

# ST 661 Note

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## Outline

pd matrices

Determinant

Orthogonal matrices

## Thm (\*)

Suppose A is symmetric, A is pd iff  $\exists$  a nonsingular matrix P s.t.  $A = P^T P$ .

Proof.  $\Leftarrow$

Suppose  $A = P^T P$  for some nonsingular P, then

$$y^T A y = y^T P^T P y = (Py)^T Py \geq 0$$

The last step sort of works like a sum of square. In addition,

$$(Py)^T Py = 0$$

only if  $Py = 0$ .

$\Rightarrow y = 0$  because P is nonsingular (or full rank)

$\Rightarrow A$  is pd since whenever  $y \neq 0$ ,  $y^T A y > 0$   $\square$

Proof.  $\Rightarrow$  is included in the HW and requires eigenvalues.

If we relax the assumption such that P is nonsingular, then we get psd.

Comment. P is not unique, unless... see the following

## Cholesky Decomposition

Suppose that A is pd, then it is possible to find a nonsingular upper triangular matrix

$$T = \begin{bmatrix} \cdot & * & * \\ 0 & \cdot & * \\ 0 & 0 & \cdot \end{bmatrix}$$

s.t.  $A = T^T T$ .

## Thm

Let  $B$  be a  $n \times p$  matrix,

- i) If  $\text{rank}(B) = p$ , then  $B^T B$  is pd.
- ii) If  $\text{rank}(B) < p$ , then  $B^T B$  is psd, not pd. (psd can be pd but not in this case.)

Proof. Exercise. Use quadric form from previous proof and rank.

## Thm

If  $A$  is pd,  $A^{-1}$  is also pd.

Proof. Use Thm (\*),

$A$  is pd  $\Rightarrow A = P^T P$  for nonsingular  $P$ , then

$$A^{-1} = (P^T P)^{-1} = P^{-1} (P^{-1})^T = (\text{new } P)(\text{new } P)^T$$

$\Rightarrow A^{-1}$  is pd.

## Determinant

Check textbook for full definition. As a demonstration, suppose

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix},$$

then  $\det(A) = a_{11}a_{22} - a_{12}a_{21}$  is a degree 2 polynomial function, for example. In general, let  $A$  be  $n \times n$ , then  $\det(A)$  (or  $|A|$ ) is a scalar degree  $n$  polynomial function of  $A$ .

## Thm

- i) If

$$D = \begin{bmatrix} d_1 & 0 & 0 \\ 0 & \dots & 0 \\ 0 & 0 & d_n \end{bmatrix},$$

is diagonal, then  $\det(D) = d_1 d_2 \dots d_n$ .

If  $D_2$  is upper (or lower) triangular matrix such as

$$D_2 = \begin{bmatrix} d_1 & * & * \\ 0 & \dots & * \\ 0 & 0 & d_n \end{bmatrix},$$

then  $\det(D) = d_1 d_2 \dots d_n$ .

- ii)  $A$  is square matrix and  $A$  is singular  $\Leftrightarrow \det(A) = 0$ .

- iii) If  $A$  is pd, then  $\det(A) > 0$ . (Not the inverse.)

If A is psd, then  $\det(A) \leq 0$ . (Again, not the inverse.)

- iv)  $\det(A) = \det(A^T)$
- v) If A is singular ( $\det(A) \neq 0$ ), then  $\det(A^{-1}) = \frac{1}{\det(A)}$ .
- vi) If cA where c is scalar and A is  $n \times n$ , then  $\det(cA) = c^n \det(A)$ .

e.g.

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

and

$$2A = \begin{bmatrix} 2a_{11} & 2a_{12} \\ 2a_{21} & 2a_{22} \end{bmatrix}.$$

## Thm

If A and B are both square  $n \times n$  matrices, then

$$\det(AB) = \det(A)\det(B).$$

## Corollary

i)

$$\det(BA) = \det(BA)$$

ii) (special case of thm)

$$\det(A^k) = (\det(A))^k$$

e.g.

$$\det(A^2) = (\det(A))^2$$

## Thm

If A is square and partitioned as

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

and  $A_{11}$  and  $A_{22}$  are both square and nonsingular (can be of different size), then

$$\det(A) = \det(A_{11})\det(A_{22} - A_{21}(A_{11})^{-1}A_{12}) = \det(A_{22})\det(A_{11} - A_{12}(A_{22})^{-1}A_{21}).$$

Intuition.

$$\det\left(\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}\right) = a_{11}a_{22} - a_{12}a_{21} = a_{11}\left(a_{22} - \frac{a_{12}a_{21}}{a_{11}}\right) = a_{22}\left(a_{11} - \frac{a_{12}a_{21}}{a_{22}}\right).$$

## Corollary

Suppose

$$A = \begin{bmatrix} A_{11} & 0 \\ A_{21} & A_{22} \end{bmatrix}$$

or

$$A = \begin{bmatrix} A_{11} & A_{12} \\ 0 & A_{22} \end{bmatrix}$$

and assume  $A_{11}$  and  $A_{22}$  are square, then

$$\det(A) = \det(A_{11})\det(A_{22}).$$

This is the extension of the previous thm where

i) If

$$D = \begin{bmatrix} d_1 & 0 & 0 \\ 0 & \cdots & 0 \\ 0 & 0 & d_n \end{bmatrix},$$

is diagonal, then  $\det(D) = d_1d_2\dots d_n$ .

## Thm

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$$

and assume

- 1)  $A_{11}$  &  $A_{12}$  are square
- 2)  $A_{11}$  is nonsingular
- 3)  $B = A_{22} - A_{21}(A_{11})^{-1}A_{12}$  is nonsingular, then

$$A^{-1} = \begin{bmatrix} A_{11}^{-1} - B^{-1}A_{21}A_{11}^{-1} + A_{11}^{-1}A_{12}B^{-1}A_{21}A_{11}^{-1} & -A_{11}^{-1}A_{12}B^{-1} \\ -B^{-1}A_{21}A_{11}^{-1} & B^{-1} \end{bmatrix}.$$

?  $\dim(A_{11}) = \dim(3 \text{ terms})$

Note. We only need  $B^{-1}$  and  $A_{11}^{-1}$  and the rest are matrix multiplication.

In addition, this is helpful when we need to compare  $A_{11}^{-1} - B^{-1}A_{21}A_{11}^{-1} + A_{11}^{-1}A_{12}B^{-1}A_{21}A_{11}^{-1}$  to  $A_{11}^{-1}$ .

e.g.

$$X_{new} = [X \quad Z]$$

$$X_{new}^T X_{new} = \begin{bmatrix} X^T \\ Z^T \end{bmatrix} [X \quad Z] = \begin{bmatrix} X^T X & X^T Z \\ Z^T X & Z^T Z \end{bmatrix}$$

## Orthogonal Matrices

Suppose

$$a = [a_1 \quad a_2]^T$$

length of a (or  $|a|$ ) =  $\sqrt{a_1^2 + a_2^2} = \sqrt{(a^T a)}$ .

a is an unit vector iff length of a (or  $|a|$ ) = 1.

Suppose

$$b = [b_1 \quad b_2]^T,$$

if a and b are both unit vectors, then

$$\cos(\theta) = a_1 b_1 + a_2 b_2 = a^T b = b^T a = \langle a, b \rangle.$$

The last term is called an inner product.

In general, if a and b are not unit vectors, then

$$\cos(\theta) = \frac{a^T b}{\sqrt{(a^T a)} \sqrt{(b^T b)}},$$

where  $\sqrt{(a^T a)}$  is length of a and  $\sqrt{(b^T b)}$  is length of b.

a and b are perpendicular (i.e.  $\theta = 90^\circ$ ) iff

$$\cos(\theta) = 0 = a^T b \quad (\text{or } b^T a = 0)$$

## Definition

In general, if a is an  $n$ -dim vector, then length of a

$$= \sqrt{(a^T a)} = \sqrt{(a_1^2 + a_2^2 + \dots + a_n^2)}.$$

## Definition

Suppose  $a, b \in \mathbb{R}^n$ , a and b are said to be orthogonal (“perpendicular” in 2D) iff

$$a^T b \quad (\text{or } b^T a) = a_1 b_1 + a_2 b_2 + \dots + a_n b_n = 0.$$

## Definition

If  $a^T a = 1 = |a|$ , then a is said to be normalized. (Any vector b can be normalized by

$$c = \frac{b}{\sqrt{(b^T b)}}.$$

Proof.  $c^T c = \dots = 1$ .

## Definition

A set of  $p$ -dim vectors  $c_1, c_2, \dots, c_p$  that are normalized and mutually orthogonal are said to be an orthonormal set of vectors.

i.e.

- i)  $c_i^T c_i = 1$  for any  $i$
- ii)  $c_i^T c_j = 0$  for any  $i \neq j$

## Definition

If a  $p \times p$  matrix  $C = (c_1, c_2, \dots, c_p)$  has orthonormal columns, then  $C$  is called an orthogonal matrix.

## Corollary

If  $C$  is orthogonal, then  $C^T C = I$ .

$$C^T C = \begin{bmatrix} c_1^T \\ c_2^T \\ \vdots \\ c_p^T \end{bmatrix} \begin{bmatrix} c_1^T & c_2^T & \cdots & c_p^T \end{bmatrix} =$$

$(i, j)$  entry of  $C^T C = c_i^T c_j = 0$  when  $i \neq j$ .  $C^T C = c_i^T c_j = 1$  when  $i = j$ , so

$$C^T C = \begin{bmatrix} 1 & 0 & 0 & \cdots \\ 0 & 1 & 0 & \cdots \\ 0 & 0 & 1 & \cdots \\ 0 & 0 & \cdots & 1 \end{bmatrix} = I.$$

Remark.

$$C^T C = I \Leftrightarrow CC^T = I$$

$$C \text{ is orthogonal} \Leftrightarrow CC^T = I$$

$CC^T = I$  means that the rows of  $C$  are orthonormal.

End. Verify  $A^{-1}$  and review the final definition.