Tools and Frameworks for Causal Inference ECON 31720 Applied Microeconometrics

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September 30, 2020

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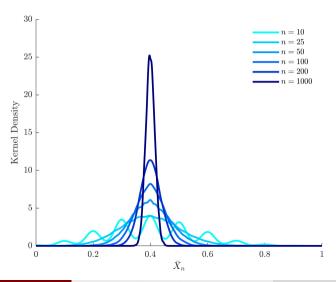
Monte Carlo experiments hinge on repeated random sampling to fulfill various goals:

- Provide a numerical approximation to integrals using empirical means
 - Applications: Method of Simulated Moments (MSM) and Maximum Simulated Likelihood (MSL)
 - The "quality" of the approximation increases with the number of simulations (via LLN)
- Investigate the **properties** of any statistical procedure via simulation

Monte Carlo Simulations: Implementation

- Specify the number of Monte Carlo samples, *m*, and the size of each sample, *n*
- Assume knowledge of the joint distribution of all random variables in the experiment
 - E.g., $Y = 5 + 1.6 \cdot \sin(X) \cdot \log(X) + R$, with $X \sim \mathcal{U}[0, 10]$, $R \sim \mathcal{N}(0, 9)$, and $X \perp R$
- **3** For each one of the *m* Monte Carlo iterations:
 - Simulate a n-dimensional sample from the joint distribution of random variables
 - E.g. $\{(Y_i, X_i, R_i)\}_{i=1}^n$ is an i.i.d. sample from the joint probability distribution of (Y, X, R)
 - Perform a deterministic computation on this sample
 - E.g. Perform local linear regression of Y on X with bandwidth h = 0.5, and store fitted values
- 6 Compute one or more statistics by averaging quantities across Monte Carlo samples
 - E.g. compute the Mean Squared Error of local linear regression fitted values

Monte Carlo Simulations: Example



Nonparametric Bootstrap

3 Frameworks for Causal Inference

- A variant of Monte Carlo simulation that can be implemented with
 - **1** Fewer parametric assumptions on the Data Generating Process
 - 2 Little additional code beyond the one required to estimate the model in the first place
- Nonparametric bootstrap is typically used to compute analytically complex statistics
 - E.g. standard errors, when working with Continuous Mapping and Delta Method is hard
- It hinges on sampling with replacement from the empirical distribution of the data
 - Let $P = \{1, 2, 3, 4, 5\}$ be the population. Examples of 3-dimensional samples with replacement are $S_1 = \{4, 1, 2\}$, $S_2 = \{5, 2, 5\}$, and $S_3 = \{4, 4, 4\}$
- Smoothness conditions must be satisfied for nonparametric bootstrap to be valid
 - E.g. Bootstrap is invalid if applied to one-to-one propensity score matching (more later)

- $X \in \mathbb{R}^{d_x}$ is a random vector distributed according to some **population cdf** F
- $\{X_i\}_{i=1}^n$ is a *n*-dimensional collection of draws from F (i.e., a **sample**)
- \widehat{F} is the **empirical cdf** of X
 - This distribution places equal probability mass to each of the n draws, $\{X_i\}_{i=1}^n$
- θ is a parameter of interest that can be estimated by $\widehat{T} = T\left(\widehat{F}\left(X_1,\ldots,X_n\right)\right)$
- A **bootstrap sample** of size n, $\{X_i^b\}_{i=1}^n$, is a collection of **i.i.d.** draws from \widehat{F}
 - Sampling with replacement is necessary for X_1^b, \dots, X_n^b to be i.i.d.

- $oldsymbol{0}$ Specify the number of bootstrap samples $\overline{oldsymbol{b}}$
- **2** Let $b \in \{1, 2, \dots, \overline{b}\}$. For each bootstrap iteration:
 - Extract a **bootstrap sample** of size n, $\left\{X_i^b\right\}_{i=1}^n$
 - Perform a deterministic computation on this bootstrap sample
 - E.g. Regress X_1 on X_2, \ldots, X_k and store the coefficient associated with X_2 , i.e., $\widehat{\beta_2^b}$
- 6 Compute one or more statistics by averaging quantities across bootstrap samples
 - E.g. compute the standard error associated with $\widehat{\beta}_2$ as $\sqrt{\frac{1}{\overline{b}}\sum_{b=1}^{\overline{b}}\left(\widehat{\beta_2^b}-\frac{1}{\overline{b}}\sum_{j=1}^{\overline{b}}\widehat{\beta_2^j}\right)^2}$
 - ullet As above, approximation quality increases with the number of bootstrap samples \overline{b}

Object	Data	Bootstrap
Population Distribution	F	Ê
Sample	$\{X_i\}_{i=1}^n$	$\left\{X_{i}^{b}\right\}_{i=1}^{n}$ i.i.d.
Empirical Distribution	Ê	\widehat{F}^{b}
Parameter	$ heta=T\left(F ight)$	$\widehat{T}=T\left(\widehat{F} ight)$
Estimator	$\widehat{T}=T\left(\widehat{F} ight)$	$\widehat{T}^b = T\left(\widehat{F}^b\right)$

Source: Lecture notes by Charles J. Geyer

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3 Frameworks for Causal Inference

Frameworks for Causal Inference

Two main frameworks for causal inference:

1 Latent variables, or all-causes, model:

$$Y = g(D, U)$$

where D and U denote the **observed** and **unobserved** determinants of Y, respectively. Together, D and U exhaustively cause the outcome.

Potential outcomes model:

$$Y = \sum_{d \in \mathcal{D}} Y(d) \mathbb{I}[D = d]$$

where Y(d) is the counterfactual Y associated with treatment state d.

Example: from Potential Outcomes to All-Causes

- ullet Consider a binary treatment $D \in \{0,1\}$
- Assume that D and Y are linked by **potential outcomes** Y(0) and Y(1)
- Let us derive a linear all-causes model from the potential outcomes model:

$$Y = DY(1) + (1 - D)Y(0)$$

$$= \underbrace{\mathbb{E}[Y(0)]}_{\equiv \alpha} + \underbrace{(Y(1) - Y(0))}_{\equiv \beta} D + \underbrace{Y(0) - \mathbb{E}[Y(0)]}_{\equiv U}$$

$$= \alpha + \beta D + U \equiv g(D, U)$$

• β could be assumed to be a **deterministic constant** (homogeneous treatment effects) or a **nondegenerate random variable** (heterogeneous treatment effects)

Example: from All-Causes to Potential Outcomes

- Maintain the assumption that the treatment is binary
- Assume a **linear all-causes model** of the observed and unobserved determinants of Y,

$$Y = \alpha + \beta D + U$$

• To derive a **potential outcomes model**, it is sufficient to define

$$Y(0) \equiv g(0, U) = \alpha + U$$

$$Y(1) \equiv g(1, U) = \alpha + \beta + U$$

- Both Y(0) and Y(1) are random variables because U is a random variable
- In addition, β may be a random variable if the effect of D is heterogeneous



3 Frameworks for Causal Inference

Unobserved Determinants of the Outcome vs. Linear Regression Residual

• In general, the conditional expectation function is **nonlinear**:

$$\mathbb{E}[Y|D] = h(D,\theta)$$

where $h(\cdot)$ is some function of a random vector D and a parameter vector θ

- $h(D, \theta)$ is typically unknown but can be approximated:
 - A convenient approximation choice is the "best" linear approximation

$$eta^* \in \arg\min_{eta \in \mathbb{R}^{d_d}} \mathbb{E}\left[\left(\mathbb{E}[Y|D] - D'eta
ight)^2\right]$$
 (BLA)

• This minimization problem is equivalent to the linear prediction problem

$$\beta^* \in \arg\min_{\beta \in \mathbb{R}^{d_d}} \mathbb{E}\left[\left(Y - D'\beta \right)^2 \right] \tag{BLP}$$

Unobserved Determinants of the Outcome vs. Linear Regression Residual

The first-order necessary conditions associated with both minimization problems are

$$\mathbb{E}[D(Y - D'\beta^*)] = \mathbb{E}[DU] = 0$$

where $U \equiv Y - D'\beta^*$ is a statistical residual

- *U* captures the "quality" of the linear approximation to $\mathbb{E}[Y|D] = h(D,\theta)$
- Being a statistical residual, U has no causal interpretation
- Analogously, β^* is the solution to a Mean Squared Error minimization problem

Unobserved Determinants of the Outcome vs. Linear Regression Residual

Consider the linear causal model

$$Y = D'\beta + U$$

- ullet If U were interpreted as encompassing the **unobserved determinants** of Y, then
 - ullet $\mathbb{E}\left[DU
 ight]=0$ would imply that observed and unobserved determinants of Y are **linearly unrelated**
 - This is not a statistical property, but a causal one, and its credibility is assessed subjectively
- The first part of this course will be devoted to studying cases in which $\beta^* = \beta$
 - Under selection on observables, β^* identifies only some components of β