

# Discontinuity Designs

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# ① Framework for Sharp Regression Discontinuity Designs

## ② Sharp Regression Discontinuity Designs: Extensions

- Multiple Cutoffs
- Multiple Running Variables

## ③ Framework for Regression Kink Designs

## ④ Regression Probability Kink Designs

## ⑤ Summary

# Framework for Sharp Regression Discontinuity Designs

- $Y \in \mathbb{R}$  is a scalar **outcome** of interest,  $D \in \{0, 1\}$  is a **binary treatment**
- $D$  and  $Y$  are linked by **potential outcomes**  $Y(0), Y(1)$
- $R \in \mathbb{R}$  is a **running variable**, not necessarily continuously distributed everywhere
- The **dependency** of  $D$  and  $R$  with  $Y(0), Y(1)$  is **not restricted**
- There exists a **cutoff**  $c \in \mathbb{R}$  such that  $D = \mathbb{I}[R \geq c]$ 
  - The treatment is a **deterministic function** of the running variable
- $\mathbb{E}[Y(d)|R = r]$  is **continuous** at  $r = c$  for  $d = 0, 1$

# Framework for Sharp Regression Discontinuity Designs

- Since  $D = 1$  if and only if  $R \geq c$  and  $D = 0$  if and only if  $R < c$ :

$$\mathbb{E}[Y|R = r] = \mathbb{E}[Y|R = r, D = 1] = \mathbb{E}[Y(1)|R = r] \quad \text{for every } r \geq c$$

$$\mathbb{E}[Y|R = r] = \mathbb{E}[Y|R = r, D = 0] = \mathbb{E}[Y(0)|R = r] \quad \text{for every } r < c$$

- Taking **limits** for  $r \downarrow c$  and  $r \uparrow c$ :

$$\lim_{r \downarrow c} \mathbb{E}[Y|R = r] = \lim_{r \downarrow c} \mathbb{E}[Y(1)|R = r] = \mathbb{E}[Y(1)|R = c]$$

$$\lim_{r \uparrow c} \mathbb{E}[Y|R = r] = \lim_{r \uparrow c} \mathbb{E}[Y(0)|R = r] = \mathbb{E}[Y(0)|R = c]$$

where the last equality follows in both cases from **continuity** of  $\mathbb{E}[Y(d)|R = r]$  at  $r = c$

- These limits can be **differenced out** to point identify

$$\text{ATE}(c) \equiv \mathbb{E}[Y(1) - Y(0)|R = c] = \lim_{r \downarrow c} \mathbb{E}[Y|R = r] - \lim_{r \uparrow c} \mathbb{E}[Y|R = r]$$

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# Sharp Regression Discontinuity Designs: Extensions

- ① **Multiple Cutoffs:** the cutoff is a discrete random variable,  $C$ , rather than a constant,  $c$ 
  - Example: plurality voting in elections with more than two competing candidates
  - Example: state or local governments setting eligibility cutoffs for a federal program
- ② **Multiple Running Variables:**  $R \in \mathbb{R}^{d_r}$ , with  $d_r > 1$ , as opposed to  $R \in \mathbb{R}$ 
  - Example: a scholarship awarded to students who score above two subject-specific thresholds
  - Example: counties that require voting by mail vs. counties that allow in-person voting

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# Cattaneo, Keele, Titiunik, and Vazquez-Bare (2016)

- $Y \in \mathbb{R}$  is a scalar **outcome** of interest,  $D \in \{0, 1\}$  is a **binary treatment**
- $C$  is a **cutoff random variable** with support  $\mathcal{C} = \{c_1, \dots, c_{\bar{j}}\}$ 
  - The probability of each cutoff realization is  $p_c \equiv \mathbb{P}(C = c) \in [0, 1]$
- $R \in \mathbb{R}$  is a continuously distributed **running variable** with density  $f_R(r)$ 
  - $f_{R|C}(r|c_j)$  denotes the density of  $R$  conditional on  $C = c_j$  for  $j = 1, \dots, \bar{j}$
- In this setting, different agents may **face different cutoffs**



# Cattaneo, Keele, Titiunik, and Vazquez-Bare (2016)

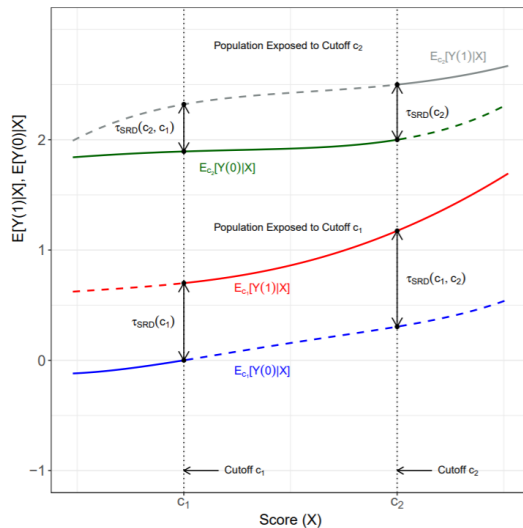
- For simplicity, focus on the **sharp design**, so  $D = \mathbb{I}[R \geq C]$
- $D$  and  $Y$  are linked by **potential outcomes**  $Y(0), Y(1)$ , which are also functions of  $C$ :

$$Y(0, C), Y(1, C) \quad \text{s.t.} \quad Y = \sum_{j=1}^{\bar{j}} \mathbb{I}[C = c_j] \times [DY(1, c_j) + (1 - D)Y(0, c_j)]$$

$Y(d, c_j)$  highlights that potential outcomes may be **affected** by the realization of  $C$

- Further assumptions:
  - ①  $\mathbb{E}[Y(d, c)|R = r, C = c]$  is **continuous in  $r$**  at  $r = c$  for every  $c \in \mathcal{C}$  and  $d = 0, 1$
  - ② The densities  $f_{R|C}(r|c)$  are **positive and continuous in  $r$**  at  $r = c$  for every  $c \in \mathcal{C}$

## Cattaneo, Keele, Titiunik, and Vazquez-Bare (2016)



# Cattaneo, Keele, Titiunik, and Vazquez-Bare (2016)

Rather than estimating **cutoff-specific effects**, one may choose to **normalize and pool**:

① **Normalize**: define the **normalized running variable**  $\tilde{R} \equiv R - C$

- In words, **center** each agent's running variable around their **cutoff realization**

② **Pool**: identify a target parameter using **standard** regression discontinuity arguments

- This approach ignores the **heterogeneity** in the distributions of  $Y(0)$  and  $Y(1)$  in terms of  $C$
- The point-identified target parameter is a **pooled estimand**:

$$\tau^P \equiv \sum_{j=1}^{\bar{j}} \mathbb{E}[Y(1, c_j) - Y(0, c_j) | R = c_j, C = c_j] \times \omega(c_j)$$

where

$$\omega(c) \equiv \frac{f_{R|C}(c|c) \times \mathbb{P}(C = c)}{\sum_{c' \in \mathcal{C}} f_{R|C}(c'|c') \times \mathbb{P}(C = c')}$$

# Cattaneo, Keele, Titiunik, and Vazquez-Bare (2016)

- ① **Constant treatment effects:** if  $Y(1, c_j) - Y(0, c_j) = \tau(c_j)$  for  $j = 1, \dots, \bar{j}$ ,  
 $\tau^P \equiv \sum_{j=1}^{\bar{j}} \tau(c_j) \times \omega(c_j)$  is a weighted average of **cutoff-specific constants**

- ② **Ignorable  $R$ :** if  $\mathbb{E}[Y(1, c_j) - Y(0, c_j) | R = c_j, C = c_j] = \mathbb{E}[Y(1, c_j) - Y(0, c_j) | C = c_j]$ ,

$$\tau^P \equiv \sum_{j=1}^{\bar{j}} \mathbb{E}[Y(1, c_j) - Y(0, c_j) | C = c_j] \times \omega(c_j)$$

so  $\tau^P$  may be estimated with **global polynomial** techniques

- ③ **Ignorable  $C$ :** if  $\mathbb{E}[Y(1, c_j) - Y(0, c_j) | R = c_j, C = c_j] = \mathbb{E}[Y(1, c_j) - Y(0, c_j) | R = c_j]$ ,

$$\tau^P \equiv \sum_{j=1}^{\bar{j}} \mathbb{E}[Y(1, c_j) - Y(0, c_j) | R = c_j] \times \mathbb{P}(C = c_j)$$

so  $\tau^P$  is a weighted average of “local” (in terms of  $R$ ) **average treatment effects**

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# Keele and Titiunik (2015)

- $Y \in \mathbb{R}$  is a scalar **outcome of interest**,  $D \in \{0, 1\}$  is a **binary treatment**
- $D$  and  $Y$  are linked by **potential outcomes**  $Y(0), Y(1)$
- Treatment assignment **changes discontinuously** at a **border**  $\mathcal{B}$ 
  - $\mathcal{B}$  is geographic boundary that separates a **treated area** ( $\mathcal{B}_t$ ) from a **control area** ( $\mathcal{B}_c$ )
- $R \in \mathbb{R}^2$  is a pair of **running variables** usually denoting **latitude and longitude**
- For simplicity, focus on the **sharp design**, so

$$D = \mathbb{I}[R_1 \geq b_1] \times \mathbb{I}[R_2 \geq b_2]$$

where  $(b_1, b_2) \in \mathcal{B}$  is a **boundary point**

# Keele and Titiunik (2015)

- As in the scalar case, **average potential outcomes** are **continuous** at the **border**:

$$\mathbb{E}[Y(d) | (R_1, R_2) = (r_1, r_2)] \text{ is continuous in } r_1, r_2 \text{ at } r_1 = b_1, r_2 = b_2$$

for every  $(b_1, b_2) \in \mathcal{B}$  and  $d = 0, 1$

- Let  $\mathbf{R} = (R_1, R_2)$ ,  $\mathbf{r} = (r_1, r_2)$ , and  $\mathbf{b} = (b_1, b_2)$ . Then

$$\lim_{\mathbf{r} \rightarrow \mathbf{b}; \mathbf{r} \in \mathcal{B}_t} \mathbb{E}[Y | \mathbf{R} = \mathbf{r}] = \lim_{\mathbf{r} \rightarrow \mathbf{b}; \mathbf{r} \in \mathcal{B}_t} \mathbb{E}[Y(1) | \mathbf{R} = \mathbf{r}] = \mathbb{E}[Y(1) | \mathbf{R} = \mathbf{b}]$$

$$\lim_{\mathbf{r} \rightarrow \mathbf{b}; \mathbf{r} \in \mathcal{B}_c} \mathbb{E}[Y | \mathbf{R} = \mathbf{r}] = \lim_{\mathbf{r} \rightarrow \mathbf{b}; \mathbf{r} \in \mathcal{B}_c} \mathbb{E}[Y(0) | \mathbf{R} = \mathbf{r}] = \mathbb{E}[Y(0) | \mathbf{R} = \mathbf{b}]$$

where the last equality follows in both cases from **continuity** of  $\mathbb{E}[Y(d) | \mathbf{R} = \mathbf{r}]$  at  $\mathbf{r} = \mathbf{b}$

## Keele and Titiunik (2015)

- As in the scalar case, these limits can be **differenced out** to identify

$$\mathbb{E}[Y(1) - Y(0)|\mathbf{R} = \mathbf{b}] = \lim_{\mathbf{r} \rightarrow \mathbf{b}; \mathbf{r} \in \mathcal{B}_t} \mathbb{E}[Y|\mathbf{R} = \mathbf{r}] - \lim_{\mathbf{r} \rightarrow \mathbf{b}; \mathbf{r} \in \mathcal{B}_c} \mathbb{E}[Y|\mathbf{R} = \mathbf{r}]$$

where  $\mathbb{E}[Y(1) - Y(0)|\mathbf{R} = \mathbf{b}]$  is the **ATE** of  $D$  on  $Y$  at the **border point**  $\mathbf{b} \in \mathcal{B}$

- In practice, one may construct a **scalar running variable** as the **Euclidean distance**

$$D(b_1, b_2) = \sqrt{(R_1 - b_1)^2 + (R_2 - b_2)^2}$$

which reduces the design to a standard **unidimensional** regression discontinuity:

$$\mathbb{E}[Y(1) - Y(0)|D(\mathbf{b}) = 0] = \lim_{d \downarrow 0} \mathbb{E}[Y|D(\mathbf{b}) = d] - \lim_{d \uparrow 0} \mathbb{E}[Y|D(\mathbf{b}) = d], \quad \mathbf{b} \in \mathcal{B}$$

- Rather than estimating **b-specific** effects, one may again choose to **normalize and pool**



## ① Framework for Sharp Regression Discontinuity Designs

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# Framework for Regression Kink Designs

- $Y \in \mathbb{R}$  is a scalar **outcome** of interest
- $D \in \mathbb{R}$  is a **continuously distributed treatment**
- $R \in \mathbb{R}$  is a continuously distributed **running variable**
- $U \in \mathbb{R}$  is a continuous **latent variable** denoting the **unobserved determinants** of  $Y$
- Consider an **all-causes model** of the outcome variable:  $Y \equiv g(D, U)$ 
  - $g(\cdot)$  is an **unknown function** of the observed and unobserved determinants of  $Y$
- The **dependency** between  $R$  and  $U$  is **not restricted**
  - The **distribution** function  $f_{U|R}(u|r)$  is **continuously differentiable** in  $r$  at  $r = c$

# Framework for Regression Kink Designs

- Analogously to regression discontinuity designs, **two** scenarios are possible:
  - ➊ **Sharp**: the treatment is  $D = h(R)$ , where  $h(\cdot)$  is a **known function**
  - ➋ **Fuzzy**: the treatment is  $D = h(R, U)$ , where  $h(\cdot)$  is an **unknown function** ( $U$  is latent)
- In **both** cases,  $g(\cdot)$  is **continuously differentiable** at the threshold
  - ➊ **Sharp**:  $g(d, u)$  is continuously differentiable in  $d$  at  $d = h(c)$
  - ➋ **Fuzzy**:  $g(d, u)$  is continuously differentiable in  $d$  at  $d = h(c, u)$  **for every  $u$**
- In **both** cases,  $h(\cdot)$  is **continuous**, but its **derivative** is **discontinuous** at the threshold
  - ➊ **Sharp**:  $h(r)$  is continuous, but  $h'(r)$  is discontinuous at  $r = c$
  - ➋ **Fuzzy**:  $h(r, u)$  is continuous **for every  $u$** , but  $h'(r, u)$  is discontinuous at  $r = c$  **for every  $u$**

# Framework for Regression Kink Designs

To identify a target parameter in a **sharp regression kink design**, consider any  $r \neq c$  and

$$\begin{aligned}
 \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} &= \frac{\partial}{\partial r} \mathbb{E}[g(h(r), U) | R=r] \quad (Y \equiv g(D, U)) \\
 &= \frac{\partial}{\partial r} \int g(h(r), u) f_{U|R}(u|r) du \quad (\text{definition of } \mathbb{E}[\cdot]) \\
 &= \int \frac{\partial}{\partial r} [g(h(r), u)] f_{U|R}(u|r) du \quad (\text{Fubini's Theorem}) \\
 &= h'(r) \int \left( \frac{\partial}{\partial d} g(h(r), u) \right) f_{U|R}(u|r) du + \int g(h(r), u) \left( \frac{\partial}{\partial r} f_{U|R}(u|r) \right) du
 \end{aligned}$$

where the last equality follows from an application of the chain rule

# Framework for Regression Kink Designs

- By assumption,  $h'(r)$  is **discontinuous** at  $r = c$
- Take the **limits** of  $\frac{\partial \mathbb{E}[Y|R=r]}{\partial r}$  as  $r \downarrow c$  and  $r \uparrow c$ :

$$\begin{aligned} \lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} &= \lim_{r \downarrow c} h'(r) \times \int \left( \frac{\partial}{\partial d} g(h(c), u) \right) f_{U|R}(u|c) du \\ &\quad + \int g(h(c), u) \left( \frac{\partial}{\partial r} f_{U|R}(u|c) \right) du \\ \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} &= \lim_{r \uparrow c} h'(r) \times \int \left( \frac{\partial}{\partial d} g(h(c), u) \right) f_{U|R}(u|c) du \\ &\quad + \int g(h(c), u) \left( \frac{\partial}{\partial r} f_{U|R}(u|c) \right) du \end{aligned}$$

# Framework for Regression Kink Designs

These limits can be **differenced out**:

$$\lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} - \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} = \left( \lim_{r \downarrow c} h'(r) - \lim_{r \uparrow c} h'(r) \right) \times \mathbb{E} \left[ \frac{\partial}{\partial d} g(h(c), U) \mid R = c \right]$$

Rearranging terms, the **Local Average Response** (LAR) of  $Y$  to  $D$  is

$$\mathbb{E} \left[ \frac{\partial}{\partial d} g(h(c), U) \mid R = c \right] = \frac{\lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} - \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r}}{\lim_{r \downarrow c} h'(r) - \lim_{r \uparrow c} h'(r)}$$

This is the **average effect** of a **marginal increase in  $D$**  on  $Y$  at  $R = c$

- The LAR **averages** marginal effects over the distribution of  $U$  among agents with  $R = c$

# Framework for Regression Kink Designs

- A similar derivation in the case of a **fuzzy regression kink design** leads to

$$\mathbb{E} \left[ \frac{\partial}{\partial d} g(h(c, U), U) \times \omega(c, U) \mid R = c \right] = \frac{\lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} - \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r}}{\lim_{r \downarrow c} \frac{\partial \mathbb{E}[D|R=r]}{\partial r} - \lim_{r \uparrow c} \frac{\partial \mathbb{E}[D|R=r]}{\partial r}}$$

where  $\omega(c, U)$  is **proportional** to the **size of the kink** (analogously to an IV first stage)

- Recall that  $D = h(R, U)$ . If a **monotonicity** assumption holds, i.e.,

$$\lim_{r \downarrow c} \frac{\partial h(r, U)}{\partial r} \geq \lim_{r \uparrow c} \frac{\partial h(r, U)}{\partial r} \quad \text{with} \quad \mathbb{P} \left( \lim_{r \downarrow c} \frac{\partial h(r, U)}{\partial r} > \lim_{r \uparrow c} \frac{\partial h(r, U)}{\partial r} \right) > 0$$

then the target parameter has a similar interpretation to the **LATE**

- Weights  $\omega(c, U)$  are **non-zero** for agents whom the kink **induces** to choose more  $D$

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# Dong (2018)

- This class of discontinuity designs is based on a working paper by Dong (2018)
- $Y \in \mathbb{R}$  is a scalar **outcome** of interest,  $D \in \{0, 1\}$  is a **binary treatment**
- $D$  and  $Y$  are linked by **potential outcomes**  $Y(0), Y(1)$
- $R \in \mathbb{R}$  is a continuously distributed **running variable**
- Suppose that **compliance** with the treatment is **one-sided**, so that

$$D \times (\mathbb{I}[R \geq c] - \mathbb{I}[R < c]) \geq 0 \quad \text{with probability one}$$

where  $c \in \mathbb{R}$ .  $D = 1$  is **not available** to agents for which  $R < c$

# Dong (2018)

- For clearer intuition, construct a **binary instrumental variable**  $Z \equiv \mathbb{I}[R \geq c]$
- Temporarily define the **propensity score** as  $p(Z) \equiv \mathbb{P}(D = 1|Z)$
- **One-sided noncompliance** implies that

$$\begin{aligned} p(1) &\equiv \mathbb{P}(D = 1|Z = 1) = \mathbb{P}(D = 1|R \geq c) \\ &\geq \mathbb{P}(D = 1|R < c) = \mathbb{P}(D = 1|Z = 0) \equiv p(0) = 0 \end{aligned}$$

## Dong (2018)

- As usual, denote **potential treatments** with  $D(z)$ ,  $z \in \{0, 1\}$
- Because  $p(0) = 0$ , **always-takers** and **defiers** can be safely assumed away
- **Agent types** can be characterized as follows:

$$T \equiv \begin{cases} n, & \text{if } D(0) = D(1) = 0 \\ cp, & \text{if } D(0) = 0 \text{ and } D(1) = 1 \end{cases}$$

- The definition of  $T$  **completely partitions** the set of realizations of  $(D(0), D(1))$
- $D(1) \geq D(0)$  almost surely, so the Imbens and Angrist **monotonicity** condition holds

# Dong (2018)

- The propensity score was previously defined as  $p(Z) \equiv \mathbb{P}(D = 1|Z)$
- This definition is **unnecessarily restrictive** because  $R$  may predict the treatment state
- Define the **propensity score** as  $p(Z, R) \equiv \mathbb{P}(D = 1|Z, R)$ 
  - $Z = \mathbb{I}[R \geq c]$  is a **deterministic function** of  $R$ , so  $p(Z, R) = p(R) \equiv \mathbb{P}(D = 1|R)$

- $Z$  being a **function** of  $R$  additionally implies the **conditional exogeneity** assumption

$$(Y(0), Y(1), D(0), D(1)) \perp\!\!\!\perp Z | R = r \quad \forall r$$

- Vytlacil (2002)'s **equivalence result** can be used to derive a **nonparametric Roy** model
- This model meets all of the **Imbens and Angrist** assumptions

# Dong (2018)

- Let  $I$  denote any open or closed interval and define a continuous random variable  $V_I$
- $V_I \perp (Y(0), Y(1), D(0), D(1), Z)$  is uniformly distributed over  $I$
- Define a **random variable**  $U$  conditional on each element in the support of  $R$ :

$$(U|R = r) \equiv \mathbb{I}[T = cp, R = r] V_{[0, p(r)]} + \mathbb{I}[T = n, R = r] V_{(p(r), 1]}$$

- For every  $r$ ,  $(U|R = r)$  is a **continuously distributed** random variable with support  $[0, 1]$
- $U$  can be used to construct the **selection model**

$$D = D(r) = \mathbb{I}[U \leq p(r)] \quad \forall r$$

where  $D(R) = D(R, Z) = D(Z)$  indicates the **potential treatment** associated with  $R$

## Dong (2018)

- For each element in the support of  $R$ , the **propensity score** can be expressed as

$$\begin{aligned}
 p(r) &\equiv \mathbb{P}(D = 1 | R = r) \\
 &= \mathbb{P}(U \leq p(R) | R = r) \quad (D(R) = \mathbb{I}[U \leq p(R)]) \\
 &= \mathbb{P}(U \leq p(r)) \\
 &= \mathbb{P}(F_U(U) \leq F_U(p(r))) \quad (U \text{ is continuous}) \\
 &= \mathbb{P}(\tilde{U} \leq F_U(p(r))) \quad \text{with } \tilde{U} \sim \mathcal{U}[0, 1] \\
 &= F_U(p(r))
 \end{aligned}$$

- Thus, the **selection model** can be written as

$$D(r) = \mathbb{I}[U \leq p(r)] = \mathbb{I}[F_U(U) \leq F_U(p(r))] = \mathbb{I}[\tilde{U} \leq p(r)] \quad \forall r$$

where  $\tilde{U} \sim \mathcal{U}[0, 1]$ . For ease of notation,  $\tilde{U}$  is denoted with as  $U$

# Dong (2018)

This nonparametric Roy model is **nested** in the Imbens and Angrist model:

- ①  $(Y(0), Y(1), D(0), D(1)) \perp\!\!\!\perp Z | R = r \ \forall r$ , because  $Z$  is a deterministic function of  $R$
- ②  $D(1) \geq D(0)$  **almost surely**, because compliance with the treatment is one-sided
- ③  $U \perp\!\!\!\perp Z | R = r \ \forall r$ , because  $U$  is a function of  $D(Z)$  and the completely idiosyncratic  $V_i$
- ④ **Potential treatments** conditional on any  $R = r$  are equal in the two models:
 
$$r \geq c \text{ and } T = n \implies (U | R = r) = V_{(p(r), 1]} > p(r) \implies D(r) = 0$$

$$r \geq c \text{ and } T = cp \implies (U | R = r) = V_{[0, p(r)]} \leq p(r) \implies D(r) = 1$$

$$r < c \text{ and } T = n \implies (U | R = r) = V_{(p(r), 1]} = V_{(0, 1]} > p(r) = 0 \implies D(r) = 0$$

$$r < c \text{ and } T = cp \implies (U | R = r) = V_{[0, p(r)]} = V_{[0, 0]} = 0 = p(r) \implies D(r) = 0$$

where the last scenario is a knife-edge case (see footnote 3 in the MTE supplement)

# Dong (2018)

- Let us make a few additional assumptions:
  - $\mathbb{E}[Y(d)|R=r, U=u]$  is a **continuously differentiable** function of  $(r, u)$  for  $d = 0, 1$
  - The propensity score,  $p(r)$ , is **continuous** and **differentiable** at  $r = c$
  - The **derivative** of  $p(r)$  is **discontinuous** at  $r = c$
- This setting is similar to a **fuzzy regression kink design**
- But the treatment is **binary** as opposed to **continuously distributed**
- A target parameter may be identified with a standard argument from the **MTE framework**...



## Dong (2018)

As usual, let us express the **mean** of  $\mathbf{Y}$  conditional on  $D = 1$  and  $R = r$ :

$$\begin{aligned}
 \mathbb{E}[Y|D = 1, R = r] &= \mathbb{E}[DY(1) + (1 - D)Y(0)|D = 1, R = r] \\
 &= \mathbb{E}[Y(1)|D = 1, R = r] \\
 &= \mathbb{E}[Y(1)|U \leq p(R), R = r] \quad (D = \mathbb{I}[U \leq p(R)]) \\
 &= \mathbb{E}[Y(1)|U \leq p(r), R = r] \\
 &= \frac{1}{p(r)} \int_0^{p(r)} \mathbb{E}[Y(1)|U = u, R = r] du \quad (U \sim \mathcal{U}[0, 1])
 \end{aligned}$$

Analogously, the **mean** of  $\mathbf{Y}$  conditional on  $D = 0$  and  $R = r$  is

$$\mathbb{E}[Y|D = 0, R = r] = \frac{1}{1 - p(r)} \int_{p(r)}^1 \mathbb{E}[Y(0)|U = u, R = r] du$$

## Dong (2018)

The **Law of Iterated Expectations** further implies that

$$\begin{aligned}\mathbb{E}[Y|R=r] &= \mathbb{E}[Y|D=1, R=r] \times \mathbb{P}(D=1|R=r) \\ &\quad + \mathbb{E}[Y|D=0, R=r] \times \mathbb{P}(D=0|R=r) \\ &= \mathbb{E}[Y|D=1, R=r] \times p(r) \\ &\quad + \mathbb{E}[Y|D=0, R=r] \times (1-p(r)) \\ &= \int_0^{p(r)} \mathbb{E}[Y(1)|U=u, R=r] du + \int_{p(r)}^1 \mathbb{E}[Y(0)|U=u, R=r] du\end{aligned}$$

## Dong (2018)

**Leibniz's rule** implies that the **derivative** of  $\mathbb{E}[Y|R = r]$  with respect to  $R$ , at  $r \neq c$ , is

$$\begin{aligned} \frac{\partial \mathbb{E}[Y|R = r]}{\partial r} &= \frac{\partial p(r)}{\partial r} \times \mathbb{E}[Y(1)|U = p(r), R = r] + \int_0^{p(r)} \frac{\partial \mathbb{E}[Y(1)|U = p(r), R = r]}{\partial r} du \\ &\quad - \frac{\partial p(r)}{\partial r} \times \mathbb{E}[Y(0)|U = p(r), R = r] + \int_{p(r)}^1 \frac{\partial \mathbb{E}[Y(0)|U = p(r), R = r]}{\partial r} du \\ &= \frac{\partial p(r)}{\partial r} \times \mathbb{E}[Y(1) - Y(0)|U = p(r), R = r] \\ &\quad + \int_0^{p(r)} \frac{\partial \mathbb{E}[Y(1)|U = p(r), R = r]}{\partial r} du + \int_{p(r)}^1 \frac{\partial \mathbb{E}[Y(0)|U = p(r), R = r]}{\partial r} du \end{aligned}$$

where  $\mathbb{E}[Y(1) - Y(0)|U = p(r), R = r]$  is the **MTE** of  $D$  on  $Y$  at  $U = p(r)$  and  $R = r$

## Dong (2018)

- By assumption, the **derivative** of the **propensity score** is **discontinuous** at  $r = c$
- Take the **limits** of  $\frac{\partial \mathbb{E}[Y|R=r]}{\partial r}$  as  $r \downarrow c$  and  $r \uparrow c$ :

$$\begin{aligned} \lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} &= \lim_{r \downarrow c} \frac{\partial p(r)}{\partial r} \times \mathbb{E}[Y(1) - Y(0)|R = c, U = p(c)] \\ &\quad + \int_0^{p(c)} \frac{\partial \mathbb{E}[Y(1)|R = c, U = u]}{\partial r} du + \int_{p(c)}^1 \frac{\partial \mathbb{E}[Y(0)|R = c, U = u]}{\partial r} du \\ \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} &= \lim_{r \uparrow c} \frac{\partial p(r)}{\partial r} \times \mathbb{E}[Y(1) - Y(0)|R = c, U = p(c)] \\ &\quad + \int_0^{p(c)} \frac{\partial \mathbb{E}[Y(1)|R = c, U = u]}{\partial r} du + \int_{p(c)}^1 \frac{\partial \mathbb{E}[Y(0)|R = c, U = u]}{\partial r} du \end{aligned}$$

# Dong (2018)

These limits can be **differenced out**:

$$\lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} - \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} = \left( \lim_{r \downarrow c} \frac{\partial p(r)}{\partial r} - \lim_{r \uparrow c} \frac{\partial p(r)}{\partial r} \right) \times \text{MTE}(U = p(c), R = c)$$

Rearranging terms, the **Marginal Treatment Effect** of  $D$  on  $Y$  at  $U = p(c)$  and  $R = c$  is

$$\mathbb{E}[Y(1) - Y(0)|U = p(c), R = c] = \frac{\lim_{r \downarrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r} - \lim_{r \uparrow c} \frac{\partial \mathbb{E}[Y|R=r]}{\partial r}}{\lim_{r \downarrow c} \frac{\partial p(r)}{\partial r} - \lim_{r \uparrow c} \frac{\partial p(r)}{\partial r}}$$

This point-identified parameter is the MTE for agents

- Whose realization of the **running variable** is  $R = c$ , and
- Who are **at the margin** of choosing  $D = 1$  if  $R = c$

- ① Framework for Sharp Regression Discontinuity Designs
- ② Sharp Regression Discontinuity Designs: Extensions
  - Multiple Cutoffs
  - Multiple Running Variables
- ③ Framework for Regression Kink Designs
- ④ Regression Probability Kink Designs
- ⑤ Summary

# Summary

- RD designs with **multiple cutoffs** or **multiple running variables** typically require an empiricist to choose whether to estimate **cutoff-specific effects** or **normalize and pool**
- **Regression probability kink designs** allow a researcher to derive a nonparametric Roy model and point identify a “local” (in terms of  $R$ ) **marginal treatment effect**