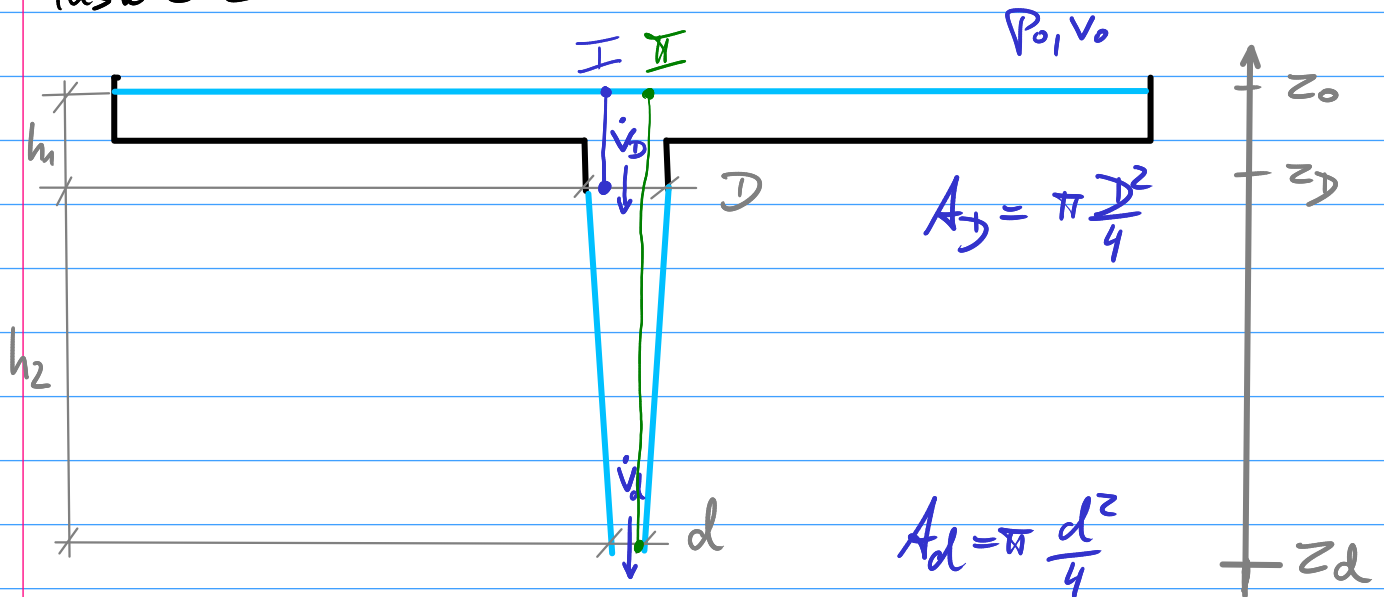


Task 3.2



(*) $\dot{V}_D = \dot{V}_d \Rightarrow A_D \cdot v_D = A_d \cdot v_d$ This equation to get the diameter d .

\Rightarrow For that we need both velocities v_D and v_d !

\Rightarrow Two Bernoulli-Eq. for two different streamlines!

Streamline I:

$$p_0 + \rho \frac{v_0^2}{2} + \rho g z_0 = p_D + \rho \frac{v_D^2}{2} + \rho g z_D \quad | - \rho g z_D$$

$$\cancel{p_0} + \cancel{\rho \frac{v_0^2}{2}} + \rho g \underbrace{(z_0 - z_D)}_{h_1} = \cancel{p_D} + \rho \frac{v_D^2}{2}$$

$$\quad | \quad \begin{matrix} \uparrow \\ \downarrow \end{matrix} \\ = \cancel{p_0}$$

like last time:

$$A_0 \gg A_D, A_d \Rightarrow \rho \frac{v_0^2}{2} \ll \rho \frac{v_D^2}{2}$$

$$\Rightarrow \quad \cancel{\rho g h_1} = \cancel{\rho \frac{v_D^2}{2}} \Rightarrow v_D = \sqrt{2gh_1}$$

Streamline II

$$\cancel{p_0} + \cancel{\rho} \frac{V_0^2}{2} + g \rho z_0 = \cancel{p_d} + \rho \frac{V_d^2}{2} + g \rho z_d$$

$\underset{=p_0}{\phantom{\cancel{p_d}}}$

like before

$$\Rightarrow \underbrace{g \rho (z_0 - z_d)}_{h_1 + h_2} = \cancel{\rho} \frac{V_d^2}{2}$$

$$\Rightarrow V_d = \sqrt{2g(h_1 + h_2)}$$

$$(*) \Rightarrow A_d = A_1 \frac{V_1}{V_d} =$$

$$\Rightarrow d = \sqrt{\frac{4A_d}{\pi}} =$$

(Taschenrechner)
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