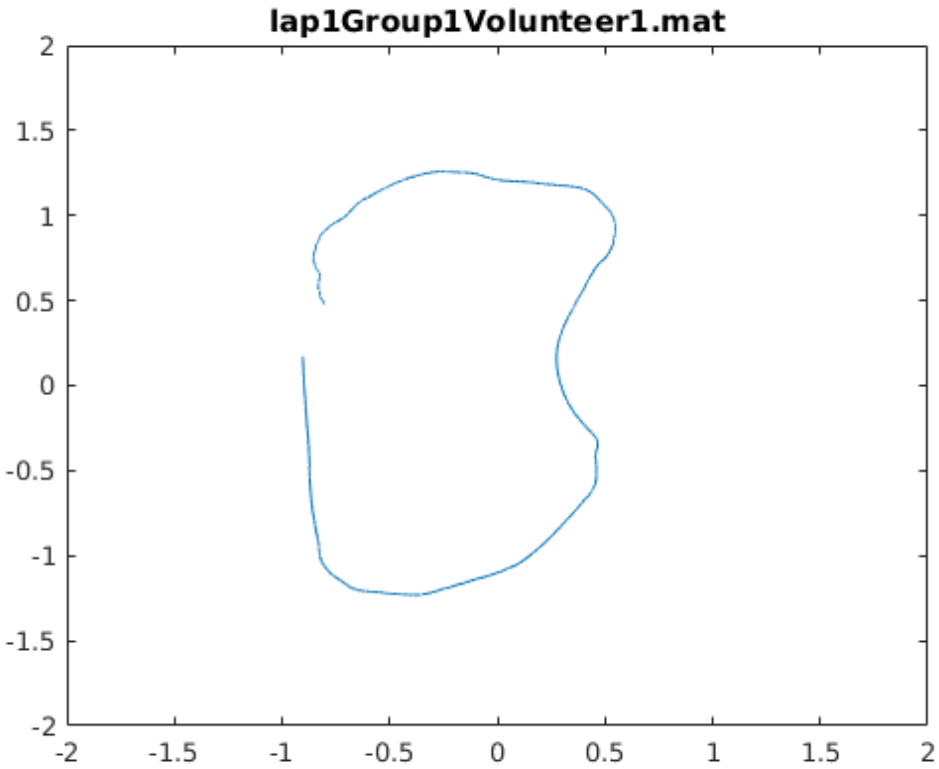
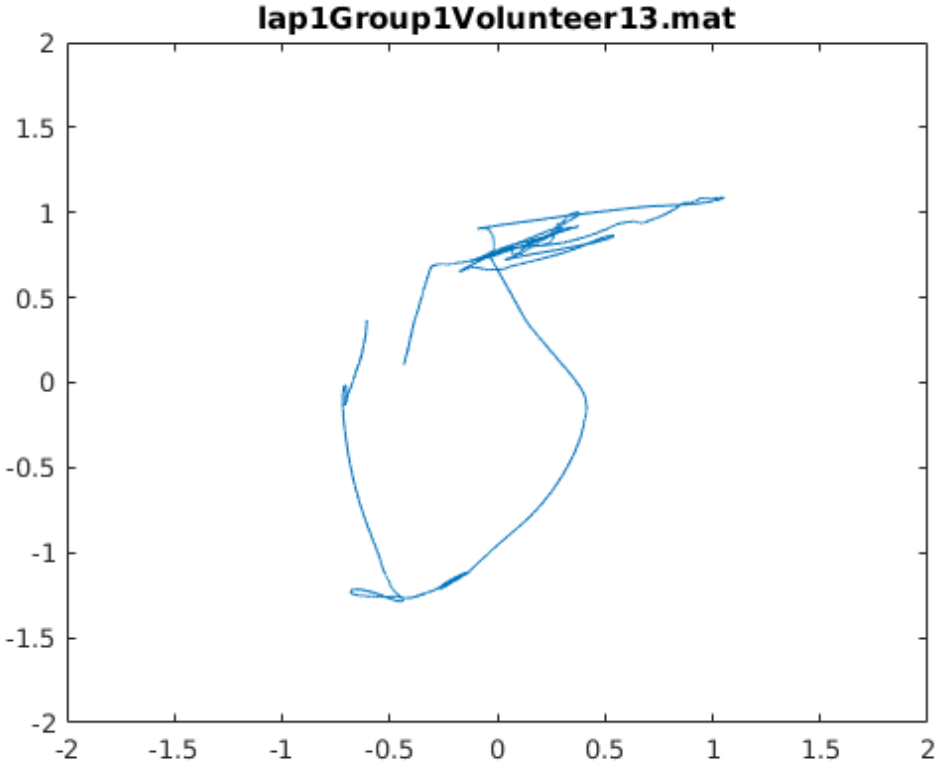
2D Plots for Visualization of Trajectories

```
%Using the script block given in Lab; Implementation of instructions for
%graphical representation of trajectories followed by the robot during the tests.
files = dir('*.mat'); %This is a script which loops through the files of a folder
for file = files'
    filename = load(file.name);
figure
        plot(filename.dataMoCap.pos_x,filename.dataMoCap.pos_y);
    title(file.name)
    axis([-2 2 -2 2])
end
```

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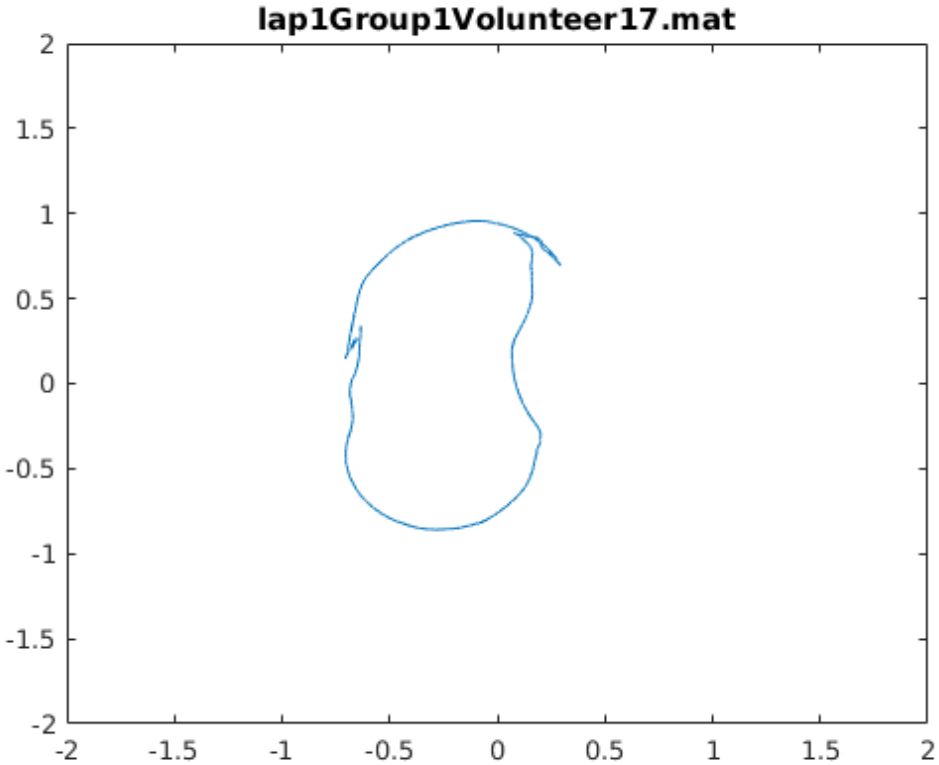
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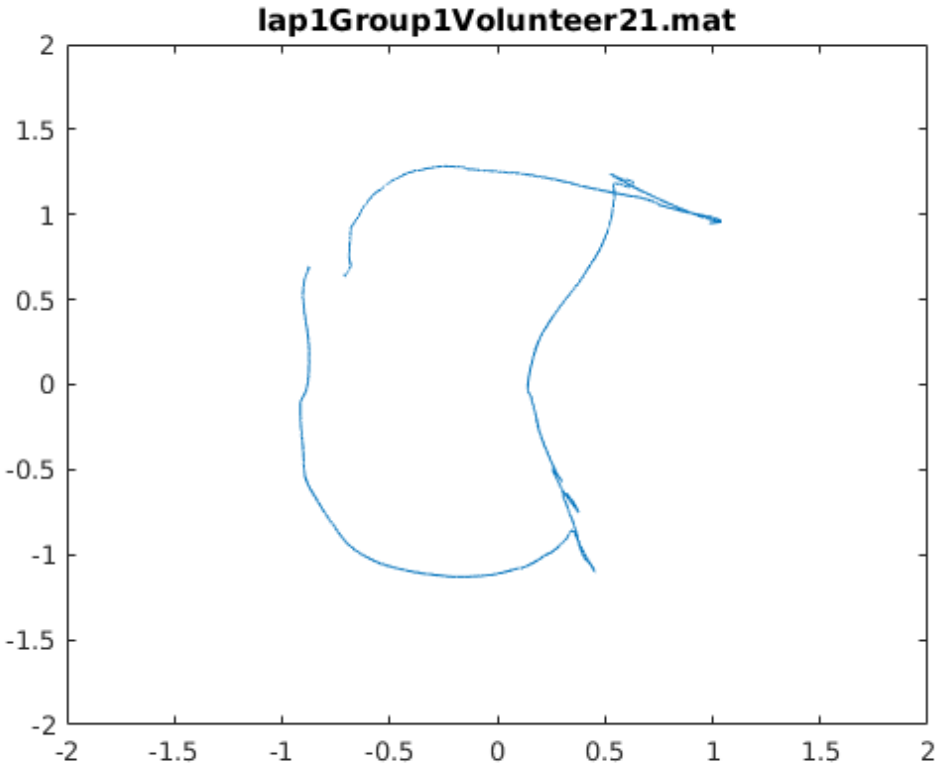
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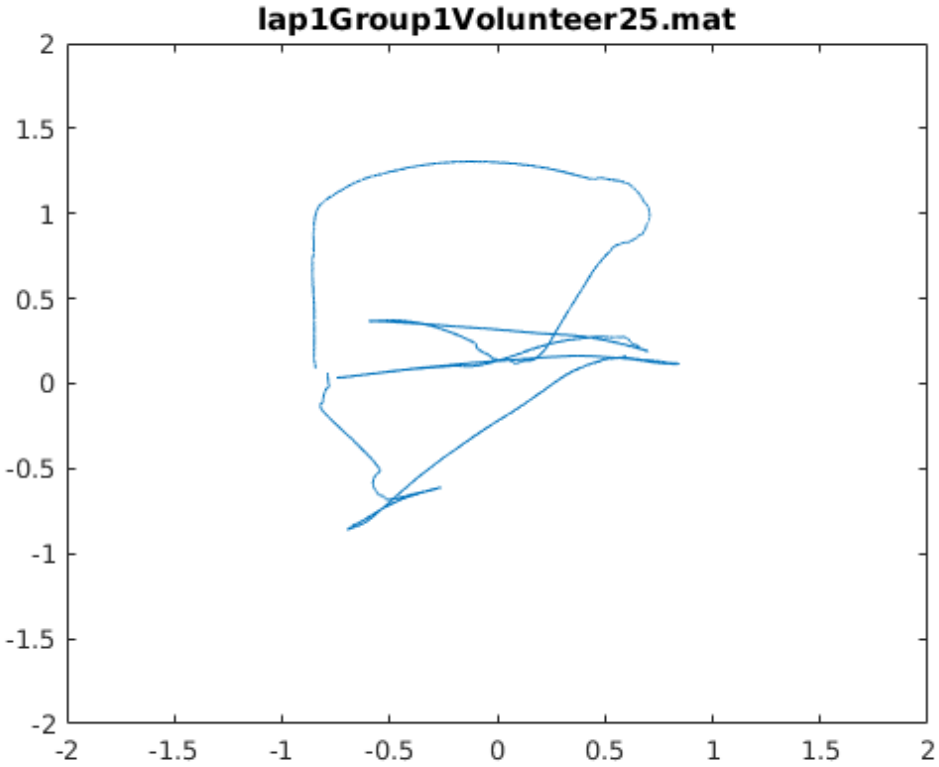
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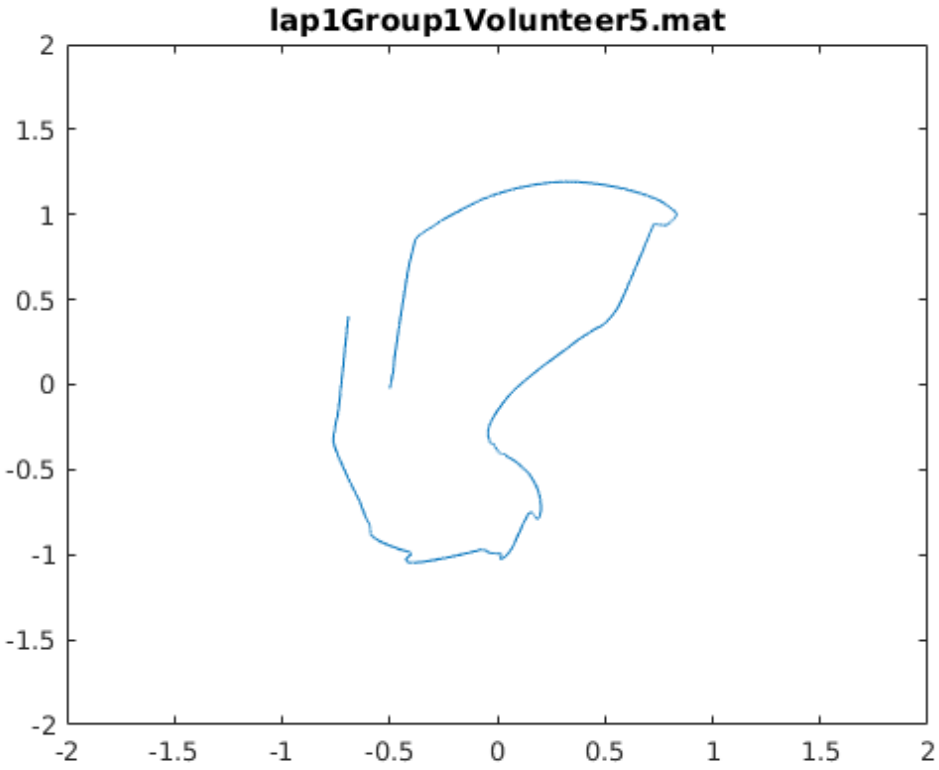
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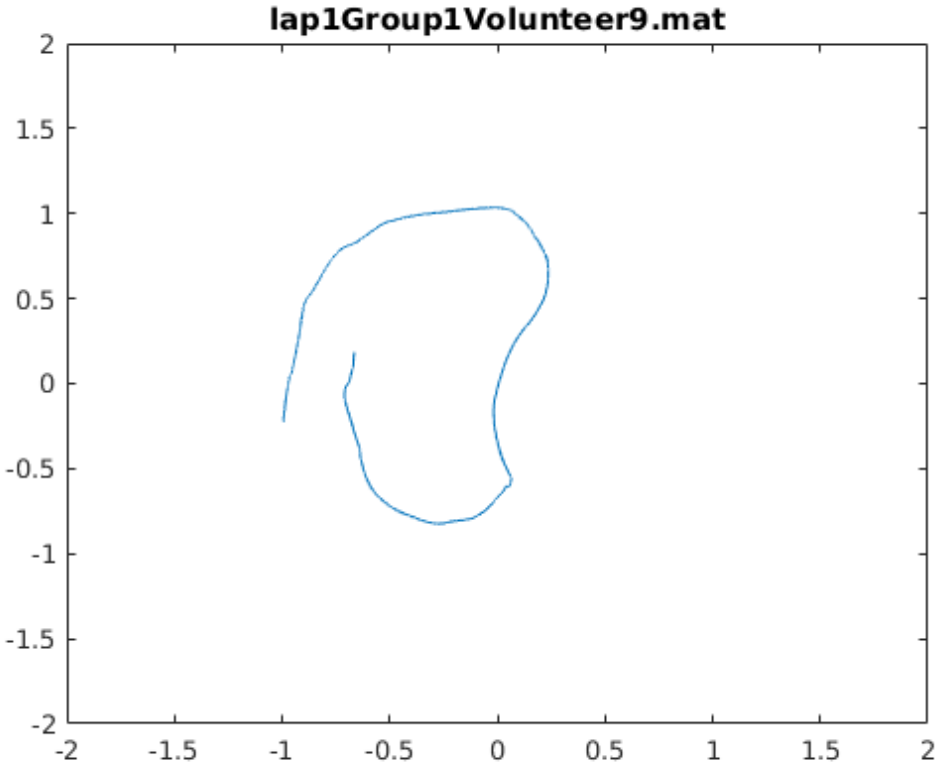
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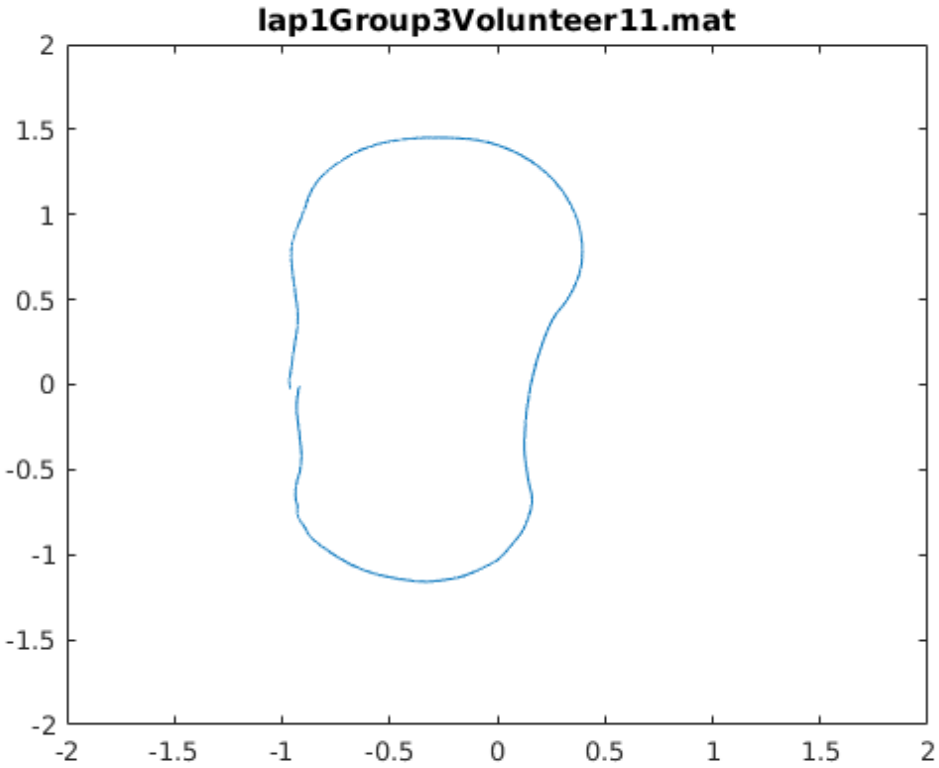
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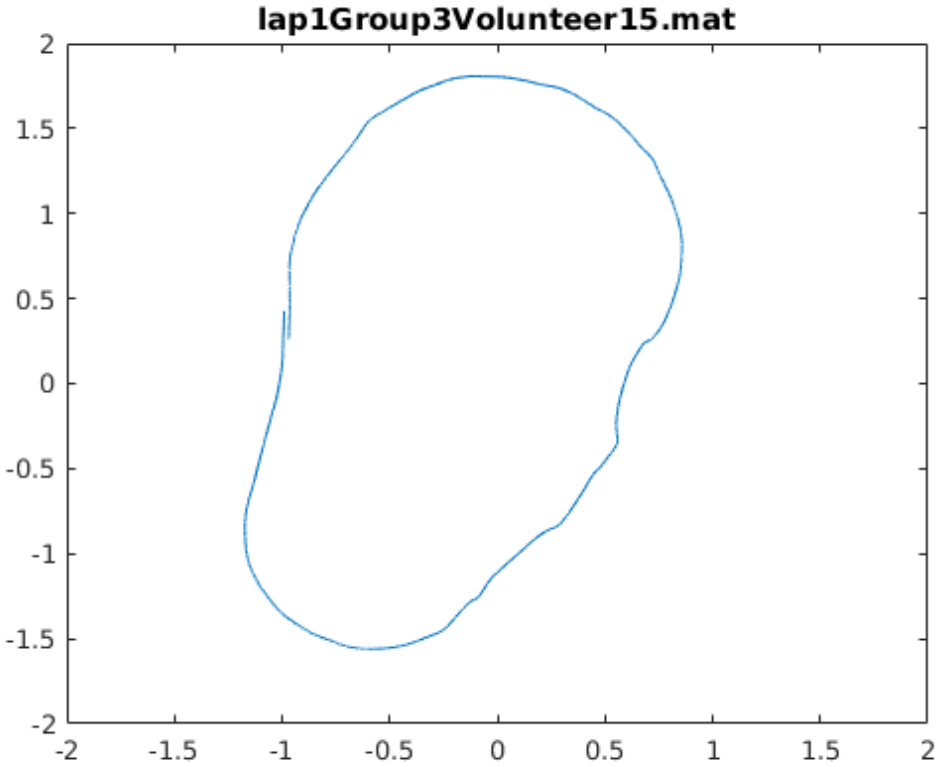
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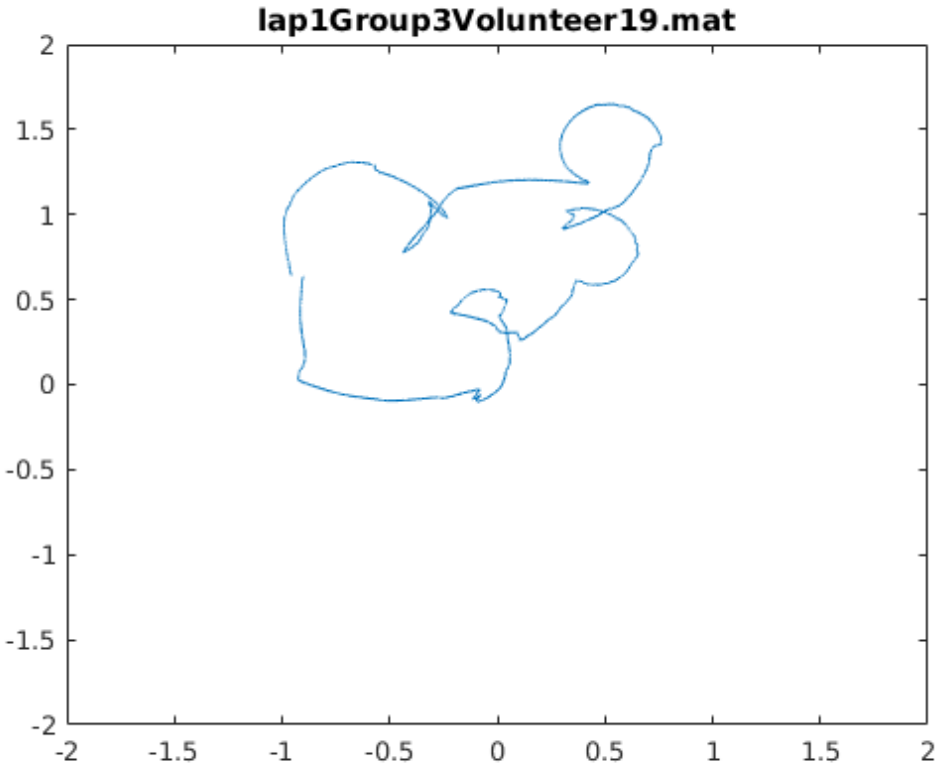
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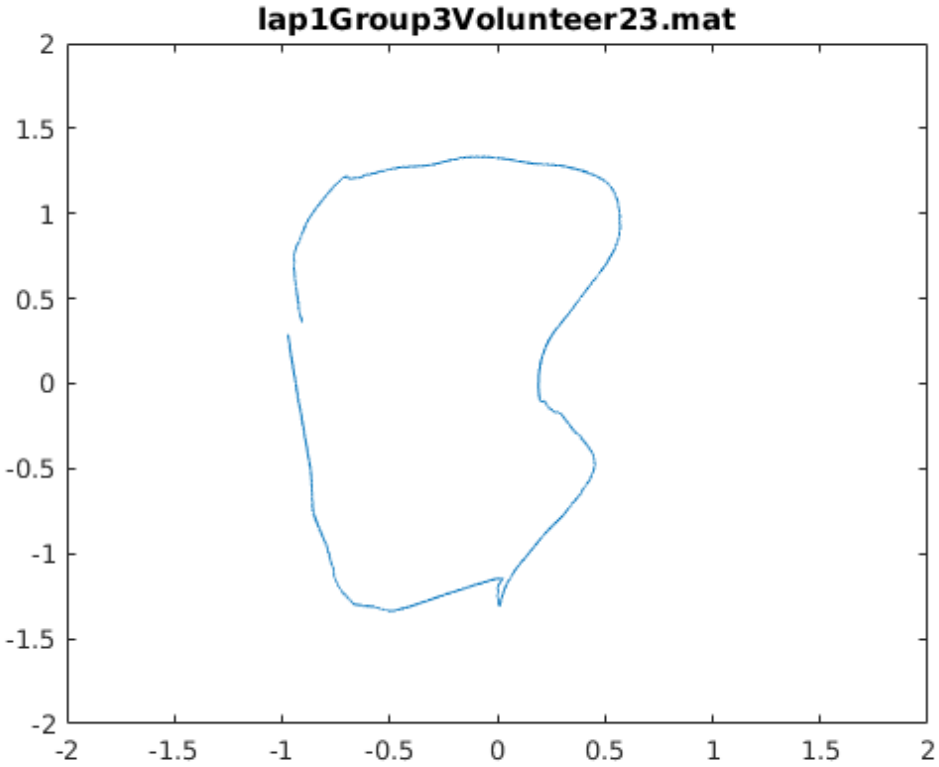
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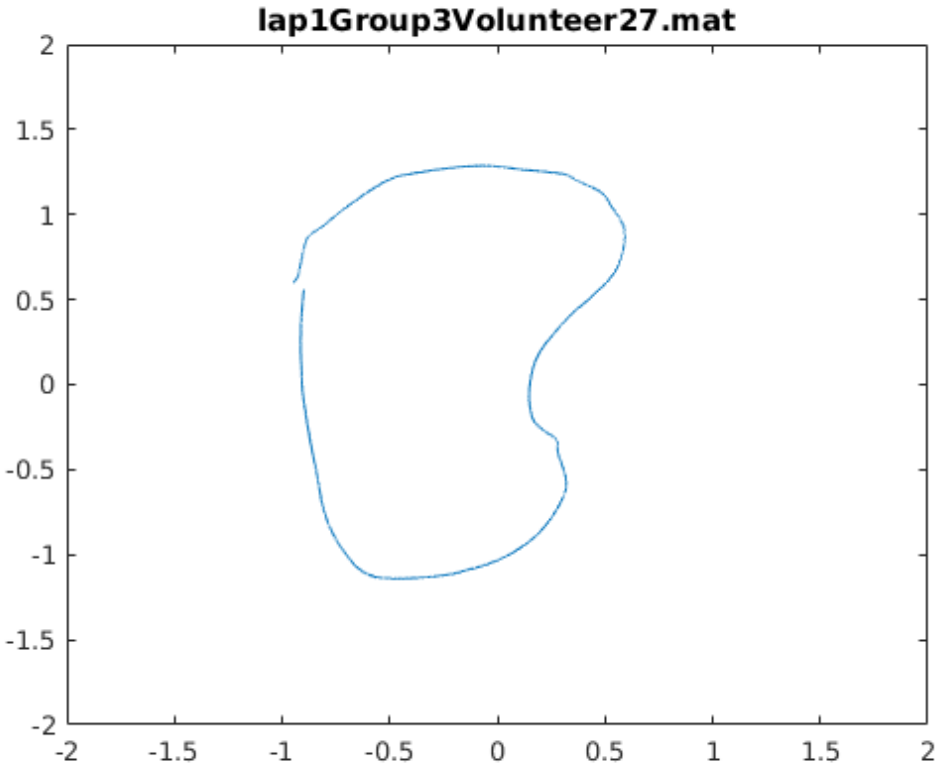
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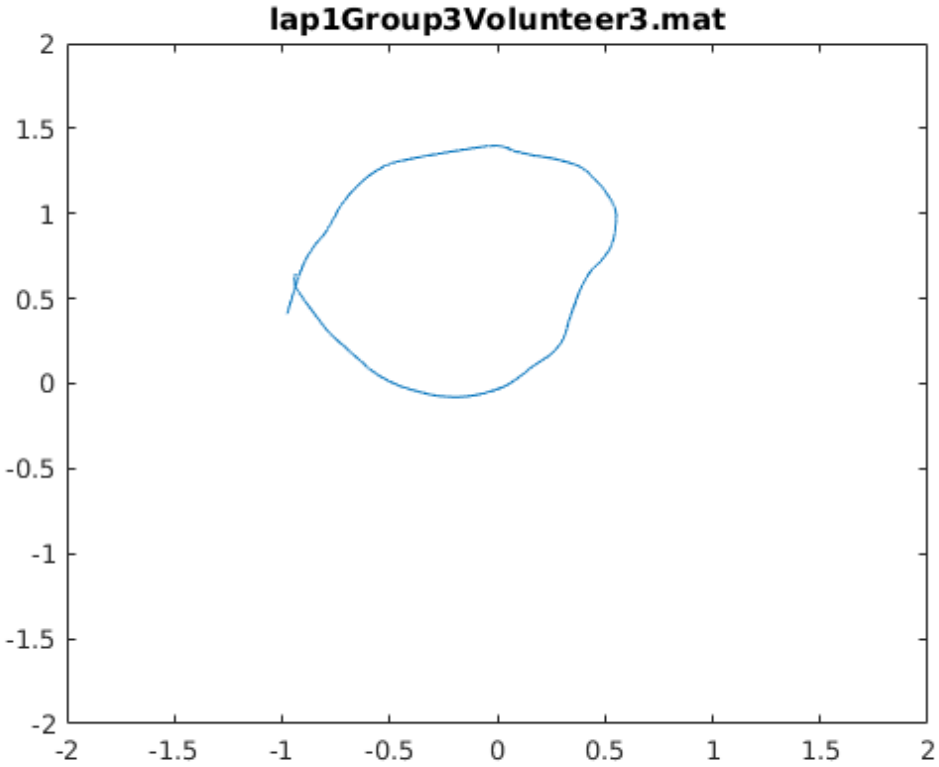
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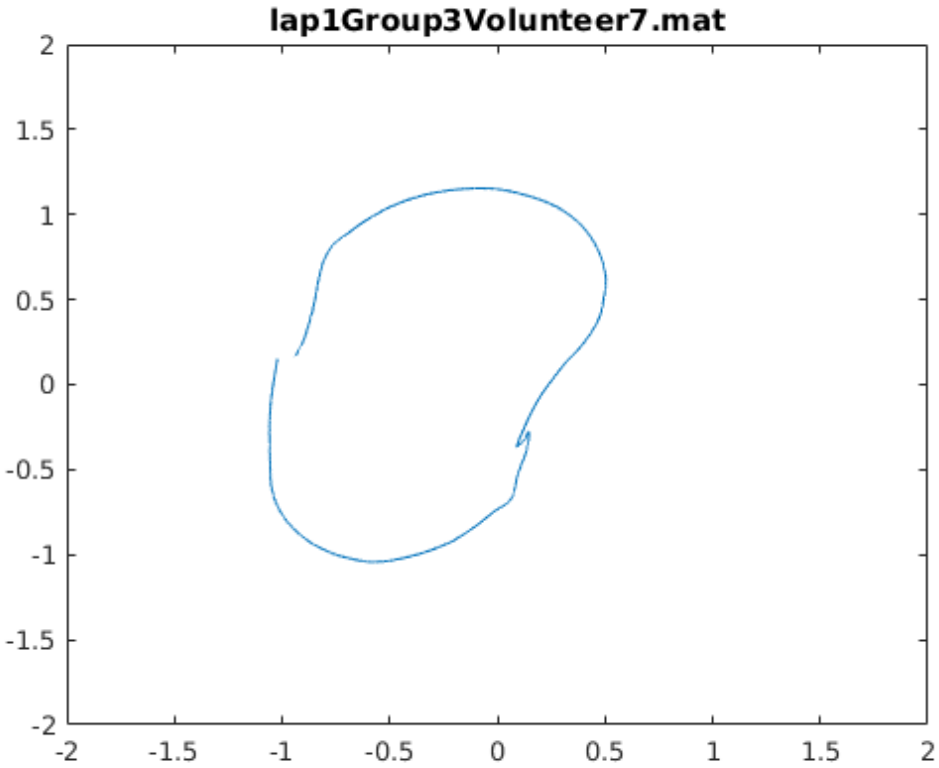
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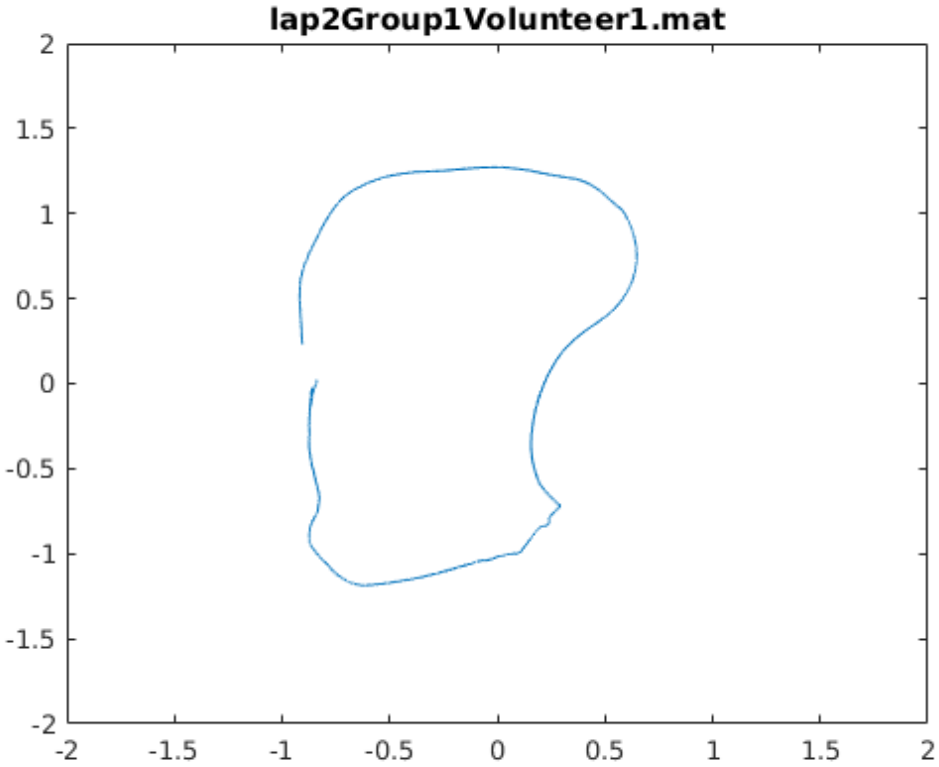
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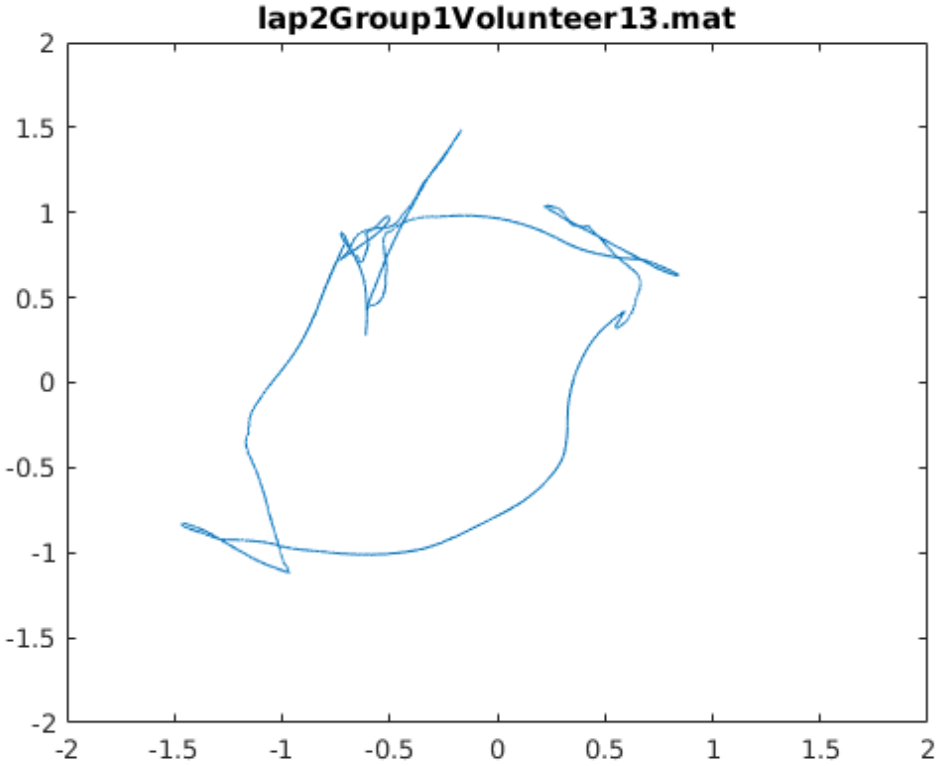
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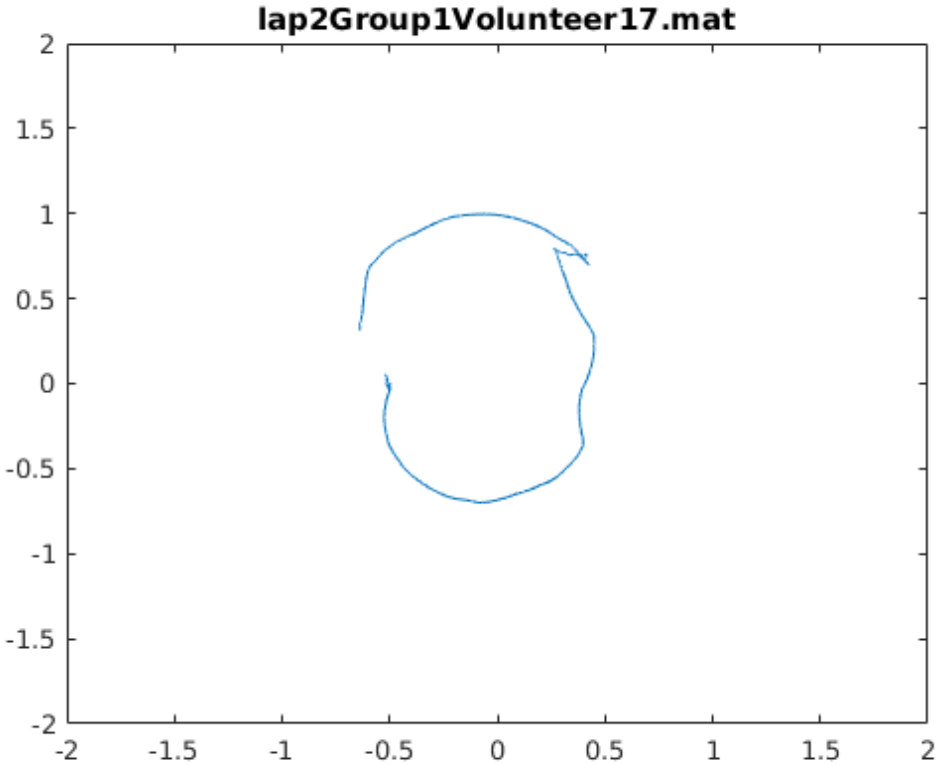
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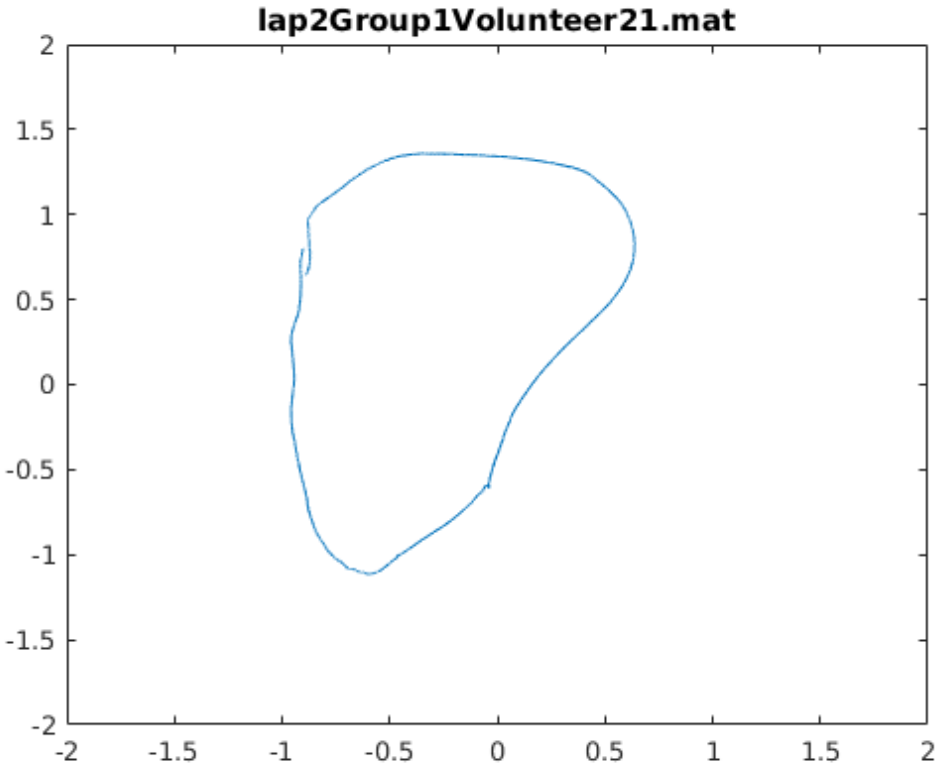
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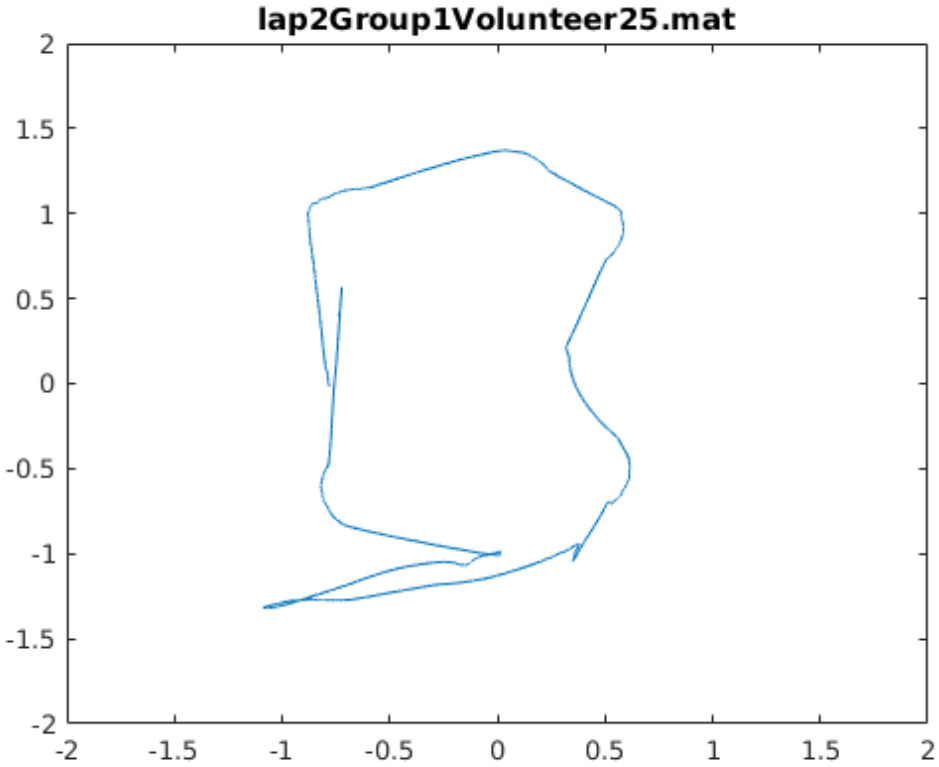
lap2Group1Volunteer25.mat
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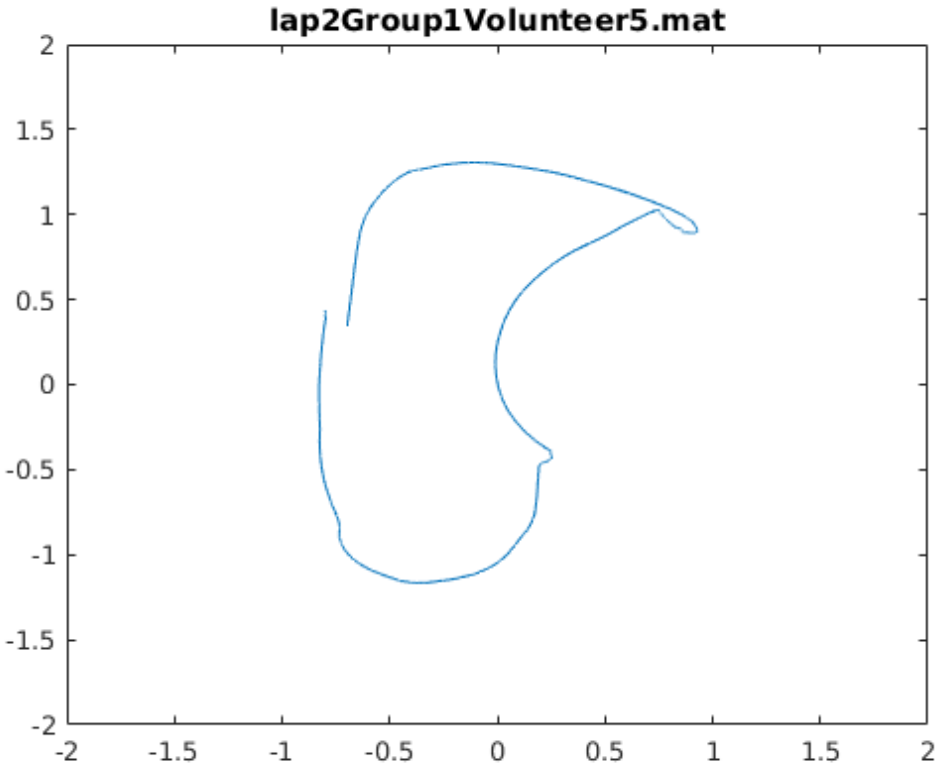
lap2Group1Volunteer5.mat
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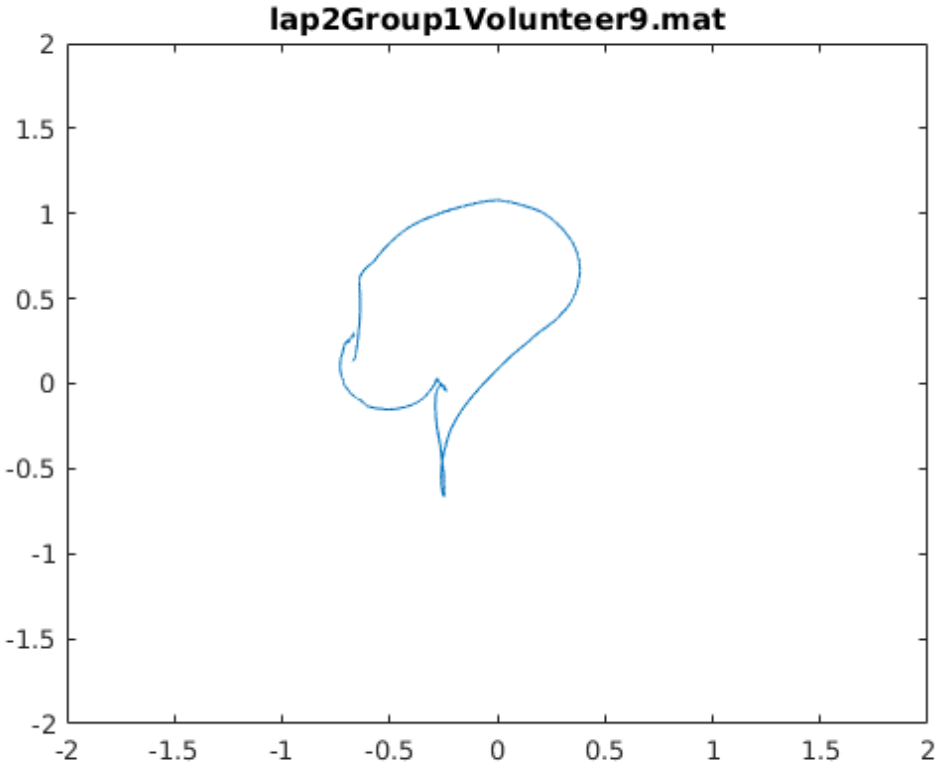
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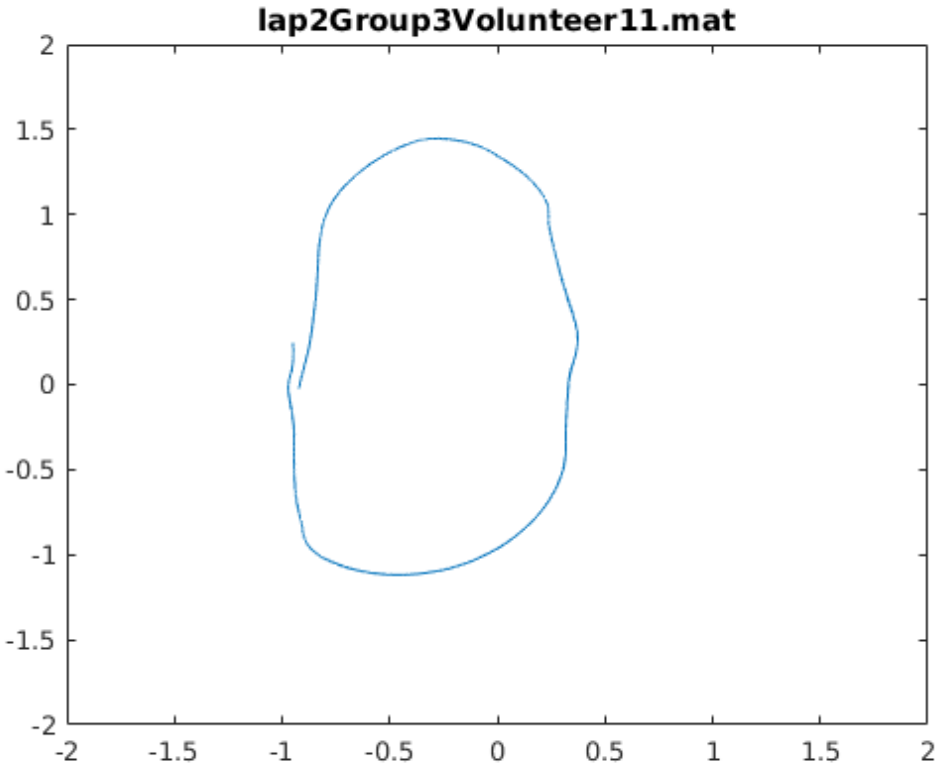
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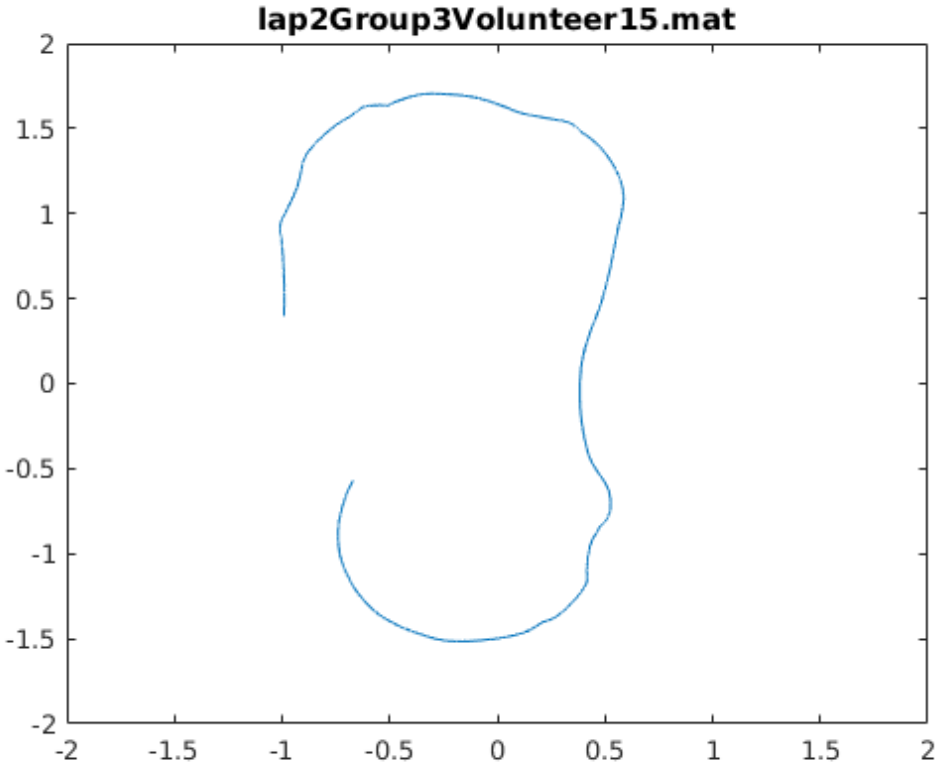
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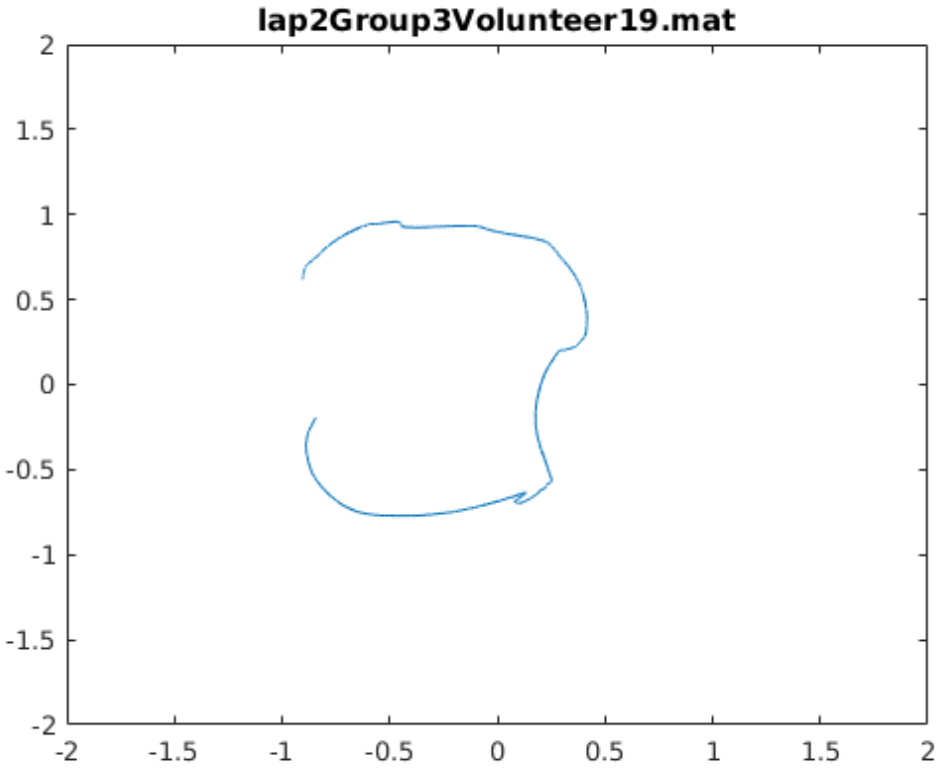
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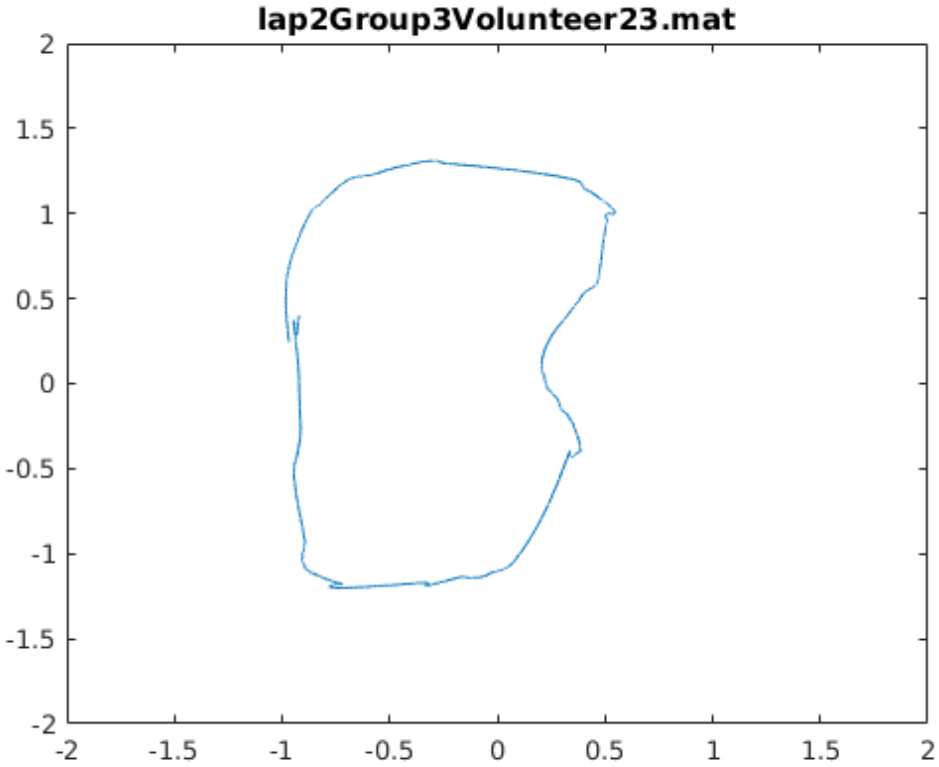
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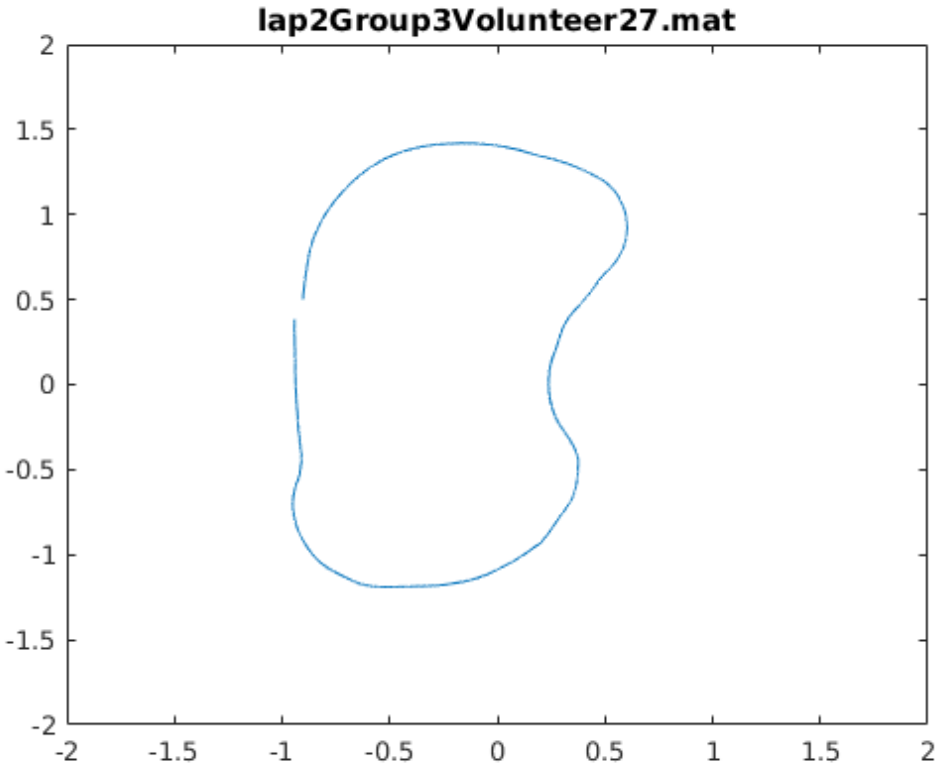
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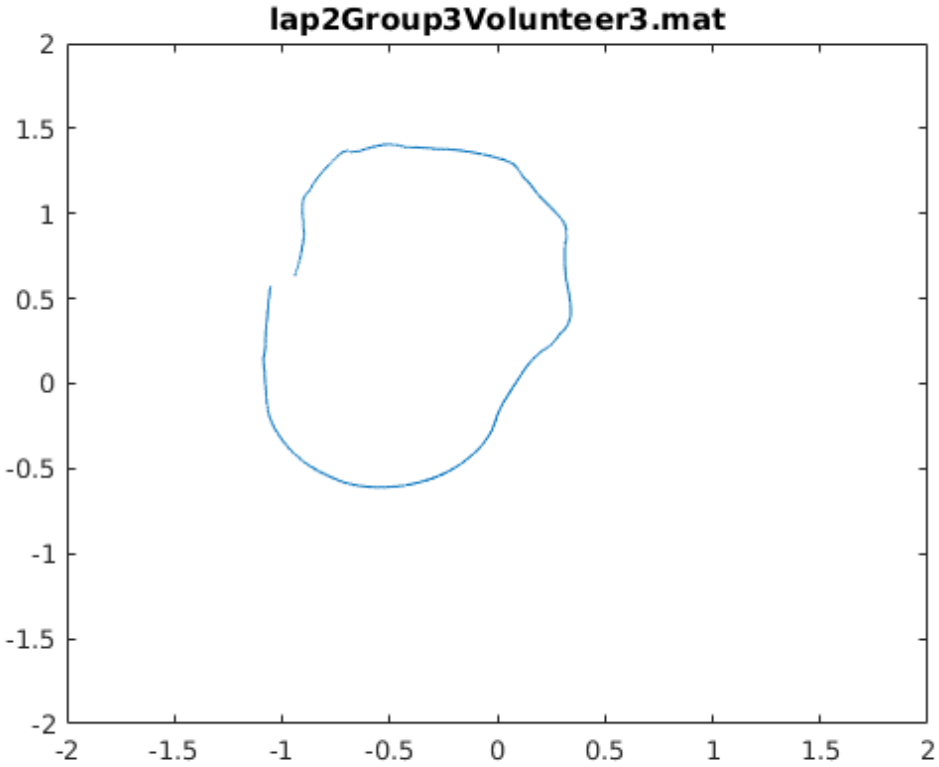
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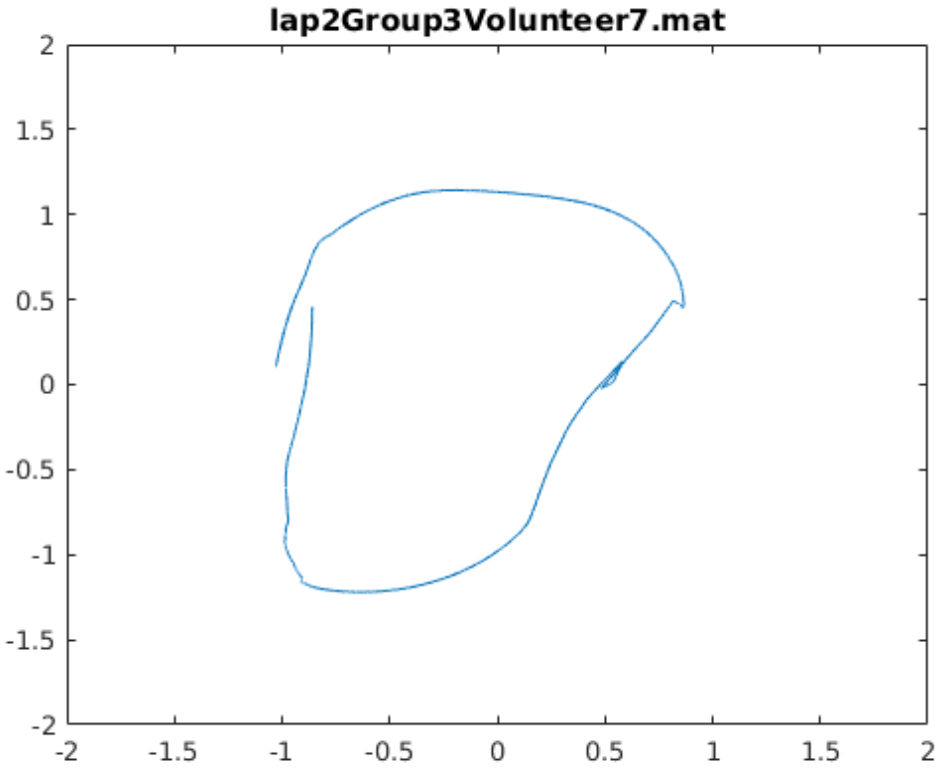

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