

$$V_{th} = 0.75 \text{ V} \quad V_{ce\text{sat}} = 0.2 \text{ V} \quad C = 20 \text{ pF}$$

$$V_{DD} = 3.5 \text{ V} \quad \beta_F = 190$$

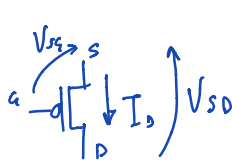
$$\beta_P = 500 \frac{\mu\text{A}}{\text{V}^2} \quad V_{TP} = -0.4 \text{ V} \quad ? = R @ t_{pHL} = 1 \text{ ns}$$

→ decide di dimensionare la resistenza tale per cui il tempo di propagazione sia 1 ns

→ c'è condensatore, analisi dinamica

→ considerazioni preliminari

p-MOS



$$\text{OFF: } V_{SG} < |V_{TP}|, I_D = 0$$

$$\text{SAT: } V_{SD} > V_{SG} - |V_{TP}|, I_D = \frac{\beta_P}{2} (V_{SG} - |V_{TP}|)^2$$

$$\text{LIN: } V_{SD} < V_{SG} - |V_{TP}|$$

$$I_D = \beta_P \left[(V_{SG} - |V_{TP}|) V_{SD} - \frac{V_{SD}^2}{2} \right]$$

→ diminuire resistenza in beta a transigione HIGH-LOW

→ trovare valori con analisi statica

$$\bullet V_i < V_{th} \Rightarrow T = \text{OFF} \rightarrow I_C = 0 \rightarrow I_D = 0 \quad I_C = \text{collettore}$$

ipotizzare se LIN o SAT

IPOTESI

$$\text{Hp: } M = \text{LIN} \rightarrow I_{Dp} = \beta_P \left[(V_{SG} - |V_{TP}|) V_{SD} - \frac{V_{SD}^2}{2} \right] = 0$$

$$\rightarrow V_{SD} = 0$$

$$\text{ma } V_{SD} = V_{DD} - V_U \rightarrow V_U = V_{DD} = V_M \rightarrow \text{calcolo valore alto}$$

VERIFICHIAMO IPOTESI LINEARITA'

$$V_{SD} < V_{SG} - |V_{TP}|$$

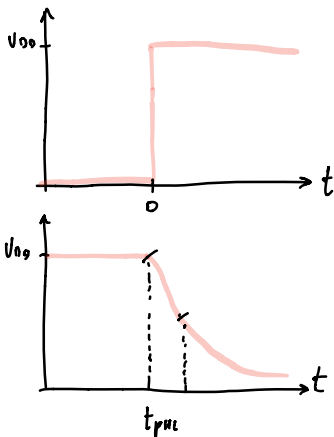
$$0 < V_{DD} - V_{th} < +0.4 \rightarrow \underline{\text{OK}}$$

- $V_i = V_{DD} \rightarrow V_{SG} = 0 \rightarrow M = \text{OFF} \rightarrow I_{SP} = 0 \rightarrow I_C = 0$
 MA $V_{PE} > V_g \rightarrow T = \text{ON} \rightarrow T = \text{SAT}$

ENTRATA
ALTA (HIGH)

$$[V_U = V_{CE \text{ SAT}} = V_L]$$

- TRANSIZIONE - COND. DINAMICHE \rightarrow ANALISI CORRENTE



$$V_i = V_{DD} \rightarrow M = \text{OFF}$$

$$V_{CE} @ t=0^+ = V_{DD} > V_{CE \text{ SAT}} \rightarrow T = \text{LW}$$

$$V_{U \text{ 50\%}} = \frac{V_H + V_L}{2} = 1.85 \text{ V} > V_{CE \text{ SAT}} \rightarrow T = \text{LW}$$

PUNTO DI TRANSIZIONE

$$\left. \begin{aligned} I_C &= \beta_F I_B = \beta_F \frac{V_{DD} - V_U}{R} \\ I_{CWO} &= -C \frac{dV_U}{dt} \\ I_{CWO} &= I_C \end{aligned} \right\} dt = \frac{-RC}{\beta_F \cdot (V_{DD} - V_U)} dV_U$$

$$\int_0^{t_{PHL}} dt = \int_{V_{DD}}^{V_{U \text{ 50\%}}} \frac{-RC}{\beta_F (V_{DD} - V_U)} dV_U$$

$$\rightarrow t_{PHL} = \frac{-RC}{\beta_F (V_{DD} - V_U)} (V_{U \text{ 50\%}} - V_{DD})$$

$$= 1.2 \cdot 10^{-9} \text{ s}$$

$$\text{MA } t_{PHL} = 10^{-9} \rightarrow R = 8.33 \text{ k}\Omega$$