# Reduced-Rank Regression Model: A Review

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### Background and Introduction

A classical multivariate linear model, which is given as

$$Y_k = CX_k + \varepsilon_k, \ k = 1, ..., T$$

where  $Y_i = (y_{1k},...y_{mk})^T$  is a mx1 response vector, C is a mxn regression coefficient matrix,  $X_k = (x_{1k},...x_{mk})^T$  is a nx1 predictor vector, and  $\varepsilon_k = (\varepsilon_{1k},...\varepsilon_{mk})^T$  is a mx1 error vector with  $E(\varepsilon_k) = 0$  and  $cov(\varepsilon_k) = \Sigma_{\varepsilon\varepsilon}$ , does not make use of the fact that the response variables are likely correlated.

In many practical situations, there is also often a need to reduce the number of parameters in the model.

#### Introduction

Further assuming reduced rank of the matrix C such that

$$rank(C) = r \leq min(m, n)$$

leads us to two implications.

- 1. Let I be the constraint vector, the linear combination,  $I^T Y_k$ , i = 1, ..., (m r), can be modeled through the distribution of the error term  $\varepsilon_k$  (w/o referencing to the predictors  $X_k$ ).
- 2. C can be expressed as C = AB, where A is of dimension mxr and B is of dimension rxn. Then, the multivariate linear model can be rewritten as

$$Y_k = A(BX_k) + \varepsilon_k, \ k = 1, ..., T,$$

where  $BX_k$  is of reduced dimension with *only* r components, and as a result, there is a gain in simplicity and interpretation.

### Introduction

The first application of reduced-rank regression model appeared in an initial work of Anderson (1951) in the field of economics. The model and its statistical properties were further examined by a few other authors.

Subsequent but separate work that were studied using related concepts were

- principle components (Rao, 1964),
- simultaneous linear prediction modeling (Fortier, 1966),
- redundancy analysis, an alternative to canonical correlation analysis (van den Wollenberg, 1977), etc.

More complex models have also been developed ever since.

# **Applications**

### Applications of the reduced-rank regression model include

- (1) the experimental properties of hydrocarbon fuel mixtures in relating response to composition (Davies and Tso, 1982),
- (2) an econometric model of the United Kingdom from 1948 to 1956 (Gudmundsson, 1977), which consists of 37 time series of response variables and 32 time series of predictors,
- (3) the relationship between measurements on solar radiation taken over various sites in Scotland and the physical characteristics of the sites (Glasbey, 1992), etc,

### **Estimation**

The parameters that are to be estimated are the matrix A of dimension mxr, B of dimension rxn and  $\Sigma_{\varepsilon\varepsilon}$  of the error term.

To estimate A and B, we need the Brillinger's theorem (Brillinger, 1981, Section 10.2), which can be proven by the Eckart-Young theorem (Eckart and Young, 1936).

# Brillinger's Theorem

Suppose the random vector (Y,X) has mean vector 0 and covariance matrix  $Cov(Y,X) = \Sigma_{yx} = \Sigma_{xy}^T$  and  $Cov(X) = \Sigma_{xx}$  is nonsingular, then for any positive-definite matrix  $\Gamma$ , the mxr matrix A and rxn matrix B, for  $r \leq min(m,n)$  that minimize

$$tr(E(\Gamma^{1/2}(Y-ABX)(Y-ABX)^T\Gamma^{1/2}))$$

are given by

$$A = \Gamma^{1/2}V$$
,  $B = V^T\Gamma^{1/2}\Sigma_{yx}\Sigma_{xx}^{-1}$ ,

where  $V=(V_1,...,V_r)$  and  $V_j$  is the (normalized) eigenvector that corresponds to the jth largest eigenvalue  $\lambda_j^2$  of the matrix  $\Gamma^{1/2}\Sigma_{yx}\Sigma_{xx}^{-1}\Sigma_{xy}\Gamma^{1/2}$ , j=1,...,r.

# Remark - SVD (Singular Value Decomposition)

Remark. Brillinger's theorem is proved by setting  $S^* = \Gamma^{1/2} \Sigma_{yx} \Sigma_{xx}^{-1}$ , where the positive square roots of  $SS^T$  are called the singular values of the matrix S.

In general, a mxn matrix S of rank s can be expressed in the singular value decomposition as  $S = V \Lambda U^T$ , where  $\Lambda = diag(\lambda_1,...\lambda_s)$  with  ${\lambda_i}^2 > 0$  and V is a mxs matrix s.t.  $V^T V = I_s$  and U is a mxs matrix s.t.  $U^T U = I_s$ .

# Estimation - $\hat{\beta}_{RR}$ (or $\hat{A}$ and $\hat{B}$ )

Back to the model, recall that in the full-rank case, the OLS estimator is given as

$$\hat{\beta}_{OLS} = C^T = (X^T X)^{-1} X^T Y,$$

in the reduced-rank case and at the simple level, the estimator can be written as

$$\hat{\beta}_{RR} = B^T A^T = (X^T X)^{-1} X^T Y V V^T = \hat{\beta}_{OLS} V V^T.$$

Note.

- 1.  $C = AB = \Gamma^{1/2}VV^T\Gamma^{1/2}Y^TX(X^TX)^{-1} = P_{\Gamma}Y^TX(X^TX)^{-1}$ , where  $P_{\Gamma}$  is an idempotent matrix for any  $\Gamma$  (Brillinger's theorem).
- 2. In the reduced-rank regression,  $\Gamma$  is typically set to be the identity matrix I.

# Estimation - $\hat{\Sigma_{\varepsilon\varepsilon}}$

To maximize

$$L(C, \Sigma_{\varepsilon\varepsilon}) = (\frac{T}{2})(log|\Sigma_{\varepsilon\varepsilon}^{-1}| - tr(\Sigma_{\varepsilon\varepsilon}^{-1}W))$$

is the same as minimizing |W| (the determinant of W), where

$$W = \tilde{\Sigma_{\varepsilon\varepsilon}} + (\tilde{C} - AB)\hat{\Sigma}_{xx}(\tilde{C} - AB)^{T}.$$

It has been shown that the solutions

$$A = \Gamma^{1/2} V, \hspace{5mm} B = V^T \Gamma^{1/2} \Sigma_{yx} \Sigma_{xx}^{-1}, \label{eq:alpha}$$

with the choice of  $\Gamma = \Sigma_{\varepsilon\varepsilon}^{-1}$ , minimizes simultaneously all the eigenvalues of  $\Sigma_{\varepsilon\varepsilon}^{-1}W$  and hence minimizes |W| (Robinson, 1974).

### **Estimation**

So,  $\hat{A}_r$  and  $\hat{B}_r$  are ML estimates for A and B. However,

$$\tilde{\Sigma_{arepsilon arepsilon}} = (1/T)(Y - \tilde{C}X)(Y - \tilde{C}X)^T$$

is the ML estimate in the full-rank regression model.

$$\hat{\Sigma_{\varepsilon\varepsilon}} = (1/T)(Y - C_r X)(Y - C_r X)^T$$

is the ML estimate under the reduced-rank structure.

### Discussion

An explicit solution for the matrices A and B can be obtained by computing eigenvalues and eigenvectors of  $SS^T$  or  $S^TS$ .

However, when an explicit solution is not possible to find, iterative procedures need to be considered.

### Reference

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### Thank you!

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