

1 Syntactic Definitions

1.1 Axiomatic System

We also define an axiomatization of *ReLo* based on other dynamic logics tailored to reason about programs. We discuss and define *ReLo*'s axioms as follows. Let φ and ψ be formulas.

Definition 1. *Axiomatic System*

(PL) *Enough Propositional Logic tautologies*

(K) $[t, \pi](\varphi \rightarrow \psi) \rightarrow ([t, \pi]\varphi \rightarrow [t, \pi]\psi)$

(And) $[t, \pi](\varphi \wedge \psi) \leftrightarrow [t, \pi]\varphi \wedge [t, \pi]\psi$

(Du) $[t, \pi]\varphi \leftrightarrow \neg \langle t, \pi \rangle \neg \varphi$

(R) $\langle t, \pi \rangle \varphi \leftrightarrow \varphi$ if $f(t, \pi) = \epsilon$

(It) $\varphi \wedge [t, \pi][t, \pi^*]\varphi \leftrightarrow [t, \pi^*]\varphi$

(In) $\varphi \wedge [t, \pi^*](\varphi \rightarrow [t, \pi]\varphi) \rightarrow [t, \pi^*]\varphi$

and the following rules.

$$\textbf{(MP)} \quad \frac{\varphi \quad \varphi \rightarrow \psi}{\psi}$$

$$\textbf{(Gen)} \quad \frac{\varphi}{[t, \pi]\varphi}$$

Axioms **(PL)**, **(K)**, **(And)** and **(Du)** are standard in Modal Logic literature (along with rules **(MP)** and **(Gen)**). Axiom **(It)** respectively denotes the reasoning over nondeterministic iteration denoted by the operator \star , following a similar idea portrayed by Axiom (vii) as in Propositional Dynamic Logic (PDL), denoting an intuitive meaning regarding the notion of program iteration: if φ holds in the current state and after a single execution of π with t , any finite nondeterministic number of iterations of π with t preserves φ 's truth value, then φ must hold after any (nondeterministic finite) number of iterations of π with t .

Axiom **(In)** is an axiom which carries the same idea for PDL. It enables the inductive reasoning on programs by carrying the following intuitive meaning: "considering that φ holds in the current state, if after any (nondeterministic finite) number of iterations of π with its respective input t φ holds, then it will hold after any number of iterations of π taking t as its input.

We discuss the proofs of validity (w.r.t. *ReLo*'s model) of **(R)**, **(It)** and **(In)** as follows.

Definition 2. *Validity of ReLo's axiomatic system*

1. **(R)**

Proof.

Suppose by contradiction that exists a state s from a model $\mathcal{M} = \langle S, R_\pi, \delta, \lambda, V \rangle$ where **(R)** does not hold. There are two possible cases.

(\rightarrow)

Suppose by contradiction $\mathcal{M}, s \Vdash \langle t, \pi \rangle \varphi$ and $\mathcal{M}, s \nVdash \varphi$. $\mathcal{M}, s \Vdash \langle t, \pi \rangle \varphi$ iff there is a state $v \in S$ such that $sR_\pi v$. Because $f(t, \pi) = \epsilon, s = v$ (i.e., in this execution no other state is reached from s). Therefore, $\mathcal{M}, s \Vdash \varphi$, contradicting $\mathcal{M}, s \nVdash \varphi$.

(\leftarrow)

Suppose by contradiction $\mathcal{M}, s \Vdash \varphi$ and $\mathcal{M}, s \nVdash \langle t, \pi \rangle \varphi$. In order to $\mathcal{M}, s \nVdash \langle t, \pi \rangle \varphi$, for every state $v \in S$ such that $sR_\pi v$, $\mathcal{M}, v \nVdash \varphi$. Because $f(t, \pi) = \epsilon, s = v$ (i.e., in this execution no other state is reached from s). Therefore, $\mathcal{M}, v \Vdash \varphi$, contradicting $\mathcal{M}, v \nVdash \varphi$.

□

2. **(It)**

Proof.

Suppose by contradiction that exists a state s from a model $\mathcal{M} = \langle S, R_\pi, \delta, \lambda, V \rangle$ where **(It)** does not hold. There are two possible cases.

(\rightarrow)

Suppose by contradiction $\mathcal{M}, s \Vdash \varphi \wedge [t, \pi][t, \pi^*]\varphi$ and $\mathcal{M}, s \nVdash [t, \pi^*]\varphi$. Therefore, $\mathcal{M}, s \Vdash \varphi$ and $\mathcal{M}, s \Vdash [t, \pi][t, \pi^*]\varphi$. For $\mathcal{M}, s \Vdash [t, \pi][t, \pi^*]\varphi$, every state $w \in S$ such that $sR_\pi w$, $\mathcal{M}, w \Vdash [t, \pi^*]\varphi$. Then, for $\mathcal{M}, w \Vdash [t, \pi^*]\varphi$, every state $v \in S$ such that $wR_{\pi^*} v$, $\mathcal{M}, v \Vdash \varphi$. From $\mathcal{M}, s \nVdash [t, \pi^*]\varphi$, there is a state $u \in S$ such that $sR_{\pi^*} u$ and $\mathcal{M}, u \nVdash \varphi$. Because $sR_\pi w$ and $wR_{\pi^*} v$ from R_{π^*} we have $sR_{\pi^*} v$. Then, for all u such that $sR_{\pi^*} u$, $\mathcal{M}, u \Vdash \varphi$ which contradicts the existence of a state u such that $sR_{\pi^*} u$ and $\mathcal{M}, u \nVdash \varphi$.

(\leftarrow)

Suppose by contradiction $\mathcal{M}, s \Vdash [t, \pi^*]\varphi$ and $\mathcal{M}, s \nVdash \varphi \wedge [t, \pi][t, \pi^*]\varphi$. Then, $\mathcal{M}, s \Vdash \neg(\varphi \wedge [t, \pi][t, \pi^*]\varphi)$ which is $\mathcal{M}, s \Vdash \neg\varphi$ or $\mathcal{M}, s \Vdash \neg[t, \pi][t, \pi^*]\varphi$. In order to $\mathcal{M}, s \Vdash [t, \pi^*]\varphi$, for each state $w \in S$ such that $sR_\pi^* w$, $\mathcal{M}, w \Vdash \varphi$. By the definition of R_π^* , $sR_\pi^* s$. Then, $\mathcal{M}, s \Vdash \varphi$ which contradicts $\mathcal{M}, s \Vdash \neg\varphi$. Now, considering $\mathcal{M}, s \Vdash \neg[t, \pi][t, \pi^*]\varphi$, for each state $v \in S$ such that $sR_\pi v$, $\mathcal{M}, v \nVdash [t, \pi^*]\varphi$. Then, to $\mathcal{M}, v \nVdash [t, \pi^*]\varphi$, there exists a state $u \in S$ such that $vR_\pi^* u$ and $\mathcal{M}, u \nVdash \varphi$. Because $sR_\pi v$ and $vR_\pi^* u$, $sR_\pi^* u$. From $\mathcal{M}, w \Vdash \varphi$, there is no state u such that $\mathcal{M}, u \nVdash \varphi$, which is a contradiction.

□

3. **(Ind)**

Proof.

Suppose by contradiction that exists a state s from a model $\mathcal{M} = \langle S, R_\pi, \delta, \lambda, V \rangle$ where **(Ind)** does not hold. Therefore, suppose $\mathcal{M}, s \Vdash \varphi \wedge [t, \pi^*](\varphi \rightarrow [t, \pi]\varphi)$ and $\mathcal{M}, s \nVdash [t, \pi^*]\varphi$. Then, $\mathcal{M}, s \Vdash \varphi$ and $\mathcal{M}, s \Vdash [t, \pi^*](\varphi \rightarrow [t, \pi]\varphi)$. Then, for all states $w \in S$ such that sR_π^*w , $\mathcal{M}, w \Vdash \varphi \rightarrow [t, \pi]\varphi$ which is $\mathcal{M}, w \Vdash \neg\varphi \vee [t, \pi]\varphi$. Then, $\mathcal{M}, w \Vdash \neg\varphi$ or $\mathcal{M}, w \Vdash [t, \pi]\varphi$. Considering $\mathcal{M}, w \Vdash \neg\varphi$, by R_π^* we have sR_π^*s . Because $\mathcal{M}, s \Vdash \varphi$, there is a state w (namely, $s = w$) where $\mathcal{M}, w \Vdash \neg\varphi$ does not hold, resulting in a contradiction. Now, considering $\mathcal{M}, w \Vdash [t, \pi]\varphi$, for each state $v \in S$ such that $wR_\pi v$, $\mathcal{M}, v \Vdash \varphi$. Because sR_π^*w and $wR_\pi v$, by the definition of R_π^* sR_π^*v . Then, if $\mathcal{M}, s \nVdash [t, \pi^*]\varphi$ then there is a state $u \in S$ such that sR_π^*u and $\mathcal{M}, u \nVdash \varphi$. Because for each state $v \in S$ such that $wR_\pi v$, $\mathcal{M}, v \Vdash \varphi$, such state u cannot exist as it is a contradiction. \square