

Parameter estimation in PDE-regularized spatial regression via parameter cascading

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Data:

- $\mathbf{p}_1,...,\mathbf{p}_n$ n locations in $\Omega \subset \mathbb{R}^2$
- $t_1,..,t_m$ time steps in $\mathcal{T}\subset\mathbb{R}$
- z_{ij} variable of interest observed at (\mathbf{p}_i, t_j)

Space-Time model:

- $f: \Omega \times \mathcal{T} \to \mathbb{R}$ deterministic spatio-temporal field
- $-z_{ij} = f(\mathbf{p}_i, t_j) + \epsilon_{ij}, \qquad i = 1, ..., n, \quad j = 1, ..., m$
- ϵ_{ij} i.i.d. residuals with zero mean and finite variance σ^2

Goal: estimate f minimizing

$$J_{\rho,\gamma}(f) = \frac{1-\rho}{nm} \sum_{i=1}^{n} \sum_{j=1}^{m} (z_{ij} - f(\mathbf{p}_i, t_j))^2 + \frac{\rho}{|\Omega|} \int_{\Gamma} \int_{\Omega} (\gamma \frac{\partial f}{\partial t} + Lf - u)^2$$

- $ho \in (0,1)$ smoothing parameter
- $Lf = -\nabla \cdot (K\nabla f)$, $K \in \mathbb{R}^{2 \times 2}$ diffusion matrix
- u = 0
- γ unknown PDE parameter to estimate via profiling estimation (parameter cascading)

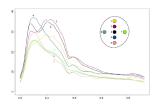
Bernardi et al., 2018, JMVA

- Space only
- Estimation of the anisotropy matrix K via parameter cascading
- Switzerland rainfall data



Arnone et al., 2019, JMVA

- Space-time
- Blood-flow velocity field in a carotid artery affected by atherosclerosis



$$J_{\rho}(f,K) = \frac{1-\rho}{n} \sum_{i=1}^{n} (z_i - f(\mathbf{p}_i))^2 + \frac{\rho}{|\Omega|} \int_{\Omega} (\nabla \cdot (K\nabla f))^2 J_{\lambda}(f) = \sum_{i=1}^{n} \sum_{j=1}^{m} (z_{ij} - f(\mathbf{p}_i, t_j))^2 + \lambda \int_{\mathcal{T}} \int_{\Omega} (\frac{\partial f}{\partial t} + Lf - u)^2 J_{\lambda}(f) = \sum_{i=1}^{n} \sum_{j=1}^{m} (z_{ij} - f(\mathbf{p}_i, t_j))^2 J_{\lambda}(f) = \sum_{i=1}^{n} \sum_{j=1}^{n} (z_{ij} - f(\mathbf{p}_i, t_j))^2 J_{\lambda}(f) = \sum_{i=1}^{n}$$

Analyze and implement a **statistical technique** to estimate f and γ by means of **parameter cascading**

True field

Estimated field

For fixed increasing values of ρ , perform:

Step 1: Estimate \hat{f} keeping γ fixed, minimizing J:

$$J_{\rho,\gamma}(f) = (1-\rho)\frac{1}{n}\sum_{i=1}^{n}\sum_{j=1}^{m}(z_{ij}-f(\mathbf{p}_{i},t_{j}))^{2} + \rho\frac{1}{|\Omega|}\int_{T}\int_{\Omega}(\gamma\frac{\partial f}{\partial t}-K\Delta f)^{2}$$

Step 2: Estimate $\hat{\gamma}$ keeping \hat{f} fixed, minimizing H:

$$H(\gamma) = \sum_{i=1}^{n} \sum_{j=1}^{m} (z_{ij} - \hat{f}_{\rho,\gamma}(\mathbf{p}_i, t_j))^2$$

In our case, we chose:

$$\rho = (0.01, 0.05, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 0.95, 0.99)$$

Pseudo-code 6/

Algorithm 1 Estimation of γ through parameter cascading

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1: Create a vector with n different values of \rho
2: for \rho_i,\ i=1,...,n do
3: if i=1 then
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- 4: Set γ to an initial value (e.g. 1)
- 5: **else**
- 6: Set γ to the estimate of the previous step
- 7: end if
- 8: Minimize the functional H and find the optimal γ
- 9: end for

For the project, the R/C++ library fdaPDE from Github was used:

github.com/fdaPDE/fdaPDE

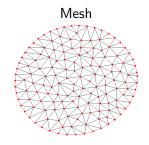
In particular, the function smooth.FEM.time was used to perform the final estimation of the paramater ρ (via GCV) and the field f.

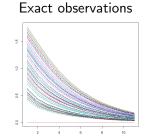
Procedure 8/

- Using FreeFem, we generated the exact solution of:

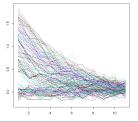
$$\frac{\partial f}{\partial t} - K\Delta f = 0$$

- To test the method, we added error to simulate data





Noisy observations



Estimations 9/3

We generated data modifying K and we obtained:

$$K = 1$$

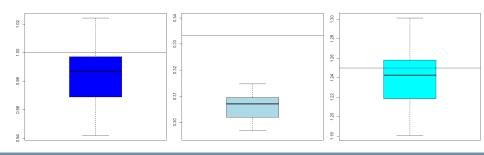
$$\hat{\gamma} = 0.9847768$$

$$K = 3$$

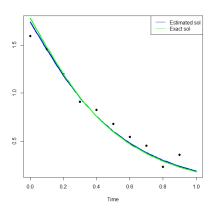
$$\hat{\gamma} = 0.3063712$$

$$K = 0.8$$

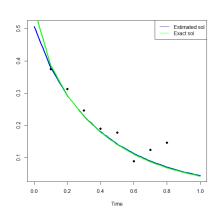
$$\hat{\gamma}=1.240424$$



Plots



Time evolution near (0,0)



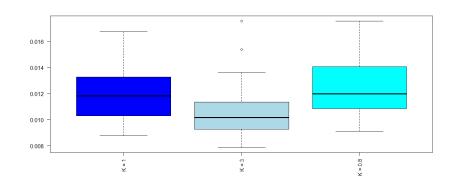
Time evolution near the boundary

K = 1

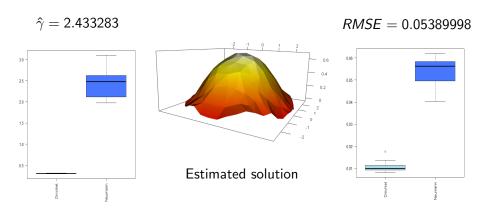
K = 3

RMSE = 0.01192373 RMSE = 0.01172951 RMSE = 0.01245426

K = 0.8



As expected, the Neumann Boundary Conditions do **not** fulfill the no-slip constraint

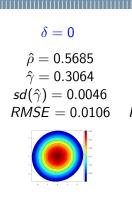


Data generation: heat equation with $K = \begin{bmatrix} k - \delta & 0 \\ 0 & k + \delta \end{bmatrix}$

Estimation:

$$J_{\rho,\gamma}(f) = (1-\rho)\frac{1}{n}\sum_{i=1}^{n}\sum_{j=1}^{m}(z_{ij}-f(\mathbf{p}_{i},t_{j}))^{2} + \rho\frac{1}{|\Omega|}\int_{T}\int_{\Omega}(\gamma\frac{\partial f}{\partial t}-\Delta f)^{2}$$

According to δ , ρ properly balances either the adherence to the observations or the PDE penalization.

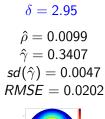


$$\hat{\gamma} = 0.3064$$
 $sd(\hat{\gamma}) = 0.0046$
 $RMSE = 0.0106$

 $\delta = 0.01$

 $\hat{\rho} = 0.5685$

$$\delta = 1$$
 $\hat{\rho} = 0.3299$
 $\hat{\gamma} = 0.3149$
 $sd(\hat{\gamma}) = 0.0050$
 $RMSE = 0.0120$







References

 E. Arnone, L. Azzimonti, F. Nobile, L. M. Sangalli, Modeling spatially dependent functional data via regression with differential regularization, *Journal of Multivariate Analysis* 170 (2019) 275–295.

- [2] L. Azzimonti, F. Nobile, L. M. Sangalli, P. Secchi, Mixed Finite Elements for spatial regression with PDE penalization, *SIAM ASA Journal on Uncertainty Quantification* (2014), 2 (1), 305-335.
- [3] M. S. Bernardi, M. Carey, J. O. Ramsay, L. M. Sangalli, Modeling spatial anisotropy via regression with partial differential regularization, *Journal of Multivariate Analysis* 167 (2018) 15–30.
- [4] L. M. Sangalli, Spatial Regression With Partial Differential Equation Regularisation, *International Statistical Review* (2021), 89, 3, 505–531