USBTMC

1 Department of Metrology and Optoelectronics

Electronic Systems Programming

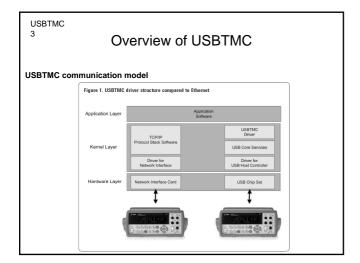
Lecture title

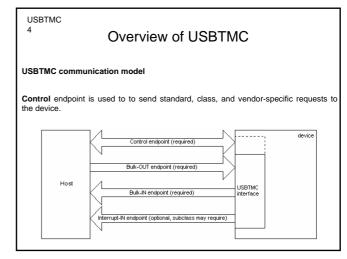
Programming of measurement instrumentation in Linux

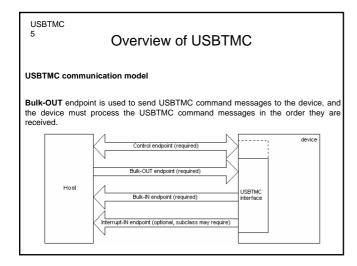
USBTMC 2 Programming of measurement instrumentation in Linux

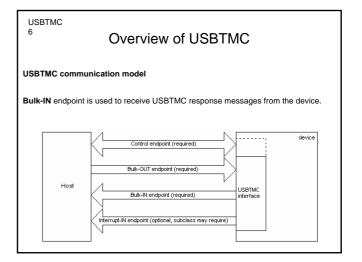
Topics:

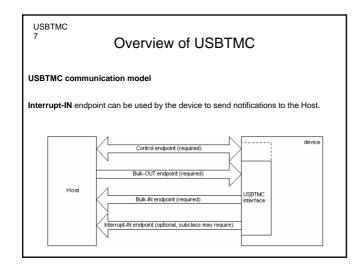
1. Overview of USBTMC
2. Interface endpoints
3. Registration with the USB Core
4. Access to the Driver from User Space
5. Installing the USBTMC Driver
6. Using the USBTMC Driver







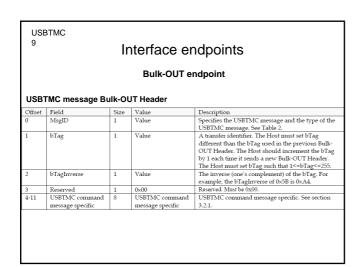


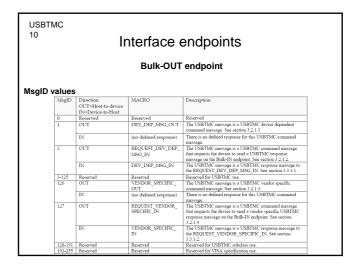


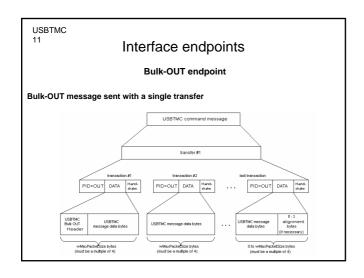
USBTMC Programming of measurement instrumentation in Linux

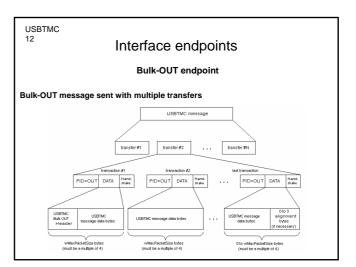
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USBTMC Interface endpoints **Bulk-OUT endpoint** Structure of the DEV_DEP_MSG_OUT message (example for *RST command) Description Number of bytes to be transferred (instrument command). TransferSize bmTransferAttributes End of message. If bit 0 is set to 1, the instrument message ends with this transfer. Otherwise, the message continues with the next transfer. All other bits are reserved (set to 0). Reserved 0x000000 Reserved. Set to 0x000000 Instrument Command 5 "*BST\n" Instrument command

```
USBTMC
                     Interface endpoints
                          Bulk-OUT endpoint
Example code: Sending a SCPI command via a DEV_DEP_MSG_OUT message
// Setup IO buffer for DEV_DEP_MSG_OUT message
usbtmc_buffer[0]=1; // DEV_DEP_MSG_OUT
usbtmc_buffer[1]=bTag; // Transfer ID (bTag)
usbtmc buffer[2]=~(bTag); // Inverse of bTag
usbtmc_buffer[3]=0; // Reserved
usbtmc_buffer[4]=command_length&255; // Transfer size (first byte)
usbtmc_buffer[5]=(command_length>>8)&255; //Transfer size (second byte)
usbtmc_buffer[6]=(command_length>>16)&255; //Transfer size (third byte)
usbtmc_buffer[7]=(command_length>>24)&255; //Transfer size (fourth byte)
usbtmc_buffer[8]=1; // Message ends with this transfer
usbtmc_buffer[9]=0; // Reserved
usbtmc_buffer[10]=0; // Reserved
usbtmc buffer[11]=0; // Reserved
```

```
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Interface endpoints

Bulk-OUT endpoint

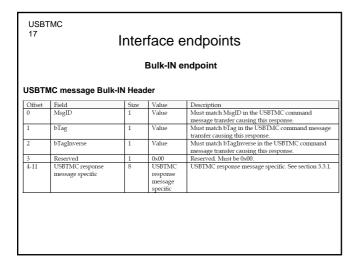
Example code: Sending a SCPI command via a DEV_DEP_MSG_OUT message (2/3)

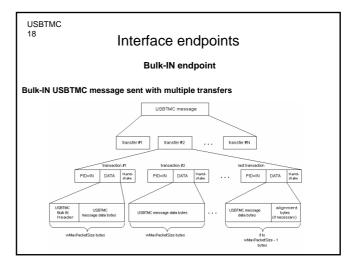
// Append write buffer (instrument command) to USBTMC message if(copy_from_user(&(usbtmc_buffer[12]),command_buffer,command_length)) {

// There must have been an addressing problem return -EPAULT;
}

// Add zero bytes to achieve 4-byte alignment n.bytes=12+command_length;
if(command_length%4) {

n_bytes+=4-command_length%4;
for(n=12+command_length;n<n_bytes;n++) usbtmc_buffer[n]=0;
}
```





USBTMC 19 Interrupt-IN endpoint Interrupt-IN DATA payload format Offset Field Size D7 D6 D5 D4...D0 Explanation | Data | Document | Document | Data | Document |

USBTMC Programming of measurement instrumentation in Linux

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USBTMC

Registration with the USB Core

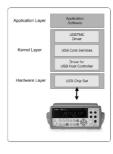
USBTMC driver needs to register with the USB core to interact with it.

A key element of this registration process is telling the USB core which devices an USBTMC driver would like to service when they become available.

Wanted devices can be filtered by various attributes, including the: devices' vendor ID, product ID or device class.

In the context of USBTMC, it is most appropriate to filter by **device class** (application-specific) and **USBTMC subclass**.

The USBTMC driver would then get notified whenever a USBTMC-compatible device is being attached, independent of its vendor or product code.



Registration with the USB Core

Example code: Registering a USB higher-level driver with the USB core layer (1/2)

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Registration with the USB Core

Registering a USB higher-level driver with the USB core layer (2/2)

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Access to the Driver from User Space

USBTMC-compatible instruments are controlled through text commands, typically following the SCPI standard. Hence communicating with a USB instrument is stream oriented. The most appropriate for such instrument is a character device driver.

Character device drivers need to implement a number of entry points that the system calls in order to interact with a device

The most basic ones are: open read write release

The **write()** entry point for USBTMC device driver takes the string to be written and wraps it into a **USBTMC DEV_DEP_MSG_OUT** message.

Similarly, the read() entry point uses a DEV_DEP_MSG_IN message to read data from a device, extract the instrument message part from the return data and copy it to the supplied user buffer.

USBTMC

Access to the Driver from User Space

Device files are created using the mknod command, and the major number specified refers to a character driver behind the (arbitrary) device file name.

The minor number is typically used to specify which device the driver will control if several devices are being serviced by the same driver.

When a character device driver is loaded into the kernel, it first needs to register its major and minor numbers with the kernel and publish its entry points.

```
USBTMC
```

Access to the Driver from User Space

```
Registering a character device driver (1/3)
```

```
// Dynamically allocate char driver major/minor numbers
                                 First major/minor number to use
if ((retcode = alloc_chrdev_region(&dev,
   0, // First minor number
  USBTMC_MINOR_NUMBERS,// Number of minor numbers to reserve
   "USBTMCCHR" // Char device driver name
  printk(KERN_ALERT "Unable to allocate major/minor numbers\n");
   goto exit_alloc_chrdev_region;
```

```
USBTMC
```

Access to the Driver from User Space

```
Registering a character device driver (2/3)
```

```
// This structure is used to publish
// the char device driver functions
static struct file_operations fops = {
       .owner=THIS_MODULE,
       .read=usbtmc_read,
       .write=usbtmc_write,
       .open=usbtmc_open,
       .release=usbtmc_release,
       .ioctl=usbtmc_ioctl,
       .llseek=usbtmc llseek.
};
```

USBTMC

Access to the Driver from User Space

Registering a character device driver (3/3)

```
// Initialize cdev structure for this character device
cdev_init(&cdev,&fops);
cdev.owner = THIS_MODULE;
cdev.ops = &fops;
// Combine major and minor numbers
printk(KERN_NOTICE "USBTMC: MKDEV\n");
devno = MKDEV(MAJOR(dev),n);
// Add character device to kernel list
printk(KERN_NOTICE "USBTMC: CDEV_ADD\n");
if((retcode = cdev_add(&cdev,devno,1))) {
      printk(KERN_ALERT "Unable to add character device\n");
      goto exit cdev add;
```

USBTMC

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USBTMC

Installing the USBTMC Driver

Compiling the driver

In order to compile source code of the driver "usbtmc.c" on the basis makefile, one should use make command. This will create a kernel object file "usbtmc.ko".

Installing the driver

In order to install the driver module in the running kernel one shold use a command

insmod ./usbtmc.ko

Similarly, the module can be unloaded from the kernel using

rmmod usbtmc

```
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              Installing the USBTMC Driver
Installing the driver
To use the driver proper device files must be created, related to the major number the
driver uses. A following script can be used to perform that task
# Find major number used
major=$(cat /proc/devices | grep USBTMCCHR | awk '{print $1}')
echo Using major number $major
# Remove old device files
rm -f /dev/${module}[0-9]
# Ceate new device files
mknod /dev/$\{module\}0 c $major 0
mknod /dev/${module}1 c $major 1
# Change access mode (RW access for everybody)
{\tt chmod~666~/dev} \\ {\tt fmodule} \\ 0
chmod 666 /dev/${module}1
//...
```

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USBTMC

3.

Using the USBTMC Driver

Interactive instrument control

Obtaining minor numbers of attached instruments:

cat /dev/usbtmc0

Minor Number Manufacturer Product Serial Number 001 Agilent Technologies 34980A Switch Measure Unit MY44003719

Sending command:

echo *RST>/dev/usbtmc1

Sending querry:

echo *IDN?>/dev/usbtmc1
cat /dev/usbtmc1

Agilent Technologies, 34980A, MY44003719, 2.19-2.19-2.07-1.05

```
Using the USBTMC Driver

Instrument control using file IO system calls
#include <stdio.h>
#include <fcntl.h>
```

```
#include <stdio.h>
#include <fcntl.h>
main() {
    int myfile;
    char buffer[4000];
    int actual;
    myfile = open("/dev/usbtmc1",O_RDWR);
    if(myfile>0) {
        write(myfile,"*IDN?\n",6);
        actual = read(myfile,buffer,4000);
        buffer[actual] = 0;
        printf("Response:\n%s\n",buffer);
        close(myfile);
    }
}
```