

Application of stat mech of disordered systems  
to computer science

## I Computer science problems

1. Decision problems : yes/no answer

Examples:

- Hamiltonian circuit (or cycle)

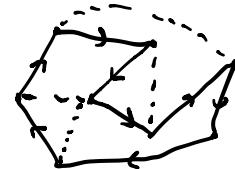
$G = (V, E)$  Is there a Hamiltonian circuit ?

a closed path that visits each vertex exactly once

- Traveling salesmen problem (TSP)

$G$  weighted  $w_{ij}$

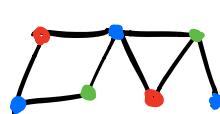
Is there a Hamiltonian cycle  $\sum_{k=1}^N w_{i_k i_{k+1}} \leq W$  ?



Applications in planning, logistics, ...

- Coloring problem (e.g. for maps)

$G$  Is there an assignment of  $q$  colors to vertices such that no edge is monochromatic ?



$$\{\sigma_1, \dots, \sigma_N\} \in \{1 \dots q\}^N$$

$$\sigma_i \neq \sigma_j \text{ for } \forall \langle ij \rangle \in E$$

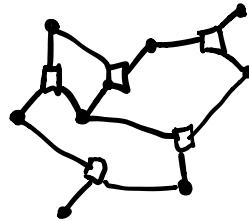
- K-XORSAT problem

↔ k-hypergraph

M edges  $a = 1 \dots M$

$$\partial a = \{i_1^a \dots i_K^a\}$$

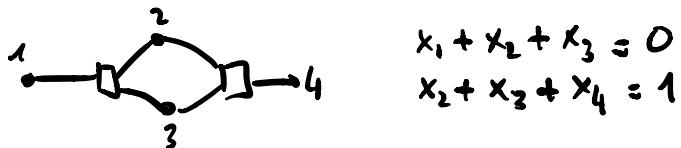
$$x_i \in \{0, 1\} \text{ and } y_a \in \{0, 1\}$$



Is there a solution to the set of linear eqs

$$x_{i_1^a} + x_{i_2^a} + \dots + x_{i_K^a} = y_a \pmod{2}$$

$$\begin{cases} 1+0=0+1=1 \\ 0+0=1+1=0 \end{cases} \quad \text{exclusive OR} \quad \text{XOR}$$



$$\text{Define } \sigma_i = (-1)^{x_i} \in \{\pm 1\}$$

$$J_a = (-1)^{y_a} \in \{\pm 1\}$$

$$\prod_{i \in \partial a} \sigma_i = J_a$$

- K-SAT problem

Same as K-XORSAT but OR instead of XOR

$$x_{i_1^a} \vee \bar{x}_{i_2^a} \vee \dots \vee \bar{x}_{i_K^a} \quad a = 1 \dots M$$

$$\sigma_{i_1^a} = J_1^a \vee \sigma_{i_2^a} = J_2^a \vee \dots \vee \sigma_{i_K^a} = J_K^a$$

- Perceptron problem (continuous variables)

Patterns  $\vec{z}_a \in \mathbb{R}^N$

Is there  $\vec{X} \in \mathbb{R}^N$  s.t.  $|\vec{X}|^2 = N$  and  $\vec{z}_a \cdot \vec{X} \geq \sigma \sqrt{N}$  ?

## 2. Complexity classes for decision problems

"quenched disorder" aka "instance" :  $G, J$

"variables" : the cycle,  $\{x_i\} \rightarrow \{\sigma_i\}$

A given instance (formula) is  
SAT if answer is yes  
UNSAT " no

"size" of the instance :  $N$ , number of vertices

**NP class** ("easy to check")

A problem is in NP if given a solution, you can check it in  $\text{poly}(N)$  time

All example above are in NP

Find a solution by "brute force" : time  $2^N, q^N, N!$

Question: is there a  $\text{poly}(N)$  algorithm to solve the problem (yes/no) ?

**P class** ( $2\text{-COL}, 2\text{-SAT}, K\text{-XORSAT}$ )

There are algorithms that give the solution in  $\text{poly}(N)$  time for all instances

Ex:  $2\text{-COL}$  : assign color 1 to a vertex, color 2 to neighbors,  
 $K\text{-XORSAT}$  : Gaussian elimination

But:  $K\text{-SAT}$ ,  $q\text{-COL}$ ,  $\text{TSP}$   
 $K \geq 3$        $q \geq 3$

For the moment no  $\text{poly}(n)$  algorithm for all instances

A NP problem can become P

NP-complete problems

"Hardest problems in NP"

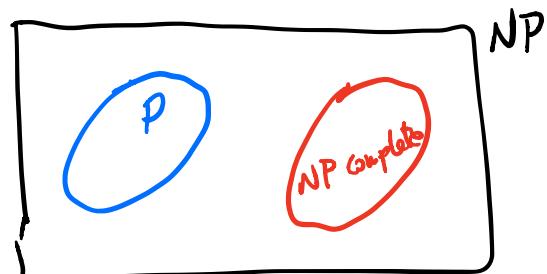
Problem A is NP-Complete if  $A \in \text{NP}$  and

for  $\forall B \in \text{NP}$  an instance of B of size N can be mapped in  $\text{poly}(N)$  time into an instance of A of size  $N' \sim \text{poly}(N)$

If  $A \in P \Rightarrow NP = P$

It is believed that  $P \neq NP$ , i.e. NP-complete problems cannot be solved in  $\text{poly}(N)$  time

1M\$ to prove or disprove (millennium prize problems)



$K\text{-SAT}$ ,  $q\text{-COL}$ ,  $\text{TSP}$  are all NP-complete  
 $K \geq 3$        $q \geq 3$

Other complexity classes for:

- optimization problems : find the best  $W$  for TSP  
find the ground state of the SK model
- counting problems : how many colorings of a  $G$ ?

## II. Stat mech approach to constraint satisfaction pbs

### 1. The partition function

$q$ -COL,  $K$ -SAT,  $K$ -XORSAT : configurations  $\underline{\sigma} = \{\sigma_1, \dots, \sigma_N\}$

$$H[\underline{\sigma}; G, J] = \sum_{a=1}^M \mathbb{1}\llbracket \underline{\sigma} \text{ violates constraint } a \rrbracket \\ = \{\# \text{ of violated constraints}\}$$

Ex. COL: no  $J$ ,  $a = \langle ij \rangle \in E$ ,  $H[\underline{\sigma}, G] = \sum_{\langle ij \rangle \in E} \delta_{\sigma_i \sigma_j}$   
(AF Potts model)

$$\text{SAT instance} \Leftrightarrow \min_{\underline{\sigma}} H[\underline{\sigma}; G, J] = 0$$

One way : stat mech at  $T=0$

$$Z(\beta; G, J) = \sum_{\underline{\sigma}} e^{-\beta H[\underline{\sigma}; G, J]} \xrightarrow{\beta \rightarrow \infty} N_{\text{sol.}}(G, J)$$

Usual situation for disordered systems

$\underline{\sigma}$  thermal average ;  $\{G, J\}$  disorder average

## 2. Random instances

Computer Science complexity classes are defined in the "worst case scenario" over  $\{G, f\}$

Paradox in the 80s

- many problems proven to be NP complete
- simple algorithms could solve many instances

Question: how do we construct difficult instances ?

Idea: random instances

- benchmarks
- practical way to construct difficult instances
- sometimes useful for applications

Examples:

$q$ -COL of Erdős-Rényi graph  $\rightarrow$  AF Potts model  
on ER graph  
 $N$  vertices,  $M = \alpha N$  edges

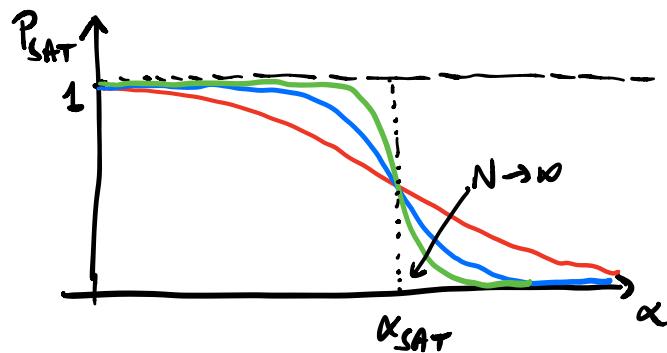
$K$ -XORSAT  
 $K$ -SAT      on a random ER  
hypergraph       $N$  vertices  
                     $M = \alpha N$  hyperedges  
                     $J = \pm 1$  at random

Control parameters:  $\alpha, \frac{q}{K}, T \rightarrow 0, N \rightarrow \infty$

Fix  $q, K$  - vary  $\alpha, N$

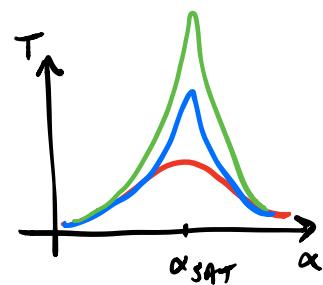
$$P_{SAT}(\alpha, N) = \{ \text{fraction of SAT instances} \}$$

Numerical results: (3-SAT)



$$P_{\text{SAT}}(\alpha, N) \rightarrow \begin{cases} 1 & \alpha < \alpha_{\text{SAT}} \\ 0 & \alpha > \alpha_{\text{SAT}} \end{cases}$$

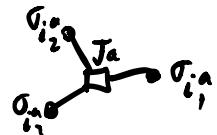
At phase transition!



Hard instances found around  $\alpha_{\text{SAT}}$

In the tutorial: discuss bounds on  $\alpha_{\text{SAT}}$  for K-XORSAT

### 3. Spin glass phase diagram.



K-XORSAT

$$H[\sigma; G, J] = \sum_{a=1}^M \frac{1 - J_a \sigma_{i_1} \sigma_{i_2} \dots \sigma_{i_k}}{2}$$

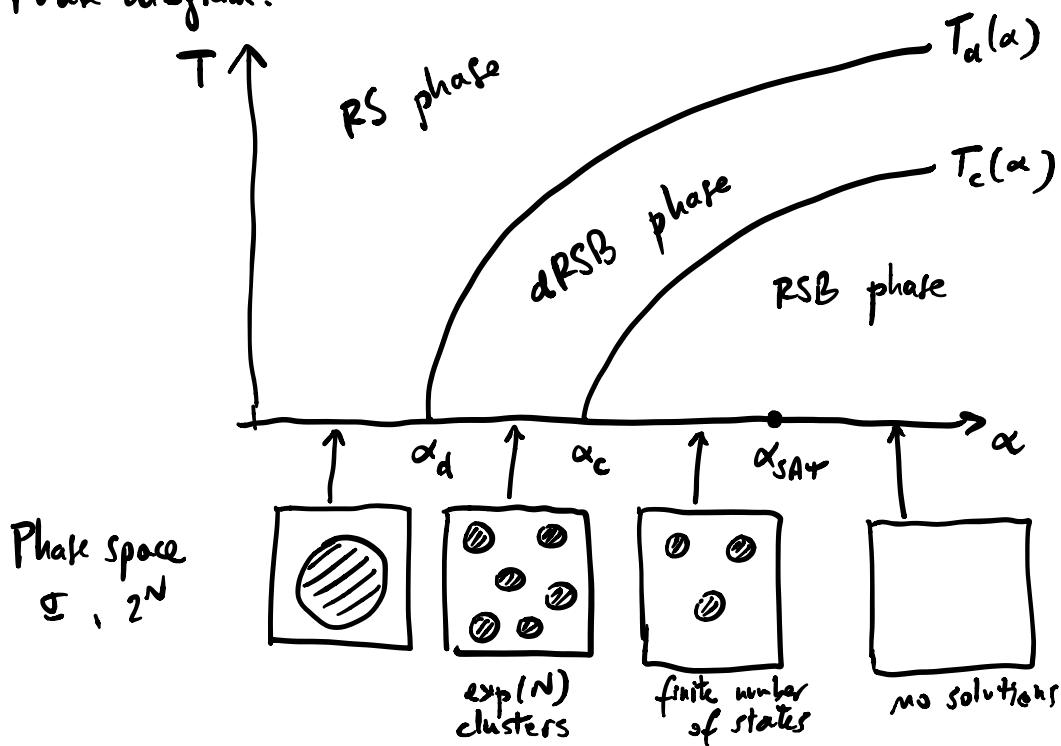
This is the pspin!

- on a ER hypergraph
- $J = \pm 1$  instead of Gaussians
- $p = K$  (note the interest of  $p \geq 3$ )

but  $\alpha \rightarrow \infty$  (after  $N \rightarrow \infty$ ) equivalent to fully connected  
(and Gaussian equivalent to  $\pm 1$ )

In  $N \rightarrow \infty$  for fixed  $K (= p)$  :  $(\alpha, T)$

Phase diagram:



Glassy phase  $\Rightarrow$  slow dynamics  $\Rightarrow$  algorithmic difficulty

Many results obtained via spin glass techniques

Many of them have been proven rigorously

Active and interdisciplinary field

(Computer science, math, stat phys, machine learning...)

#### 4. Conclusions

- Main message : quenched disorder  
two kind of averages  
Self averaging
- Spin glasses useless materials but "prototypes" of complex systems  
Techniques have broad applicability
- Replica method a bit mysterious but now is quite well understood - rigorous proofs
- Importance of dynamics