Introduction to Computer Design

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Computer evolution

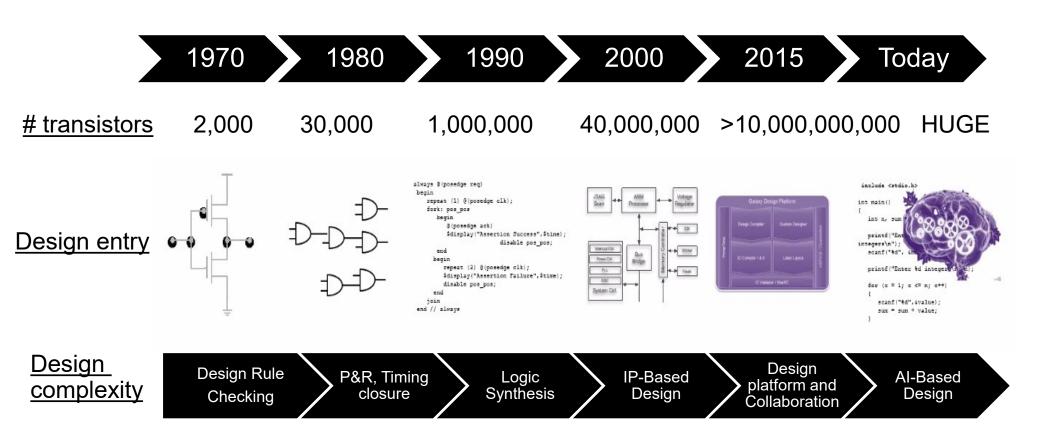
The first general-purpose computer was created in the late 40s.

A Personal Computer, that can now be bought for about \$500, is practically equivalent (in terms of performance and memory) to what could be bought for about \$1M in 1985.

This evolution has been made possible by

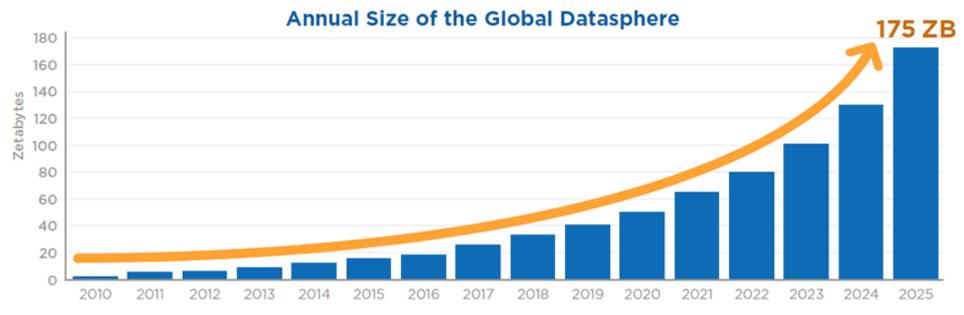
- Advances in semiconductor technology
- Innovations in computer design.

Chip-design history



Annual size of the global Datasphere

Figure 1 - Annual Size of the Global Datasphere



source: IDC Datasphere whitepaper

zettaByte ZB -> 10²¹ -> 2⁷⁰

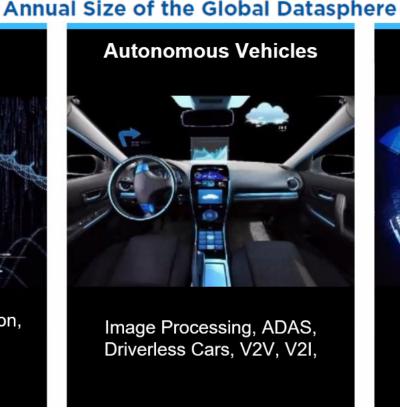
Annual size of the global Datasphere

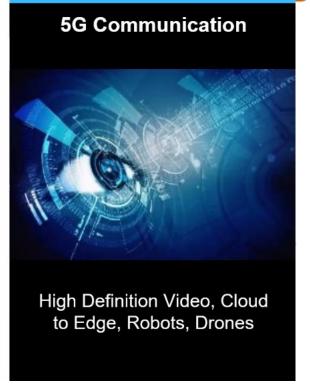
Figure 1 - Annual Size of the Global Datasphere

Machine Learning

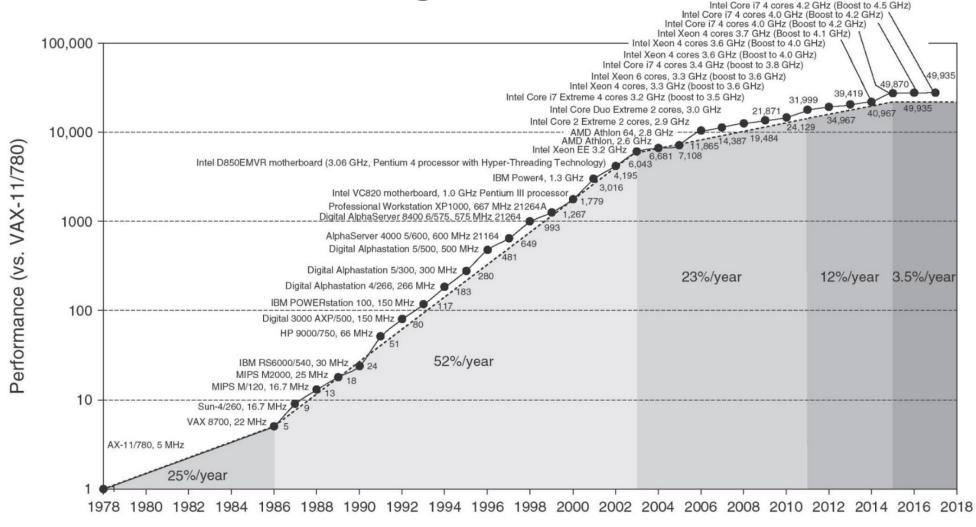
Machine Learning

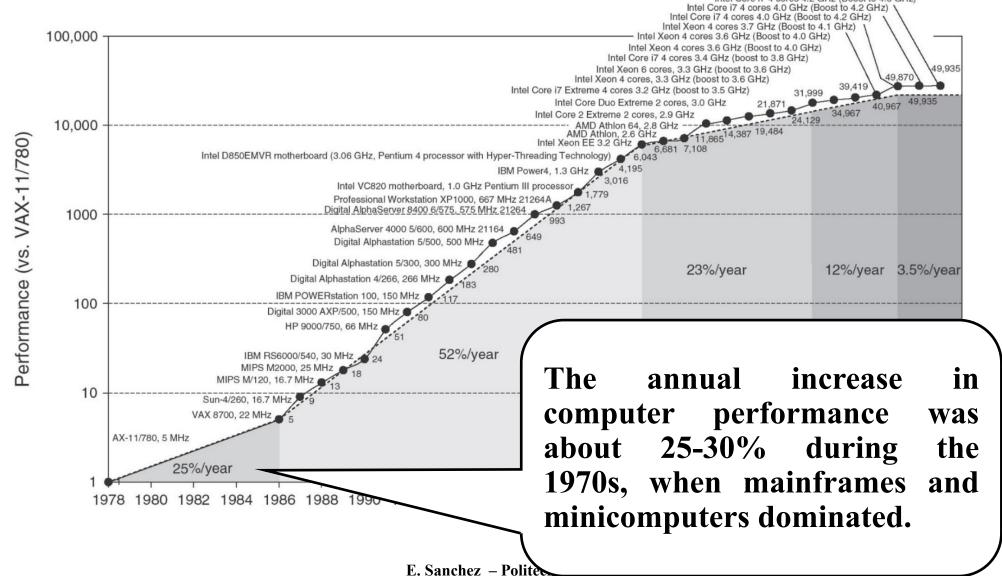
Big Data, Pattern Recognition,
Computational Learning,
Artificial Intelligence

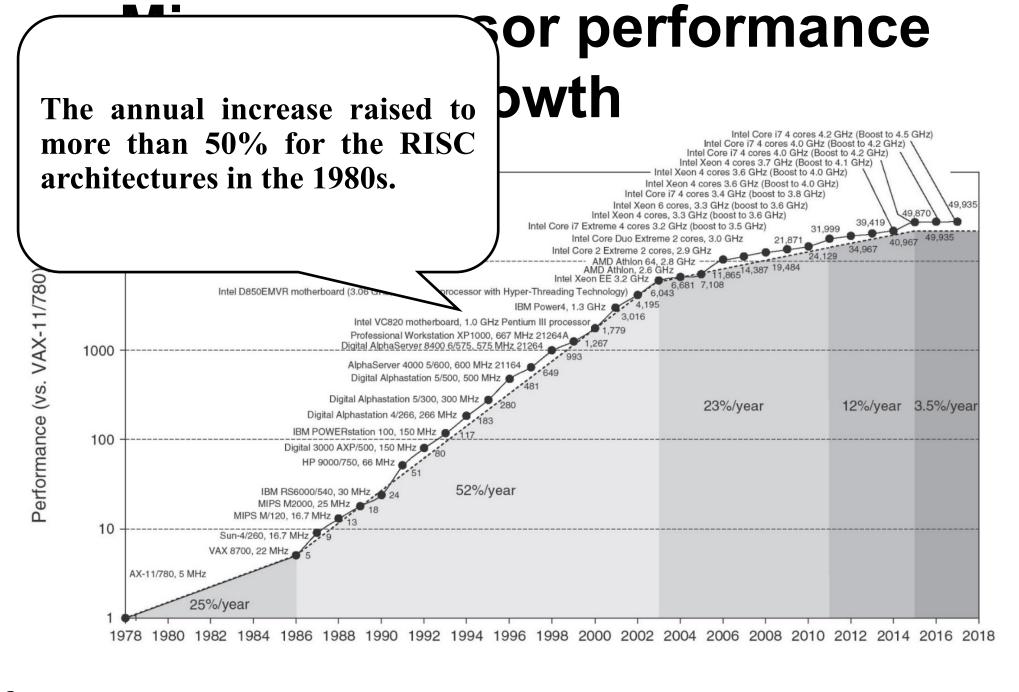




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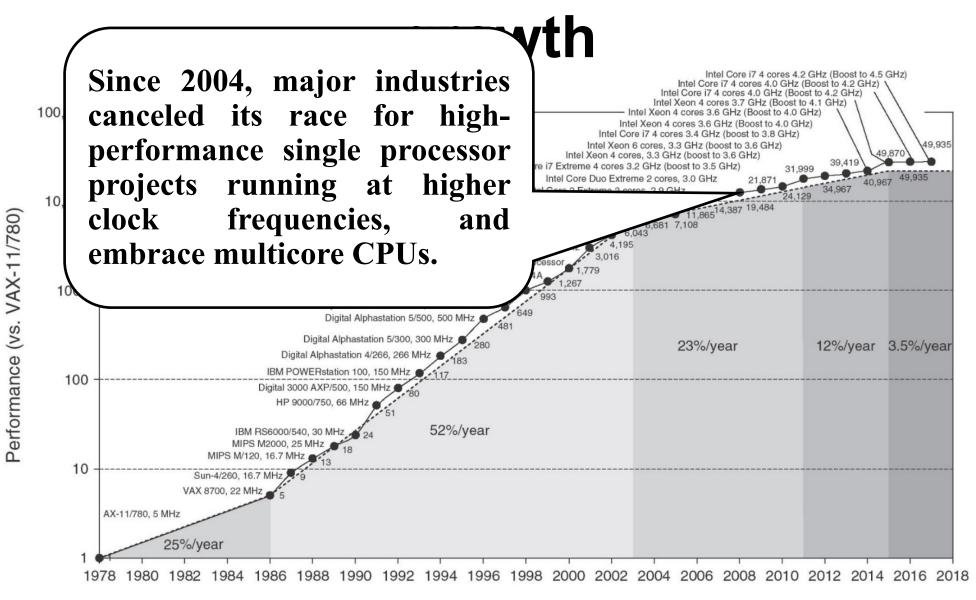




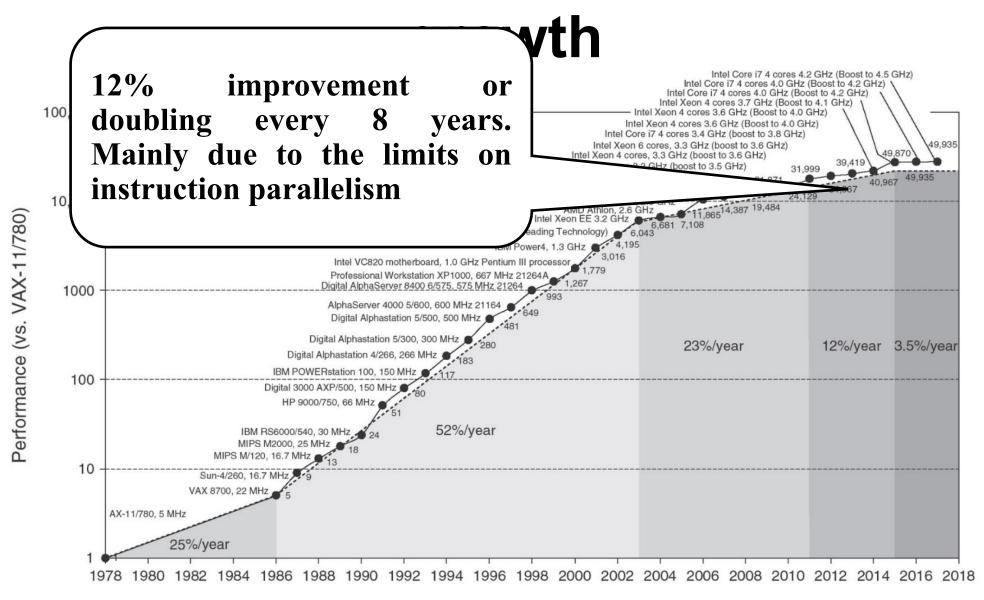
or performance Starting from 2002, the yearly processor performance increase Intel Core i7 4 cores 4.2 GHz (Boost to 4.5 GHz) Intel Core i7 4 cores 4.0 GHz (Boost to 4.2 GHz) dropped to about 20% due to Intel Core i7 4 cores 4.0 GHz (Boost to 4.2 GHz) Intel Xeon 4 cores 3.7 GHz (Boost to 4.1 GHz) Intel Xeon 4 cores 3.6 GHz (Boost to 4.0 GHz) Intel Xeon 4 cores 3.6 GHz (Boost to 4.0 GHz) Power issues Intel Core i7 4 cores 3.4 GHz (boost to 3.8 GHz) Intel Xeon 6 cores, 3.3 GHz (boost to 3.6 GHz) Intel Xeon 4 cores, 3.3 GHz (boost to 3.6 GHz) Lower instruction-level ore i7 Extreme 4 cores 3.2 GHz (boost to 3.5 GHz) parallelism Unchanged memory latency. Digital Alphastation 5/500, 500 MH Digital Alphastation 5/300, 300 l 12%/year 3.5%/year 23%/year Digital Alphastation 4/266, 26 100 52%/year 10 VAX 8700, 22 MHz AX-11/780, 5 MHz 25%/year 1980 1982 1984 1986 1988 1990 1992 1994 1996 1998 2000 2002 2004 2006 2008 2010 2012 2014 2016 2018

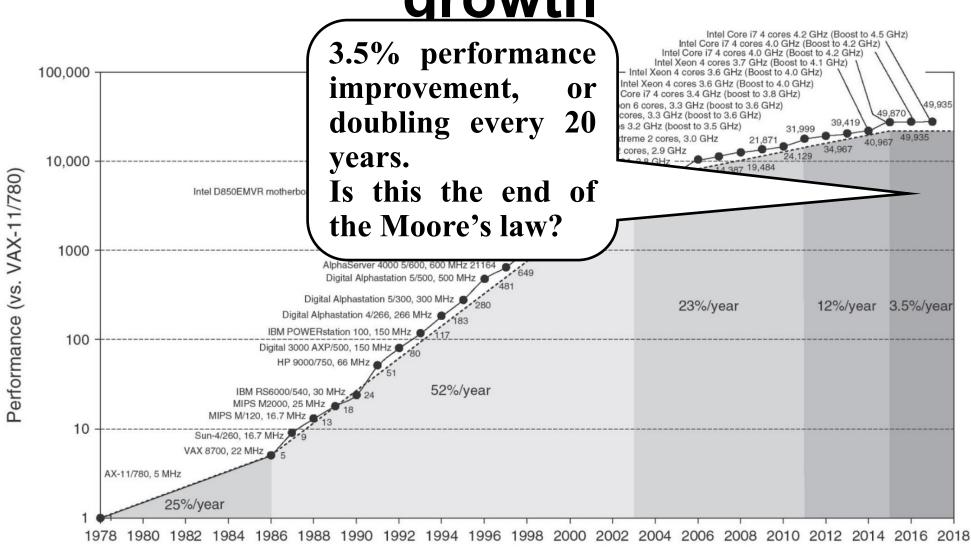
Performance (vs.

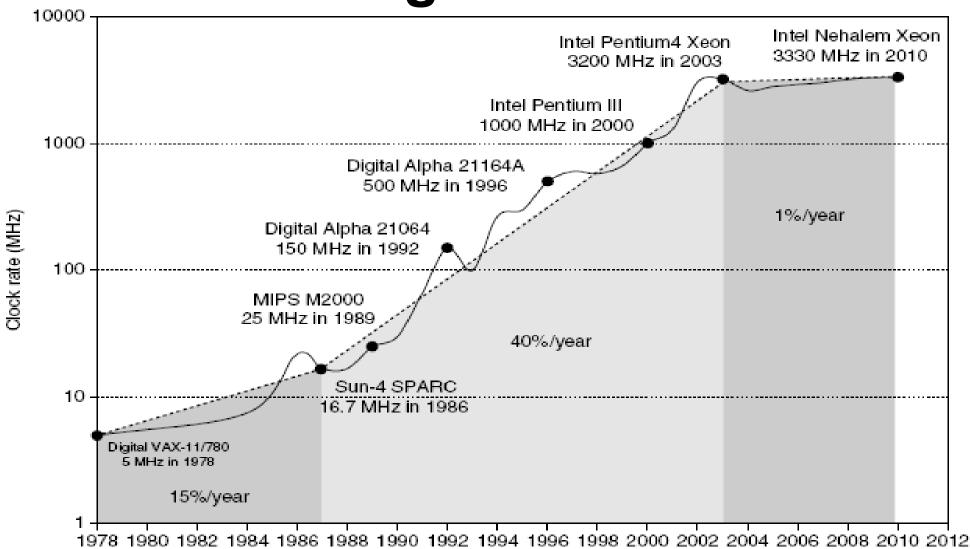
Microprocessor performance

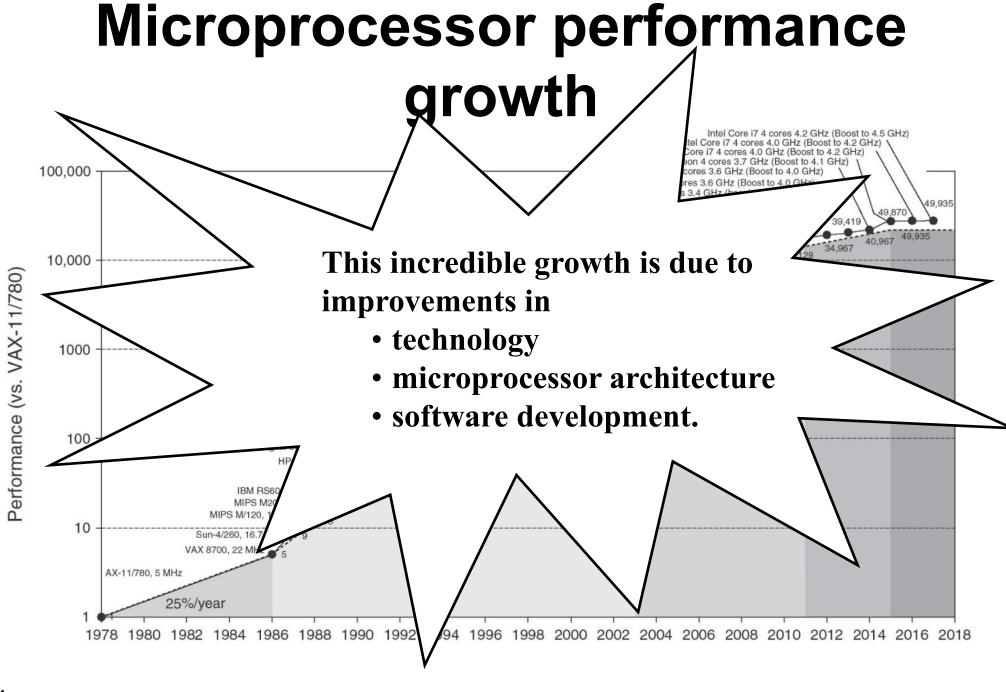


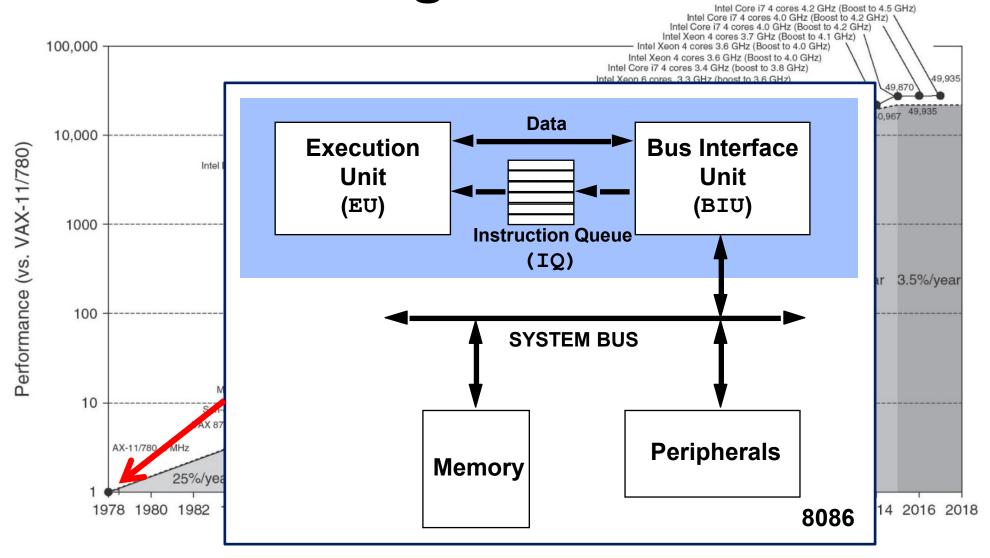
Microprocessor performance

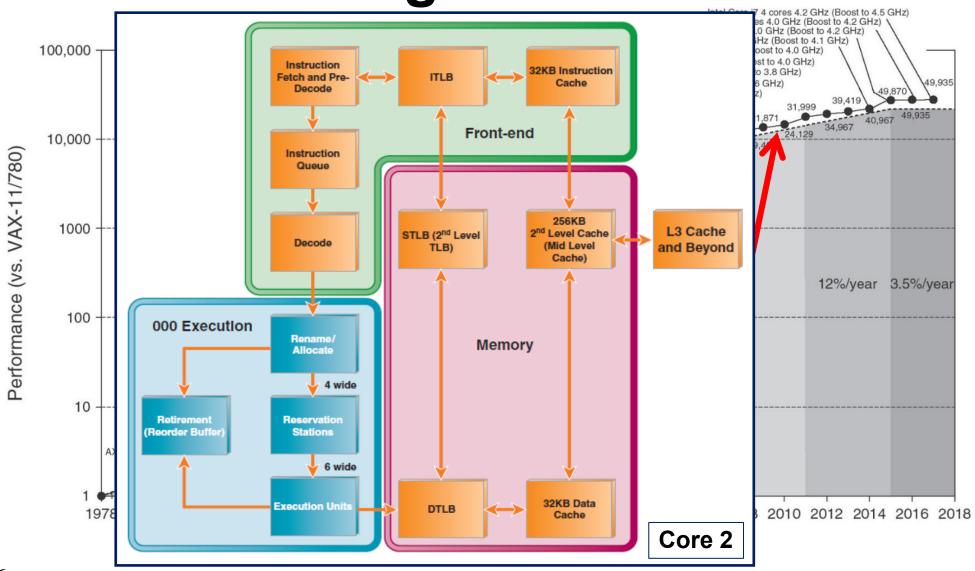


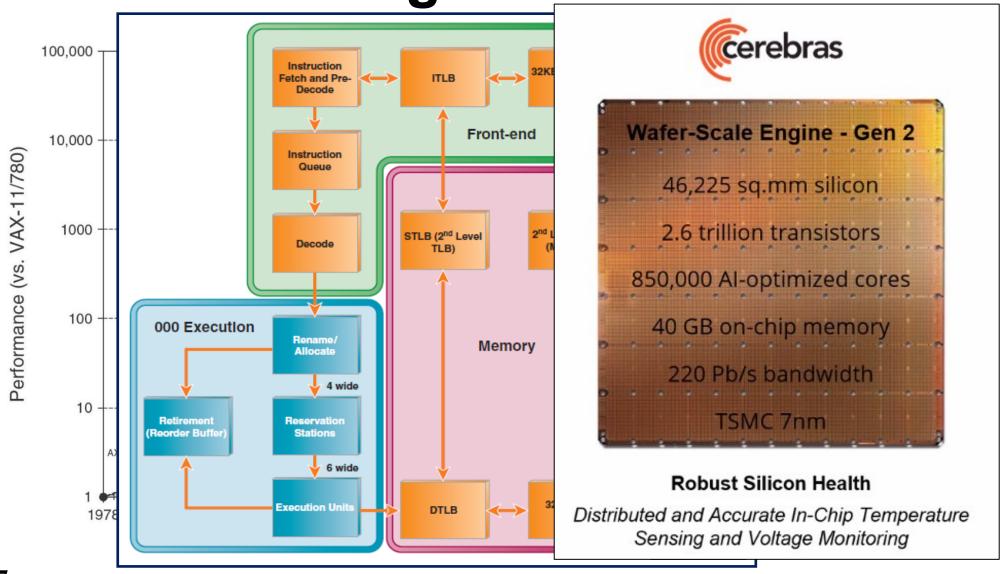








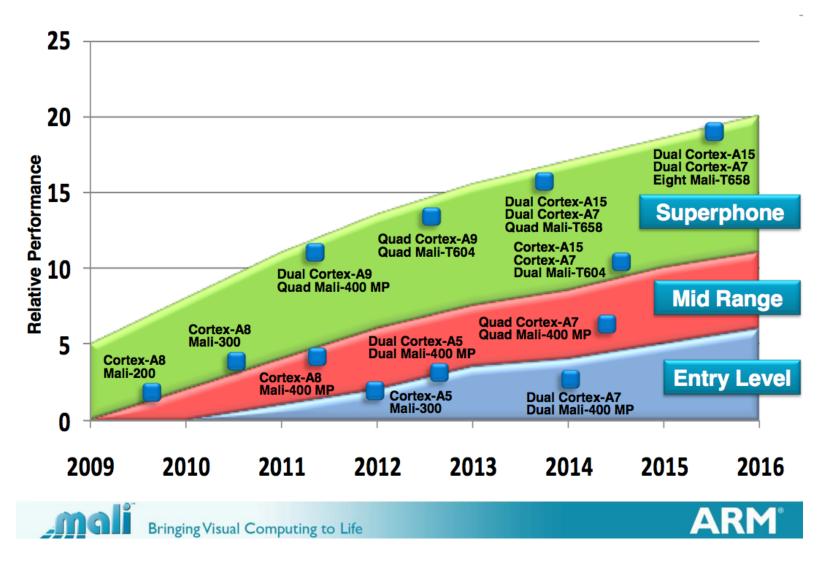




Trend

The major players in the microprocessor market (Intel, AMD, IBM, ARM) are not investing anymore in the development of faster processors, but rather on multiprocessor single chip systems (i.e., multicore devices).

Scalable Mobile Processor Evolution



The computer market

It is currently split in 5 different areas:

- Personal Mobile Device (PMD)
- Desktop computing
- Servers
- Clusters / Warehouse Scale Computers (WSC)
- Embedded computers.

Personal Mobile Device (PMD)

This area includes smart phones, and tablet computers Emphasis on energy efficiency and real-time applications.

System price: \$100 - \$1,000

Microprocessor price: \$10 - \$100

Desktop computing

This area covers from PCs to workstations.

The main target of this area is to optimize the *price-performance* ratio.

System price: \$300 - \$2,500

Microprocessor price: \$50 - \$500

Servers

These systems provide larger-scale and more reliable computing services.

The main parameters of products in this area are:

- Availability
- Scalability
- Throughput

System price: \$5,000 - \$10,000,000

Microprocessor price: \$200 - \$2,000

Clusters / Warehouse-Scale Computers (WAS)

"Software as a Service (SaaS)"

"Platform as a Service (PaaS)"

Emphasis on availability, price-performance, and power consumption

Supercomputers, emphasis: floating-point performance and fast internal networks

System price: \$100,000 - \$200,000,000

Microprocessor price: \$50 - \$250

Embedded computers

It covers all special-purpose computer-based applications (from microwaves to coffee machines, from automotive to videogames)

Adopted microprocessors vary from cheap low-end 8-bit processors to very efficient (and expensive) high-end processors, but are not able to run third-party software.

System price: \$10 - \$100,000

Microprocessor price: \$0.01 - \$100

Embedded computers

Special requirements often existing in this area are

- Real-time performance requirements
- Memory minimization
- Power consumption minimization
- Reliability constraints.

Embedded computers

Embedded problems are often solved resorting to one of the following solutions:

- Standard processor + custom logic + custom SW
- Standard processor + custom SW
- Standard DSP + custom SW.

Programmable devices (FPGAs) are playing a growing role.

Classes of Parallelism

- Data-level Parallelism (DLP):
 Many data items that can be operated on at the same time
- Task-level Parallelism (TaskLP): Different tasks of a work can operate independently.

Parallel Architectures

- Instruction-level Parallelism (ILP):
 Modestly exploits Data-level Parallelism
- Vector Architectures and Graphic Processor Unit (GPUs):
 - **Exploits Data-level Parallelism**
- Thread-level Parallelism (TLP):
 - **Exploits Data-level Parallelism and Task-level Parallelism**
- Request-level Parallelism (RLP):
 - Exploits parallelism among decoupled tasks.

Designing a computer

It means

- determining which attributes are important for the new machine
- designing a machine which
 - maximizes performance and
 - matches cost and power constraints.

Computer architecture

In the last decades, computer design took advantage of both

- Architectural innovation
- Technology improvements.

It was estimated that the difference between the highestperformance microprocessors available in 2001 and what would have been obtained by relying solely on technology is more than a factor of 15.

Computer architecture

It includes three aspects of computer design:

- Instruction set architecture
- Organization
- Hardware.

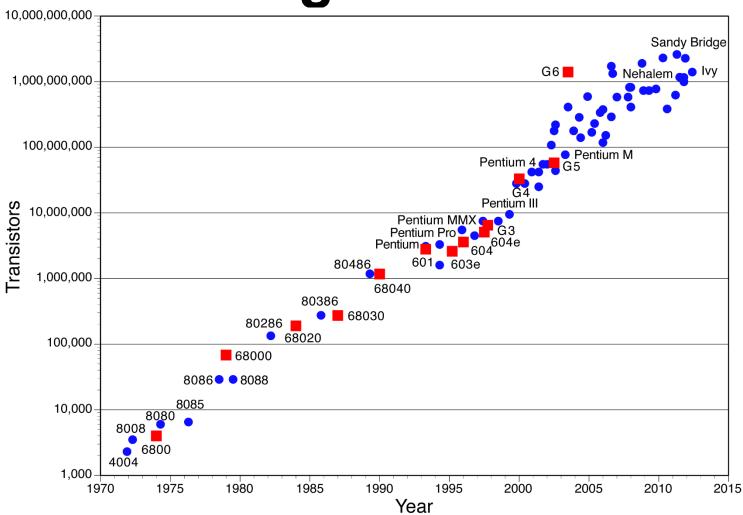
Computer architect must design a computer meeting:

- Functional requirements
- Price
- Power
- Performance
- Dependability.

Moore's Law

The number of devices (i.e., transistors) that can be integrated into a single chip doubles every 18/24 months.

Intel processors complexity growth



IC manufacturing cost

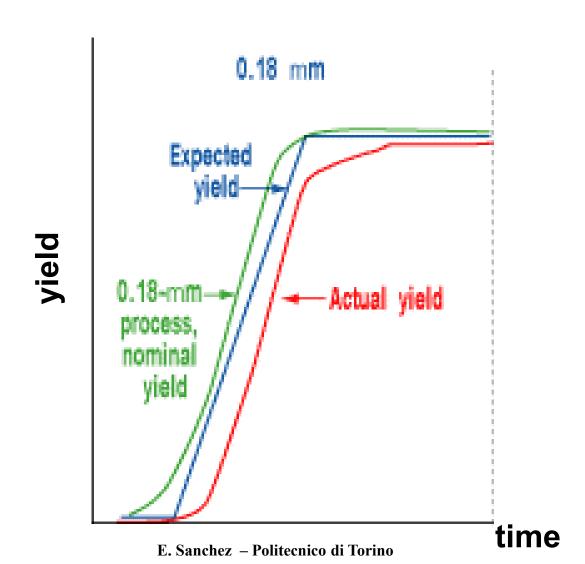
When evaluating it, it is important not to forget the impact of *yield*, i.e., the percentage of products that pass the test phase.

The production process for every product undergoes an evolution which normally leads to an improvement in yield (also known as *learning curve*).

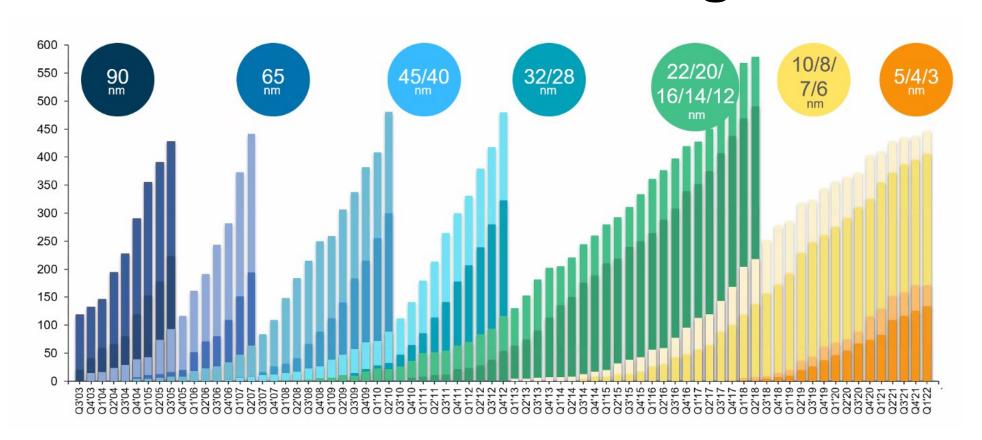
When yield increases, the cost decreases.

More than 50% of manufacturing cost is due to validation and testing procedures!!

Yield behavior



Industry adoption of new transistor technologies



Power consumption

Continuous increase in system complexity and device integration often lead to problems with power consumption.

Power consumption may be critical under two aspects:

- Power (static and dynamic)
- Energy (mainly for portable devices).

Power

Until now it has been dominated by dynamic power, i.e., that consumed by each transistor when switching between different states.

The dynamic power for each transistor can be evaluated by the formula

Power_{dynamic} = $\frac{1}{2}$ × capacitive load × voltage² × frequency Power_{static}= V × I (25% of total power consumption)

For this reason, voltage continuously dropped in the last years.

Energy

It is given by

Energy_{dynamic} = capacitive load \times voltage² It is mainly of interest for mobile devices.

Dependability

Dependability is the quality of the system to deliver a correct service.

Dependability of computer systems is traditionally very high, but it can be lowered by

- Bugs in the design of the hardware
- Bugs in the software
- Defects in the hardware (introduced by the manufacturing process)
- Faults happening during the product operation.

Safety-critical applications

In the past, possible misbehaviors of computer systems were critical in some areas, such as

- Space
- Avionics
- Nuclear plants control.

In the past years, computer-based systems expanded to other safety-critical areas, such as

- Rail-road traffic control
- Automotive
- Biomedical
- Telecommunications.

Dependability importance

It increased very much, because in several areas it is crucial to guarantee that the system matches the dependability constraints, e.g., in terms of probability of behaving as expected for long periods.

Dependability evaluation

Dependability is often measured using

- Mean Time To Failure (MTTF) or Failures In Time (FIT), which is its reciprocal. 1 FIT = 1 failure in one billion hours
- Mean Time Between Failures (MTBF)
- Mean Time To Repair (MTTR)

The three measures are related by the formula

$$MTBF = MTTF + MTTR$$

Finally, availability is the probability that a system works correctly in a generic time instant.

Computer performance

What is performance?

User point of view:

performance = response time (time between start and completion of an operation)

System manager point of view:

performance = throughput (total amount of work done in the time unit).

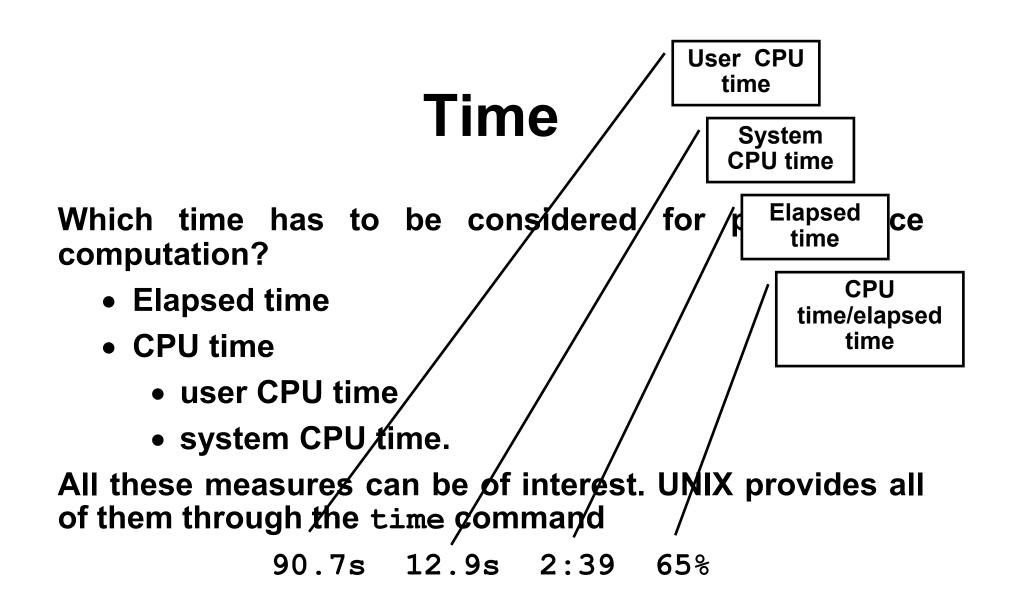
Time

Which time has to be considered for performance computation?

- Elapsed time
- CPU time
 - user CPU time
 - system CPU time.

All these measures can be of interest. UNIX provides all of them through the time command

90.7s 12.9s 2:39 65%



Performance evaluation

It is often performed by letting the computer to execute applications and observing its behavior.

Unfortunately, the choice of the applications severely affects the performance.

In the ideal case, one should use as workload the mix of applications the user will run.

However, they are normally unknown, and largely variable from one user to another.

Therefore, some benchmarks are selected to mimic real cases.

Program benchmarks

Possible benchmarks:

- Real programs (e.g., C compilers, text processors, special-purpose tools), possibly modified
- Kernels (e.g., Livermore Loops, Linpack)
- Toy benchmarks (e.g., Quicksort, Sieve of Eratostenes)
- Synthetic benchmarks (e.g., Whetstone, Dhrystone).

Benchmark suites

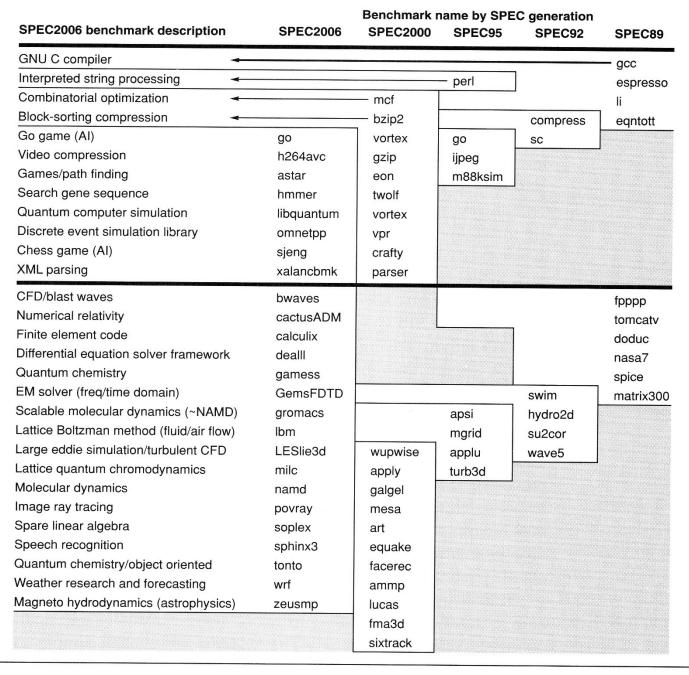
They contain a number of different programs, so that the weakness of any component is lessened by the presence of the others.

Benchmark sets are normally composed of:

- kernels
- program fragments
- applications.

SPEC evolution

Standard
Performance
Evaluation
Corporation



MiBench Benchmarks

Auto./Industrial	Consumer	Office	Network	Security	Telecomm.	
basicmath	jpeg	ghostscript	dijkstra	blowfish enc.	CRC32	
bitcount	lame	ispell	patricia	blowfish dec.	FFT	
qsort	mad	rsynth	(CRC32)	pgp sign	IFFT	
susan (edges)	tiff2bw	sphinx	(sha)	pgp verify	ADPCM enc.	
susan (corners)	tiff2rgba	stringsearch	(blowfish)	rijndael enc.	ADPCM dec.	
susan (smoothing)	tiffdither			rijndael dec.	GSM enc.	
	tiffmedian			sha	GSM dec.	
	typeset					

Reproducibility

Information about execution times on benchmarks should allow reproducibility.

This means reporting detailed information about

- hardware (system configuration)
- software (OS, compiler, program)
- program input.

Comparing and summarizing performance

Problem 1

I know the performance of one machine on a set of programs: which is its global performance?

Problem 2

I know the performance of two machines on the same set of programs: which is their relative performance?

A number of metrics have been proposed.

Index i runs over all benchmarks in the set

Total execution time

$$\sum_{i=1}^{n} Time_{i}$$

Normalized execution time

A reference machine is adopted (e.g., VAX-11/780) and execution times are normalized with respect to it.

Arithmetic Mean

Arithmetic mean:

$$\frac{1}{n} \sum_{i=1}^{n} Time_{i}$$

Weighted mean

Weighted arithmetic mean:

$$\sum_{i=1}^{n} Weight_{i} \times Time_{i}$$

Suggested solution

To measure a real workload and weight the programs according to their frequency of execution.

Program inputs should be carefully specified.

Example of weighted arithmetic mean execution time

	Machines			Weightings		
	A	В	С	W(1)	W(2)	W(3)
Program PI (secs)	1.00	10.00	20.00	0.50	0.909	0.999
Program P2 (secs)	1000.00	100.00	20.00	0.50	0.091	0.001
Arithmetic mean: W(1)	500.50	55.00	20.00	···		
Arithmetic mean: W(2)	91.91	18.19	20.00	~~		
Arithmetic mean: W(3)	2.00	10.09	20.00	,,,,,		

Guidelines and Principles for Computer Design

- Amdahl's law
- CPU performance equation.

Amdahl's Law: preliminaries

$$speedup = \frac{performance\ with\ enhancement}{performance\ without\ enhancement}$$

The speedup resulting from an enhancement depends on two factors:

- fraction_{enhanced}: the fraction of the computation time that takes advantage of the enhancement
- speedup_{enhanced}: the size of the enhancement on the parts it affects.

Amdahl's Law

execution time_{old}
$$\times ((1 - fraction_{enhanced}) + \frac{fraction_{enhanced}}{speedup_{enhanced}})$$

$$speedup_{overall} = \frac{execution time_{old}}{execution time_{new}} =$$

 $(1-fraction_{enhanced}) + \frac{fraction_{enhanced}}{speedup}$

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Example

An enhancement makes one machine 10 times faster for 40% of the programs the machine runs. Which is the overall speedup?

$$fraction_{enhanced} = 0.4$$

 $speedup_{enhanced} = 10$

speedup_{overall} =
$$\frac{1}{(1-0.4) + \frac{0.4}{10}} = 1.56$$

Choosing between two solutions: an example

Two solutions are available for increasing the floatingpoint performance of one machine.

Solution 1

Increasing by 10 the performance of square root operations (responsible for 20% of the execution time) by adding specialized hardware.

Solution 2

Increasing by 2 the performance of all the floating-point operations (responsible for 50% of the execution time).

Which solution makes the machine faster?

Amdahl's Law application

Solution 1

speedup₁ =
$$\frac{1}{(1-0.2) + \frac{0.2}{10}} = 1.22$$

Solution 2

speedup₂ =
$$\frac{1}{(1-0.5) + \frac{0.5}{2}} = 1.33$$

Measuring the time required to execute a program

Possible approaches:

- by observing the real system
- by simulation
- by applying the CPU performance equation.

The CPU Performance Equation

CPU time =
$$(\sum_{i=1}^{n} CPI_i \times IC_i) \times Clock$$
 cycle time

where

- CPI_i is the number of clock cycles required by instruction i
- *IC_i* is the number of times instruction i is executed in the program
- clock cycle time is the inverse of clock frequency.

Equation

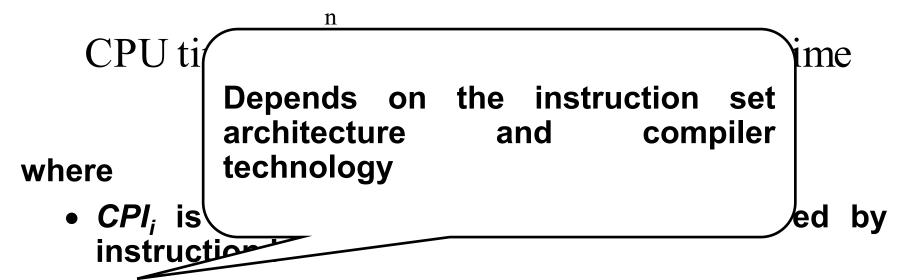
Depends on the hardware organization and instruction set architecture

bck cycle time

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The CPU Performance Equation



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The CPU Performance Equation

CPU time =
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 cycle time

where

instruction

Depends hardware the • CPI, is the technology and organization

• IC; is the n in the program

• clock cycle time is the inverse of clock frequency.

The CPU Performance Equation limitations

In pipelined processors, CPI_i may vary for a given instruction, depending on different parameters

- Instructions executed before and after
- Memory system behavior (e.g., cache miss or hit)

Therefore, evaluating the execution time analytically becomes much harder.