

Telegram Bot



Telegram Bot

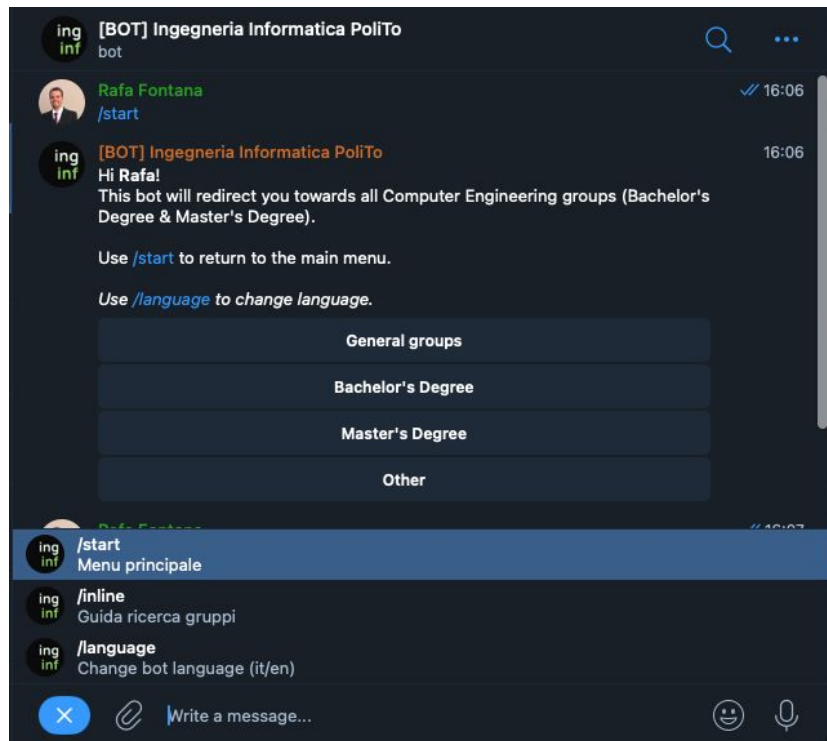


Bots are third-party applications that run inside Telegram. Users can interact with bots sending them messages, commands and inline requests. You control the bots sending HTTPS requests to our Bot API.

[What can be done with bots?](#)

Telegram Bot and IoT

For this course, Telegram-bots will essentially take the place of an app that is usually developed for a commercial project. We will see the basics steps to create a bot, communicate with it and use it to retrieve information and interact with our systems.



Requirements

Before we start to code, we need to do two things:

- Install the Python library called `telepot`

```
Terminal  
pip3 install telepot
```

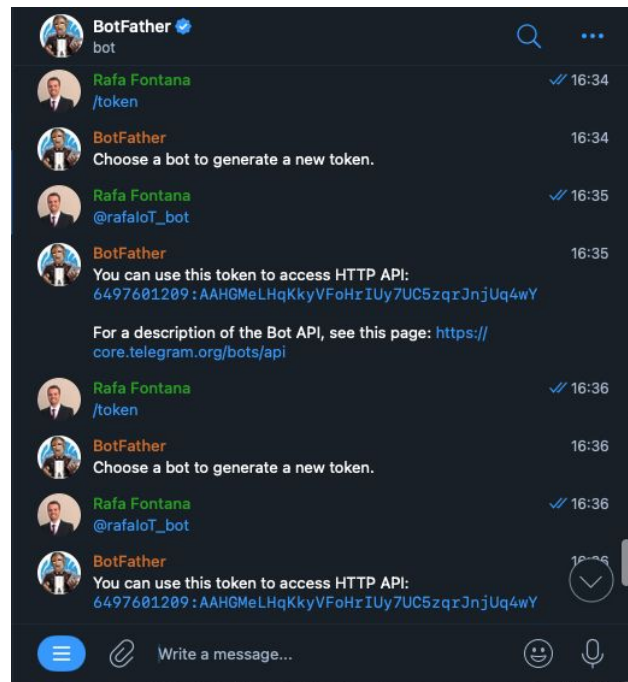
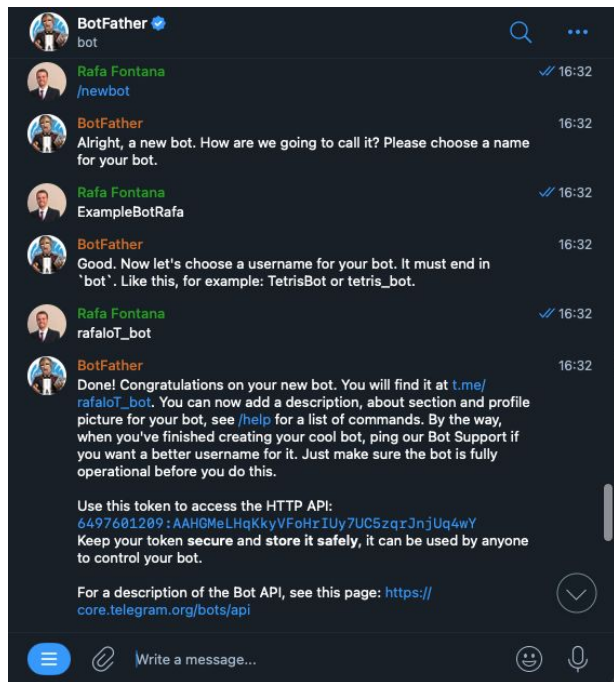
- Contact [Botfather](#) to obtain a token for our bot

Once we have the token we can save it in a json file

⚠⚠⚠ **For the project, we can store the token on the Catalog** ⚠⚠⚠



BotFather



Simple Echo Bot

Bot Initialization

```
import telepot
from telepot.loop import MessageLoop
import json
import requests

class MyBot:
    def __init__(self, token):
        # Local token
        self.tokenBot=token
        # Catalog token
        #self.tokenBot=requests.get("http://catalogIP/telegram_token").json()["telegramToken"]
        self.bot=telepot.Bot(self.tokenBot)
        MessageLoop(self.bot,{'chat': self.on_chat_message}).run_as_thread()
```

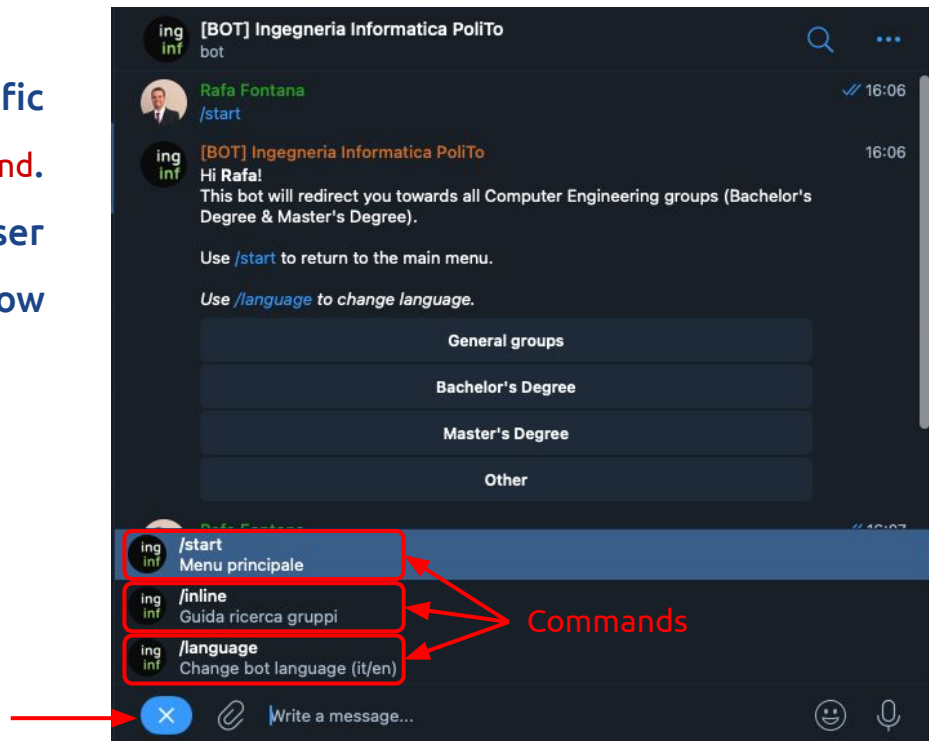
Simple Echo Bot

On-chat_message callback

```
def on_chat_message(self,msg):  
    content_type, chat_type ,chat_ID = telepot.glance(msg)  
    message=msg['text']  
  
    self.bot.sendMessage(chat_ID,text="You sent:\n"+message)
```

Commands

Usually Telegram bot accept some specific commands in the chat given in the format **/command**. With BotFather we can add some hints for the user but then we need to specify inside the code how this command will be handled



Bot + Actuation via MQTT 1/4

Now we will see how to send commands using MQTT to switch on/off the simulated led (`lightActuator.py`) we used in the previous exercises (MQTT Exercises - 03_MQTT).

```
class Led:
    def __init__(self, clientID, topic, broker, port):
        self.client = MyMQTT(clientID, broker, port, self)
        self.topic = topic
        self.status = None

    def start(self):
        self.client.start()
        self.client.mySubscribe(self.topic)

    def stop(self):
        self.client.stop()

    def notify(self, topic, msg):
        d = json.loads(msg)
        self.status = d['e'][0]['v']
        client = d['bn']
        timestamp = d['e'][0]['t']
        print(f'The led has been set to {self.status} at time {timestamp} by the client {client}')
```

Bot + Actuation via MQTT 2/4

We need to do two steps:

1. Adding an instance of the class `MyMQTT` to enable our bot to be a publisher
2. Handle the command sent from the user to switch the led on or off

Bot + Actuation via MQTT 3/4

Enable MQTT

```
class SimpleSwitchBot:
    #....
    self.client=MyMQTT("telegramBot",broker,port,None)
    self.client.start()
    self.topic=topic
    self.__message={
        'bn':"telegramBot",
        'e':[
            {'n':'switch','v':'', 't':'','u':'bool'},
        ]
    }
    #....
```

Bot + Actuation via MQTT 4/4

Manage Commands

```
def on_chat_message(self,msg):
    content_type, chat_type ,chat_ID = telepot.glance(msg)
    message=msg['text']
    if message==" /switchon":
        payload=self.__message.copy()
        payload['e'][0]['v']="on"
        payload['e'][0]['t']=time.time()
        self.client.myPublish(self.topic,payload)
        self.bot.sendMessage(chat_ID,text="Led switched on")
    elif message==" /switchoff":
        payload=self.__message.copy()
        payload['e'][0]['v']="off"
        payload['e'][0]['t']=time.time()
        self.client.myPublish(self.topic,payload)
        self.bot.sendMessage(chat_ID,text="Led switched off")
    else:
        self.bot.sendMessage(chat_ID,text="Command not supported")
```

Bot callback and Keyboards 1/2

Keyboard tools

```
from telepot.namedtuple import InlineKeyboardMarkup, InlineKeyboardButton
```

Query callback

```
MessageLoop(self.bot, {'chat': self.on_chat_message,  
                        'callback_query': self.on_callback_query}).run_as_thread()
```

Bot callback and Keyboards 2/2

In the callback query we will define the behaviour to follow according to the value of **callback_data**

```
def on_callback_query(self,msg):
    query_ID , chat_ID , query_data = telepot.glance(msg,flavor='callback_query')

    payload = self.__message.copy()
    payload['e'][0]['v'] = query_data
    payload['e'][0]['t'] = time.time()
    self.client.myPublish(self.topic, payload)
    self.bot.sendMessage(chat_ID, text=f"Led switched {query_data}")
```

Exercise 1

Create a telegram bot with a REST interface that is able to receive POST requests with a body like `{"alert":"...","action":"..."}` and sends a message to an user.

Tip

In your project, the body should contain also something that identifies the user. In this way, the bot can ask to the catalog which is the `chat_id` corresponding to that user. Just for this exercise, you can obtain the `chat_id` from the `/start` message

Exercise 2

Create a telegram bot with an MQTT interface. The bot should be subscribed to a topic like `"MyProjectID/alert/#"` and should receive messages like `{"alert":"...", "action":"..."}` and sends a message to a user.

Tip

In your project, the body should contain also something that identifies the user. In this way, the bot can ask to the catalog which is the `chat_id` corresponding to that user. Just for this exercise, you can obtain the `chat_id` from the `/start` message