}) \cdot f_\epsilon(\epsilon_t | c)}{\mathbb{P}(c \mid \mathcal{F}_{t-1}) \cdot f_\epsilon(\epsilon_t | c) + (1 - \mathbb{P}(c \mid \mathcal{F}_{t-1})) \cdot f_\epsilon(\epsilon_t | r)}$$

Reputation and Outcomes

- Output is determined by **beliefs** $\mathbb{E}_t [\pi_{t+1}]$ and **actual inflation** $\pi_t = g_t + \epsilon_t$

$$\pi_t = \kappa y_t + \beta \mathbb{E}_t [\pi_{t+1}] = \kappa y_t + \beta \mathbb{E}_t [\mathbb{1}_c a_{t+1}^c + (1 - \mathbb{1}_c) g_{t+1}^*]$$

- Private sector solves a **signal extraction** problem to update beliefs

$$\mathbb{P}(c \mid \pi_t, \mathcal{F}_{t-1}) = \frac{\mathbb{P}(c \mid \mathcal{F}_{t-1}) \cdot f_\epsilon(\epsilon_t | c)}{\mathbb{P}(c \mid \mathcal{F}_{t-1}) \cdot f_\epsilon(\epsilon_t | c) + (1 - \mathbb{P}(c \mid \mathcal{F}_{t-1})) \cdot f_\epsilon(\epsilon_t | r)}$$

Reputation and Outcomes

- Output is determined by **beliefs** $\mathbb{E}_t [\pi_{t+1}]$ and **actual inflation** $\pi_t = g_t + \epsilon_t$

$$\pi_t = \kappa y_t + \beta \mathbb{E}_t [\pi_{t+1}] = \kappa y_t + \beta \mathbb{E}_t [\mathbb{1}_c a_{t+1}^c + (1 - \mathbb{1}_c) g_{t+1}^*]$$

- Private sector solves a **signal extraction** problem to update beliefs

$$p_{t+1} = \frac{p_t \cdot f_\epsilon(\pi_t - a_t^c)}{p_t \cdot f_\epsilon(\pi_t - a_t^c) + (1 - p_t) \cdot f_\epsilon(\pi_t - g_t^*)}$$

Rational type's problem

Given an announcement c ,

- The problem of the rational type is, given expectations g_c^\star

$$\mathcal{L}^c(p, a) = \min_g \mathbb{E} \left[(y^\star - y)^2 + \gamma \pi^2 + \beta \mathcal{L}^c(p', \phi_c(a)) \right]$$

subject to $\pi = g + \epsilon$

$$\pi = \kappa y + \beta [p' \phi_c(a) + (1 - p') g_c^\star(p', \phi_c(a))]$$

$$p' = p + p(1 - p) \frac{f_\epsilon(\pi - a) - f_\epsilon(\pi - g_c^\star(p, a))}{p f_\epsilon(\pi - a) + (1 - p) f_\epsilon(\pi - g_c^\star(p, a))}$$

- Rational expectations requires g_c^\star to be the policy associated with \mathcal{L}^c

Continuation Equilibrium

Definition

Given an announcement c , a *continuation equilibrium* is a pair (\mathcal{L}^c, g_c^*) such that

- \mathcal{L}^c is the rational type's value function at expectations g_c^*
- g_c^* is the policy function associated with \mathcal{L}^c

A First Look at Different Plans

Observation

- Plans $c \in \mathcal{C}$ are

$$c = (a_0, \chi, \omega)$$

- For $a, b \in \mathbb{R}$

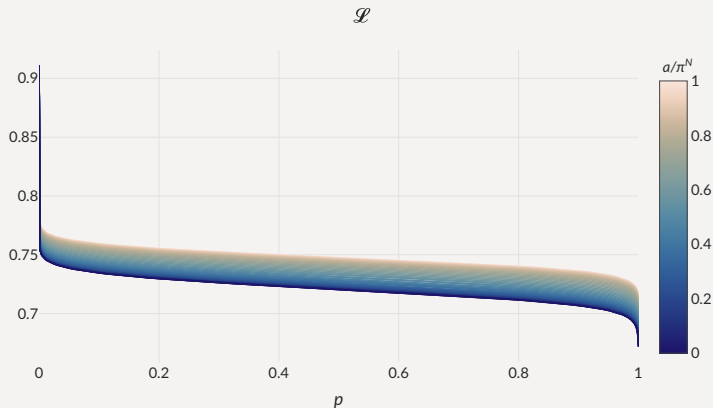
(\mathcal{L}, g^*) is a continuation
equilibrium for (a, χ, ω)



(\mathcal{L}, g^*) is a continuation
equilibrium for (b, χ, ω)

- Means $a \mapsto \mathcal{L}^c(p, a)$ compares the same plan at different times and different plans

The Value Function



- \mathcal{L} decreasing in p
- \mathcal{L} convex-concave in p
- \mathcal{L} increasing in a
for large p only

Lemma 1

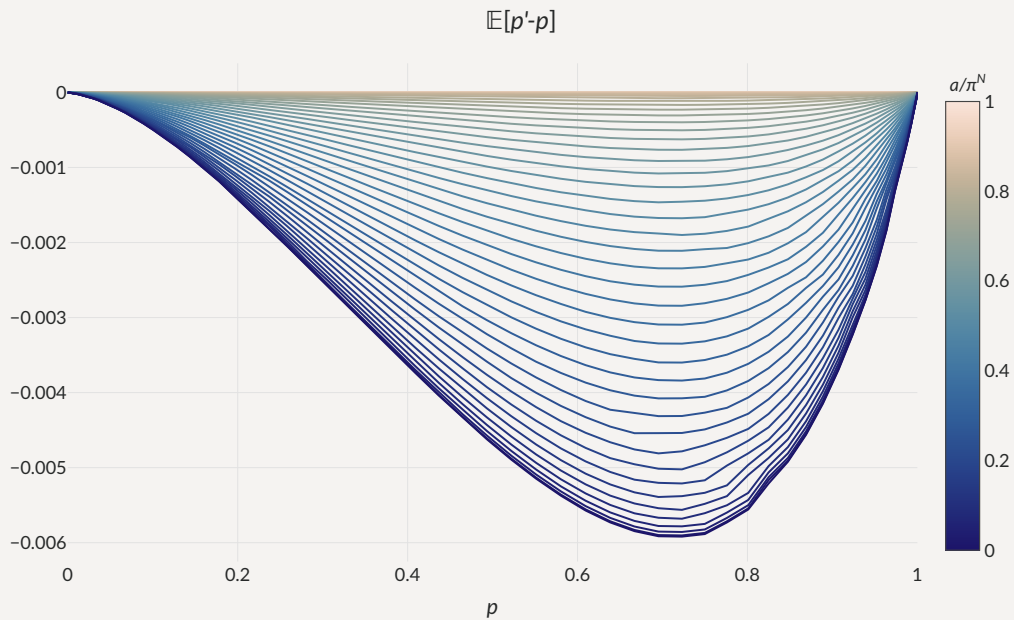
► Idea

In any continuation equilibrium,

$$\mathbb{E}_t [p_{t+1} \mid \text{rational}] \leq p_t$$

So $\{p_t\}_t$ is a supermartingale

Reputation Dynamics



From the Phillips curve

$$\frac{\partial y}{\partial \pi} = \frac{1}{\kappa} \left[1 - \beta \frac{\partial p'}{\partial \pi} \left(\phi_c(a) - g^*(p', \phi_c(a)) + (1 - p') \frac{\partial g^*(p', \phi_c(a))}{\partial p'} \right) \right]$$

- More inflation

1. Increases output by $\frac{1}{\kappa}$
2. Shifts inflation expectations from $\phi_c(a)$ towards $g^*(p', \phi_c(a))$
... p' decreases with higher π when $g^*(p, a) > a$
3. Shifts expectations of the rational type's future choice

From the Phillips curve

$$\frac{\partial y}{\partial \pi} = \frac{1}{\kappa} \left[1 - \beta \frac{\partial p'}{\partial \pi} \left(\phi_c(a) - g^*(p', \phi_c(a)) + (1 - p') \frac{\partial g^*(p', \phi_c(a))}{\partial p'} \right) \right]$$

- More inflation

1. Increases output by $\frac{1}{\kappa}$
2. Shifts inflation expectations from $\phi_c(a)$ towards $g^*(p', \phi_c(a))$
... p' decreases with higher π when $g^*(p, a) > a$
3. Shifts expectations of the rational type's future choice

From the Phillips curve

$$\frac{\partial y}{\partial \pi} = \frac{1}{\kappa} \left[1 - \beta \frac{\partial p'}{\partial \pi} \left(\phi_c(a) - g^*(p', \phi_c(a)) + (1 - p') \frac{\partial g^*(p', \phi_c(a))}{\partial p'} \right) \right]$$

- More inflation

1. Increases output by $\frac{1}{\kappa}$
2. Shifts inflation expectations from $\phi_c(a)$ towards $g^*(p', \phi_c(a))$
... p' decreases with higher π when $g^*(p, a) > a$
3. Shifts expectations of the rational type's future choice

From the Phillips curve

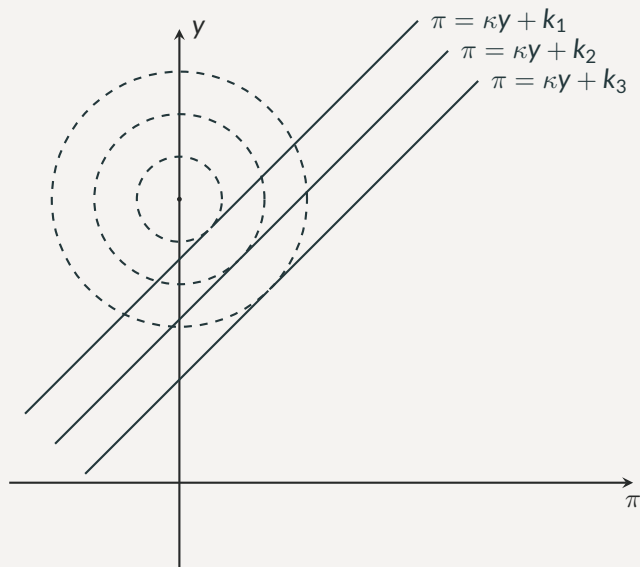
$$\frac{\partial y}{\partial \pi} = \frac{1}{\kappa} \left[1 - \beta \frac{\partial p'}{\partial \pi} \left(\phi_c(a) - g^*(p', \phi_c(a)) + (1 - p') \frac{\partial g^*(p', \phi_c(a))}{\partial p'} \right) \right]$$

- More inflation

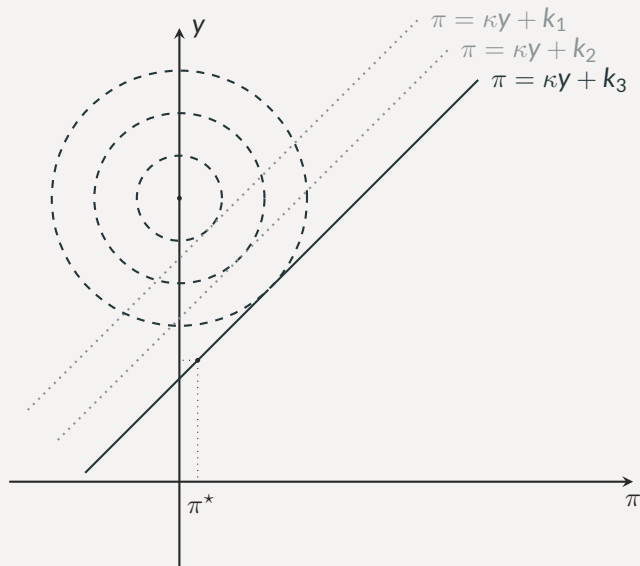
1. Increases output by $\frac{1}{\kappa}$
2. Shifts inflation expectations from $\phi_c(a)$ towards $g^*(p', \phi_c(a))$

... p' decreases with higher π when $g^*(p, a) > a$

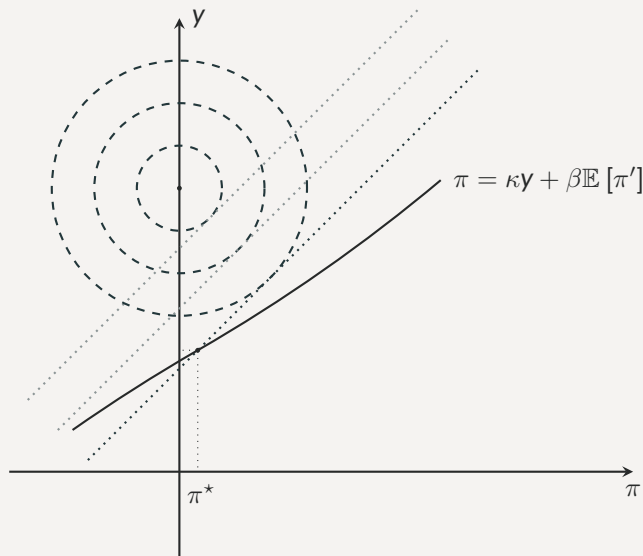
3. Shifts expectations of the rational type's future choice



- Without reputation:
if $\beta \mathbb{E} [\pi'] = k_j$
choose point on j th PC
- If announced a
and in eq'm
 $g^*(p, a) = a$
 \implies get straight PC
- If $g^*(p, a) > a$
 $\implies \frac{\partial p'}{\partial \pi}$ matters

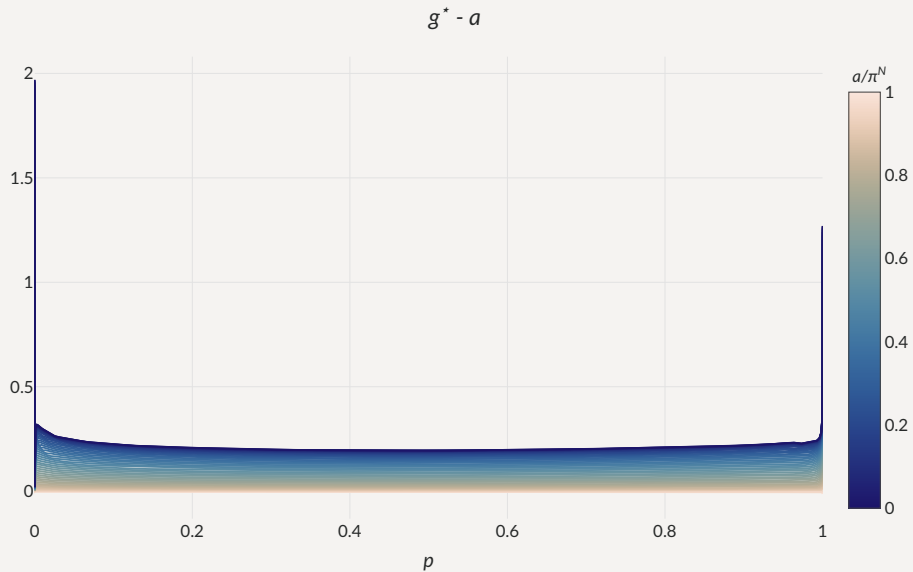


- Without reputation:
if $\beta \mathbb{E} [\pi'] = k_j$
choose point on j th PC
- If announced a
and in eq'm
 $g^*(p, a) = a$
 \implies get **straight** PC
- If $g^*(p, a) > a$
 $\implies \frac{\partial p'}{\partial \pi}$ **matters**



- Without reputation:
if $\beta \mathbb{E}[\pi'] = k_j$
choose point on j th PC
- If announced a
and in eq'm
 $g^*(p, a) = a$
 \implies get straight PC
- If $g^*(p, a) > a$
 $\implies \frac{\partial p'}{\partial \pi}$ matters

Equilibrium Deviations



- Let π^N be the Nash equilibrium inflation of the stage game. Then

$$\forall c \in \mathcal{C} : \quad g_c^*(p, a) \leq \pi^N$$

- Define the *remaining credibility* of a plan as

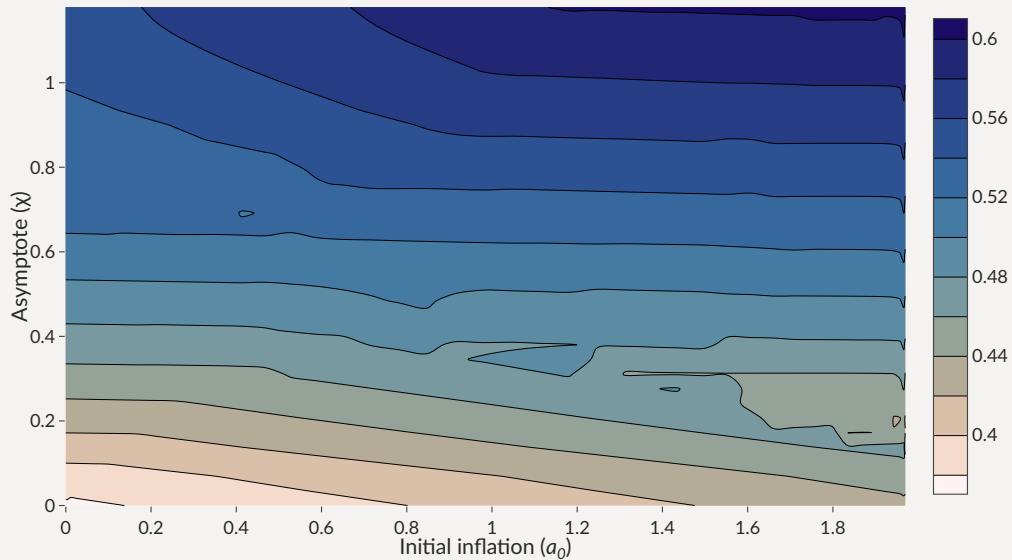
$$C_c(p, a) = (1 - \beta) \frac{\pi^N - g_c^*(p, a)}{\pi^N - a} + \beta \mathbb{E} [C_c(p'_c(p, a), \phi_c(a))]$$

- If $0 \leq g^*(p, a) \leq \pi^N$ always, then $C_c \in [0, 1]$

Plans

Credibility

$$\lim_{p \rightarrow 0} C(p, a, \omega^*, \chi)$$

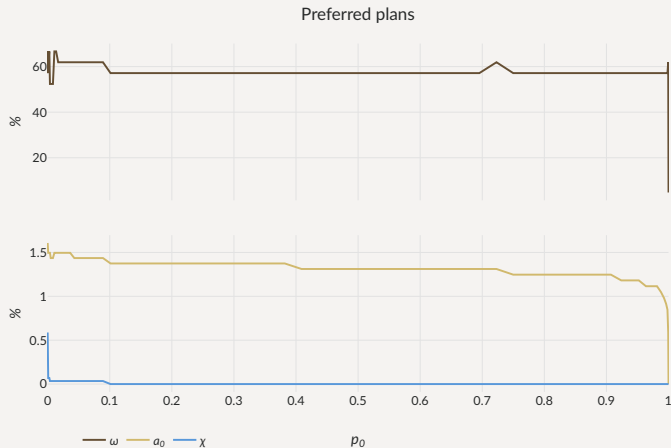


Plans

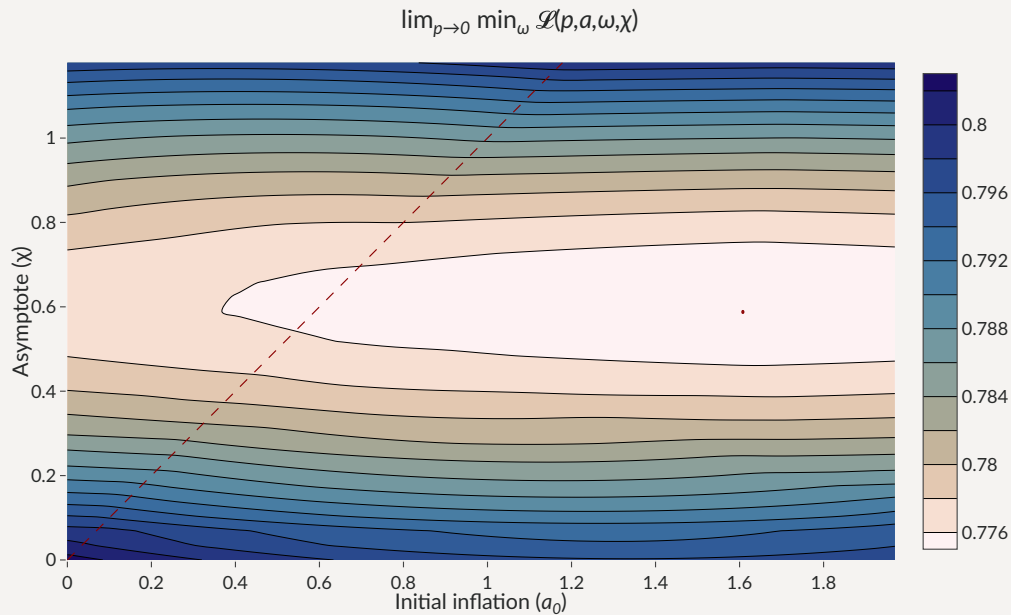
- For each $c \in \mathcal{C}$, find $\mathcal{L}^c(p, a), g_c^*(p, a)$.
- Generates big matrix $\mathcal{L}(p, a; \omega, \chi)$
- First pass: preferred plan **at each p**

Plans

- For each $c \in \mathcal{C}$, find $\mathcal{L}^c(p, a), g_c^*(p, a)$.
- Generates big matrix $\mathcal{L}(p, a; \omega, \chi)$
- First pass: preferred plan **at each p**



K-equilibrium



Initial announcement

What plan to choose?

Back to the initial announcement: two notions

- Kambe (1999): gov't announces type c and *becomes committed* to c with **exogenous** p_0 probability

- Tractable: p_0 independent of c

- So the limit we consider is

$$\lim_{p_0 \rightarrow 0} \min_{a_0, \omega, \chi} \mathcal{L}(p_0, a_0, \omega, \chi)$$

- Not entirely arbitrary
 - For given p_0 , plans that minimize \mathcal{L} should be played **often**

- If in **equilibrium** gov't announces type c with density $\mu(c)$,

$$p_0(c; z, \mu) = \frac{z\nu(c)}{z\nu(c) + (1-z)\mu(c)}$$

- So study

$$\lim_{z \rightarrow 0} \min_{\mu} \int \mathcal{L}(p_0(a_0, \omega, \chi; z, \mu), a_0, \omega, \chi) d\mu$$

- Need to find equilibrium μ

What plan to choose?

Back to the initial announcement: two notions

- Kambe (1999): gov't announces type c and *becomes committed* to c with **exogenous** p_0 probability

- Tractable: p_0 independent of c

- So the limit we consider is

$$\lim_{p_0 \rightarrow 0} \min_{a_0, \omega, \chi} \mathcal{L}(p_0, a_0, \omega, \chi)$$

- Not entirely arbitrary
 - For given p_0 , plans that minimize \mathcal{L} should be played **often**

- If in **equilibrium** gov't announces type c with density $\mu(c)$,

$$p_0(c; z, \mu) = \frac{z\nu(c)}{z\nu(c) + (1-z)\mu(c)}$$

- So study

$$\lim_{z \rightarrow 0} \min_{\mu} \int \mathcal{L}(p_0(a_0, \omega, \chi; z, \mu), a_0, \omega, \chi) d\mu$$

- Need to find equilibrium μ

What plan to choose?

Back to the initial announcement: two notions

- Kambe (1999): gov't announces type c and *becomes committed* to c with **exogenous** p_0 probability

- Tractable: p_0 independent of c

- So the limit we consider is

$$\lim_{p_0 \rightarrow 0} \min_{a_0, \omega, \chi} \mathcal{L}(p_0, a_0, \omega, \chi)$$

- Not entirely arbitrary
 - For given p_0 , plans that minimize \mathcal{L} should be played **often**

- If in **equilibrium** gov't announces type c with density $\mu(c)$,

$$p_0(c; z, \mu) = \frac{z\nu(c)}{z\nu(c) + (1-z)\mu(c)}$$

- So study

$$\lim_{z \rightarrow 0} \min_{\mu} \int \mathcal{L}(p_0(a_0, \omega, \chi; z, \mu), a_0, \omega, \chi) d\mu$$

- Need to find equilibrium μ

What plan to choose?

Back to the initial announcement: two notions

- Kambe (1999): gov't announces type c and *becomes committed* to c with **exogenous** p_0 probability

- Tractable: p_0 independent of c

- So the limit we consider is

$$\lim_{p_0 \rightarrow 0} \min_{a_0, \omega, \chi} \mathcal{L}(p_0, a_0, \omega, \chi)$$

- Not entirely arbitrary
 - For given p_0 , plans that minimize \mathcal{L} should be played **often**

- If in **equilibrium** gov't announces type c with density $\mu(c)$,

$$p_0(c; z, \mu) = \frac{z\nu(c)}{z\nu(c) + (1-z)\mu(c)}$$

- So study

$$\lim_{z \rightarrow 0} \min_{\mu} \int \mathcal{L}(p_0(a_0, \omega, \chi; z, \mu), a_0, \omega, \chi) d\mu$$

- Need to find equilibrium μ

Equilibrium for given z

- We want k and μ such that

$$\int_{\mathcal{C}} \mu(c) = 1$$

$$p_0(c) = \frac{z\nu(c)}{z\nu(c) + (1-z)\mu(c)}$$

$$\mathcal{L}(p_0(c), c) = k \quad \text{if } \mu(c) > 0$$

$$\mathcal{L}(p_0(c), c) \geq k \quad \text{if } \mu(c) = 0$$

- We do

- Start with $k_0 \leq \mathcal{L}(0, c) = \mathcal{L}^N$
- Partition states

$$\mathcal{L}(1, c) \geq k \rightarrow \mu(c) = 0$$

$$\mathcal{L}(1, c) < k$$

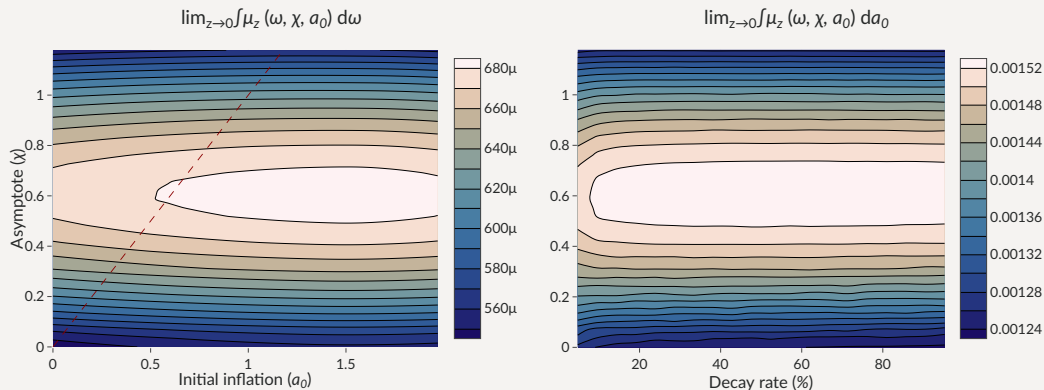
- In second case find $\mu(c)$ such that

$$\mathcal{L}(p_0(c), c) = k$$

This is possible if $k \leq$ value in static Nash

- Set $\mu(c) = \mathcal{B}^{-1}(p_0(c); \nu, z)$ if unset
- Check whether $\int_{\mathcal{C}} \mu(c) = 1$

Equilibrium distribution of announcements



- Gradualism: $\mathbb{P}(a_0 > \chi) = 65\%$. $\mathbb{P}(a_0 > 5\chi) = 16.7\%$. $\mathbb{P}(\text{decay} \leq 10\%) = 9.97\%$.
- Imperfect credibility: $\mathbb{P}(\chi = 0) = 2.49\%$.

Concluding remarks

Concluding remarks

- Model of reputational dynamics and policy
 - Simple environment
 - Focus on low reputation limit
- Credibility dynamics concerns influence choice of policy
 - Tradeoff between **promises** and **incentives**
 - Gradual plans boost reputation-building incentives for **future** decision-makers
- Structure of reputation maps into the incentive constraint of a planner's problem
 - ... creating large option values of complying
 - ... which are larger when the plan is backloaded