

Kap 3, p. 23

$$f(x,y) = \frac{x-y}{x+y}$$

$$\partial_x f = \frac{1 \cdot (x+y) - (x-y) \cdot 1}{(x+y)^2} = \frac{2y}{(x+y)^2}$$

$$\partial_y f = \frac{(-1)(x+y) - (x-y) \cdot 1}{(x+y)^2} = -\frac{2x}{(x+y)^2}$$

$$\partial_y(\partial_x f) = \frac{2(x+y)^{\cancel{2}} - 2y \cancel{2}(x+y)^{\cancel{1}} \cdot 1}{(x+y)^{\cancel{2}+3}}$$

$$= \frac{2x+2y-4y}{(x+y)^3} = \frac{2x-2y}{(x+y)^3}$$

$$\partial_x(\partial_y f) = -\frac{2(x+y)^{\cancel{2}} - 2x \cancel{2}(x+y)^{\cancel{1}} \cdot 1}{(x+y)^{\cancel{2}+3}}$$

$$= -\frac{2x+2y-4x}{(x+y)^3} = -\frac{-2x+2y}{(x+y)^3}$$

$$= \frac{2x-2y}{(x+y)^3}$$

Kap 3, p. 28

$$f(x,y) = \ln(x^2+y)$$

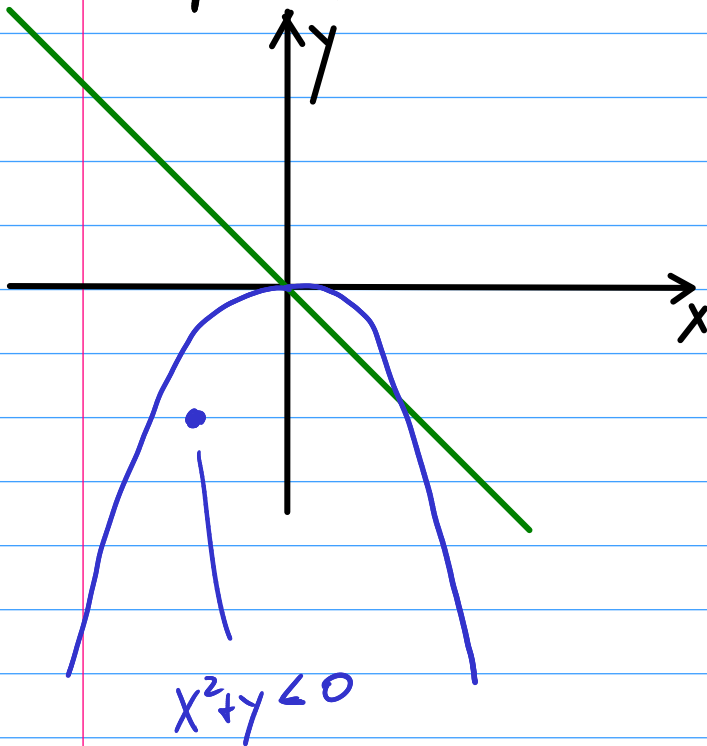
$$\partial_x f = \frac{1}{x^2+y} \cdot 2x = 2x(x^2+y)^{-1}$$

$$\partial_y f = \frac{1}{x^2+y} \cdot 1 = (x^2+y)^{-1}$$

$$\begin{aligned}\partial_y(\partial_x f) &= \partial_{yx} f = 2x(-1)(x^2+y)^{-2} \cdot 1 \\ &= -\frac{2x}{(x^2+y)^2}\end{aligned}$$

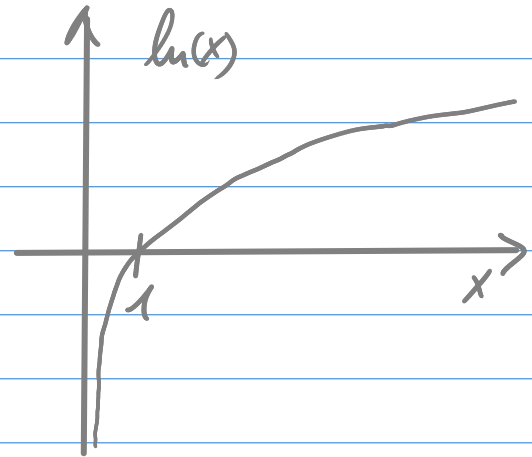
$$\begin{aligned}\partial_x(\partial_y f) &= \partial_{xy} f = (-1)(x^2+y)^{-2} \cdot 2x \\ &= -\frac{2x}{(x^2+y)^2}\end{aligned} \quad \checkmark$$

Kap 3, p. 28



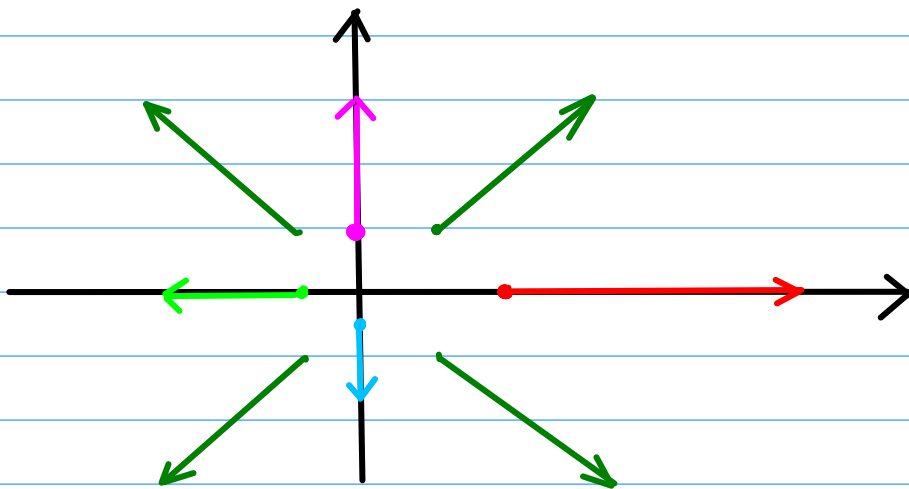
$$x + y = 0 \Rightarrow y = -x$$

$$x^2 + y = 0 \Rightarrow y = -x^2$$



p. 30

$$f(x, y) = x^2 + y^2 \Rightarrow \text{grad } f = (2x, 2y)$$



Kap3, P.32

$$f(x,y), g(x,y) : \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\begin{aligned} \text{grad}(f \cdot g) &= (\partial_x(f \cdot g), \partial_y(f \cdot g)) \\ &= ((\partial_x f) \cdot g + f(\partial_x g), (\partial_y f) \cdot g + f(\partial_y g)) \\ &= ((\partial_x f)g, (\partial_y f)g) + (f(\partial_x g), f(\partial_y g)) \\ &= g(\underbrace{\partial_x f, \partial_y f}) + f(\underbrace{\partial_x g, \partial_y g}) \\ &= g \text{ grad } f + f \text{ grad } g \end{aligned}$$

Kap 3, p. 33

$$f(x,y) = e^x - e^{-y}$$

$$g(x,y) = x^2 + y^{-2}$$

$$\begin{array}{l} \text{N.R.:} \\ \partial_y(-e^{-y}) \\ = -\partial_y(e^{-y}) \\ = -(-e^{-y}) = e^{-y} \end{array}$$

$$f \cdot g = (e^x + e^{-y})(x^2 + y^{-2})$$

$\Rightarrow$  Ableitungen häßlich / lässlich / fehleranfällig!

$$\text{grad } f = (e^x, e^{-y})$$

$$\text{grad } g = (2x, -2y^{-3})$$

$$\text{grad}(f \cdot g) = g \text{ grad } f + f \text{ grad } g$$

im Prinzip  
fertig

$$\text{grad}(C \cdot f) = C \text{ grad } f = \begin{pmatrix} C e^x \\ C e^{-y} \end{pmatrix}^T$$

$$\text{grad}(f+g) = \text{grad } f + \text{grad } g$$

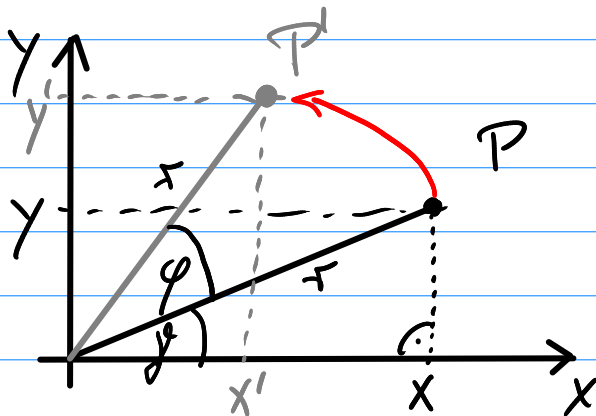
$$\text{grad}\left(\frac{f}{g}\right) = \frac{1}{g^2} (g \text{ grad } f - f \text{ grad } g)$$

im Prinzip  
fertig

$$= \frac{1}{g} \text{ grad } f - \frac{f}{g^2} \text{ grad } g$$

Kap 3, p. 38/39

$$\begin{aligned} \mathcal{R}(x,y) &= \begin{pmatrix} x \cos \varphi - y \sin \varphi \\ x \sin \varphi + y \cos \varphi \end{pmatrix} \\ &= \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \end{aligned}$$



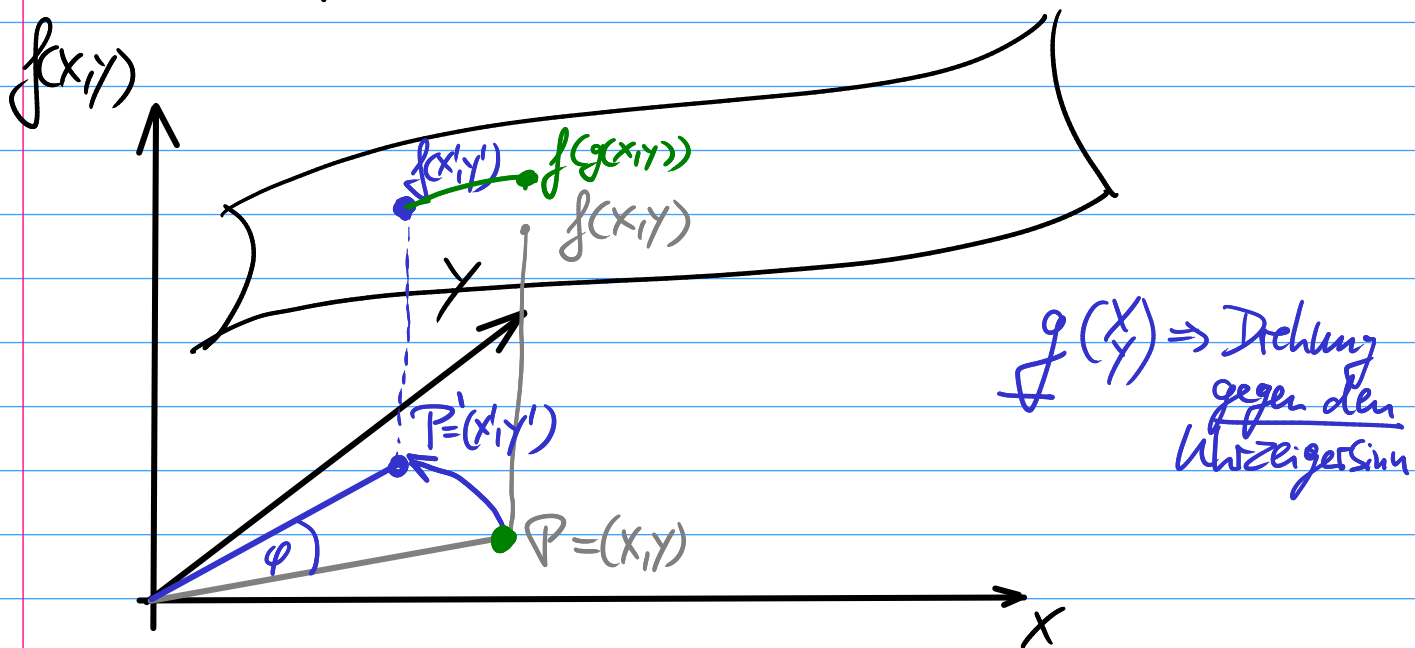
Drehung um Winkel  $\varphi$   
um den Ursprung

$$\begin{aligned} x' &= r \cos(\varphi + \psi) = r (\cos \varphi \cos \psi - \sin \varphi \sin \psi) \\ &= \cos \varphi \underbrace{r \cos \psi} - \sin \varphi \underbrace{r \sin \psi} \\ &= \cos \varphi \quad x \quad - \sin \varphi \quad y \end{aligned}$$

$$\begin{aligned} y' &= r \sin(\varphi + \psi) = r (\sin \varphi \cos \psi + \cos \varphi \sin \psi) \\ &= \sin \varphi \underbrace{r \cos \psi} + \cos \varphi \underbrace{r \sin \psi} \\ &= \sin \varphi \quad x \quad + \cos \varphi \quad y \end{aligned}$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

Kap 3, p. 38/39



$x, y \rightarrow$  gerundet  $\rightarrow$  Zahlenwert  $f(g(x, y))$

Die Plottoutine macht, das was sie soll:

Sie malt den Zahlenwert  $f(g(x, y))$  über die Stelle  $x, y$ .  $\Rightarrow$  Drehung im Uhrzeigersinn!