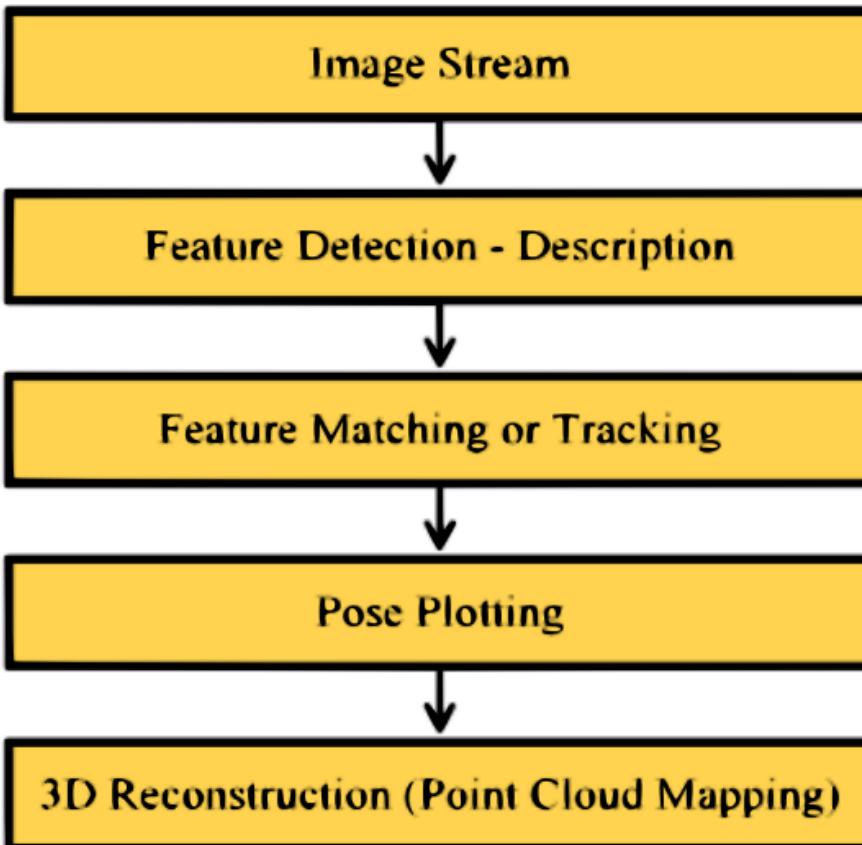


## Front End

## Back End



Feature Points  
Filtering

Camera Pose  
Estimation

Depth Estimation  
through triangulation

Optimization of  
Trajectory and Point  
Cloud (Kalman  
Filtering / Bundle  
Adjustment)