

Robot control with ROS

0. Setup

0.1 Python

```
pip install numpy scipy
```

0.2 ROS - Gazebo

```
# uncomment this line to add keys, sometime it could be needed
# sudo apt-key adv --keyserver keyserver.ubuntu.com --recv-keys F42ED6FBAB17C654

# install packages
sudo apt install ros-noetic-ros-control ros-noetic-ros-controllers
```