-carrier_is_attached[carrier1]	SHOP_methodmethod_get_carrier_2_8_precondition[jumper,central_warehouse,carrier1]()	robot_attach_carrier[jumper,carrier1,central_warehouse]()					SHOP_methodmethod_get_carrier_2_8_precondition[walker,central_warehouse,carrier1]()	robot_attach_carrier[walker,carrier1,central_warehouse]()			SHOP_methodmethod_get_carrier_2_8_precondition[drone,central_warehouse,carrier1]()	
-robot_is_attached[jumper]	-carrier_is_attached[carrier1]	+robot_at_location[jumper,central_warehouse]		SHOP_methodmethod_move_jumping_1_4_precondition[jumper,central_warehouse,loc1,loc2]()		move_jumping[jumper,central_warehouse,loc1,loc2]()	+robot_at_location[walker,central_warehouse]	+robot_at_location[walker,central_warehouse]	SHOP_methodmethod_get_carrier_4_10_precondition[walker,central_warehouse,carrier1,drone]()	robot_detach_carrier[walker,carrier1,central_warehouse]()	+robot_at_location[drone,central_warehouse]	
+carrier_at_location[carrier1,central_warehouse]	-robot_is_attached[jumper]	, II	SHOP_methodmethod_get_carrier_4_10_precondition[jumper,central_warehouse,carrier1,drone]()	+robot_at_location[jumper,central_warehouse]	·	+robot_at_location[walker,central_warehouse]	+carrier_at_location[carrier1,central_warehouse]	+robot_has_carrier[walker,carrier1]	+robot_at_location[walker,central_warehouse]	+robot_at_location[drone,central_warehouse]	+carrier_at_location[carrier1,central_warehouse]	<del>-</del>
+carrier_at_location[carrier1,central_warenouse]	-robot_has_carrier[jumper,carrier1]	+robot_is_attached[jumper]	+robot_at_location[jumper,central_warehouse]	+robot_has_carrier[jumper,carrier1]	robot_detach_carrier[jumper,carrier1,central_warehouse]()	+carrier_at_location[carrier1,central_warehouse]	-robot_has_carrier[walker,carrier1]	+robot_is_attached[walker]	+robot_has_carrier[walker,carrier1]	+carrier_at_location[carrier1,central_warehouse]	-robot_has_carrier[drone,carrier1]	robot_attach_carrier[drone,carrier1,central_warehouse]() goal
+robot_at_location[jumper,central_warehouse]	+carrier_at_location[carrier1,central_warehouse]	+carrier_is_attached[carrier1]		+robot_is_attached[jumper]	+robot_at_location[jumper,central_warehouse]	-robot_is_attached[walker]	-robot_is_attached[walker]	+carrier_is_attached[carrier1]	+robot_is_attached[walker]	-robot_is_attached[drone]	-robot_is_attached[drone]	
	+robot_at_location[jumper,central_warehouse]	-robot_has_carrier[drone,carrier1]	-robot_at_location[jumper,loc2]	+carrier_is_attached[carrier1]	-robot_at_location[jumper,loc2]	-carrier_is_attached[carrier1]	-carrier_is_attached[carrier1]	-robot_has_carrier[drone,carrier1]	+carrier_is_attached[carrier1]	-carrier_is_attached[carrier1]	-carrier_is_attached[carrier1]	