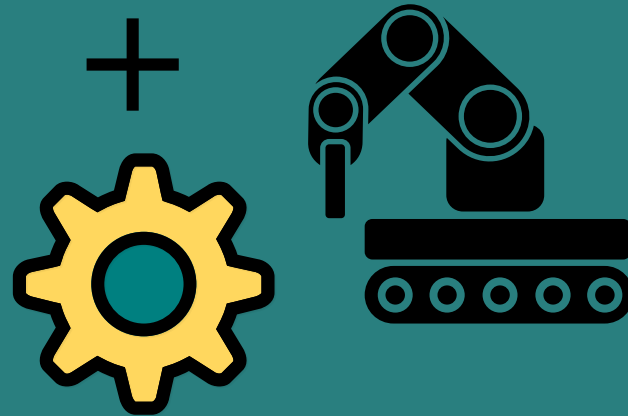


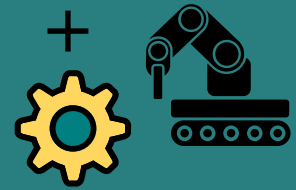
 ROS



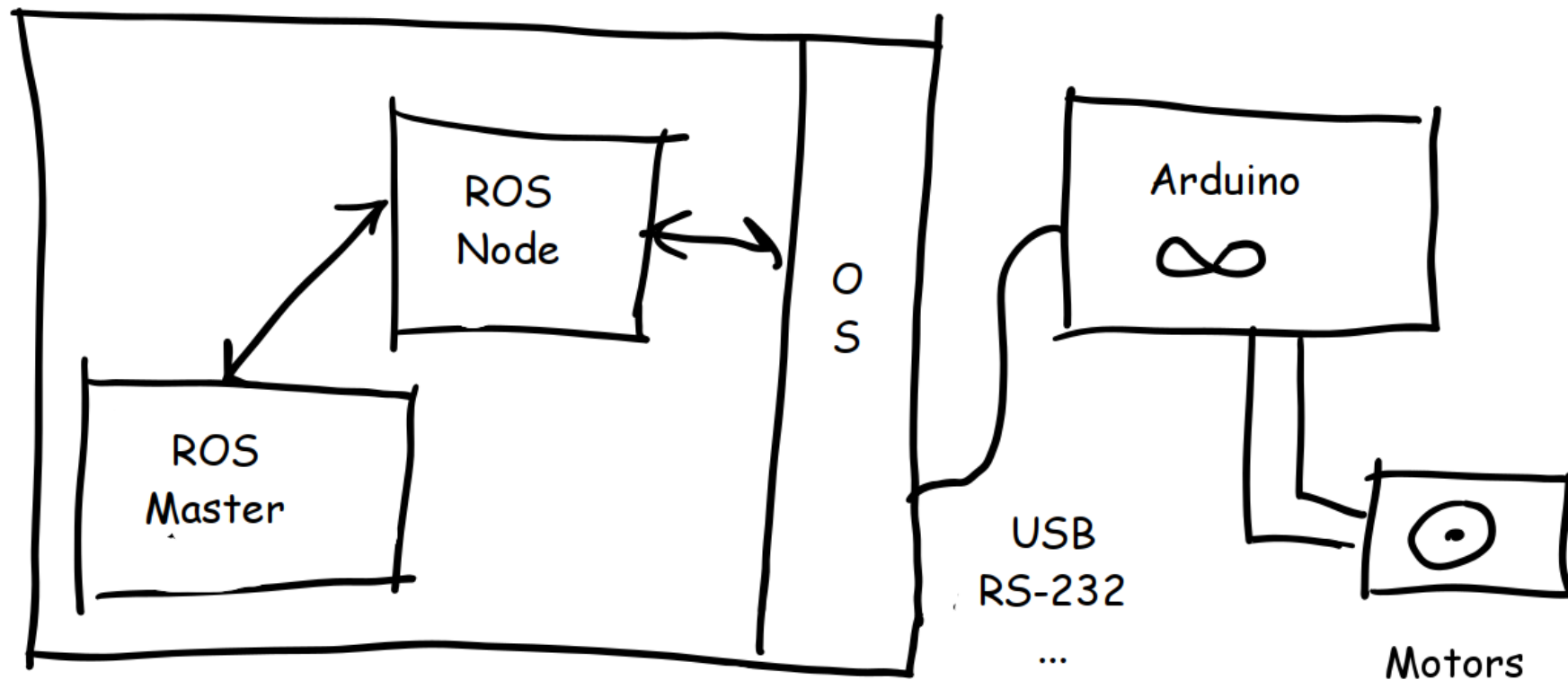
# MACHINEKIT AND ROS

COMBINING MACHINEKIT AND ROS FOR RT MOTION CONTROL WITH  
ROS1 OR ROS2

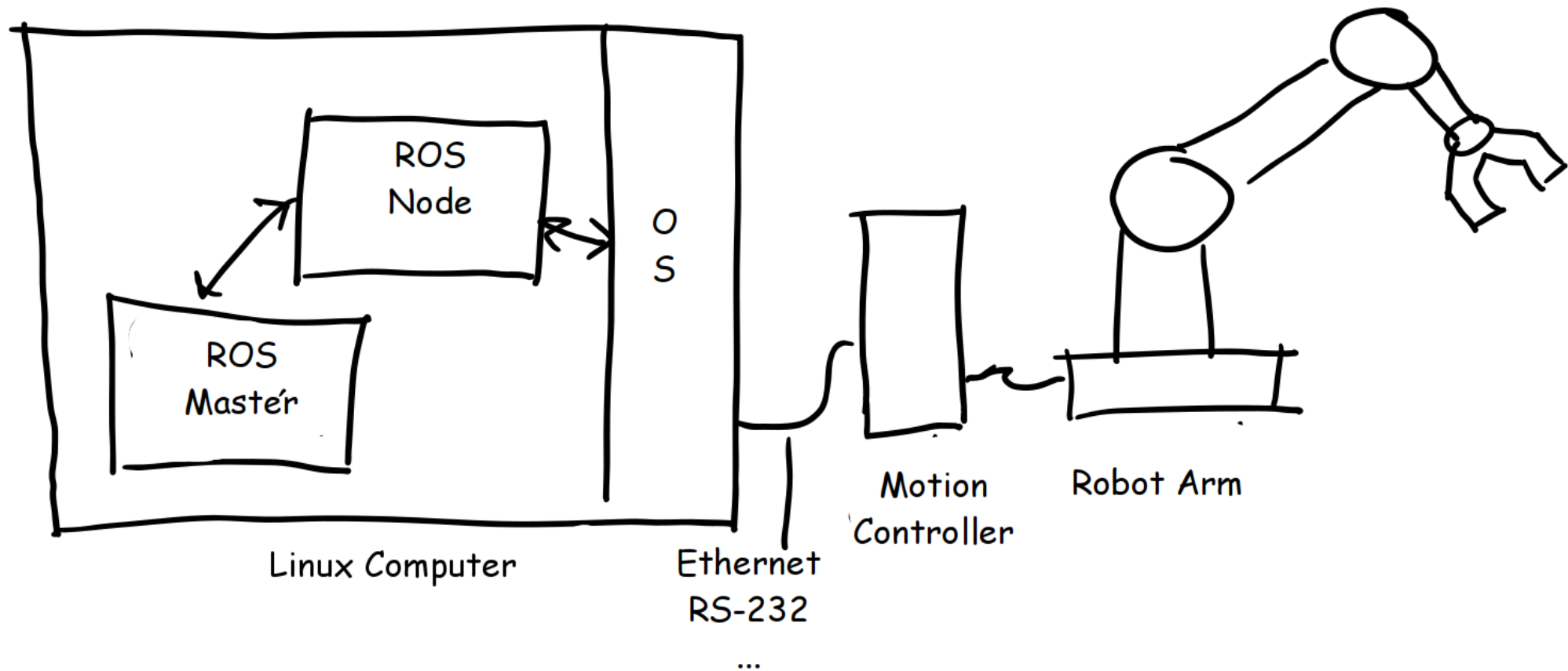
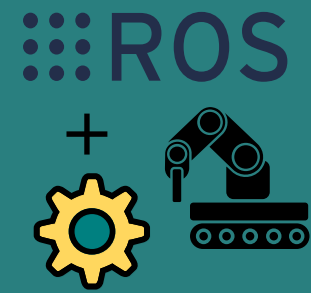
Alexander Rössler

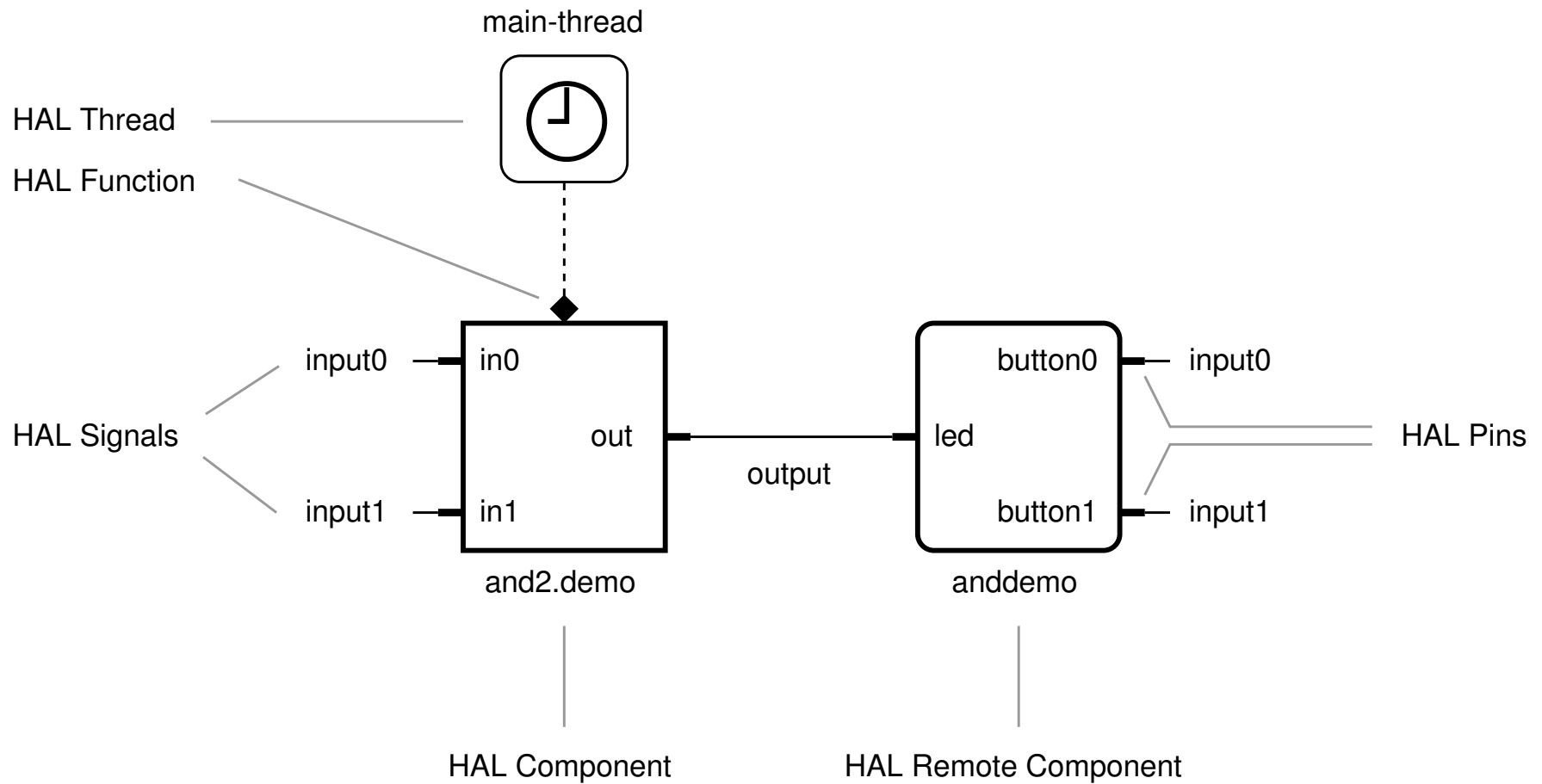


# CURRENT MOTION CONTROL

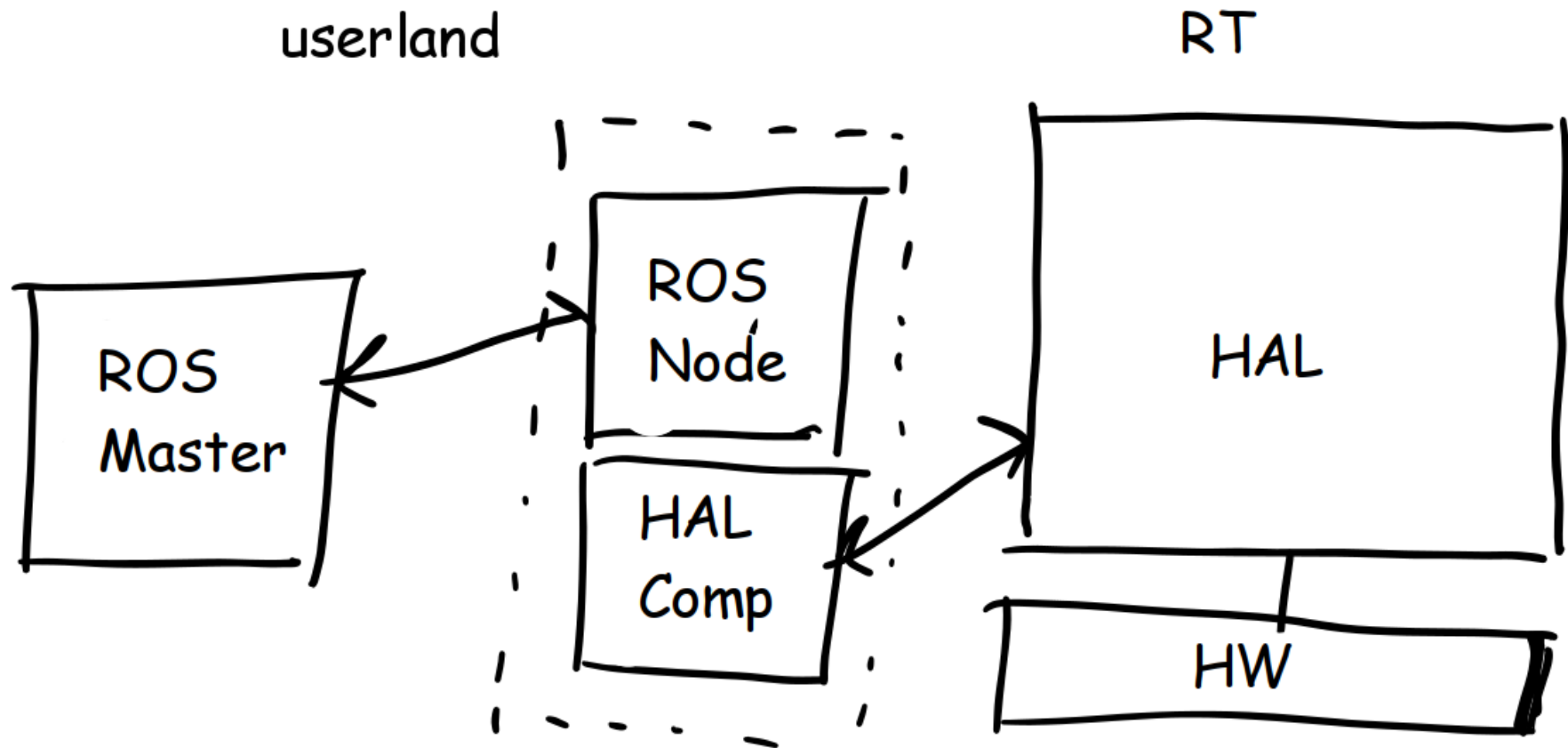
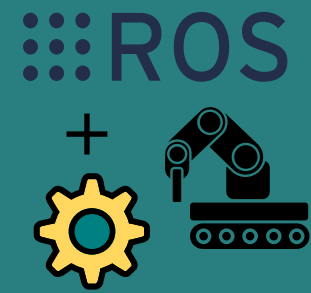


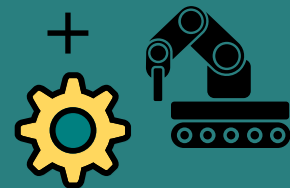
# CURRENT MOTION CONTROL



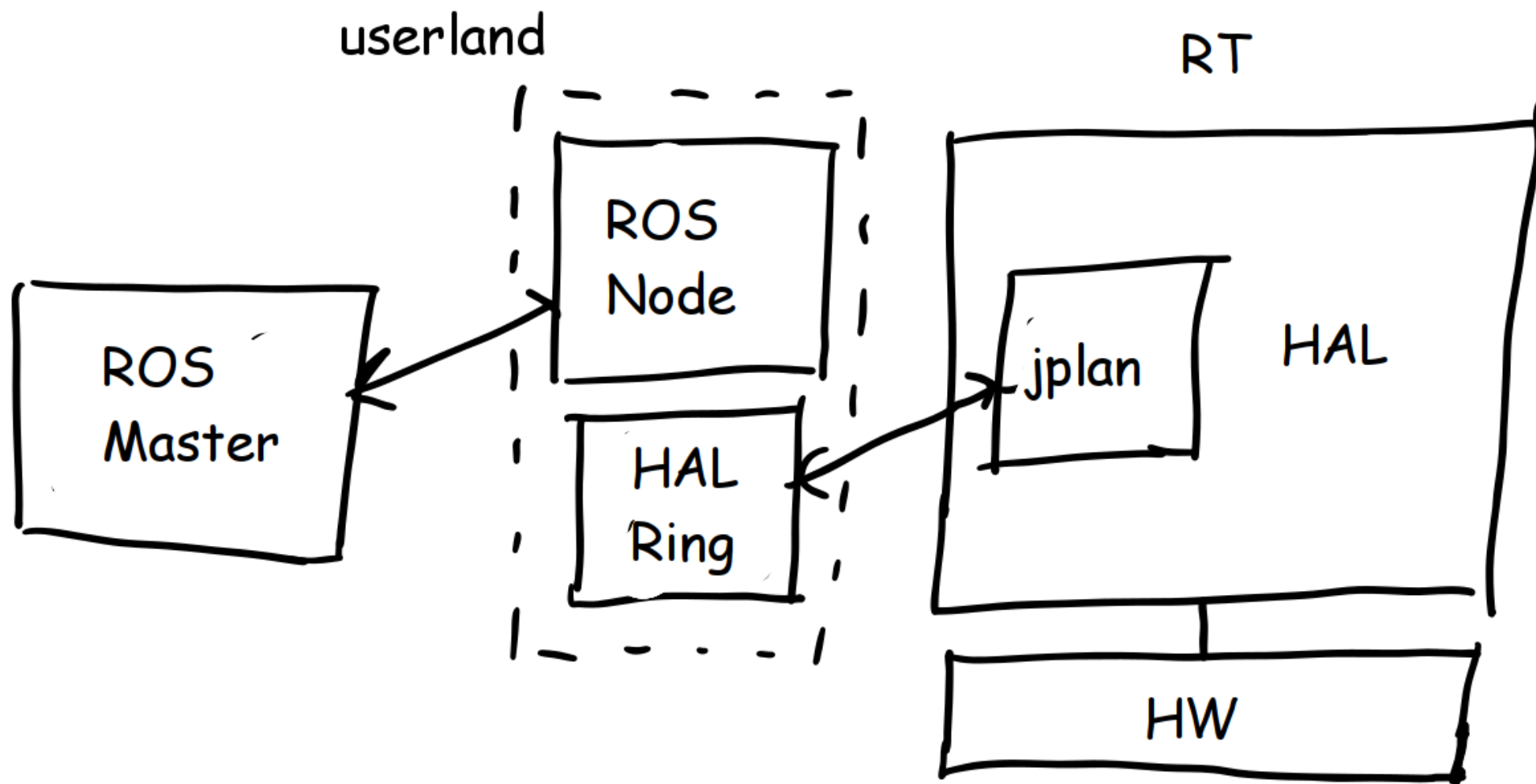


# ROS Node → HAL Comp

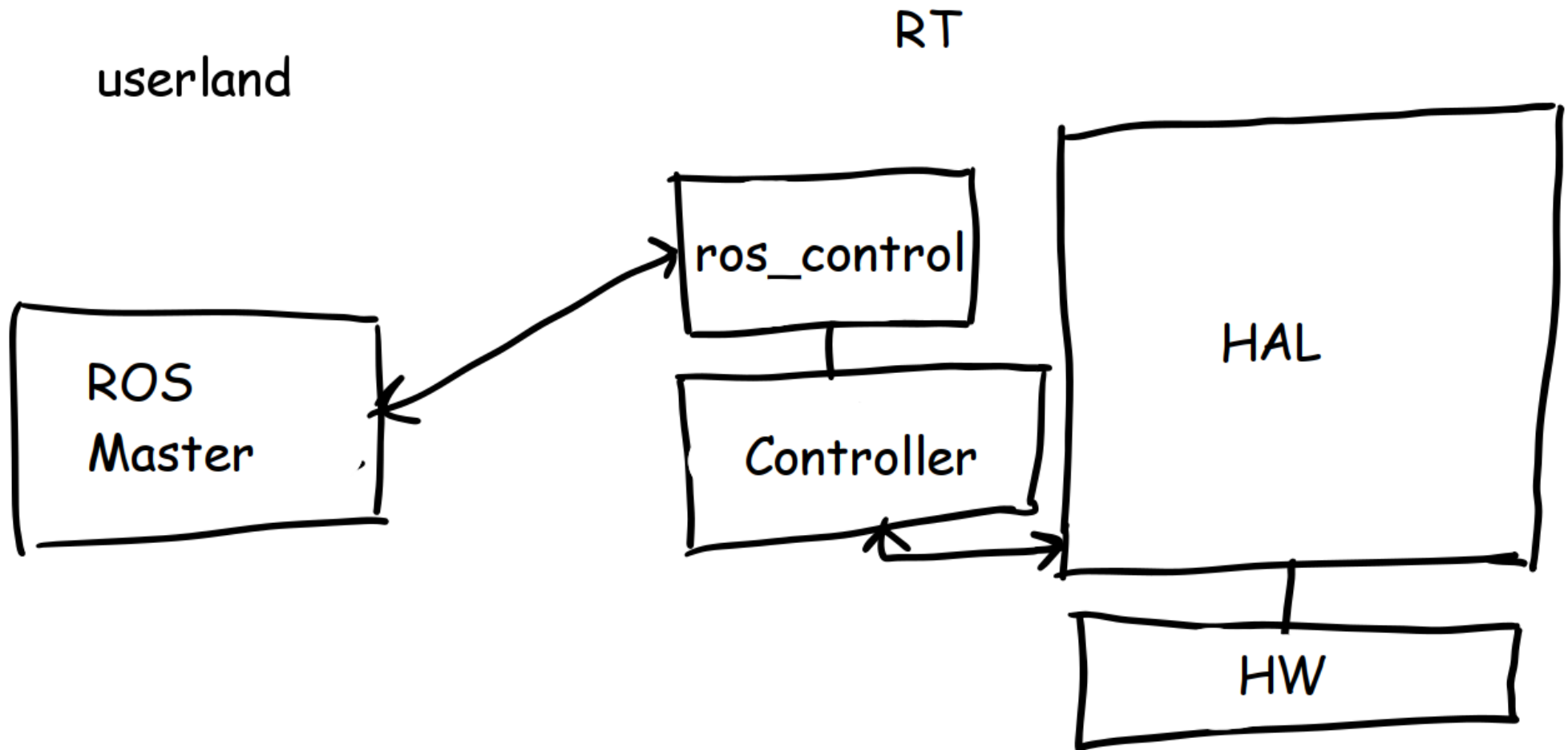
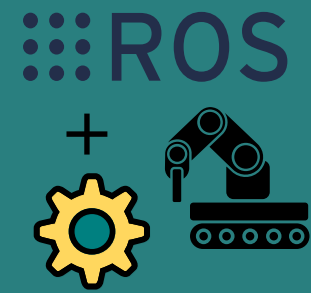


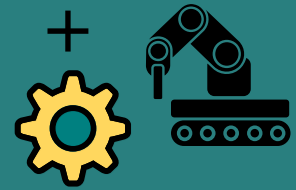


# ROS Node → HAL PLAYOUT



# MACHINEKIT ROS CONTROL





## LINKS + QUESTIONS?

- <https://machinekoder.com/machinekit-ros-open-source-robots/>
- <http://machinekit.io>
- [alex@machinekoder.com](mailto:alex@machinekoder.com)