



Università  
di Catania



# First Person (Egocentric) Vision for Human-Centric Assistance: History, Building Blocks, and Applications

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<http://iplab.dmi.unict.it/fpv> - <https://www.nextvisionlab.it/>



# IMAGE PROCESSING LABORATORY



- Located in Catania, Sicily, Italy
- More than 25 people:
  - 2 Full Professors;
  - 2 Associate Professors;
  - 2 Assistant Professors
  - 3 Research Fellows;
  - 3 Postdocs;
  - 16 PhD Students;
  - Students and consultants;
- Collaborations with local industries;
- Research interests:
  - First Person (Egocentric) Vision;
  - Multimedia Security and Forensics;
  - Cultural Heritage;
  - Social Media Mining;



[iplab.dmi.unict.it](http://iplab.dmi.unict.it)



Antonino Furnari



Francesco Ragusa

# Before we begin...

The slides of this tutorial are available online at:

<http://www.antoninofurnari.it/talks/iciap2022>



# Agenda

## **Part I: Definitions, motivations, history and research trends [14.00 - 15.45]**

- **What is first person vision? What is it for?**
- **What makes it different from third person vision?**
- **History of First Person Vision: visions, ideas, research, devices;**
- **Where do we go from here? Research trends, datasets and challenges.**

## **Part II: Building Blocks for First Person Vision Systems [16.15 – 18.00]**

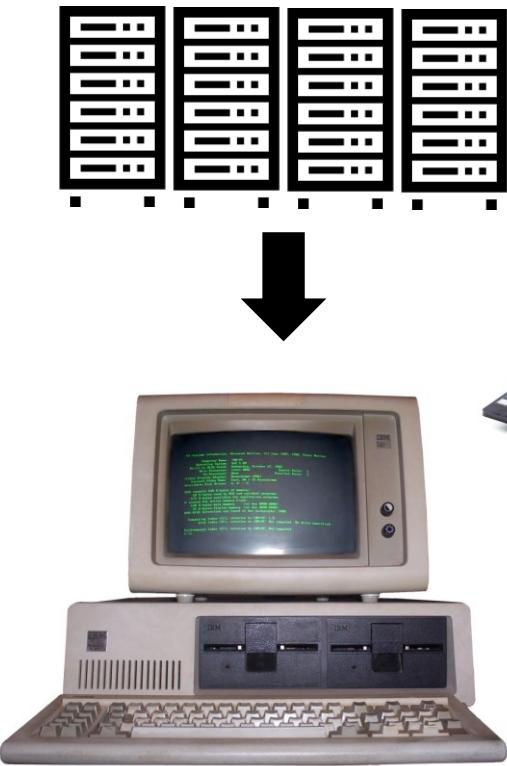
- Data Acquisition & Datasets;
- Fundamental Tasks in First Person Vision:
  - Localization;
  - Hand/Object Detection;
  - Attention;
  - Action/Activities;
  - Anticipation
- Conclusion

# Part I

Definitions, Motivations, History, Research Trends and Applications

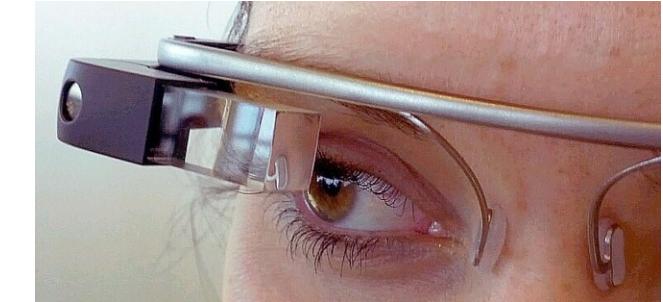
# The Revolution of Personal Computing

After personal computers and smartphones, mixed reality is the third wave of computing



**Personal Computers:** computing for the mass, but not mobile and not context aware - dedicated access to computing

– [Marc Pollefeys](#), Lab Director, Microsoft Mixed Reality and AI Zurich



**Smartphones:** mobile computing is always accessible, but forces to switch between the digital and real world

**Eyeworn Devices:** computing everywhere with minimal switch between real and digital worlds

# What Shall We Expect from Wearable Computers?

Wearable Computers define a world in which the user is central and access to computation is simplified and **blended** in the real world

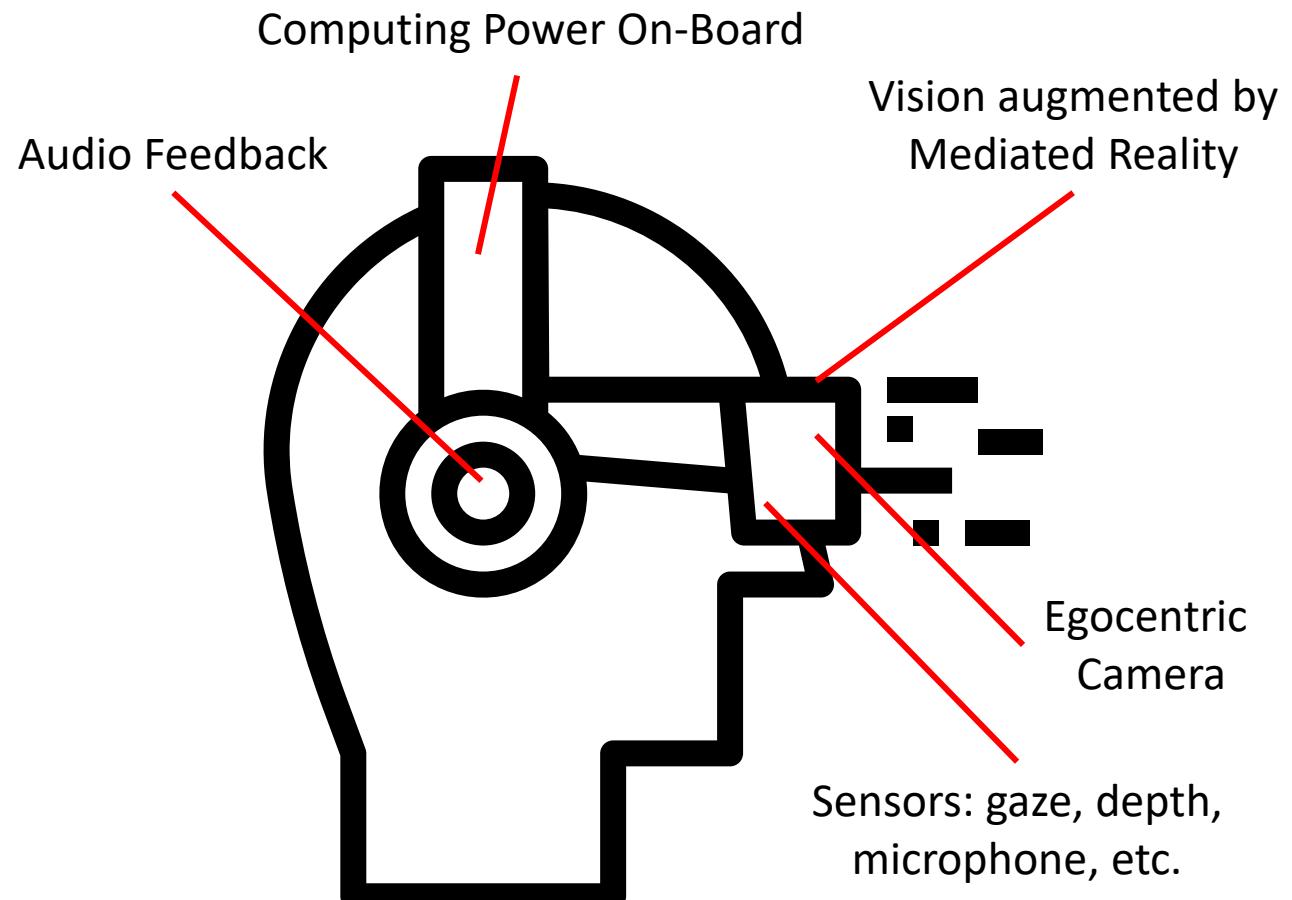
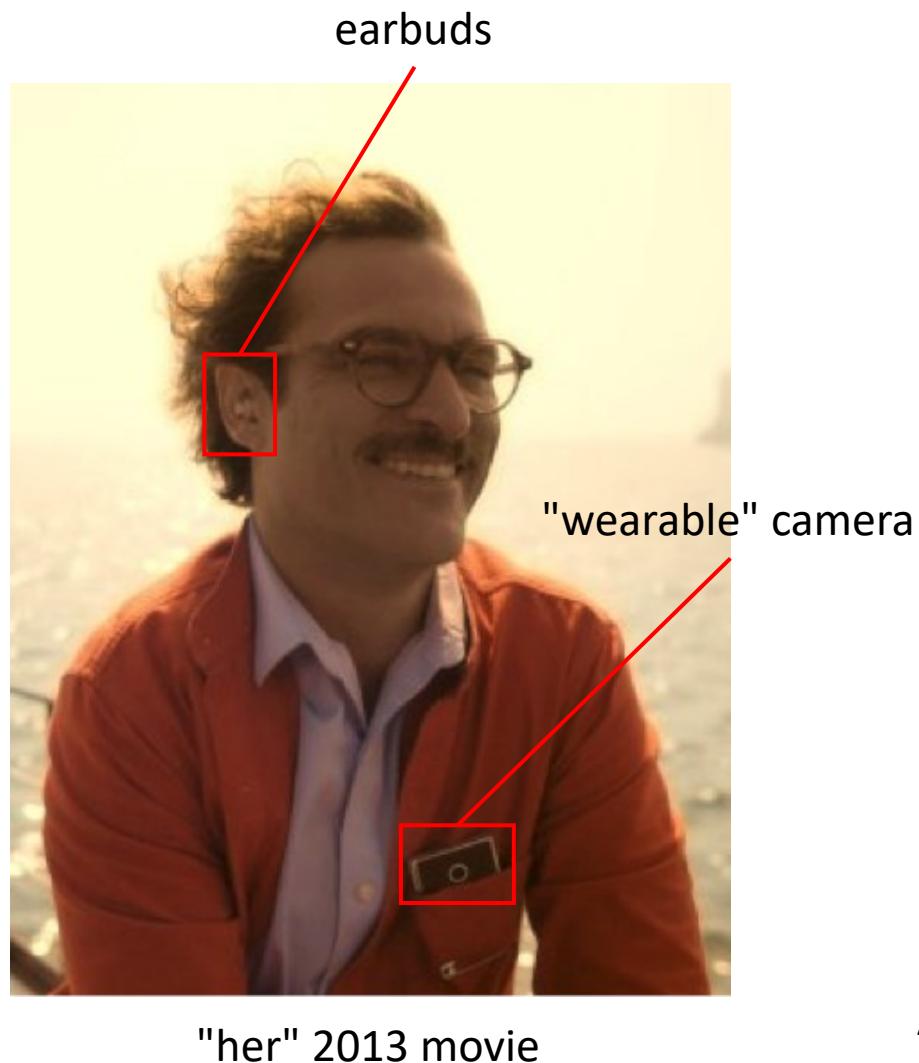


Wearable Computers are the perfect interface to build **personal assistants** capable of automating computation to augment our abilities.

Hence, they need to **understand** where we are, how the physical world around us is made, and what are our objectives.

**Vision is fundamental!**

# An AI-Powered Virtual Assistant



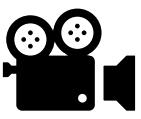
<https://thenounproject.com/Turkkub/>

A wearable device which perceives the world from our "egocentric" point of view is perfect for implementing a virtual assistant



KINOCHECK

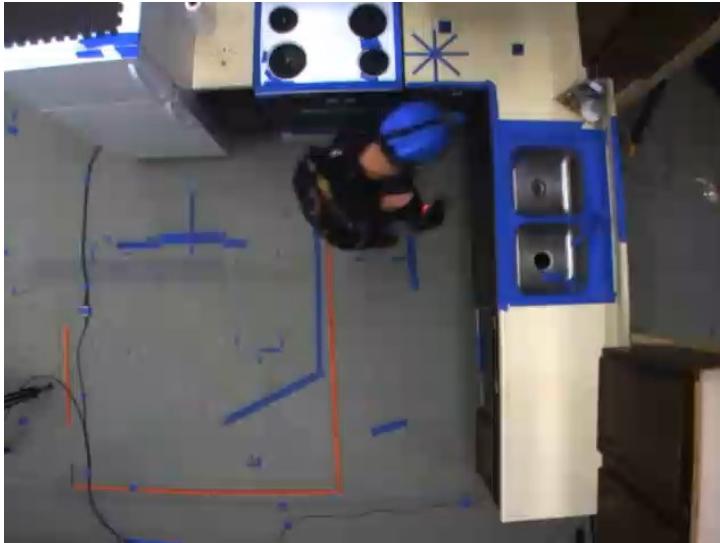
# Can't we just apply standard CV?



First Person Camera



Third Person Camera



### Fixed Camera



- ✓ Easy to setup
- ✓ Controlled Field of View
- ✗ Doesn't always see everything
- ✗ Not really portable

### Wearable Camera



- ✓ Content is always relevant
- ✓ Intrinsically mobile
- ✗ High variability
- ✗ Operational constraints



# Features of First Person Vision

- **Sees «what the user sees»**
  - The acquired video always «tells something» about the user;
    - Behavior understanding, Embodied perception;
- **Naturally mobile**
  - FPV can be used to build intelligent systems able to assist the user and augment their abilities;
    - Third wave of personal computing;
- **Exposed to huge amounts of personal data**
  - FPV can be used to build AIs which learn from personal data;
    - Can learn to predict the user's goal.

**Virtual Personal Assistant**

# “All about the user”

“First Person Vision, which senses the environment and the subject’s activities from his/her view point, is advantageous for understanding the behavior, intent, and environment of a person.”



Takeo Kanade and Martial Herbert. "First-person vision." *Proceedings of the IEEE* 100.8 (2012): 2442-2453.

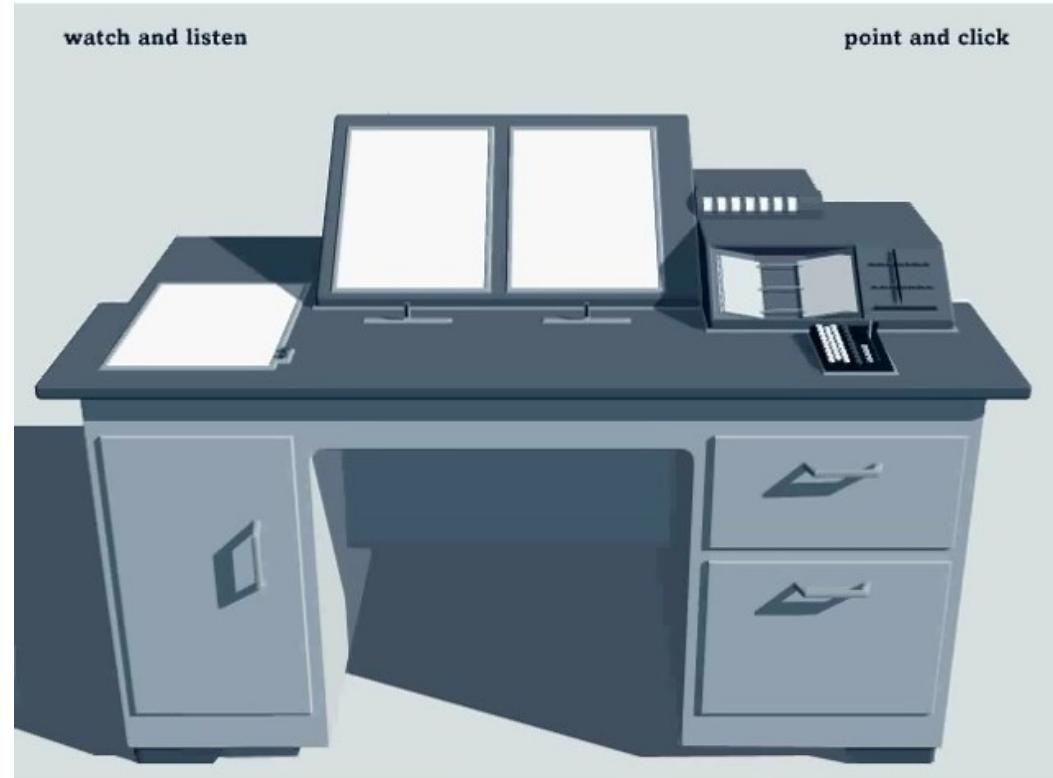
# Note on Terminology

Different terms have been used to refer to very similar concepts. The most common ones are as follows:

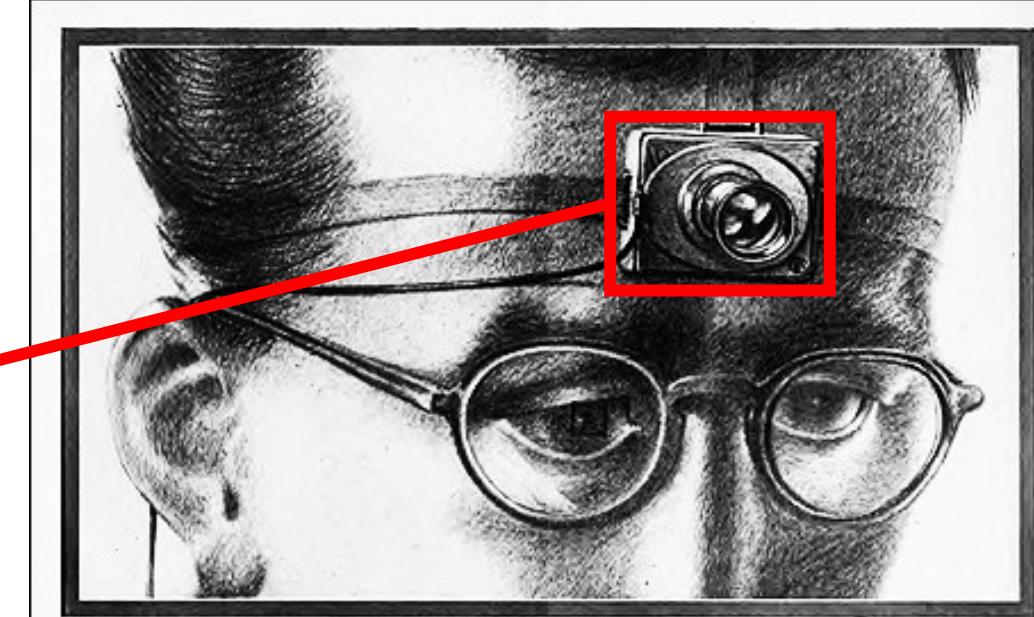
Term	Etymology
First Person Vision (FPV)	Computer Vision for images and videos acquired from a First Person View, as opposed to the classic Third Person View
Egocentric Vision (Ego-Vision)	Computer Vision for visual data «about me» (from Greek/Latin «ego»=«I»)
Wearable Vision	Computer Vision for wearable devices

# Bush's Memex, 1945

“Certainly, progress in photography is not going to stop. [...] Let us project this trend ahead to a logical, if not inevitable, outcome. The camera hound of the future wears on his forehead a lump a little larger than a walnut.”



<https://www.youtube.com/watch?v=c539cK58ees>



## AS WE MAY THINK

A TOP U.S. SCIENTIST FORESEES A POSSIBLE FUTURE WORLD IN WHICH MAN-MADE MACHINES WILL START TO THINK

by VANNEVAR BUSH

DIRECTOR OF THE OFFICE OF SCIENTIFIC RESEARCH AND DEVELOPMENT  
Condensed from the Atlantic Monthly, July 1945

This has not been a scientists' war; it has been a war in which all have had a part. The scientists, burying their old professional competition in the demand of a common cause, have shared greatly and learned much. It has been exhilarating to work in effective partnership. What are the scientists to do next?

For the biologists, and particularly for the medical scientists, there can be little indecision, for their war work has hardly required them to leave the old paths. Many indeed have been able to carry on their war research in their familiar peacetime laboratories. Their objectives remain much the same.

It is the physicists who have been thrown most violently of stride, who have left academic pursuits for the making of strange destructive gadgets, who have had to devise new methods for their unanticipated assignments. They have done their part on the devices that made it possible to turn back the enemy. They have worked in combined effort with the physicists of our allies. They have felt within themselves the stir of achievement. They have been part of a great team. Now one asks where they will find objectives worthy of their best.

There is a growing insulation of research. But there is increased evidence that we are being bogged down today as specialization extends. The investigator is staggered by the findings and conclusions of thousands of other workers—conclusions which he cannot find time to grasp, much less to remember, as they appear. Yet specialization becomes increasingly necessary for prog-

ress, and the effort to bridge between disciplines is correspondingly superficial.

Professionally our methods of transmitting and reviewing the results of research are generations old and by now are morally inadequate for their purpose. If the aggregate time spent in writing scholarly works and in reading them could be evaluated, the ratio between these amounts of time might well be startling. Those who conscientiously attempt to keep abreast of current thought, even in restricted fields, by close and continuous reading might well shy away from an examination calculated to show how much of the previous month's efforts could be produced on call.

Mendel's concept of the laws of genetics was lost to the world for a generation because his publication did not reach the few who were capable of grasping and extending it. This sort of catastrophe is undoubtedly being repeated all about us as truly significant attainments become lost in the mass of the inconsequential.

Publication has been extended far beyond our present ability to make real use of the record. The summation of human experience is being expanded at a prodigious rate, and the means we use for threading through the consequent maze to the momentarily important item is the same as was used in the days of square-rigged ships.

But there are signs of a change as new and powerful instrumentalities come into use. Photocells capable of seeing things in a physical sense, advanced photography which can record what is seen or even what is not, thermionic tubes capable of controlling potent forces under the guidance of



# The Birth of Wearable Computing

Steve Mann's "wearable computer" and "reality mediator" inventions of the 1970s have evolved into what looks like ordinary eyeglasses.



<http://wearcam.org>

In the 80s and 90s Steve Mann (PhD in Media Arts and Sciences at MIT, 1997) invented a number of wearable computers featuring video capabilities, computing capabilities, and a wearable screen for feedback.

# WearCam, Steve Mann, 1994-1996

- In 1994 Steve Mann invented the first wearable camera;
- WearCam streamed images to Mann's personal page from 1994 to 1996;



NCSA Mosaic: Document View

[File](#) [Options](#) [Navigate](#) [Annotate](#) [News](#) [Help](#)

Title: WEARCAM.ORG as Roving Reporter (Cool Site of the Day)

URL: [http://www.wearcam.org/previous\\_experiences/eastcampusfire/](http://www.wearcam.org/previous_experiences/eastcampusfire/)

**wearcam.org as roving reporter; (c) Steve Mann, Feb. 1995**

feb. 22, 1995: most of my day quite boring, walking to lab, pizza at food trucks etc. around 10pm i see a fire hose; i'm following it now

looks like must be a fire, fire trucks, shall i go to right for view? (email or talk me in@.. or tnc)

isn't it cool, those on mosaic, world wide web for first time see news as it happens?

no, but i could envision this as a new form of news gathering. i go to make lookpainting of fire truck

[Back](#) [Forward](#) [Home](#) [Reload](#) [Open...](#) [Save As...](#) [Clone](#) [New Window](#) [Close Window](#)

Steve Mann, "Wearable computing: a first step toward personal imaging," in *Computer*, vol. 30, no. 2, pp. 25-32, Feb. 1997.

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*Steve Mann*  
MIT Media Lab

# *Wearable Computing: A First Step Toward Personal Imaging*



**Miniaturization of components has enabled  
systems that are wearable and nearly invisible,  
so that individuals can move about and  
interact freely, supported by their personal  
information domain.**

# Wearable Computer Vision: The Goal



Clip from movie Termintor 2-Judgment day: <https://youtu.be/9MeaaCwBW28>

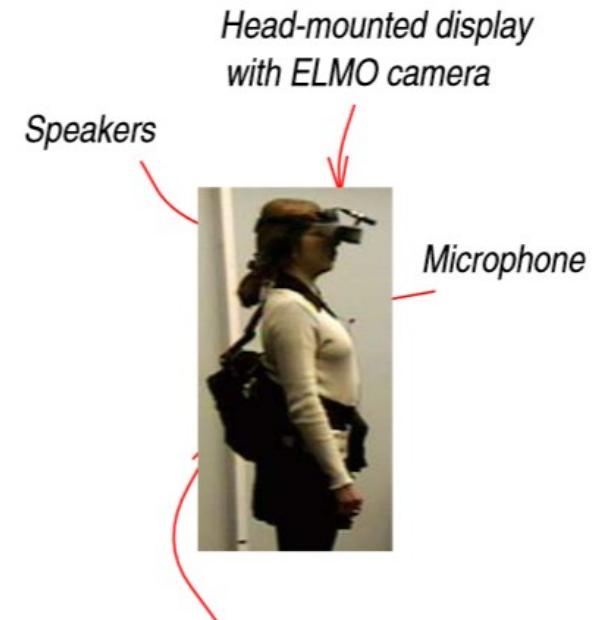
Ref: [https://www.redsharknews.com/vr\\_and\\_ar/item/3539-terminator-2-vision-the-augmented-reality-standard-for-25-years](https://www.redsharknews.com/vr_and_ar/item/3539-terminator-2-vision-the-augmented-reality-standard-for-25-years)

# MIT Media Lab in 1997



# DyPERS, 1998

[www.nuriaoliver.com/dypers/](http://www.nuriaoliver.com/dypers/)



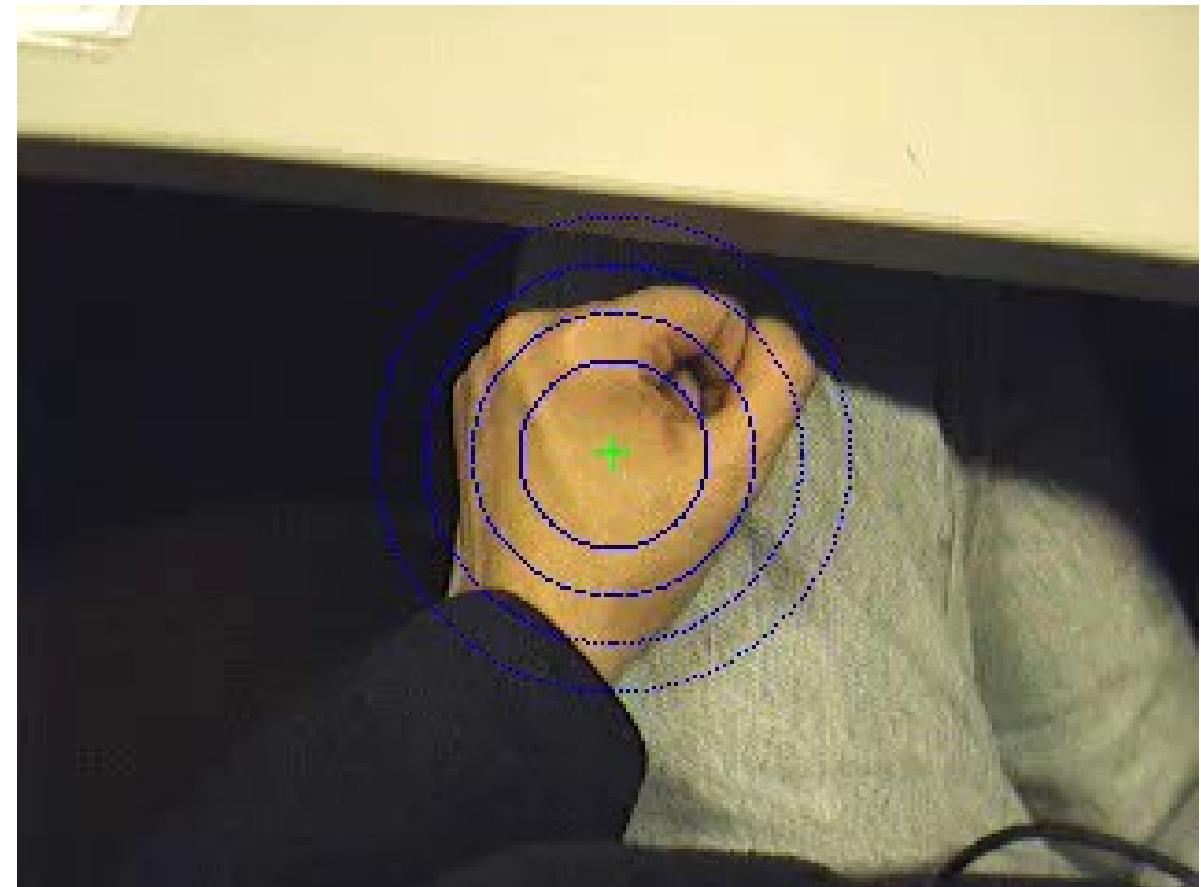
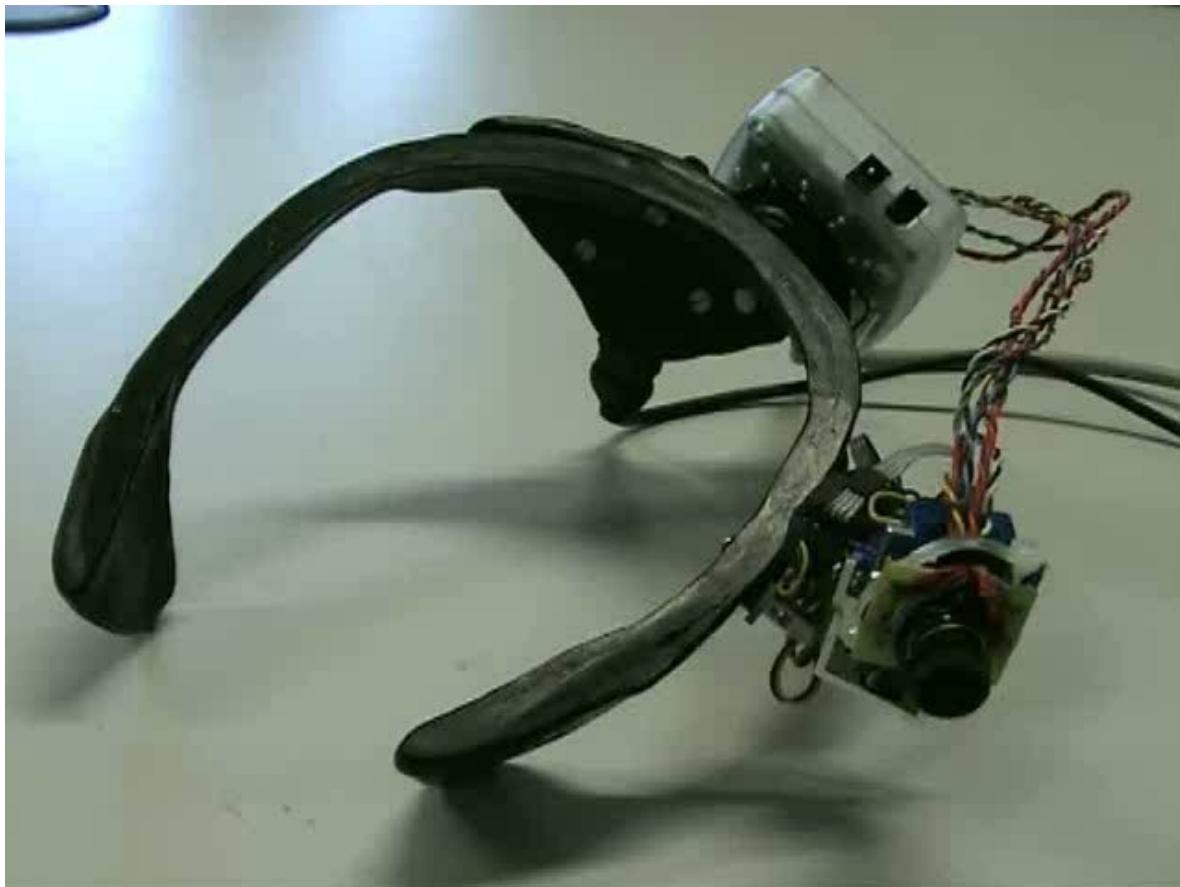
Wavecom transmitter/receiver units

VISUAL TRIGGER	ASSOCIATED SEQUENCE
 	
	
?  	 GARBAGE NO PLAY-BACK

Jebara, T., Schiele, B., Oliver, N., & Pentland, A. (1998). DyPERS: Dynamic personal enhanced reality system. In *In Proc. 1998 Image Understanding Workshop*.

# Wearable Visual Robots, 2002 - 2004

<http://people.cs.bris.ac.uk/~wmayol/research/>



W.W. Mayol, B. Tordoff and D.W. Murray. Wearable Visual Robots. Selected papers from ISWC00, Personal And Ubiquitous Computing Journal. Springer-Verlag. Volume 6 pp37-48. 2002.

W.W. Mayol, A.J. Davison, B.J. Tordoff, N.D. Molton, and D.W. Murray. Interaction between hand and wearable camera in 2D and 3D environments. Proc. British Machine Vision Conference 2004.

# SLAM and Augmented Reality, 2004-2008

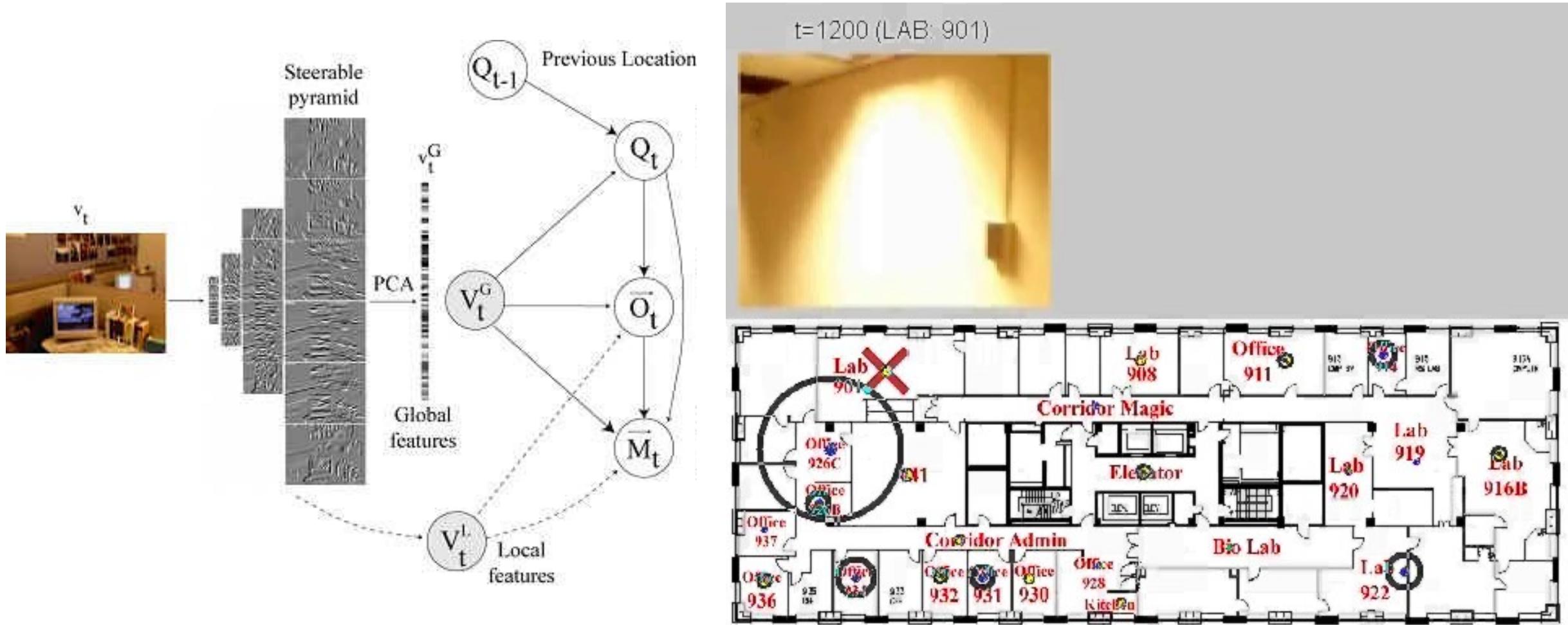
<http://people.cs.bris.ac.uk/~wmayol/research/>



- W.W. Mayol, A.J. Davison, B.J. Tordoff, N.D. Molton, and D.W. Murray. Interaction between hand and wearable camera in 2D and 3D environments. Proc. British Machine Vision Conference 2004. London, UK, September. 2004.
- Pished Bunnun, Walterio Mayol-Cuevas, OutlinAR: an assisted interactive model building system with reduced computational effort. 7th IEEE and ACM International Symposium on Mixed and Augmented Reality. September 2008.

# Place and scene recognition from FPV, 2003

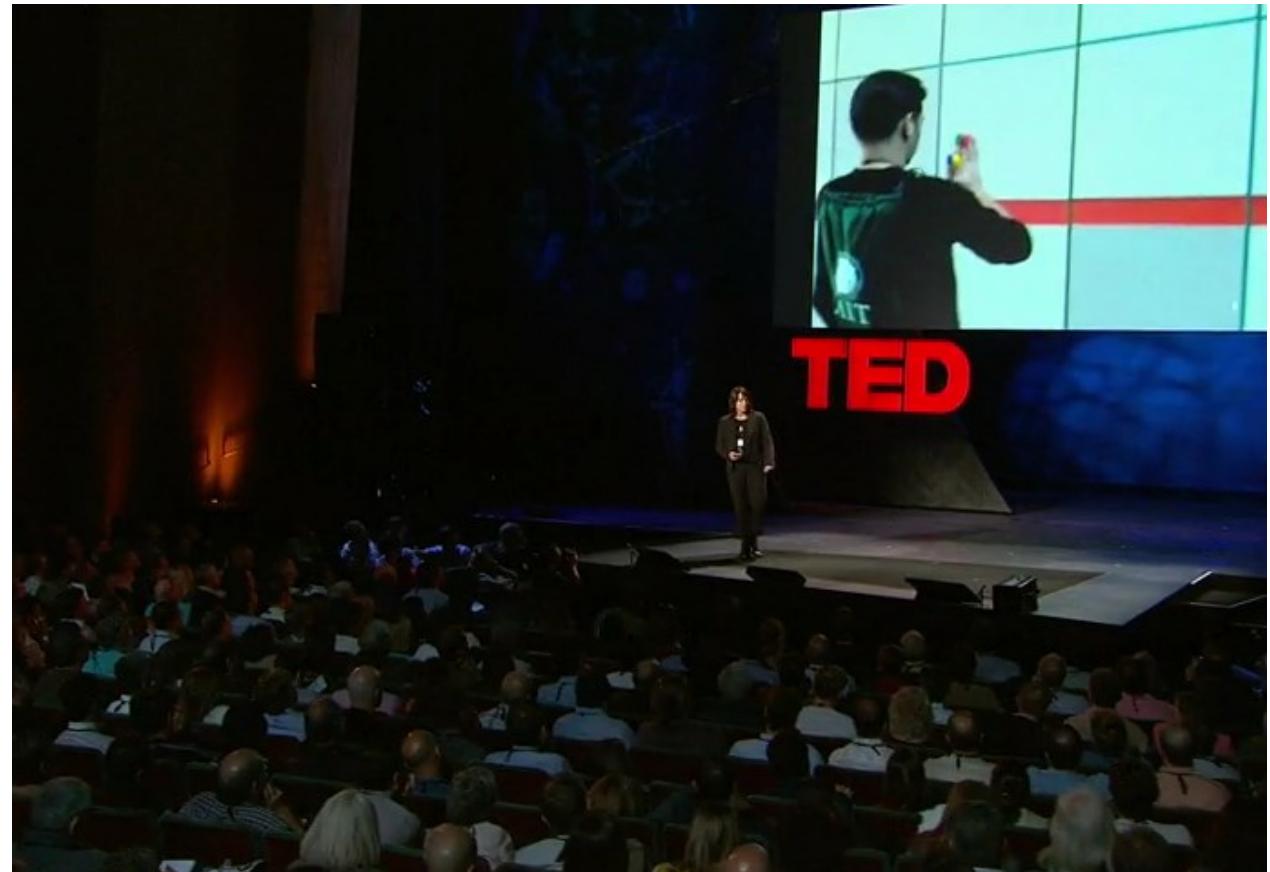
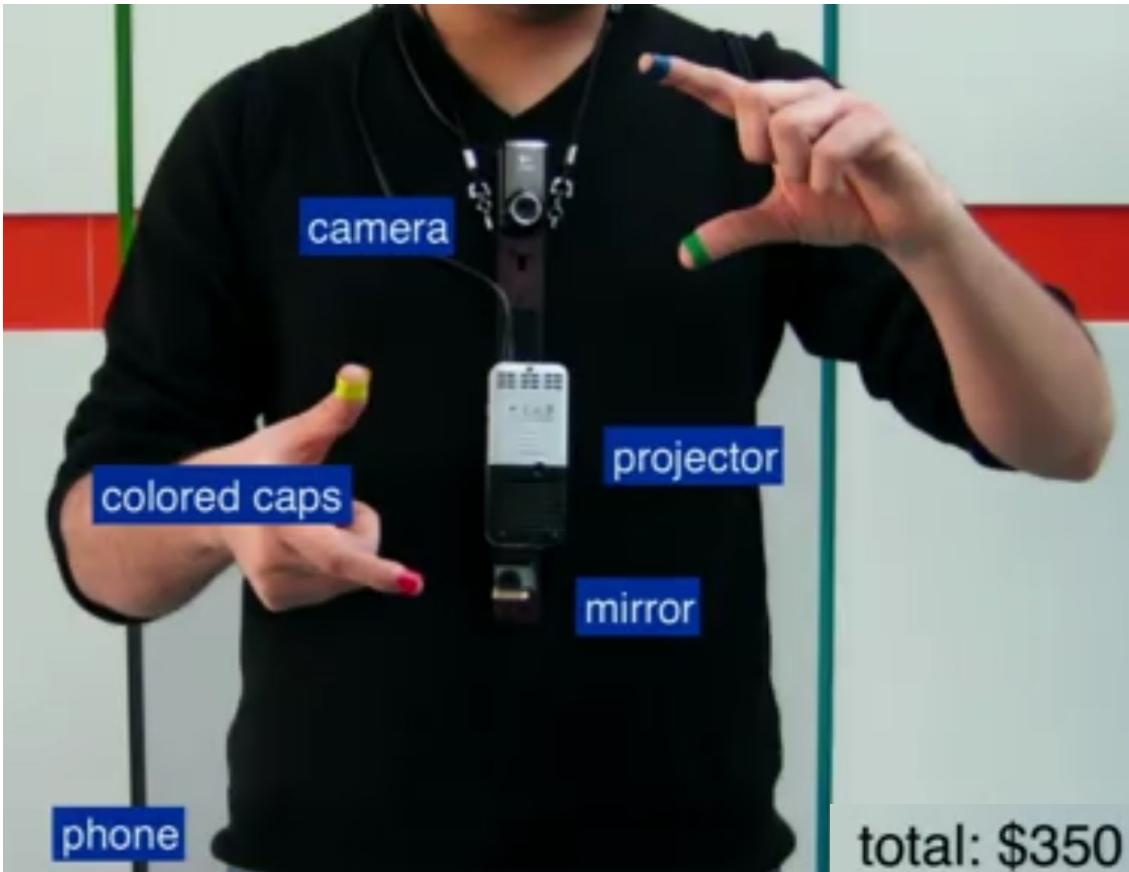
<https://www.cs.ubc.ca/~murphyk/Vision/placeRecognition.html>



# Sixth Sense, 2009

**Neck worn camera with a projector and a gesture-based user interface.**

«to give people access to information without requiring that the user changes any of their behavior»



RADIO SILENCE

# Hardware, 1990s – 2000s

A COMMON HARDWARE  
PLATFORM WAS MISSING!



# Microsoft SenseCam, 2004

## "A day in Rome"



- SenseCam is a wearable camera that takes photos automatically;
- Originally conceived as a «personal blackbox» accident recorder;
- Used in the MyLifeBits project, inspired by Bush's Memex;
- Inspired a series of conferences and many research papers.

<https://www.microsoft.com/en-us/research/project/sensecam/>

# Research using Microsoft SenseCam

## Do Life-Logging Technologies Support Memory for the Past? An Experimental Study Using SenseCam

Abigail Sellen, Andrew Fogg, Mike Aitken\*, Steve Hodges, Carsten Rother and Ken Wood

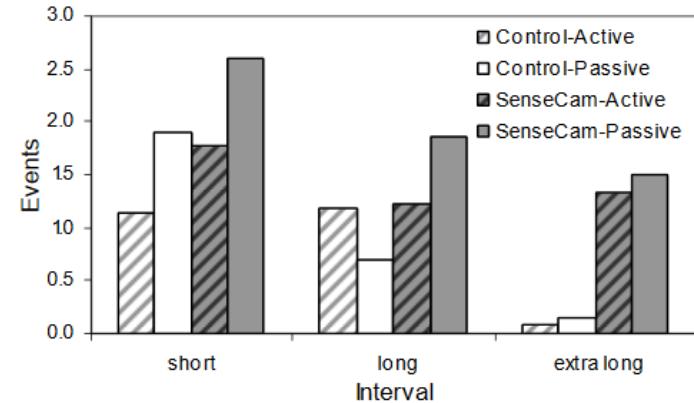
Microsoft Research Cambridge

7 JJ Thomson Ave, Cambridge, UK, CB3 0FB

\*Behavioural & Clinical Neuroscience Institute

Dept. of Psychology, University of Cambridge

(health, memory augmentation)



2007



(a) Reading in bed



(b) Having dinner

## MyPlaces: Detecting Important Settings in a Visual Diary

Michael Blighe and Noel E. O'Connor

Centre for Digital Video Processing, Adaptive Information Cluster  
Dublin City University, Ireland

{blighem, oconnorn}@eeng.dcu.ie

(lifelogging, place recognition)

2008

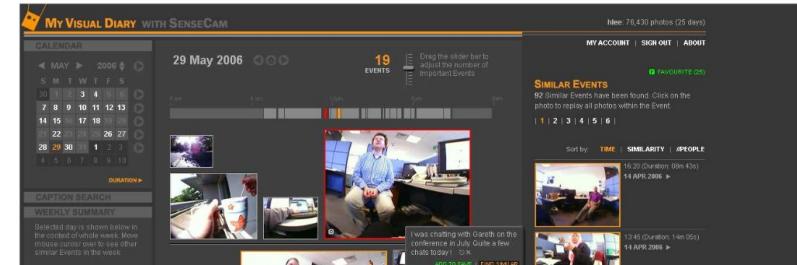
## Constructing a SenseCam Visual Diary as a Media Process

Hyowon Lee, Alan F. Smeaton, Noel O'Connor, Gareth Jones, Michael Blighe, Daragh Byrne,

Aiden Doherty, and Cathal Gurrin

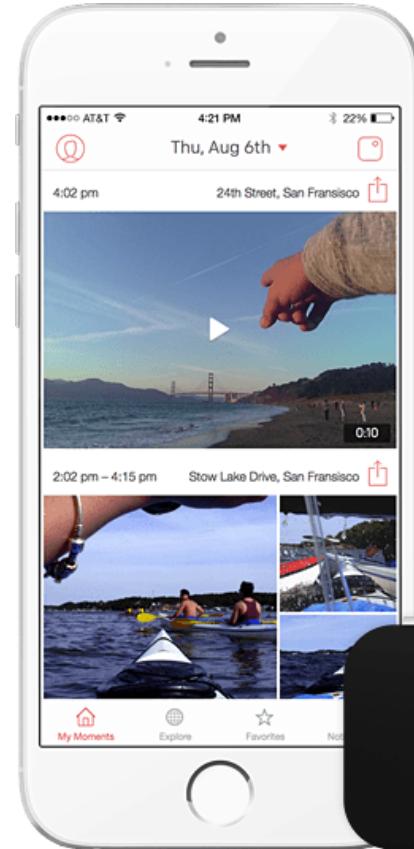
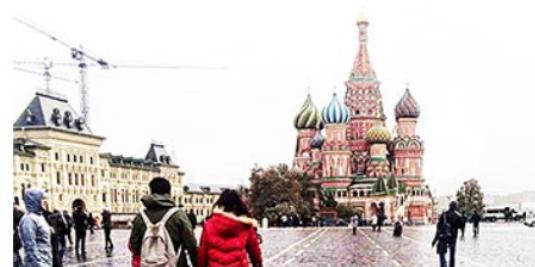
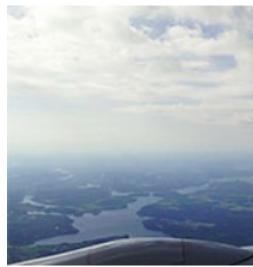
Centre for Digital Video Processing & Adaptive Information Cluster,  
Dublin City University

(lifelogging, multimedia retrieval)



2008

# Narrative Clip, 2012



<http://getnarrative.com/>

# Research Using Narrative Clip

Multi-face tracking by extended bag-of-tracklets in egocentric photo-streams

Maedeh Aghaei<sup>a,\*</sup>, Mariella Dimiccoli<sup>a,b</sup>, Petia Radeva<sup>a,b</sup>  
(lifelogging, face tracking)

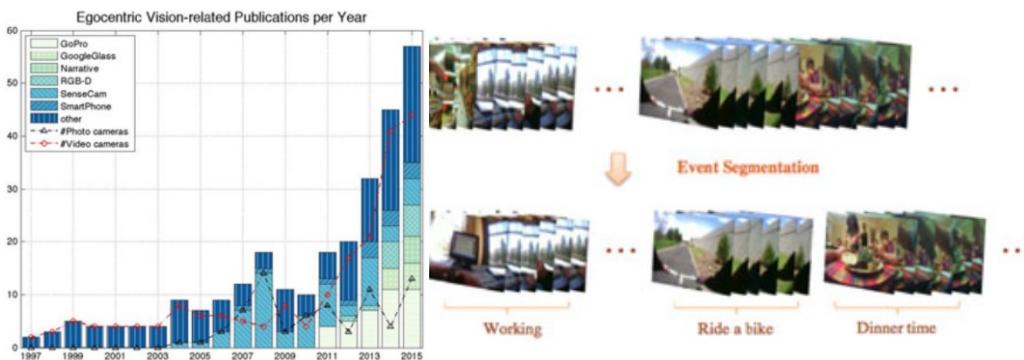


2017



SR-clustering: Semantic regularized clustering for egocentric photo streams segmentation

Mariella Dimiccoli<sup>a,c,1,\*</sup>, Marc Bolaños<sup>a,1,\*</sup>, Estefania Talavera<sup>a,b</sup>, Maedeh Aghaei<sup>a</sup>,  
Stavri G. Nikolov<sup>d</sup>, Petia Radeva<sup>a,c,\*</sup>  
(lifelogging, event segmentation)



## Toward Storytelling From Visual Lifelogging: An Overview

Marc Bolaños, Mariella Dimiccoli, and Petia Radeva  
(lifelogging, survey)

2016

2017

# WHAT ABOUT VIDEO?



# GoPro HD Hero, 2010

different wearing modalities



head-mounted



chest-mounted



wrist-mounted



helmet-mounted

<https://www.youtube.com/watch?v=D4iU-EOJYK8>



# Looxcie, 2010

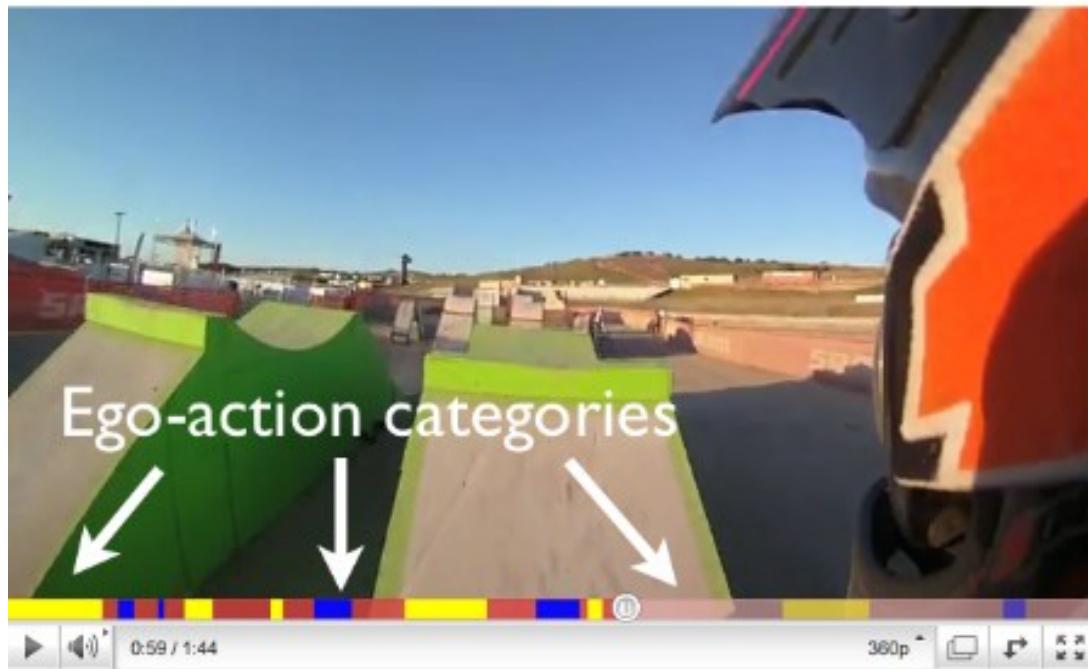


«mobile, connected, hands free, streaming video camera»

(unsupervised action recognition, video indexing)

# Unsupervised Ego-Action Learning, 2011

[https://www.youtube.com/watch?v=12CZu4Xlb\\_U](https://www.youtube.com/watch?v=12CZu4Xlb_U)

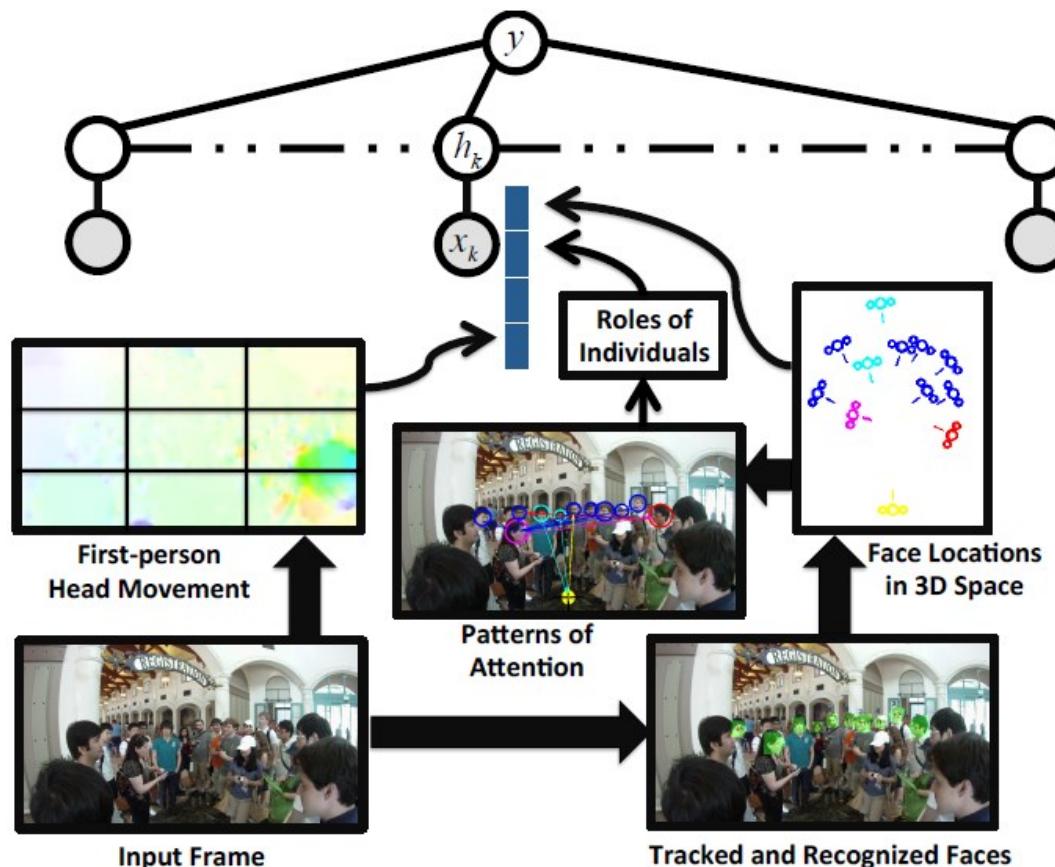


Kitani, K. M., Okabe, T., Sato, Y., & Sugimoto, A. (2011, June). Fast unsupervised ego-action learning for first-person sports videos. In *Computer Vision and Pattern Recognition (CVPR), 2011 IEEE Conference on* (pp. 3241-3248). IEEE.

(detection and recognition of social interactions)

# Social Interaction Recognition, 2012

<https://player.vimeo.com/video/37507972>

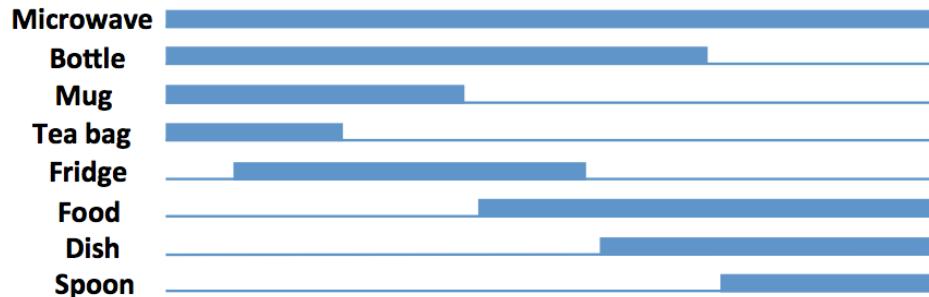


Fathi, A., Hodgins, J. K., & Rehg, J. M. (2012, June). Social interactions: A first-person perspective. In *Computer Vision and Pattern Recognition (CVPR), 2012 IEEE Conference on* (pp. 1226-1233). IEEE.

(egocentric video summarization)

# Egocentric Video Summarization, 2013

<http://vision.cs.utexas.edu/projects/egocentric/storydriven.html>



**Our method**

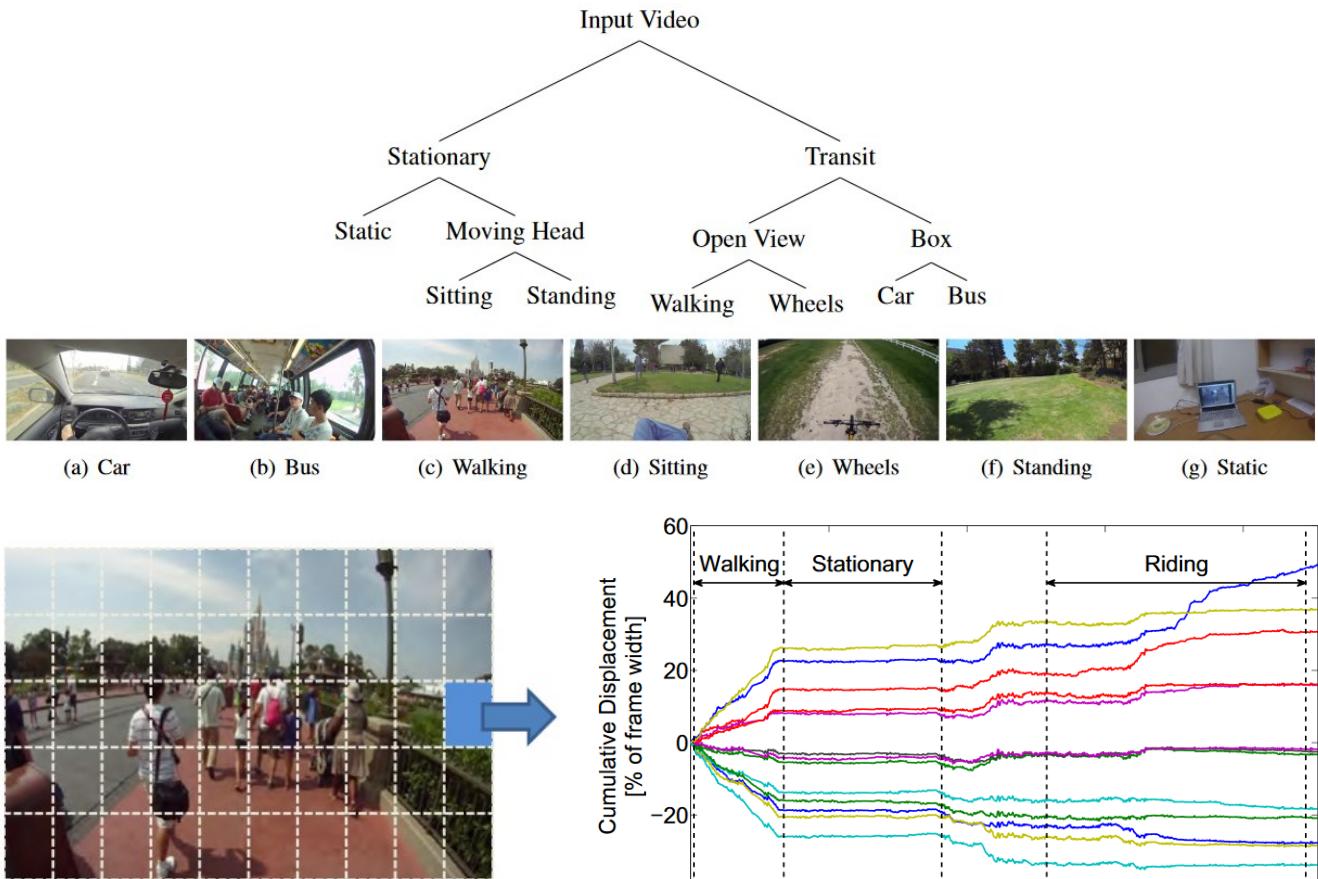


**Uniform sampling**

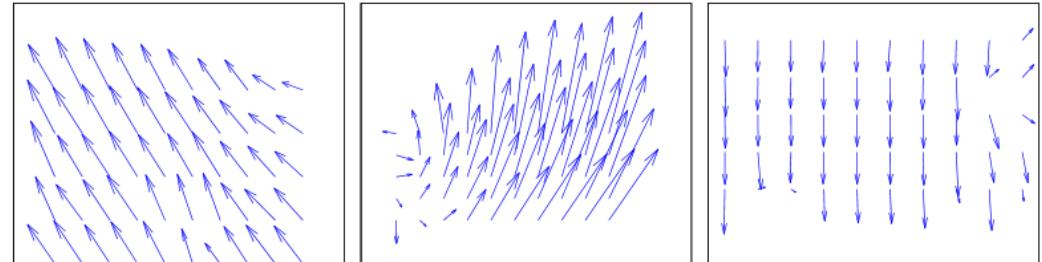


- Story-Driven Summarization for Egocentric Video. Zheng Lu and Kristen Grauman. Computer Vision and Pattern Recognition (CVPR), 2013
- Discovering Important People and Objects for Egocentric Video Summarization. Yong Jae Lee, Joydeep Ghosh, and Kristen Grauman. CVPR 2012

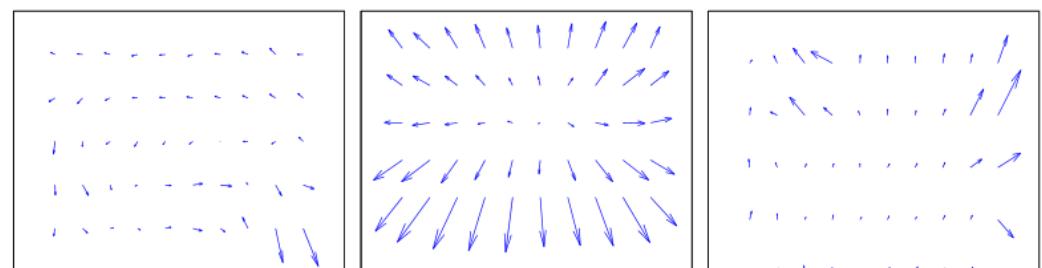
# Temporal Segmentation of Egocentric Video, 2014



Sitting      Walking      Riding Bus



(a) Instantaneous  $(x, y)$  displacement vectors are dominated by the head rotation, and the effects of the activity, e.g. sitting, walking, or riding, is too small to observe.

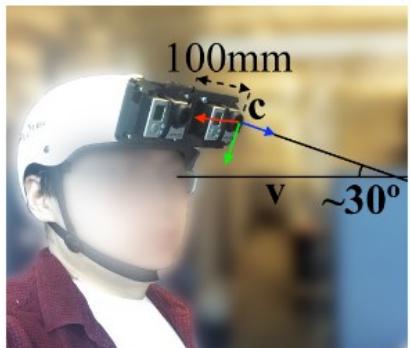


(b) Motion vectors obtained from the cumulative displacement curves as given in Eq. 3. Effects of head rotations are removed, and the direction of vectors are now noiseless. For 'walking' the vectors are large and have radial direction. In the 'sitting' case, the magnitude mostly zero. Riding ('car'/bus') has a mixed pattern.

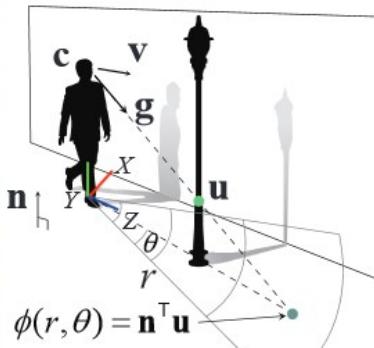
(future localization, navigation)

# Future Localization in Egocentric Video, 2016

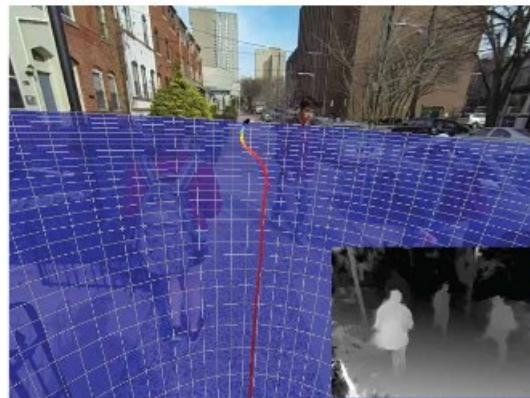
[https://www-users.cs.umn.edu/~hspark/future\\_loc.html](https://www-users.cs.umn.edu/~hspark/future_loc.html)



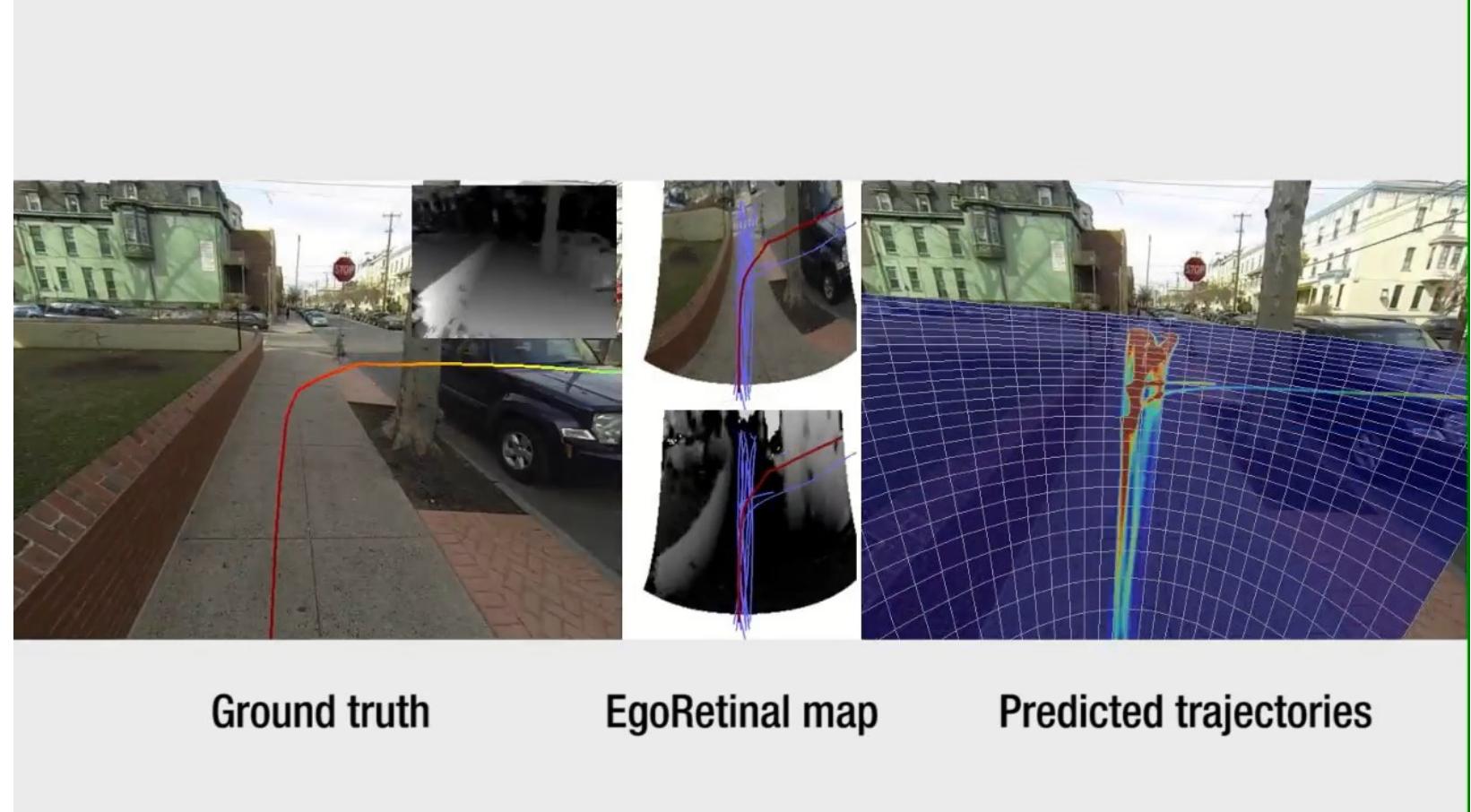
(a) Ego-stereo cameras



(b) Geometry



(c) Egocentric RGBD image



Ground truth

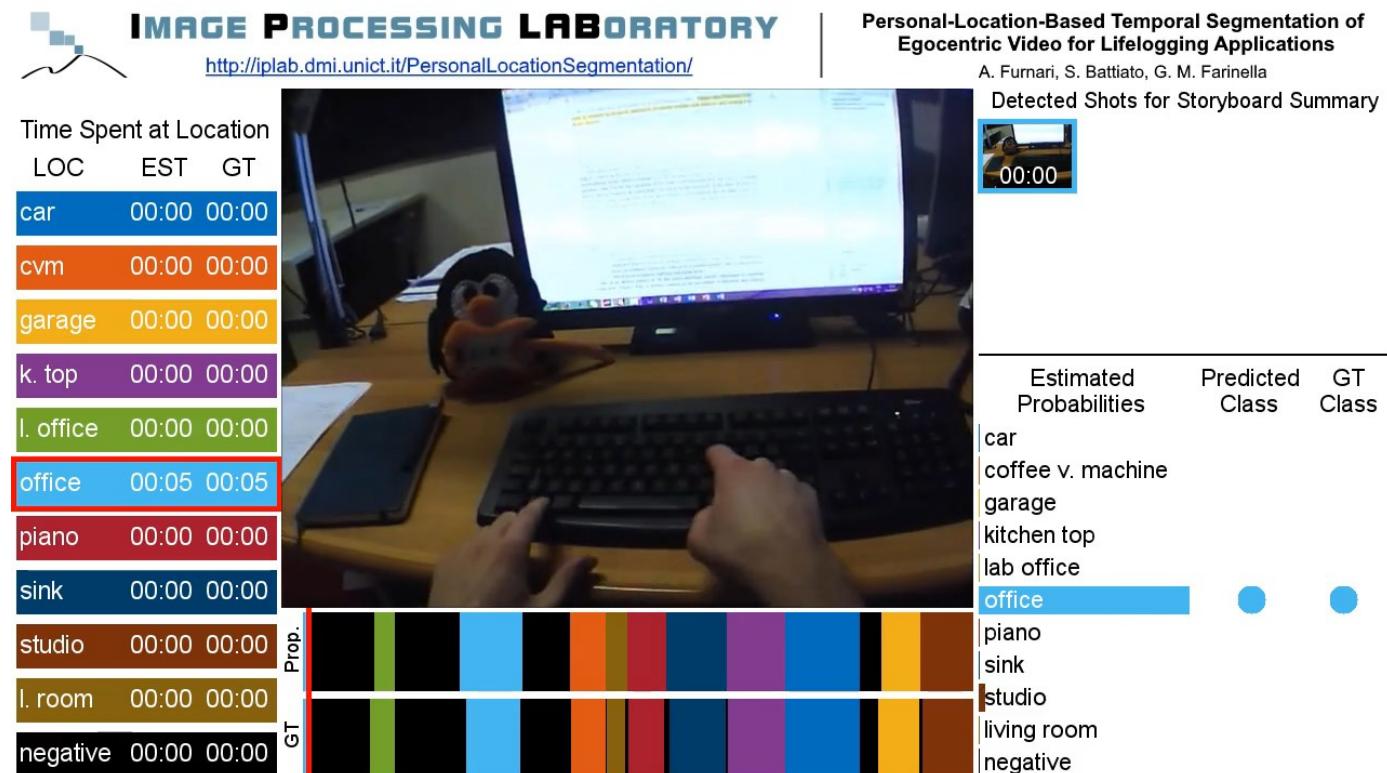
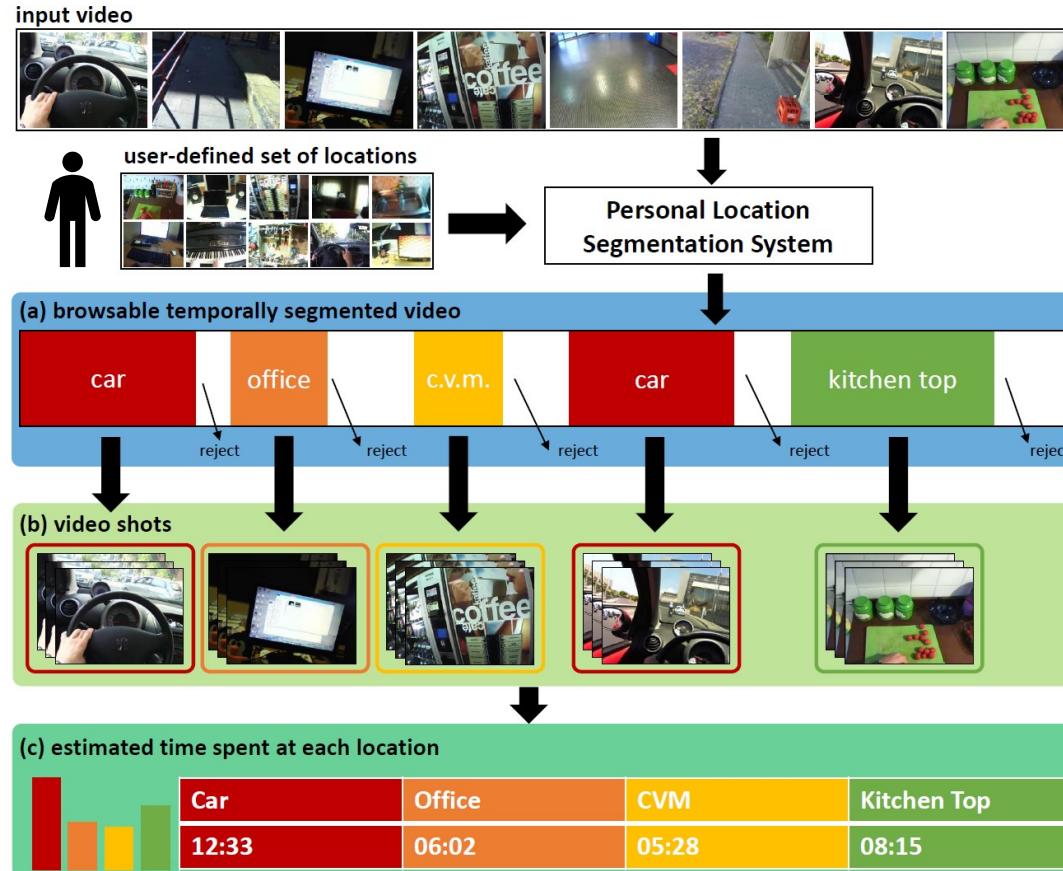
EgoRetinal map

Predicted trajectories

(localization, indexing, context-aware computing)

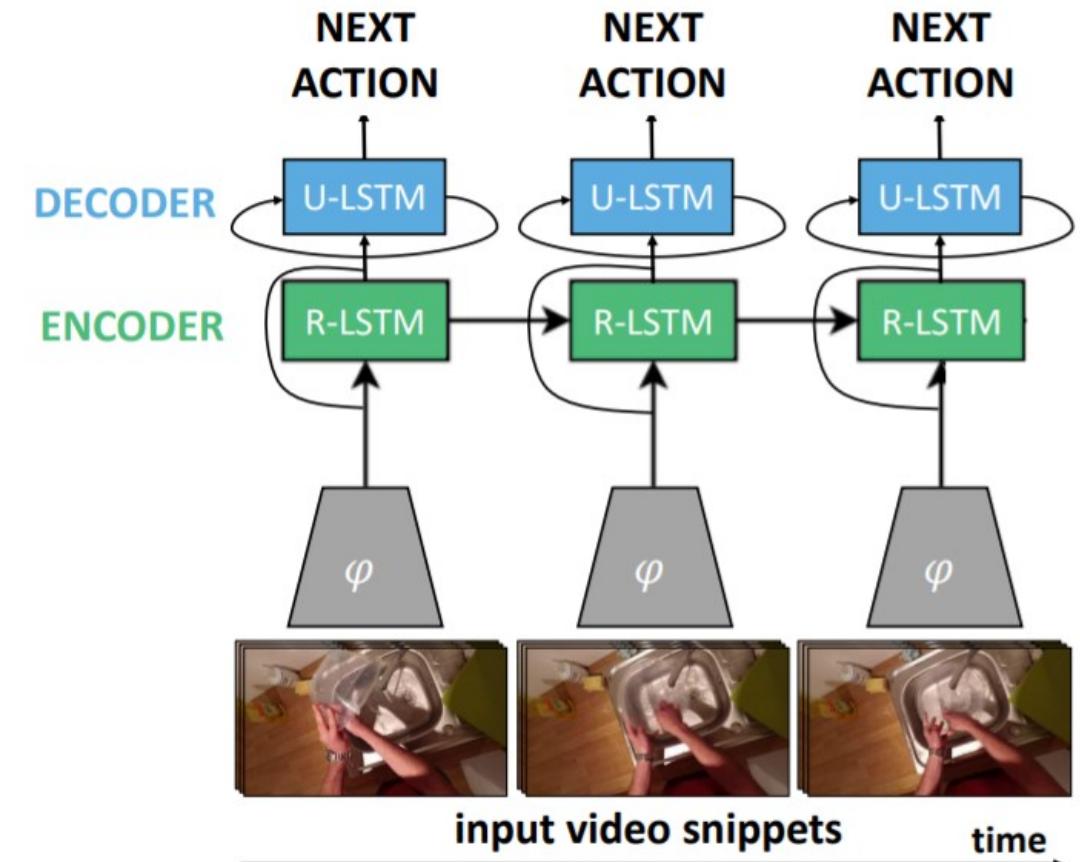
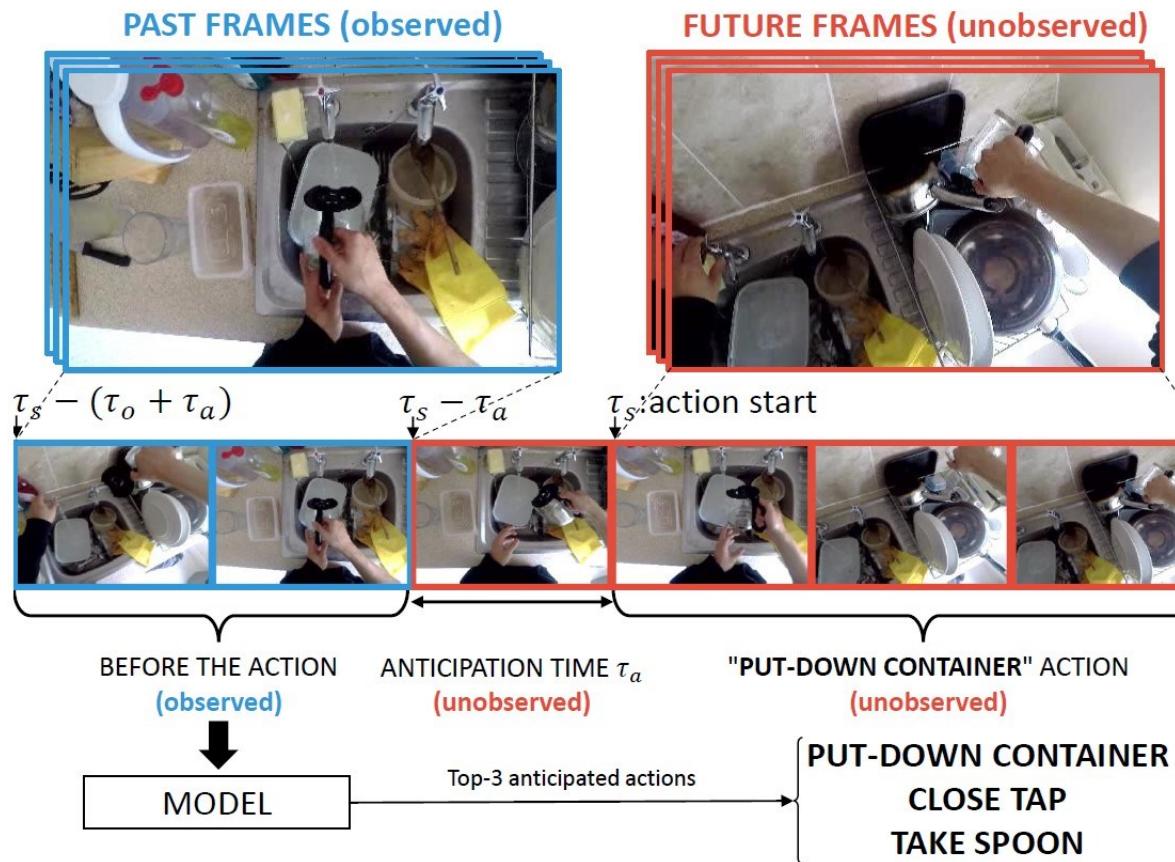
# Egocentric Location Recognition, 2018

<http://iplab.dmi.unict.it/PersonalLocationSegmentation/>



- A. Furnari, G. M. Farinella, S. Battiato, Recognition of Personal Locations from Egocentric Videos, IEEE Transactions on Human-Machine Systems, 2016.
- A. Furnari, S. Battiato, G. M. Farinella, Personal-Location-Based Temporal Segmentation of Egocentric Video for Lifelogging Applications . Journal of Visual Communication and Image Representation , 52 , pp. 1-12, 2018.

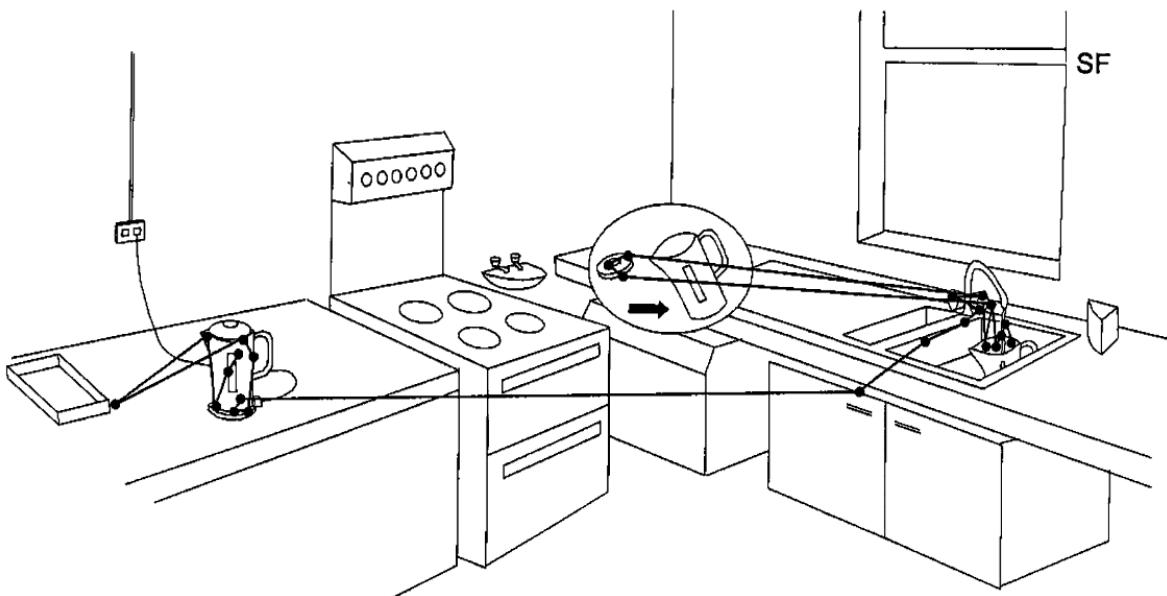
# Egocentric Action Anticipation, 2020



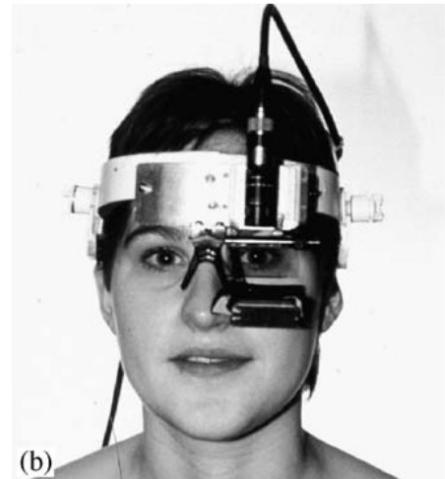
# Gaze Trackers

Eye movements and the control of actions in everyday life

Michael F. Land



**Gaze is important for First person Vision!**



Prototype by Land (1993)



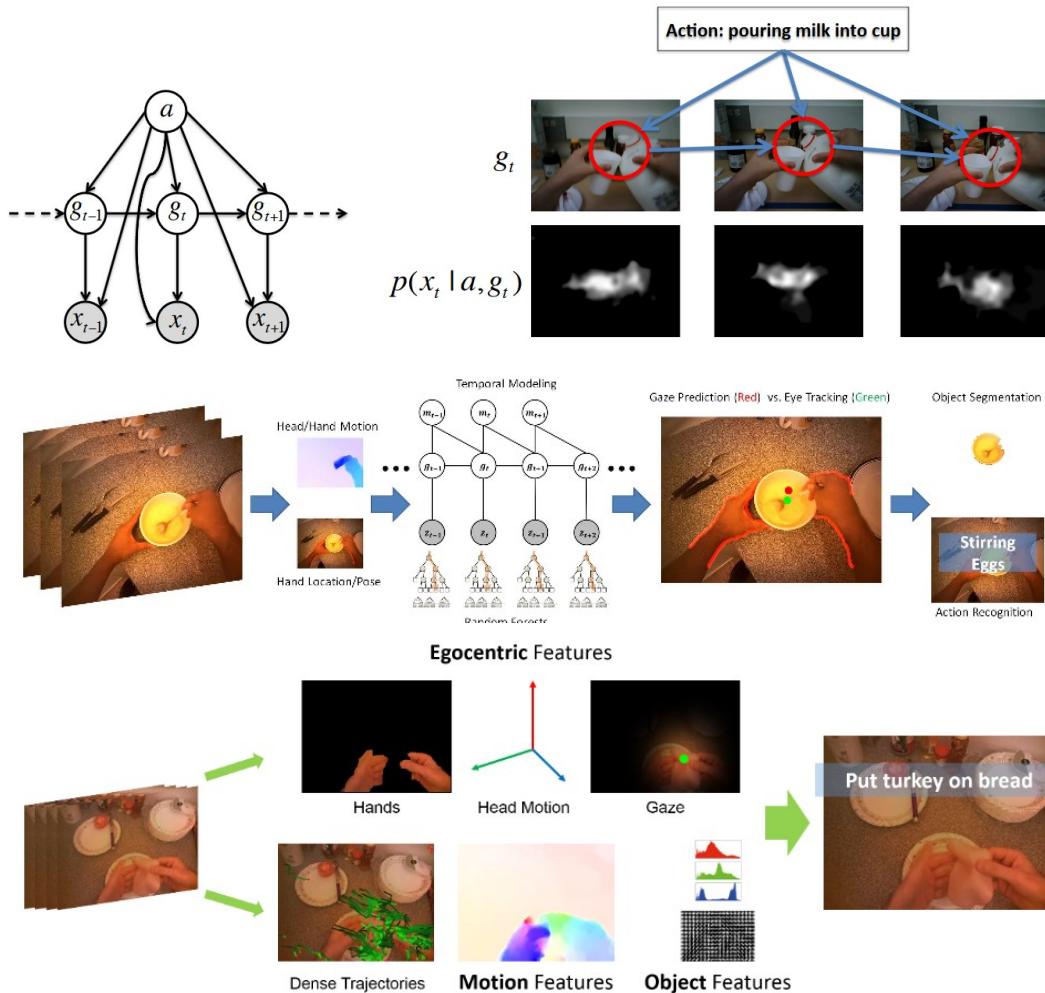
Mobile Eye-XG (2013) Pupil Eye Tracker (2014)



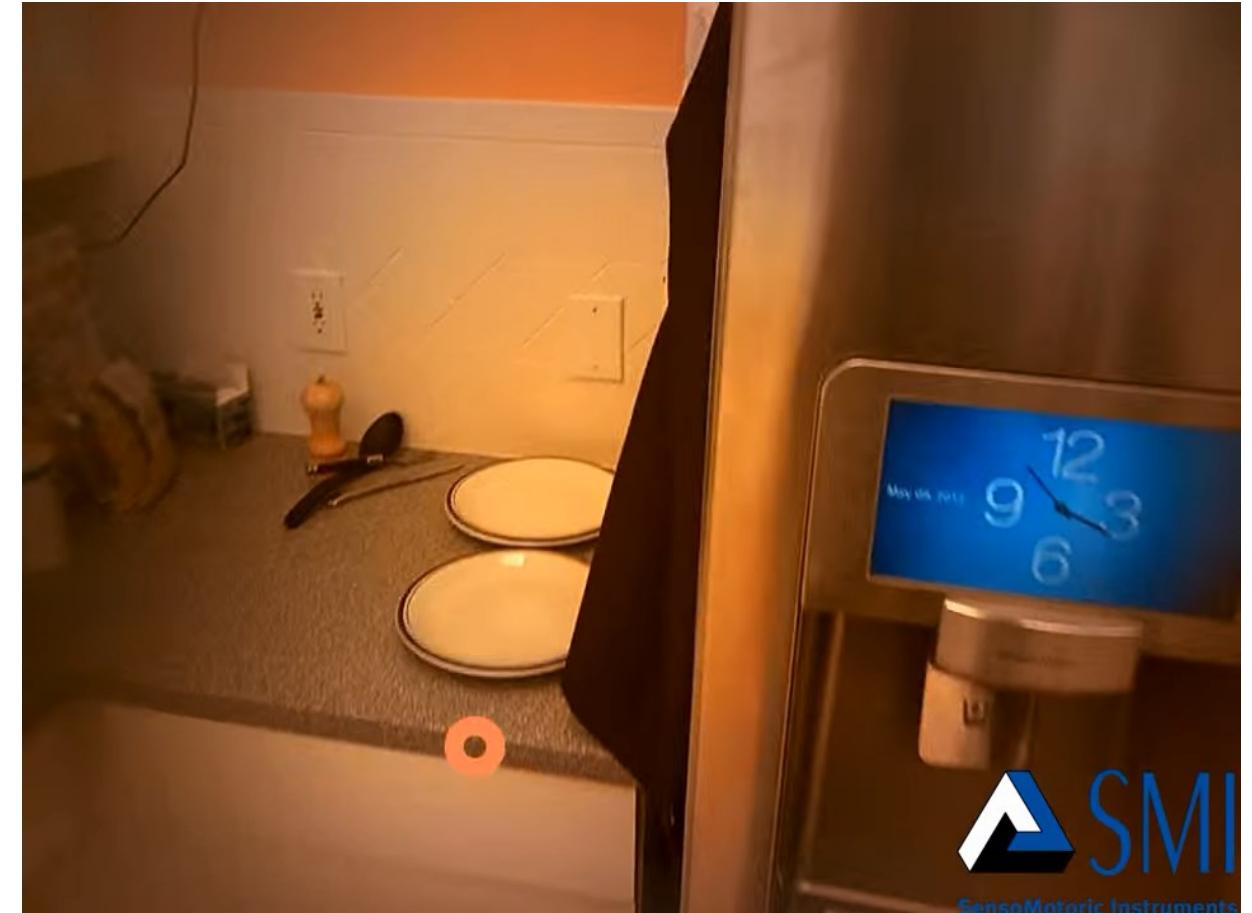
Tobii Pro Glasses 2 (2014)

(action recognition)

# Gaze & Actions Using Gaze, 2012 - 2015



[http://ai.stanford.edu/~alireza/GTEA\\_Gaze\\_Website/](http://ai.stanford.edu/~alireza/GTEA_Gaze_Website/)



**SMI**  
SensoMotoric Instruments

- Fathi, A., Li, Y., & Rehg, J. M. (2012, October). Learning to recognize daily actions using gaze. In *European Conference on Computer Vision* (pp. 314-327). Springer, Berlin, Heidelberg.
- Li, Yin, Alireza Fathi, and James M. Rehg. "Learning to predict gaze in egocentric video." *Proceedings of the IEEE International Conference on Computer Vision*. 2013.
- Li, Y., Ye, Z., & Rehg, J. M. (2015). Delving into egocentric actions. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition* (pp. 287-295).

(object usage discovery, assistance)

# You-Do, I-Learn, 2016

Learning Mode



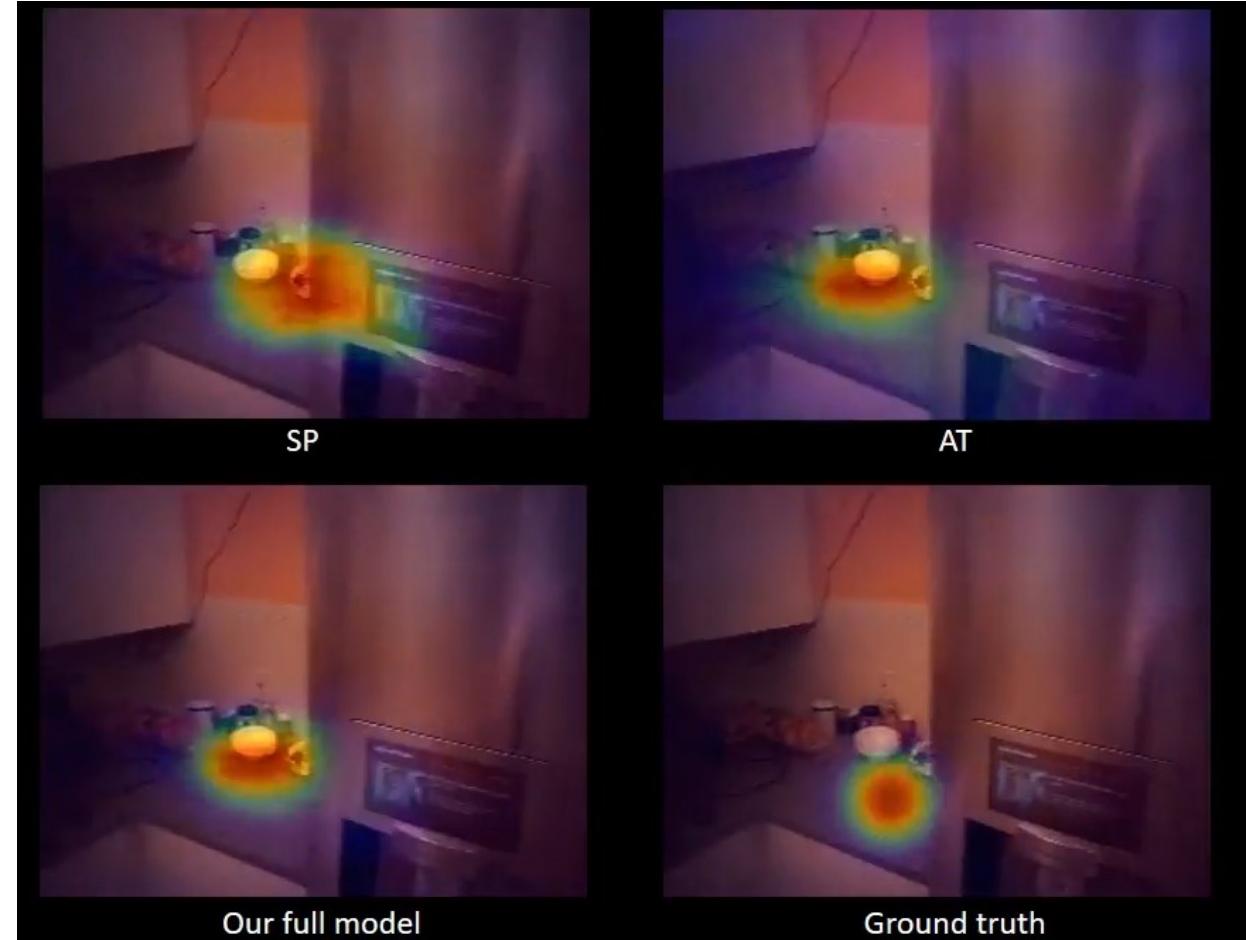
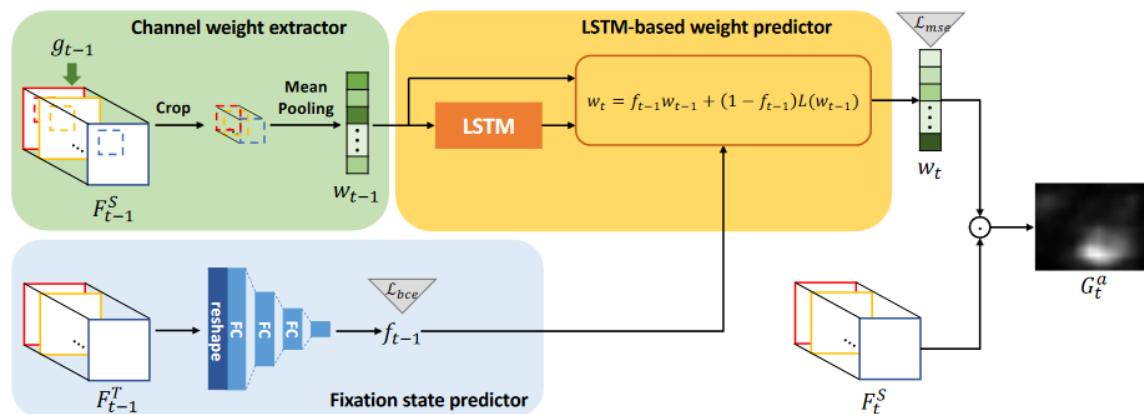
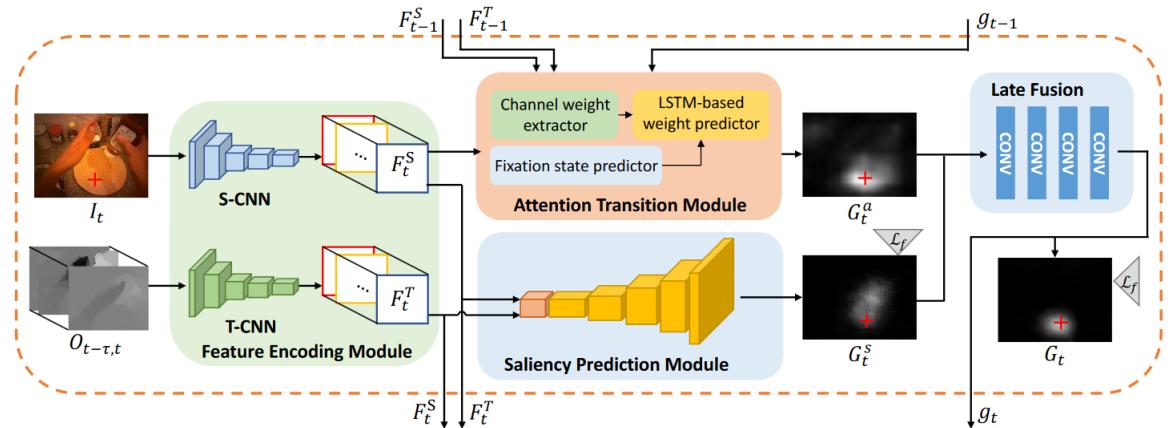
Assistive Mode



Map 4

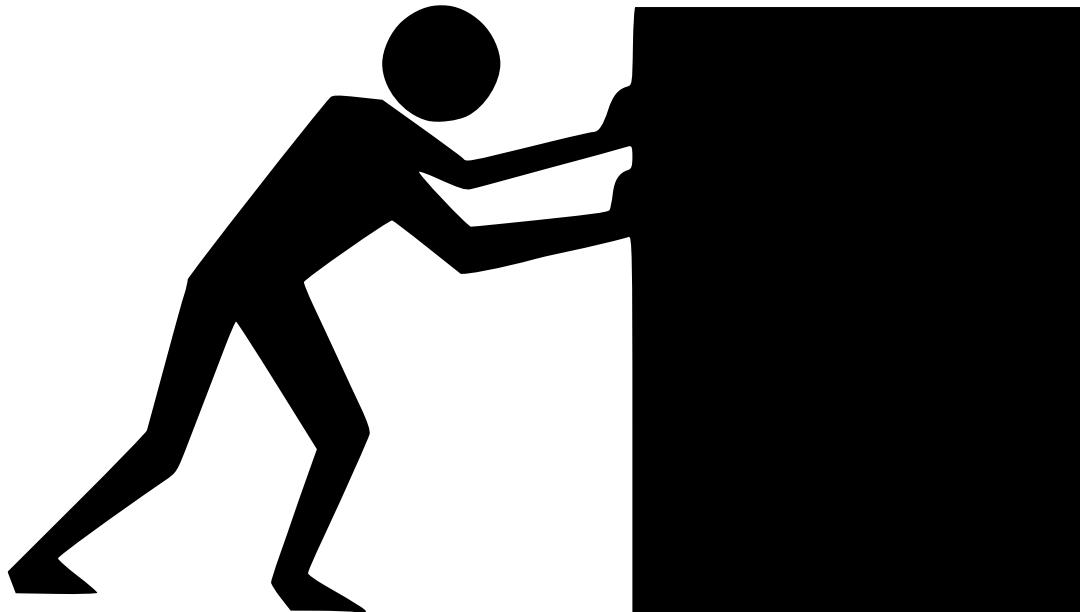
(gaze prediction)

# Gaze Prediction, 2018



# Acquisition devices helped research

however, they moved the focus from action to analysis

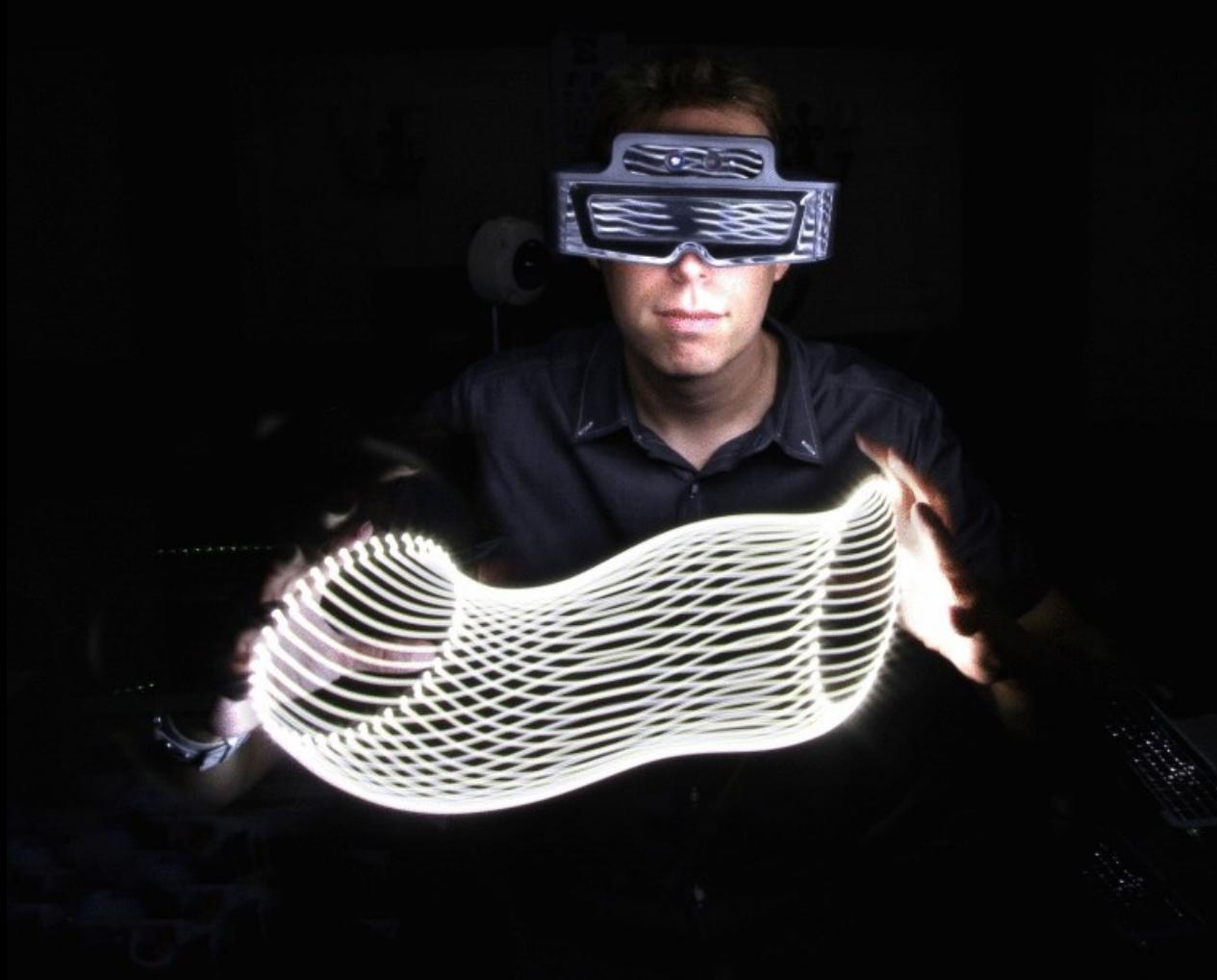


ACTION



ANALYSIS

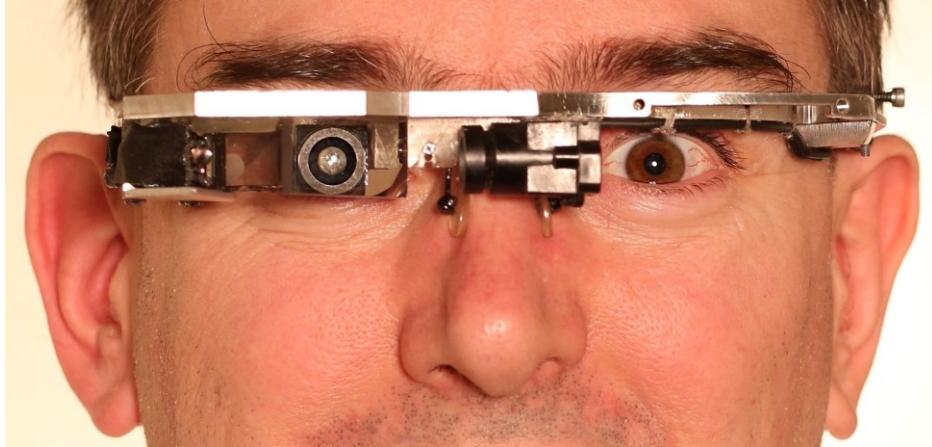
# Is the Cyborg dream still possible?



[wearcam.org/](http://wearcam.org/)

# EyeTap, Steve Mann, 2000s

<https://www.youtube.com/watch?v=jSAGHqcVupE>



Mann, S., Fung, J., Aimone, C., Sehgal, A., & Chen, D. (2005). Designing EyeTap digital eyeglasses for continuous lifelong capture and sharing of personal experiences. *Alt. Chi, Proc. CHI 2005*.

# Google Glass, 2012



- Google envisioned a future in which smart glasses replace smartphones;
- The goal of Google Glass was to make computation available to the user when they need it and get out of the way when they don't.

<https://www.youtube.com/watch?v=YAXTQL3jPFk>

# Brief Timeline of Google Glass (up to 2014)

2009

- Google creates a research lab to work on a prototype of smart glasses. The first prototype looked like a scuba mask attached to a laptop you carried around with a backpack.

2011

- Early designs to make Google Glass light and portable. The product is there, but there is not clear use for it.

2012

- Google Glass is officially announced to the public with a futuristic video of what it will allow to do (but still doesn't). People love the concept of Google Glass.

2013

- The Glass Explorer program is launched as an early access campaign to gain insight into how people would use Google Glass.

2014

- Google Glass turns out to be an immature product with no clear use case. Its video recording capabilities raise serious privacy issues and the product is ridiculed by the media. The launch of a consumer version is suspended.

# The Failure of Google Glass, 2014

<https://www.youtube.com/watch?v=ClvI9fZaz6M>



**Google Glass failed because of the lack of clear use cases + privacy issues.**

# Consumer Wearable Cameras

Is this it?

SenseCam



2004

Vicon Revue



2010

Autographer



2013

Looxcie

2014



2010

Google Glass

2014



2012

Success Cases



# Epson Moverio Smart Glasses with See-Through Display for Augmented Reality, since 2012



<https://www.epson.co.uk/products/see-through-mobile-viewer/moverio-bt-300>

# Vuzix (Since 2012)



**Manufacturing  
Solutions**

[LEARN MORE](#)

**Warehouse  
Solutions**

[LEARN MORE](#)

**Field Service &  
Remote Assist  
Solutions**

[LEARN MORE](#)

**Tele-Medicine  
Solutions**

[LEARN MORE](#)



# OrCam MyEye, since 2015



**Health, assistive technologies**

<https://www.orcam.com/>

# OrCam MyEye, since 2015



<https://www.orcam.com/>

<https://www.microsoft.com/hololens>

**Mixed Reality**

Microsoft HoloLens, since 2016 – HoloLens2 in 2020



<https://youtu.be/eqFqtAJMtYE>

real use cases in industrial scenarios, where privacy is not a issue

# Google Glass Enterprise Edition, since 2017



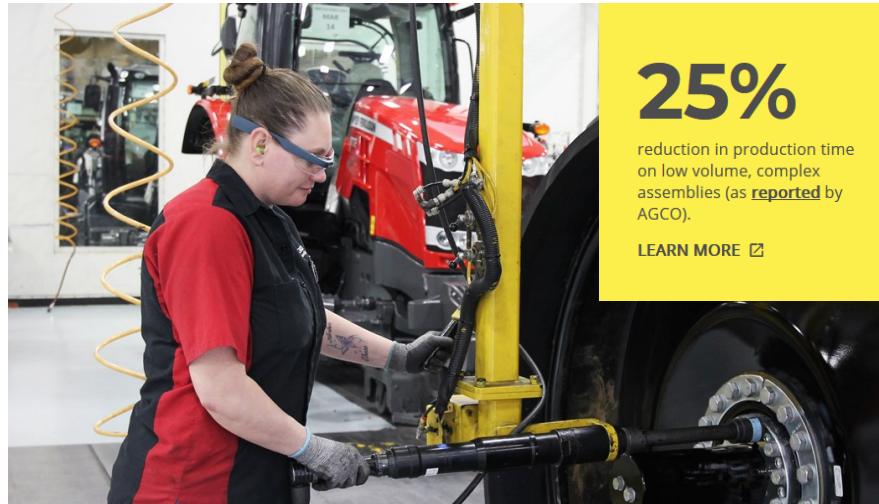
Stay hands-on



Work smarter



Instant expertise



**25%**

reduction in production time  
on low volume, complex  
assemblies (as [reported](#) by  
AGCO).

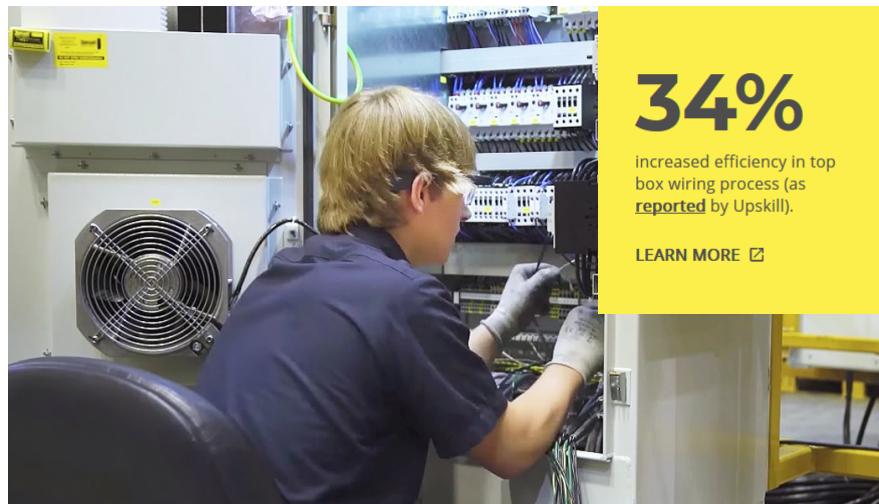
[LEARN MORE](#)



**15%**

greater operational efficiency  
on average (as [reported](#) by  
DHL).

[LEARN MORE](#)



**34%**

increased efficiency in top  
box wiring process (as  
[reported](#) by Upskill).

[LEARN MORE](#)

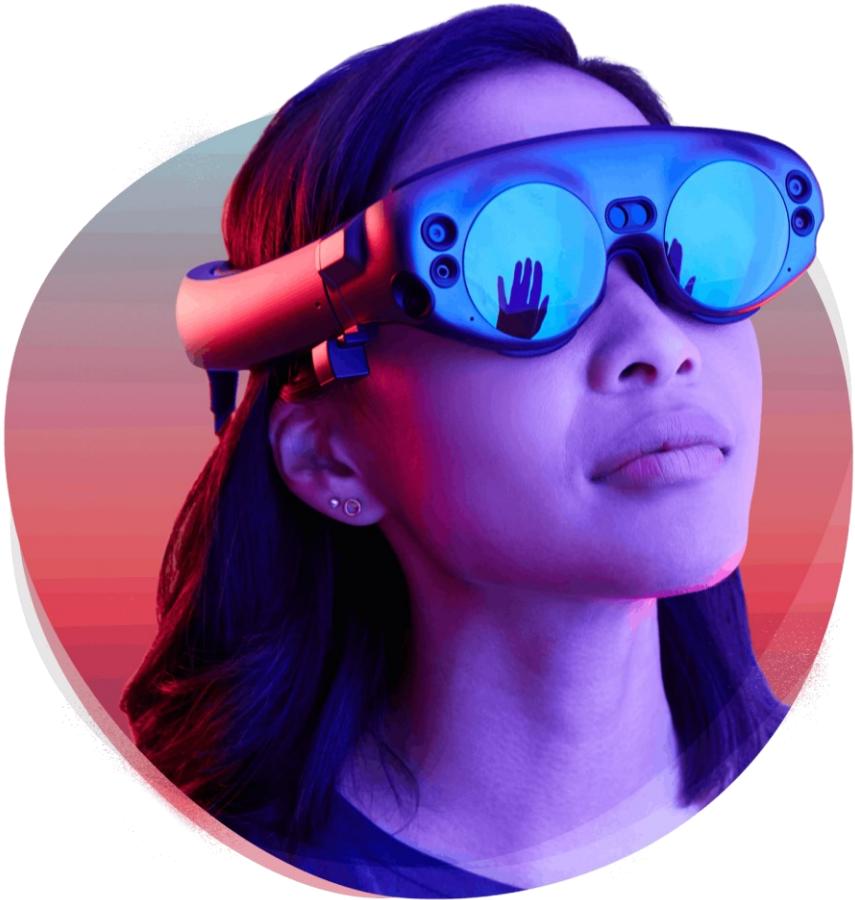


**2 HOURS**

of doctor time saved per day  
on average (as [reported](#) by  
Augmedix).

[LEARN MORE](#)

# Magic Leap, since 2018



<https://www.magicleap.com/magic-leap-one>

# Magic Leap 2 Announced (March 2022)



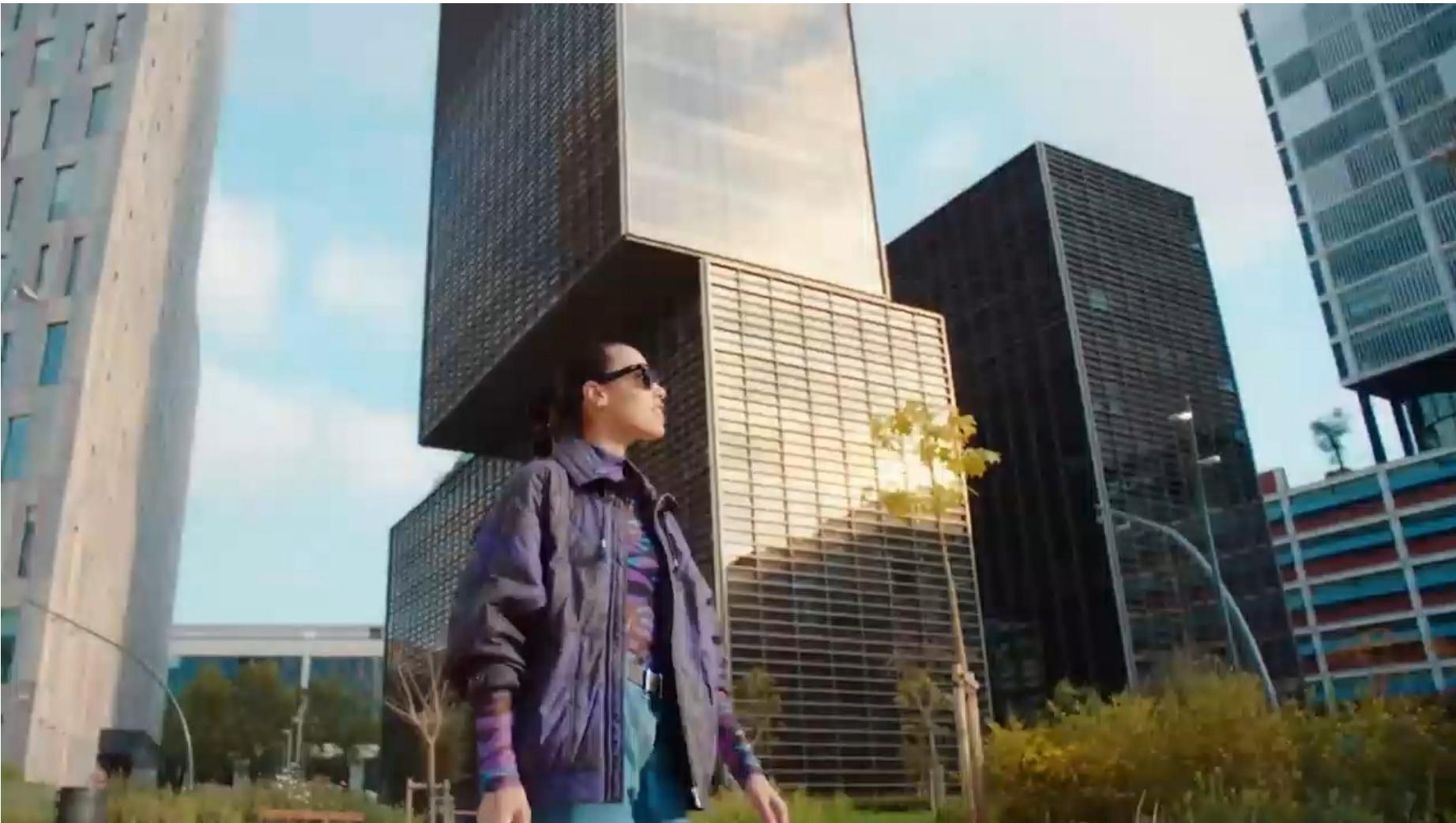
**Magic Leap 2. The most immersive AR headset for enterprise.**

# Meta's Project Aria



<https://about.facebook.com/realitylabs/projectaria/>

# Facebook Rayban Stories



<https://www.ray-ban.com/italy/ray-ban-stories>

nreal



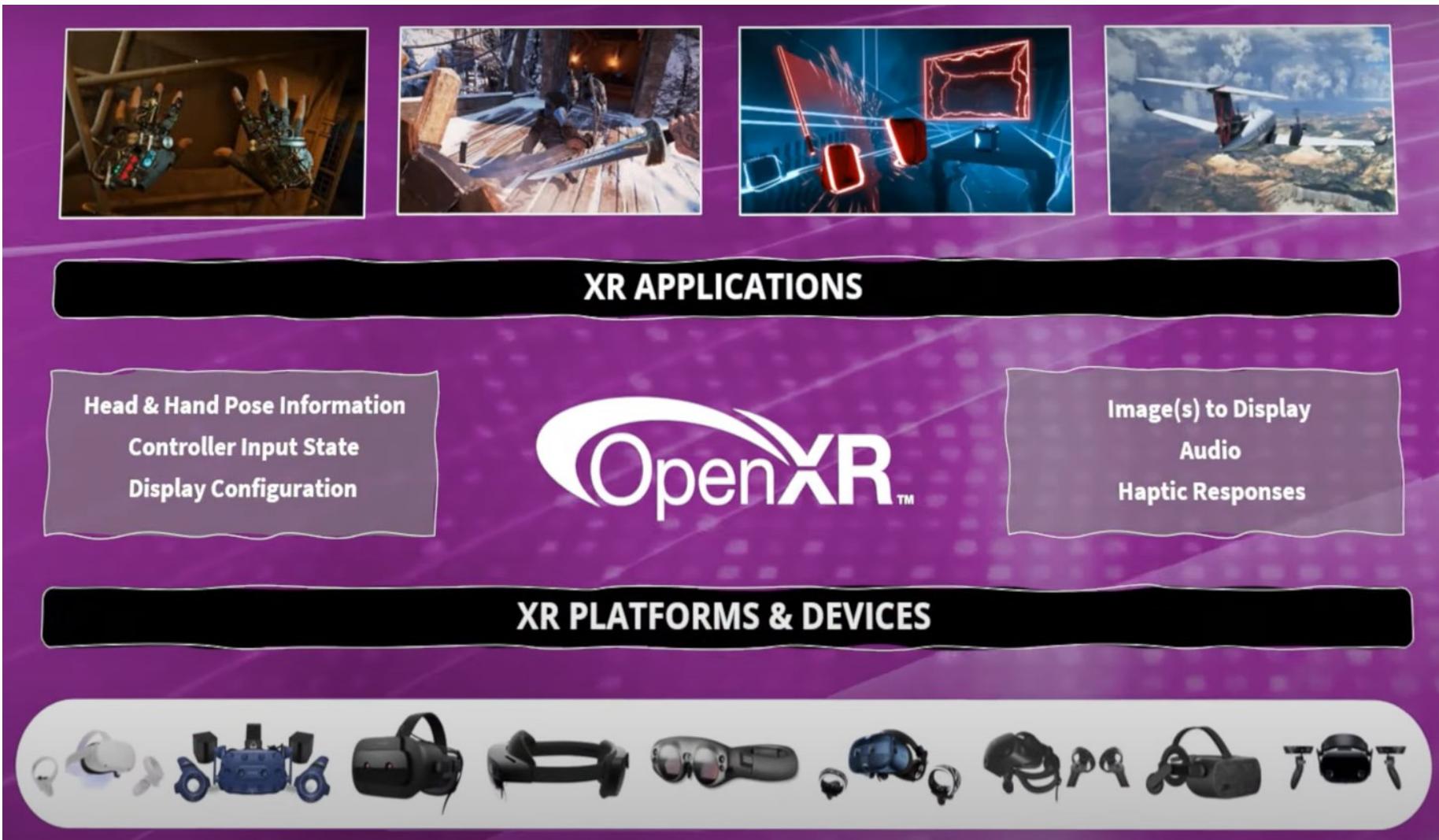
<https://www.nreal.ai/>



Too Many Devices?  
towards standardization...

# OpenXR

Unified API supported by many AR and VR devices



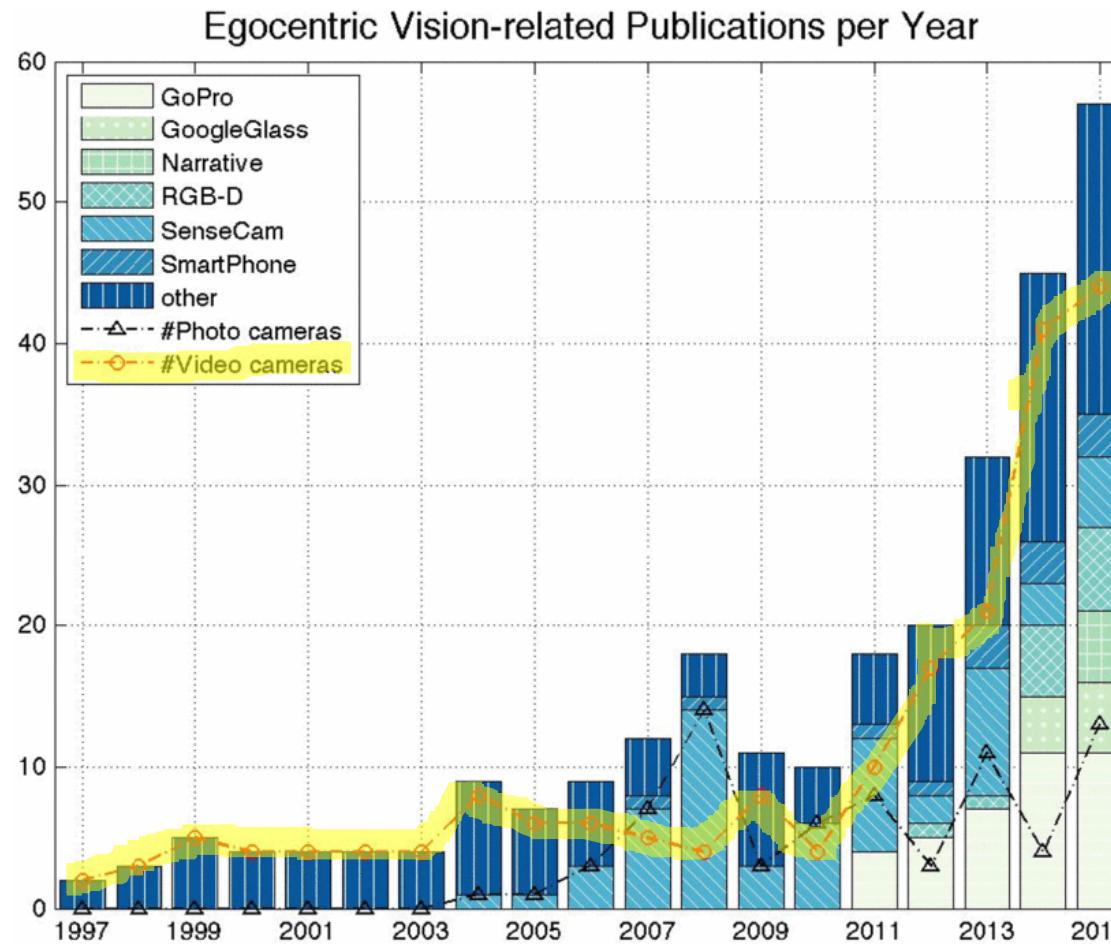
# Snapdragon Spaces

The Snapdragon Spaces XR Developer Platform reduces developer friction by providing a uniform set of augmented reality features independent of device manufacturers. This allows developers to seamlessly blend the lines between our physical and digital realities and transform the world around us in ways limited only by our imaginations.



<https://www.qualcomm.com/products/features/snapdragon-spaces-xr-platform>

# First Person Vision Research – Trends



**Growing number of research papers on First Person Vision, especially with video**

M. Bolaños, M. Dimiccoli and P. Radeva, "Toward Storytelling From Visual Lifelogging: An Overview," in *IEEE Transactions on Human-Machine Systems*, vol. 47, no. 1, pp. 77-90, Feb. 2017.

# Consumer Devices

Narrative Clip

(<http://getnarrative.com/>)



€ 229

GoPro

(<https://shop.gopro.com>)



From € 220

Pupil Eye Tracker

(<https://pupil-labs.com/store/>)



From € 2850

Microsoft HoloLens 2

(<https://www.microsoft.com/en-us/hololens/buy>)



From \$ 3500

Magic Leap

(<https://www.magicleap.com/magic-leap-one>)



\$ 2295

nreal

(<https://shop.nreal.ai/cart>)



From \$1,199

# First Person Vision Research – Conferences

Many conferences/workshops/symposia on wearable computing/first person vision:

## Past:

- **SenseCam** series – 2009, 2010, 2012, 2013;
- Workshop on Lifelogging Tools and Applications (**LTA**) – 2016;
- Workshops on Egocentric Vision @ CVPR – 2009, 2012, 2014, 2016

## Current:

- International Symposium on Wearable Computers (**ISWC**) – yearly since 1997;
- **UbiComp/Pervasive/HUC** – yearly since 1999;
- ECCV/ICCV Workshop on Assistive Computer Vision and Robotics (**ACVR**) – yearly since 2013;
- **EPIC@X** Workshop Series – yearly since 2016.
- **EGO4D** Workshops – since 2022.
- Special issues in top journals (e.g., TPAMI);
- Many works on First Person Vision appearing in top computer vision conferences (CVPR, ICCV, ECCV) and Journals (TPAMI, TIP, IJCV, PR);

# First Person Vision Research – Datasets ( up to 2018)

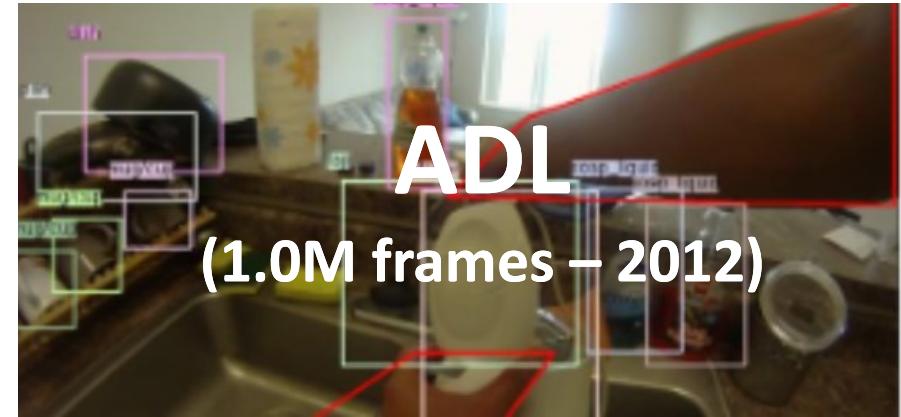
Source: <https://arxiv.org/abs/1804.02748>



[http://www.cs.cmu.edu/~espriggs/  
cmu-mmact/annotations/](http://www.cs.cmu.edu/~espriggs/cmu-mmact/annotations/)



<http://www.cbi.gatech.edu/fpv/>



[https://www.csee.umbc.edu/~hpirsiav/  
papers/ADLdataset/](https://www.csee.umbc.edu/~hpirsiav/papers/ADLdataset/)



<https://allenai.org/plato/charades/>



<http://www.cbi.gatech.edu/fpv/>



<http://epic-kitchens.github.io/>



# EPIC-KITCHENS TEAM



UNIVERSITÀ  
degli STUDI  
di CATANIA



**Dima Damen**  
Principal Investigator  
University of Bristol  
United Kingdom



**Sanja Fidler**  
Co-Investigator  
University of Toronto  
Canada



**Giovanni Maria Farinella**  
Co-Investigator  
University of Catania  
Italy



**Davide Moltisanti**  
(Apr 2017 - )  
University of Bristol



**Michael Wray**  
(Apr 2017 - )  
University of Bristol



**Hazel Doughty**  
(Apr 2017 - )  
University of Bristol



**Toby Perrett**  
(Apr 2017 - )  
University of Bristol



**Antonino Furnari**  
(Jul 2017 - )  
University of Catania



**Jonathan Munro**  
(Sep 2017 - )  
University of Bristol



**Evangelos Kazakos**  
(Sep 2017 - )  
University of Bristol



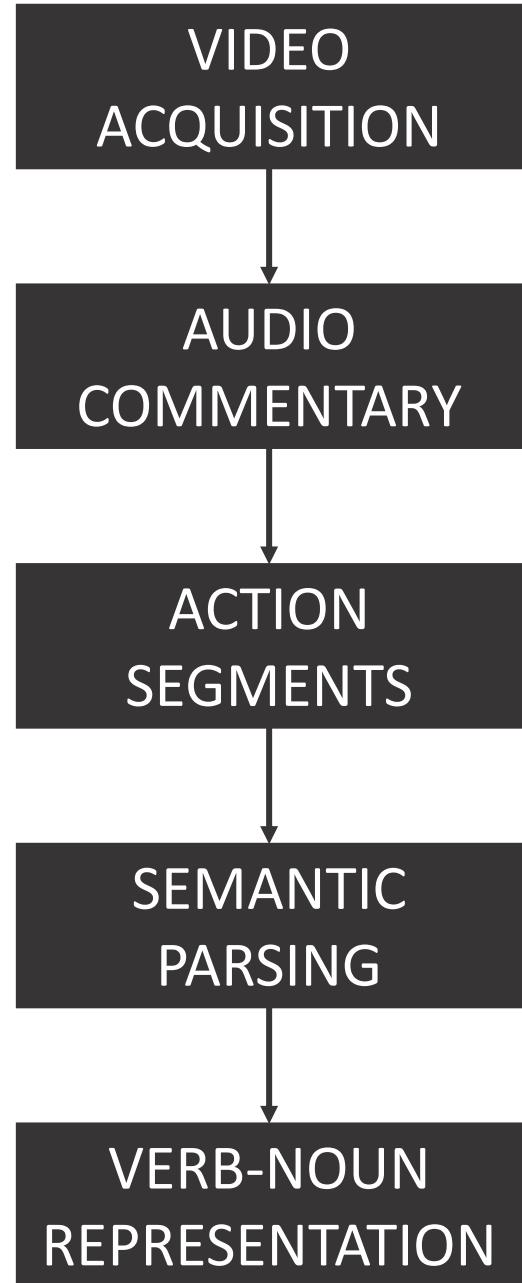
**Will Price**  
(Oct 2017 - )  
University of Bristol



32  
KITCHENS

# EPIC-KITCHENS ANNOTATION

NOVEL  
AUDIO COMMENTARY APPROACH



CUT ONION



TURN-OFF TAP



DRY CUP





EPIC  
KITCHENS



University of  
**BRISTOL**

UNIVERSITÀ  
degli STUDI  
di CATANIA  
SIGILLAE STVDIVM GENERALE  
1434

<https://epic-kitchens.github.io/>

# EPIC-KITCHENS-100



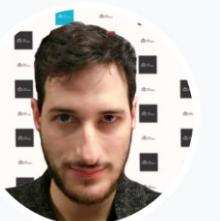
Dima Damen  
University of Bristol



Hazel Doughty  
University of Bristol



Giovanni M. Farinella  
University of Catania



Antonino Furnari  
University of Catania



Evangelos Kazakos  
University of Bristol



Jian Ma  
University of Bristol



Davide Moltisanti  
University of Bristol



Jonathan Munro  
University of Bristol



Toby Perrett  
University of Bristol



Will Price  
University of Bristol



Michael Wray  
University of Bristol

**EPIC-KITCHENS-55****EPIC-KITCHENS-100**

No. of Hours	55	100
No. of Kitchens	32	45
No. of Videos	432	700
No. of Action Segments	39,432	89,979
Action Classes	2,747	4,025
Verb Classes	125	97
Noun Classes	331	300
Splits	Train/Test	Train/Val/Test
No. of Challenges	3	6 (4 new challenges)



- Action Recognition
  - Challenges open for submission!
  - The winners will be announced at CVPR 2022!
- Action Detection
- Action Anticipation
- Unsupervised Domain Adaptation for Action Recognition
- Multi-Instance Retrieval

# EPIC-KITCHENS – 2019 Challenges Report

**EPIC-KITCHENS - 2019 Challenges Report**

Dima Damen, Will Price, Evangelos Kazakos  
University of Bristol, UK

Antonino Furnari, Giovanni Maria Farinella  
University of Catania, Italy

**Abstract**

*This report summarises the EPIC-KITCHENS 2019 challenges, and their findings. It serves as an introduction to all technical reports that were submitted to the EPIC@CVPR2019 workshop, and an official announcement of the winners.*

**1. EPIC-KITCHENS**

The largest dataset in egocentric vision has a number of unique features that distinguished its collection. Primarily, the dataset was collected in a *non-scripted* manner. Participants were asked to record all kitchen interactions in their *native environments*, i.e. their kitchens, for three consecutive days. This enabled capturing daily interactions that are often not included in scripted recordings, such as baking or emptying the bin. More importantly, the frequencies of interactions form a valid prior to daily interactions and demonstrate a long-tail unbalanced distribution of labels.

In addition to its natural interactions, EPIC-KITCHENS proposed approaches to enable scalability of collecting annotations in video. Videos were narrated by the participants themselves, providing weak supervision of temporal boundaries and an open vocabulary description of captured actions in people's native languages. While the vocabulary was refined using clustering into semantic classes, the temporal bounds were altered through Amazon Mechanical Turk (AMT) providing start/end time annotations for around 40K action segments. The annotations were further enriched by annotating bounding boxes of active objects with their corresponding labels. When combined with the raw video, this provides a rich dataset for learning from egocentric video.

**2. Reception and User Statistics**

Since its introduction, EPIC-KITCHENS received significant attention with a total of 13K page views since April 2018. The dataset has been downloaded 1.5K times, with international coverage (Fig 1), and the CodaLab competitions have 170 accepted participants. The Action Recognition challenge received the largest number of participants (103 participants) and submissions (230 submissions). The Action Anticipation challenge has 44 participants, and received 46 submissions. Of these, 10 teams have declared their affiliation and submitted technical reports for the Action Recognition challenge compared to 5 in the Action Anticipation challenge. This report includes details of these teams' submissions. A snapshot of the complete leaderboard, when the 2019 challenge concluded, is available at <http://epic-kitchens.github.io/2019#results>.

The Object Detection challenge has not received submissions that outperform the baseline. This is, up to our knowledge, due to two key factors. The first is the duration required to train the models. In [2], we clarify that the model required 2 weeks to train on an 8-GPU node. The second is the distinction from other datasets that are typically used

## Winners of the 2019 edition

	Team	Member	Affiliations
<b>Action Recognition</b>	① UTS-Baidu (wasun)	Xiaohan Wang Yu Wu Linchoa Zhu Yi Yang	University of Technology Sydney, Baidu Research University of Technology Sydney, Baidu Research University of Technology Sydney University of Technology Sydney
	② FAIR (deeptigp)	Deepti Ghadiyaram Matt Feiszli Du Tran Xueteng Yan Heng Wang Dhruv Mahajan	Facebook AI Facebook AI Facebook AI Facebook AI Facebook AI Facebook AI
	③ FBK-HUPBA (sudhakran)	Swathikiran Sudhakaran Sergio Escalera Oswald Lanz	FBK, University of Trento CVC, Universitat de Barcelona FBK, University of Trento
<b>Action Anticipation</b>	① RML (Nour)	Nour Eldin Elmadany Yifeng He Ling Guan	Ryerson University Ryerson University Ryerson University
	② Inria-Facebook (masterchef)	Antoine Miech Ivan Laptev Josef Sivic Heng Wang Lorenzo Torresani Du Train	Inria, Ecole Normale Supérieure Inria, Ecole Normale Supérieure Inria, Ecole Normale Supérieure, CIRC Facebook AI Facebook AI Facebook AI
	③ NTU (zhe2325138)	Zhe-Yu Liu Ya-Liang Chung Chih-Hung Liang Yun-Hsuan Liu Ke-Jyun Wang Winston Hsu	National Taiwan University National Taiwan University National Taiwan University National Taiwan University National Taiwan University National Taiwan University
	③ Bonn (yassersouri)	Yaser Souri Tridivraj Bhattacharyya Juergen Gall Luca Minciullo	University of Bonn University of Bonn University of Bonn Toyota Motor Europe

# EPIC-KITCHENS – 2020 Challenges Report

**EPIC-KITCHENS-55 - 2020 Challenges Report**

Dima Damen, Evangelos Kazakos, Will Price, Jian Ma, Hazel Doughty  
University of Bristol, UK

Antonino Furnari, Giovanni Maria Farinella  
University of Catania, Italy

**Abstract**

*This report summarises the EPIC-KITCHENS-55 2020 challenges, and their findings. It serves as an introduction to all technical reports that were submitted to the EPIC@CVPR2020 workshop, and an official announcement of the winners.*

**1. EPIC-KITCHENS-55**

As the largest dataset in egocentric vision, EPIC-KITCHENS-55 continued to receive significant attention from the research community over the past year. EPIC-KITCHENS-55 has a number of unique features that distinguished its collection, including *non-scripted* and *untrimmed* nature of the footage captured in participants' *native environments*. More details on the dataset's collection and annotation pipeline are available in this year's PAMI extended version [3].

This report details the submissions and winners of the 2020 edition of the three challenges available on CodaLab: Action Recognition, Action Anticipation and object detection. For each challenge, submissions were limited per team to a maximum of 50 submissions in total, as well as a maximum daily limit of 1 submission. In Sec. 2, we detail the general statistics of dataset usage in its first year. The results for the Action Recognition, Action Anticipation and Object Detection in Video challenges are provided in Sec. 3, 4 and 5 respectively. The winners of the 2020 edition of these challenges are noted in Sec. 6.

Details of the 2019 challenges are available from the technical report [4].

Figure 1: Heatmap of countries based on EPIC-KITCHENS-55 page view statistics.

shows page views of the dataset's website, based on country. The Action Recognition challenge received the largest number of participants (46 teams) and submissions (368 submissions). The Action Anticipation challenge has 20 participating teams, and received 244 submissions. The Object Detection in Video challenge has 16 participating teams and 182 submissions. Of these, 8 teams have declared their affiliation and submitted technical reports for the Action Recognition challenge compared to 5 in the Action Anticipation challenge and 4 in the Object Detection in Video challenge. This report includes details of these teams' submissions. A snapshot of the complete leaderboard, when the 2020 challenge concluded on the 30th of May, is available at <http://epic-kitchens.github.io/2020#results>.

## Winners of the 2020 edition

	S1	S2	Team	Member	Affiliations
Action Recognition	①	①	UTS-Baidu (wasun)	Xiaohan Wang Yu Wu Linchao Zhu Yi Yang Yueling Zhuang	University of Technology Sydney, Baidu Research University of Technology Sydney, Baidu Research University of Technology Sydney University of Technology Sydney Zhejiang University
	②	③	NUS-CVML (action-banks)	Fadime Sener Dipika Singhania Angela Yao	University of Bonn National University of Singapore National University of Singapore
	④	②	GT-WISC-MPI (aptx4869lm)	Miao Liu Yin Li	Georgia Institute of Technology University of Wisconsin-Madison
	③	⑤	FBK-HUPBA (sudhakran)	James M. Rehg Swathikiran Sudhakaran Sergio Escalera	Georgia Institute of Technology FBK, University of Trento CVC, Universitat de Barcelona
	③	⑥	SAIC-Cambridge (tnet)	Oswald Lanz Juan-Manuel Perez-Rua Antoine Toisoul Brais Martinez Victor Escorcia Li Zhang Xianian Zhu Tao Xiang	FBK, University of Trento Samsung AI Centre, Cambridge Samsung AI Centre, Cambridge Univ of Surrey
	①	③	NUS-CVML (action-banks)	Fadime Sener Dipika Singhania	University of Bonn National University of Singapore
Action Anticipation	②	①	Ego-OMG (edessale)	Angela Yao Eadom Desselene Michael Maynard Chinmaya Devaraj Cornelia Fermuller Yiannis Aloimonos	National University of Singapore University of Maryland, College Park University of Maryland, College Park University of Maryland, College Park University of Maryland, College Park University of Maryland, College Park
	②	②	VI-I2R (chengyi)	Ying Sun Yi Cheng Mei Chee Leong Hui Li Tan Kenan E. Ak	A*STAR, Singapore A*STAR, Singapore A*STAR, Singapore A*STAR, Singapore A*STAR, Singapore
Object Detection in Video	①	②	hutom (killerchef)	Jihun Yoon Seungbum Hong Sanha Jeong Min-Kook Choi	hutom hutom hutom hutom
	③	①	FB AI (gb7)	Gedas Bertasius Lorenzo Torresani	Facebook AI Facebook AI
	②	③	DHARI (kide)	Kaide Li Bingyan Liao Laifeng Hu Yaonong Wang	ZheJiang Dahua Technology ZheJiang Dahua Technology ZheJiang Dahua Technology ZheJiang Dahua Technology

# EPIC-KITCHENS – 2021 Challenges Report

## EPIC-KITCHENS-100- 2021 Challenges Report

Dima Damen, Adriano Fragomeni, Jonathan Munro, Toby Perrett, Daniel Whettam, Michael Wray  
University of Bristol, UK

Antonino Furnari, Giovanni Maria Farinella  
University of Catania, Italy

Davide Moltisanti  
NTU, Singapore

### Abstract

This report summarises the EPIC-KITCHENS-100 2021 challenges, and their findings. It serves as an introduction to all technical reports that were submitted to the EPIC@CVPR2021 workshop, and an official announcement of the winners.

### 1. EPIC-KITCHENS-100

In July 2020, EPIC-KITCHENS-100 was released as the next version of the EPIC-KITCHENS dataset. EPIC-KITCHENS-100, like its previous version EPIC-KITCHENS-55, has a number of unique features that distinguished its collection, including *non-scripted* and *untrimmed* nature of the footage captured in participants' *native environments*. The dataset was extended in footage, up to 100 hours of annotated egocentric footage. More importantly, the pipeline for annotations was revised and improved on every step including the pause-and-talk narrator, which increased the density and correctness of the annotations. More details and statistics on EPIC-KITCHENS-100 can be found at [5]. Notably, each submission is requested to provide their level of supervision following the proposed Supervision Levels Scale (SLS) [9].

This report details the submissions and winners of the 2021 edition of the five challenges available on CodaLab: Action Recognition, Action Anticipation, Action Detection, Unsupervised Domain Adaptation for Recognition and Multi-Instance Retrieval. For each challenge, submissions were limited per team to a maximum of 50 submissions in total, as well as a maximum daily limit of 1 submission. In Sec. 2, we detail the general statistics of dataset usage. The results for all challenges are provided in Sec. 3-7. The winners of the 2021 edition of these challenges are noted in

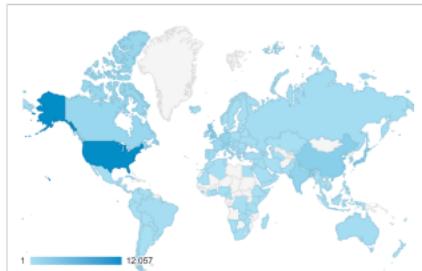


Figure 1: Heatmap of countries based on EPIC-KITCHENS-100 webpage view statistics.

United States	744	China	447	Japan	237
Germany	162	United Kingdom	89	India	82
Unknown	73	France	65	Canada	51
Spain	50	Netherlands	49	Singapore	44
Australia	36	Turkey	33	Italy	33
South Korea	31	Russia	16	Iran	10
Finland	8	Taiwan	7	Austria	7
Malaysia	6	Switzerland	6	Brazil	6
Greece	5	Ireland	4	Thailand	3
Israel	3	Mexico	3	Poland	3
Romania	2	Pakistan	2	Slovakia	2
Vietnam	2	Belgium	2	Croatia	2
Sweden	2	Ukraine	1	Libya	1
Belarus	1	Portugal	1	Algeria	1
Morocco	1	Myanmar	1	Argentina	1

Table 1: Downloads for EPIC-KITCHENS dataset, by country

2021 challenge concluded on the 28th of May is

## Winners of the 2021 edition

	Team	Member	Affiliations
①	SCUT-JD (hrgscs)	Zeyu Jiang Changxing Ding Canwei Zhang Dacheng Tao	South China University of Technology South China University of Technology South China University of Technology JD Explore Academy
②	NUS-HUST-THU-Alibaba (ZiyuanHuang)	Zhiyuan Huang Xiang Wang Yutong Feng Shiwei Zhang Jianwen Jiang Zhurong Xia Mingqian Tang Nong Sang Marcelo H. Ang Jr Swathikaran Sudhakaran	National University of Singapore Huazhong University of Science and Technology Tsinghua University DAMO Academy, Alibaba Group DAMO Academy, Alibaba Group DAMO Academy, Alibaba Group DAMO Academy, Alibaba Group Huazhong University of Science and Technology National University of Singapore Samsung AI Center, Cambridge
③	SAIC-FBK-UB (Sudhakaran)	Adrian Butal Juan-Manuel Perez-Rua Alex Falcon Sergio Escalera Oswald Lanz Brais Martinez Georgios Tzimiroopoulos	Samsung AI Center, Cambridge Fondazione Bruno Kessler - FBK, Trento Universitat de Barcelona, Spain Fondazione Bruno Kessler - FBK, Trento Samsung AI Center, Cambridge Samsung AI Center, Cambridge
Action Recognition			
①	AVT-FB-UT (shef)	Rohit Girdhar Kristen Grauman Yutaro Yamamoto	Facebook AI Research Facebook AI Research Panasonic System Networks R&D Lab
②	Panasonic-CNSIC-PSNRD (panasonic)	Kazuki Hanazawa Masahiro Shida Tsuyoshi Kodake Shinji Takenaka Yuji Sato Takeshi Fujimatsu	Panasonic System Networks R&D Lab Panasonic System Networks R&D Lab Panasonic System Networks R&D Lab Panasonic System Networks R&D Lab Connected Solutions Company, Panasonic Connected Solutions Company, Panasonic
③	ICL-SJTU (Shawn0822)	Xiao Gu Jianing Qiu Yao Guo Benny Lo Guang-Zhong Yang	Imperial College London Imperial College London Shanghai Jiao Tong University Imperial College London Shanghai Jiao Tong University
Action Anticipation			
①	HUST-NUS-THU-Alibaba (ZiyuanHuang)	Zhiyuan Huang Xiang Wang Yutong Feng Shiwei Zhang Jianwen Jiang Mingqian Tang Changxin Gao Marcelo H. Ang Jr	Huazhong University of Science and Technology National University of Singapore Huazhong University of Science and Technology Tsinghua University DAMO Academy, Alibaba Group DAMO Academy, Alibaba Group Huazhong University of Science and Technology National University of Singapore
②	LocTransformer (evangelion)	Nong Sang Chen-Lin Zhang Jianxin Wu Yin Li	Huazhong University of Science and Technology Nanjing University Nanjing University University of Wisconsin-Madison
③	A*STAR (chengyi)	Yi Cheng Fen Fang Ying Sun	A*STAR, Singapore A*STAR, Singapore University of Tokyo, Japan
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②	Torino (plnet)	Chiara Pizzari Mirco Planamente Emanuele Alberti Barbara Caputo	PoliTecnicco di Torino, Italy PoliTecnicco di Torino, Italy PoliTecnicco di Torino, Italy PoliTecnicco di Torino, Italy
③	IIE-MRG (haoxiaoshuai)	Xiaoshuai Hao Wanqian Zhang Dejie Yang Shu Zhao Dayan Wu Bo Li Weiping Wang	Institute of Information Engineering, CAS Institute of Information Engineering, CAS
UDA for Recognition			
①			
MI Retrieval			



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Mellon  
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HYDERABAD

**GT** Georgia Institute  
of Technology

Universidad de  
los Andes  
Colombia

**FACEBOOK AI**

### Ego4D: Around the World in 3,000 Hours of Egocentric Video

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# EGO4D – Massive Scale



120 Parts.

120 hours

## Ego4D – A Massive-Scale Egocentric Dataset

3,025 Hours

855 Participants

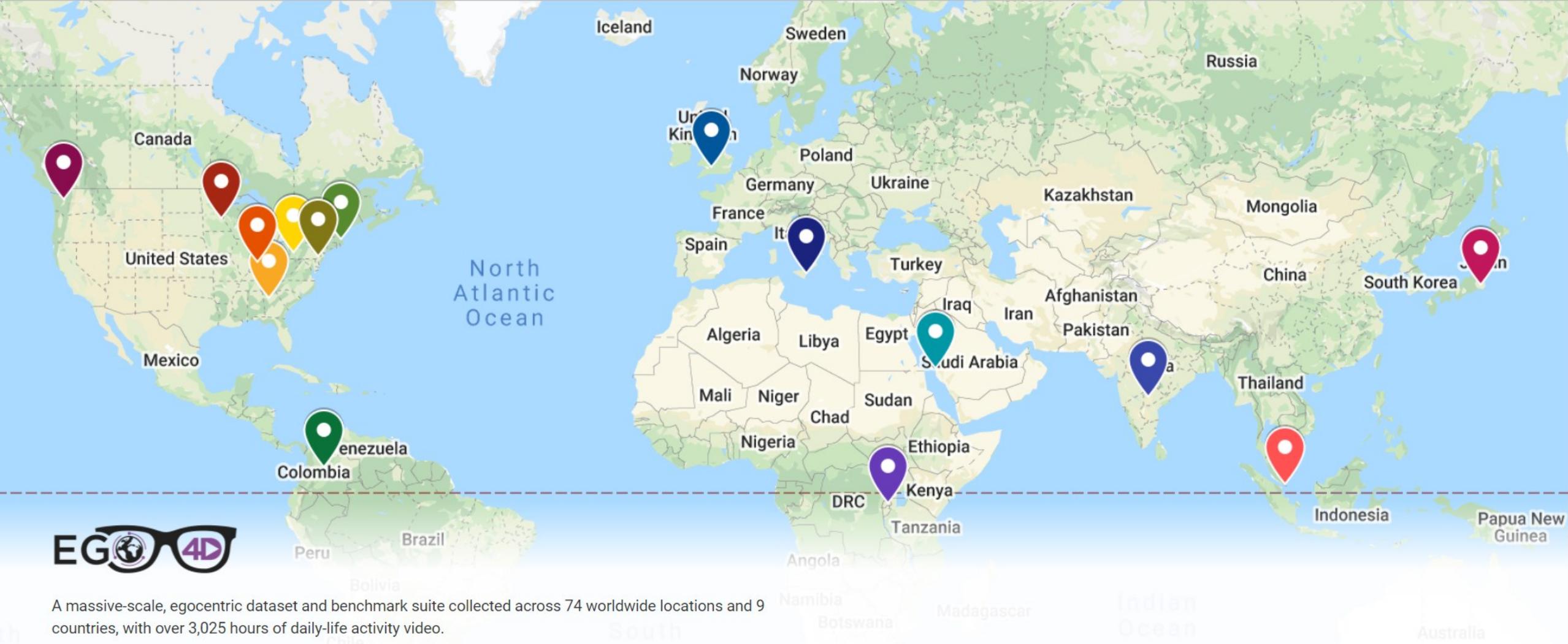
5 Benchmark Tasks

Find out more: <https://ego4d-data.org/>



Animation by Michael Wray – <https://mrray.github.io>

Animation by Michael Wray - [https://www.youtube.com/watch?v=\\_p78-V2RiKo](https://www.youtube.com/watch?v=_p78-V2RiKo)



855 Subjects



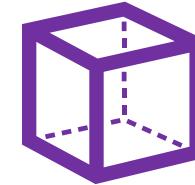
74 Locations



9 Countries



3025 Hours



3D Scans



Audio



Gaze



# Challenges



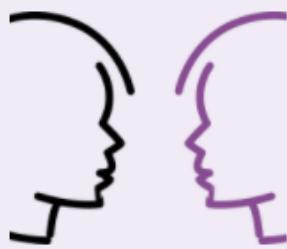
Episodic Memory



Hand-Object  
Interactions



AV Diarization



Social

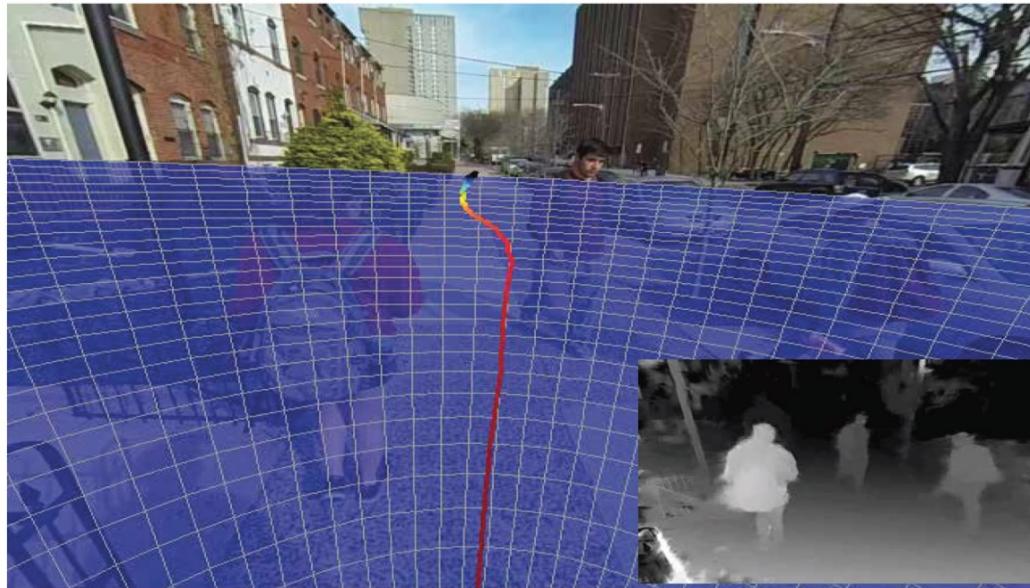


Forecasting

# Four Ego4D Forecasting Challenges

## Two related Position and Trajectory Prediction

Future Locomotion Movements



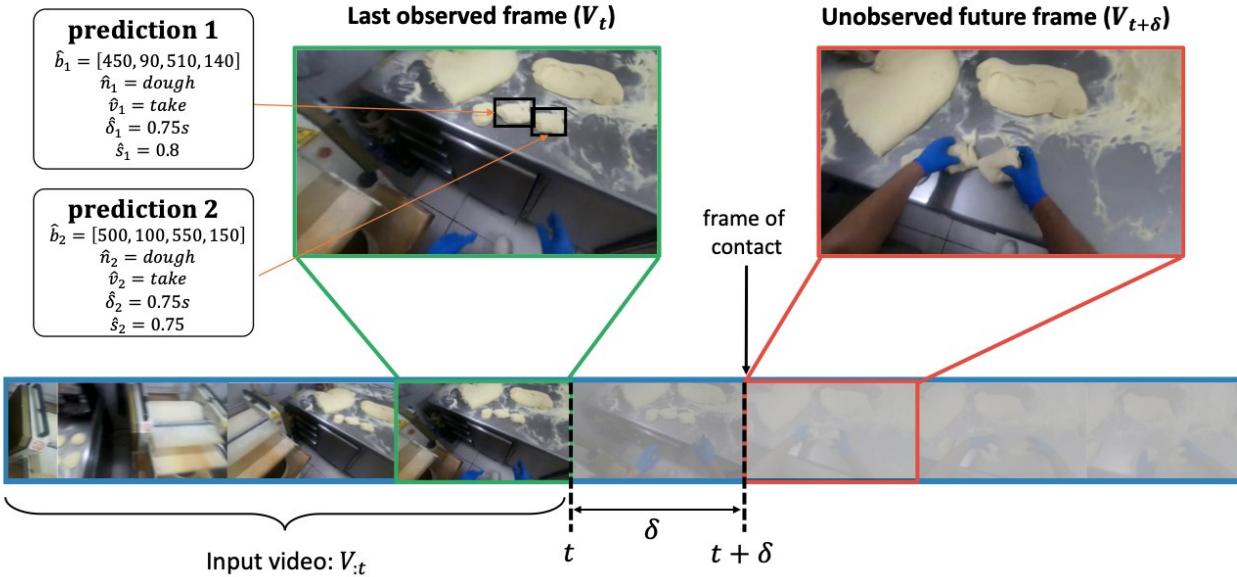
Future Hands Movements



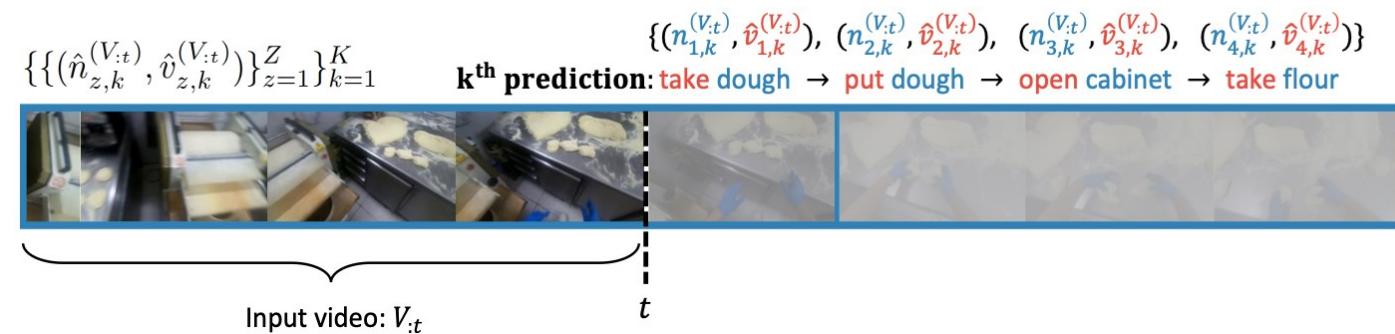
# Four Ego4D Forecasting Challenges

## Two related Object Interaction Anticipation

### Short-Term Anticipation



### Long-Term Anticipation



# 1st Ego4D Workshop @ CVPR 2022

Held in conjunction with 10th EPIC Workshop

19 and 20 June 2022

## Overview

In 2022, we will host 16 challenges, representing each of Ego4D's five benchmarks. These are:

### Episodic memory:

- **Visual queries with 2D localization and VQ 3D localization:** Given an egocentric video clip and an image crop depicting the query object, return the last time the object was seen in the input video, in terms of the tracked bounding box (2D + temporal localization) or the 3D displacement vector from the camera to the object in the environment.
- **Natural language queries:** Given a video clip and a query expressed in natural language, localize the temporal window within all the video history where the answer to the question is evident.
- **Moments queries:** Given an egocentric video and an activity name (e.g., a "moment"), localize all instances of that activity in the past video

### Hands and Objects:

- **Temporal localization:** Given an egocentric video clip, localize temporally the key frames that indicate an object state change.
- **Object state change classification:** Given an egocentric video clip, indicate the presence or absence of an object state change.
- **State change object detection:** Given an egocentric video clip, identify the objects whose states are changing and outline them with bounding boxes.

### Audio-Visual Diarization & Social:

- **Audio-visual localization:** Given an egocentric video clip, localize the speakers in the visual field of view.
- **Audio-visual speaker diarization:** Given an egocentric video clip, identify which person spoke and when they spoke.
- **Audio-only Diarization Challenge:** Given an egocentric video clip, identify which person spoke and when they spoke based on audio alone.
- **Speech transcription:** Given an egocentric video clip, transcribe the speech of each person.
- **Talking to me:** Given an egocentric video clip, identify whether someone in the scene is talking to the camera wearer.
- **Looking at me:** Given an egocentric video clip, identify whether someone in the scene is looking at the camera wearer.

### Forecasting:

- **Locomotion forecasting:** Given a video frame and the past trajectory, predict the future ego positions of the camera wearer (in the form of a 3D trajectory).
- **Hand forecasting:** Given a short preceding video clip, predict where the hand will be visible in the future, in terms of a bounding box center in keyframes.
- **Short-term hand object prediction:** Given a video clip, predict the next active objects, the next action, and the time to contact.
- **Long-term activity prediction:** Given a video clip, the goal is to predict what sequence of activities will happen in the future? For example, after kneading dough, what will the baker do next?

16 challenges;  
Deadline: 1st June;  
Winners announced during the workshop.

<http://ego4d-data.org/Workshop/CVPR22/>

# Doing research on First Person Vision now is much easier than in the past!

- Consumer wearable devices;
- Capability to handle huge quantities of data:
  - Hardware (CPUs, GPUs);
  - Deep Learning;
- Industrial interest:
  - Microsoft's HoloLens2;
  - Magic Leap;
  - Google Glass Enterprise Edition;
  - Meta's Project Aria;
- Conferences and workshops on FPV;
  - + many papers on FPV published in top vision conferences (CVPR, ICCV, ECCV);
- Datasets and standard challenges are available.

# Take-Home Messages

- Technological advances allowed the creation of efficient platforms for First Person Vision;
- First Person Vision has a great potential for focused application scenarios:
  - Assistive Technologies;
  - Health;
  - Industrial scenarios;
- Big players are moving towards consumer products, with different hardware platform becoming increasingly available;
- It's a good moment for First Person Vision research, with technology advancing and datasets/challenges attracting the interest of the community.

# Question Time



# Agenda

## Part I: Definitions, motivations, history and research trends [14.00 - 15.45]

- What is first person vision? What is it for?
- What makes it different from third person vision?
- History of First Person Vision: visions, ideas, research, devices;
- Where do we go from here? Research trends, datasets and challenges.

## Part II: Building Blocks for First Person Vision Systems [16.15 – 18.00]

- Data Acquisition & Datasets;
- Fundamental Tasks in First Person Vision:
  - Localization;
  - Hand/Object Detection;
  - Attention;
  - Action/Activities;
  - Anticipation
- Conclusion

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