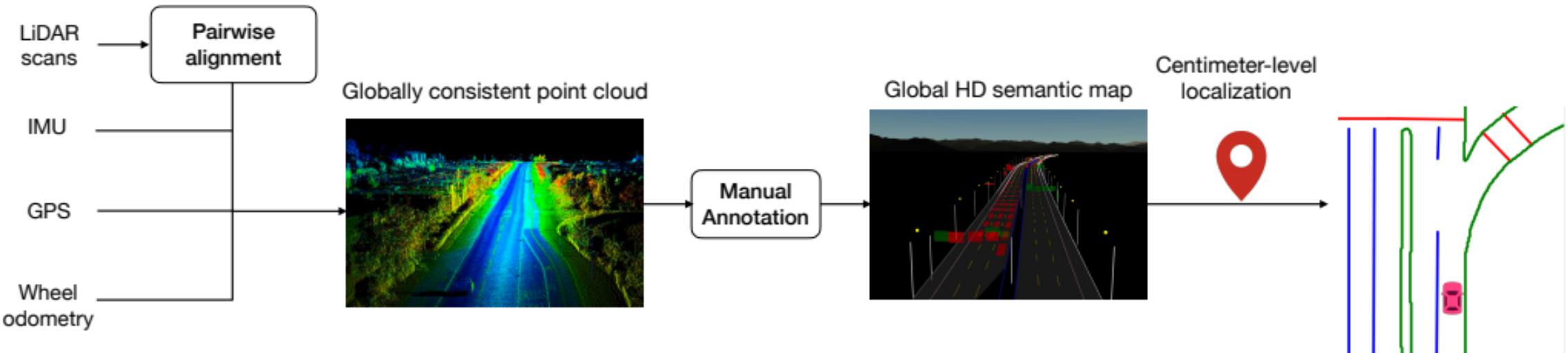


## Global map construction

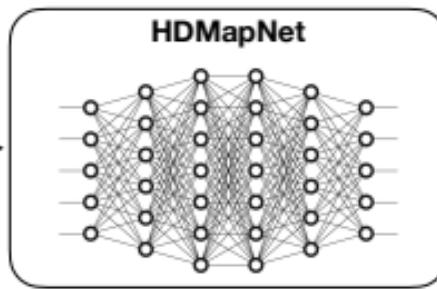
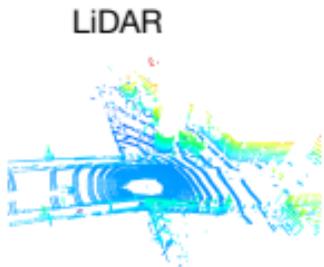


## Local semantic map learning (Ours)

Surrounding cameras



and/or



Local HD map