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akwnoelasfsa

I, Francisco SILI, hereby declare that this thesis has not been and will not be,
submitted in whole or in part to another university for the award of any other degree.

La Plata,
30th September 2024

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TESIS DE DOCTORADO

My thesis title

by Francisco SILI

ABSTRACT

some text

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TO DO'S AND NOTES TO KEEP IN MIND

use **orange** to highlight that there needs to be made sure that there is a discussion in previous chapters - in editing clarify where that discussion should happen!

purple: this needs a reference, have used from memory or notes

red: open question

Fixes, to dos

- test
- need to include a definition on met in the object definition part?

Thoughts to work with

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- how is the reconstruction considered overall? are there different

INTRODUCTION

This thesis presents a search for new phenomena in high-mass final states with a photon and a jet in proton-proton (pp) collisions at a centre-of-mass energy of 13 TeV using data collected by the [ATLAS](#) detector. [ATLAS](#) (“A Toroidal LHC ApparatuS”) is one of the two general-purpose detectors at the Large Hadron Collider ([LHC](#)) and the biggest multi-purpose particle detector ever built. It is used to investigate a wide range of physics, from Standard Model ([SM](#)) measurements, such as precision tests of quantum chromodynamics or study of the properties of the Higgs boson, to the search of new phenomena like extra dimensions and dark matter candidates. The LHC, built by the European Organization for Nuclear Research ([CERN](#)) and installed in a 27-kilometre circular tunnel, is the world’s largest and most powerful particle collider. This machine is capable of colliding energetic beams of protons (or heavier nuclei) at rates upward of millions per second. The precision and high beam energy of the LHC allow to explore the tera-electronvolt scale, an energy range never before achieved in a particle collider.

The thesis is divided into three parts. The first part describes the theory background and motivations of the work, in which the first chapter describes the Standard Model ([SM](#)) showing the excellent agreement there is between the theory and the experimental data. It also shows the actual problems of the [SM](#), which motivates the search for New Physics.

The second part describes the experiment. CHAPTER describes the [ATLAS](#) experiment, with each sub-detector in detail, to finally describes how the samples for data analysis are produced. The reconstruction of the different physics objects is explained in CHAPTER. At the end of the second part, a special chapter is dedicated to the photon identification, where a new method for correcting the shower shapes is explained and detailed.

The third part of the thesis is dedicated to the photon+jet resonance search. In CHAPTER, the general strategy and motivation of the search is discussed. The samples generation is discussed in CHAPTER, where the final event selection is given in CHAPTER. The methods for the background estimation as well as background modeling is given in CHAPTER AND CCHAPETER. The systematic uncertainties are discussed in CHAPTER, and finally in CHAPTER and CHAPTER, the statistical analysis with the results are shown.

Finally, the conclusions of the work are present in CHAPTER.

Part I

Theory Motivation

THE STANDARD MODEL AND BEYOND

1

*"Nothing in life is to be feared. It is
only to be understood. Now is the
time to understand more, so that we
may fear less"*

Marie Curie

another template text

Part II

Experimental setup

THE ATLAS EXPERIMENT

2

Something.

Someone

The work in this thesis has been performed using data from the [ATLAS](#) detector, one of the particle detectors recording collisions of protons accelerated by the [LHC](#) particle accelerator at European Organization for Nuclear Research ([CERN](#)). In the following chapter, an introduction to the [LHC](#) is given in Section 2.1, followed by a discussion of the [ATLAS](#) detector in Section 2.2. The discussion is focused on aspects important to the analyses of this thesis.

2.1 LHC

The [LHC](#) [1, 2] is the largest hadron accelerator in the world, located at [CERN](#), in the French-Swiss border. It has a longitude of 27 km, located between 50 and 174 meters underground. The [LHC](#) is designed to collide protons (and heavy ions) at a center of mass energy of 14 TeV. To keep the protons and heavy ions on the accelerator ring, overall 9593 magnets are used. These magnets include superconducting dipole and quadrupole magnets, cooled down to 1.9 K (-271 °C). The dipole magnets generate a magnetic field of 8.3 T.

In Figure 2.1 a general overview of the [LHC](#) accelerator facilities is shown. The protons are sourced from hydrogen gas by stripping its electrons and are accelerated in a first linear accelerator (LINAC2) to 50 MeV. Subsequently, the protons are successively accelerated in the Proton Synchrotron Booster ([PSB](#)), the Parton Shower ([PS](#)), and the Super Proton Synchrotron ([SPS](#)), where they reach an energy of 450 GeV before being injected into the [LHC](#). Overall 8 radiofrequency cavities can push the energy of the protons in the [LHC](#) up to 14 TeV.

The protons are injected as bunches of $\mathcal{O}(10^{11})$ protons into the [LHC](#) with a spacing of 25 ns (7.5 m). These bunches are later brought to collision in so-called bunch crossings. The filling scheme of the pre-accelerator chain, in combination with finite switching times of the injection and dumping magnets, results in regular patterns of filled and empty bunches.

The [LHC](#) so far provided proton and heavy ion beams for two data-taking periods, and is under-

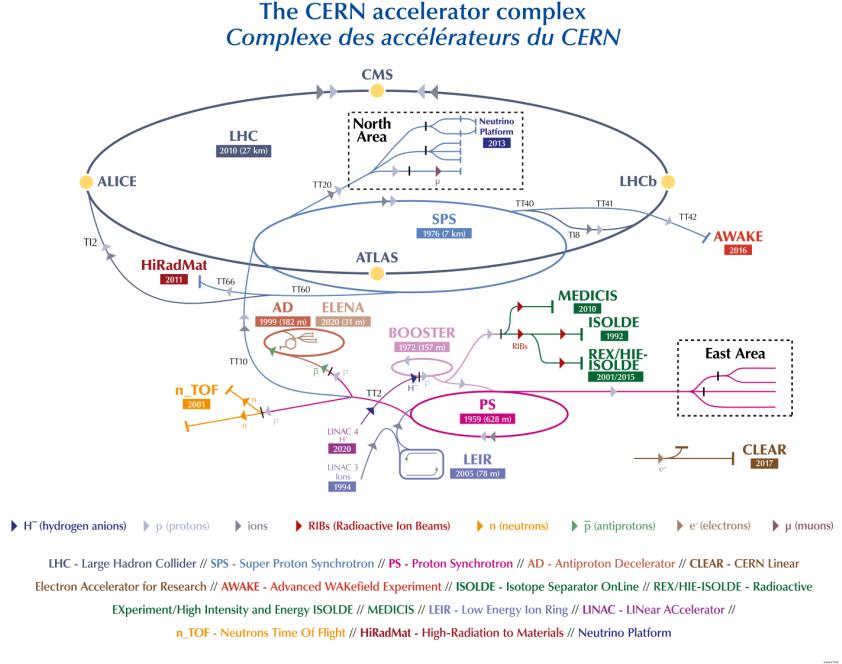


Figure 2.1: Overview of the LHC complex where all the accelerators that lead up to the LHC are shown [3].

going a third. Between 2009 and 2013 (known as Run 1), the LHC operated with centre-of-mass energy (\sqrt{s}) of 7 TeV and 8 TeV. After a long shutdown (LS1), the second run (Run 2) started in 2015 and ended in 2018, providing 13 TeV collisions to the experiments around the LHC ring. In 2022 the Run-3 began, at which pp collisions happen at an energy of 13.6 TeV, estimated to run until 2026. The four yellow dots in shown Figure 2.1 there are four interaction points, housing the ALICE [4], LHCb [5], CMS [6], ATLAS [7], LHCf [8], TOTEM [9], MoEDAL [10] experiments, among many other experiments.

One of the most important parameters to characterize the functioning of the accelerator is the instantaneous luminosity \mathcal{L} , defined as the number of particles per unit time per unit area, and can be calculated from the relation

$$\mathcal{L} = \frac{N_b^2 n_b f_{rev} \gamma_r}{4\pi \epsilon_n \beta^*} F \quad (2.1)$$

where N_b is the number of particles per bunch, n_b the bunches per beam, γ_r is the relativistic gamma factor, ϵ_n is the normalised transverse beam emittance and β^* being the beta function at the collision point which determining the transverse spread of the particle beam. The correction term F takes into account the beam crossing angle. The revolution frequency is represented by f_{rev} which is ~ 11 kHz, and with the bunch-spacing of 25 ns, allows for beam crossing at the four interaction points with a frequency of ~ 40 MHz.

A measure for the total recorded data is the integrated luminosity over time is given by

$$N_{event} = L_{int} \sigma_{event} = \sigma_{event} \int \mathcal{L} dt, \quad (2.2)$$

connecting the luminosity with the number of events. More details regarding the luminosity measurements in ATLAS are shown in Section 2.3.

2.2 ATLAS

[ATLAS](#) is one of the multi-purpose detectors of the [LHC](#), located at Point-1 along the [LHC](#). It was designed and built to study the pp (and heavy ion) collisions at the TeV scale.

The overall shape of the detector is that of a cylinder as shown in Figure 2.2. It has a length of 44m and 25m in diameter, being the largest particle detector built so far. The [ATLAS](#) detector is divided geometrically in two parts: the central part called *barrel*, and the outer caps called *end-caps*.

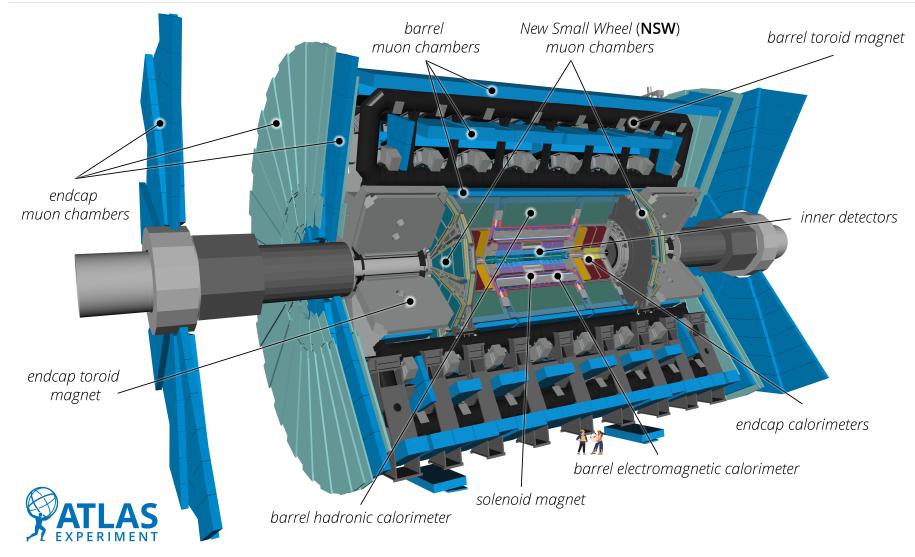


Figure 2.2: Overview of the [ATLAS](#) detector and all its sub-detectors, including the systems added during the LS2 [11].

[ATLAS](#) is built in layers of sub-detectors, each of which designed to have a different role on the identification and reconstruction of particles produced in the collisions. [ATLAS](#) provides hermetic coverage around the beam axis, enabling detection of all charged particles generated in the collisions in the plane orthogonal to the beam axis. This is particularly important in searches for new physics, relying on analyses of momentum balances in the orthogonal plane.

It is built up of multiple layers, starting from the innermost component, the Inner Detector ([ID](#)), providing tracking hits close to the beam pipe. Around the [ID](#), there is a superconductor solenoid which creates an axial magnetic field of ~ 2 T to curve the [ID](#) tracks of charged particles. After the first magnet, there is a system of two calorimeters: the [ECAL](#) and [HCAL](#). The former is in charge of measuring the kinetic energy of photons and electrons, and the latter measures the energy of the jets. The outermost parts of [ATLAS](#) are built by the muon spectrometer, providing momentum reconstruction for muons passing through the inner detector layers. Intertwined with the muon spectrometer, there are a total of 8 barrel toroid coils, providing a total magnetic field of 4 T (0.5 T per coil) to measure the momentum of muons. The toroid magnetic field is completed by the end-cap toroids, also generating a magnetic field up to 4T for muons leaving [ATLAS](#) close to the beam pipe.

Every component in [ATLAS](#) working together enables the reconstruction and identification of a

Table 2.1: General performance goals of the [ATLAS](#) detector. The units of p_T and E are in GeV. Extracted from Ref. [7]

Detector Component	Required resolution	η coverage	
		Measurement	Trigger
Tracking	$\sigma_{p_T}/p_T = 0.05\% p_T \oplus 1\%$	± 2.5	
EM calorimetry	$\sigma_E/E = 10\%/\sqrt{E} \oplus 0.7\%$	± 3.2	± 2.5
Hadronic calorimetry (jets)			
barrel and end-cap	$\sigma_E/E = 50\%/\sqrt{E} \oplus 3\%$	± 3.2	± 3.2
forward	$\sigma_E/E = 100\%/\sqrt{E} \oplus 10\%$	$3.1 < \eta < 4.9$	$3.1 < \eta < 4.9$
Muon spectrometer	$\sigma_{p_T}/p_T = 10\% \text{ at } p_T = 1 \text{ TeV}$	± 2.7	± 2.4

variety of particles with high precision. An overview of the design capabilities of [ATLAS](#) in terms of the momentum and energy resolution is given in Table 2.1, adapted from Ref. [7]. Here the resolution given lists first a stochastic term, measuring the uncertainty based on the statistically dominated interaction of a particle with the material, followed by a noise term, which accounts for uncertainties due to electronic noise in the readout process.

2.2.1 ATLAS Coordinate system

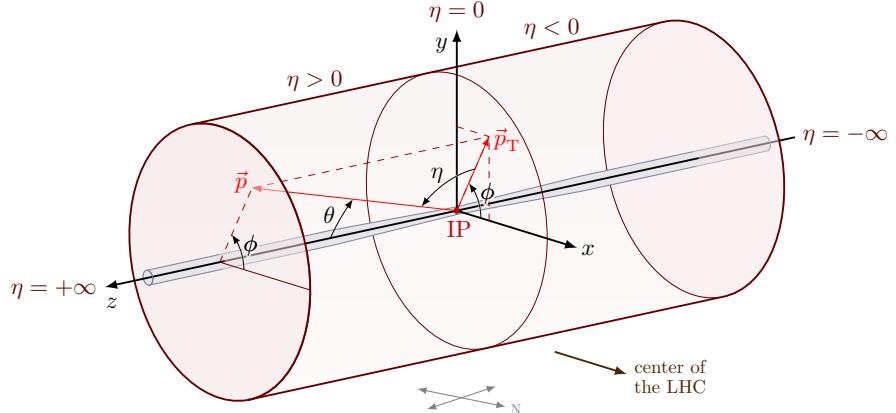


Figure 2.3: [ATLAS](#) coordinate system [11].

The coordinate system used within [ATLAS](#), displayed in Figure 2.3, is used throughout this thesis and shortly described in the following [7]. The origin of the right-handed coordinate system is at the nominal interaction point, with the positive x-axis pointing towards the centre of the [LHC](#). The x-y plane is perpendicular to the beam axis, defining the z-axis. Towards the surface defines the positive y-axis. An azimuthal angle ϕ is defined around the beam axis, and a polar angle θ is the angle from the beam axis. Instead of θ the rapidity y is used for heavy objects:

$$y = \frac{1}{2} \ln[(E + p_z)/(E - p_z)]. \quad (2.3)$$

Differences in rapidity are invariant under boosts along the beam axis. For massless objects or relativistic objects ($m \ll p$), the pseudorapidity is used instead:

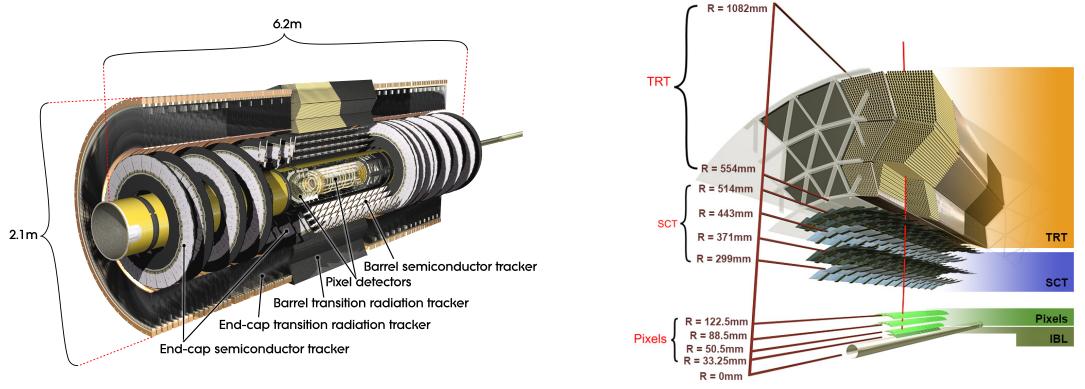
$$\eta = -\ln(\tan(\theta/2)). \quad (2.4)$$

To quantify the distance between two objects, ΔR is defined:

$$\Delta R = \sqrt{\Delta\phi^2 + \Delta\eta^2} \quad (2.5)$$

The transverse momentum and energy are defined in the x-y plane, with the transverse momentum given as $p_T = \sqrt{p_x^2 + p_y^2}$.

2.2.2 Inner Detector



(a) ID with all its submodules in the barrel and endcap [12]. (b) Layers of the ID showing their distance to the beam [13].

Figure 2.4: ATLAS ID diagrams showing the different submodules, with their corresponding dimensions.

A cross-section of the Inner Detector (ID) system [14] is shown in Figure 2.4, highlighting the distance of each subsystem from the beampipe. The innermost part of the ID is the Insertable B-Layer (IBL), followed by three layers of pixel detectors. At 299 mm radial distance from the beam pipe, four layers of SemiConductor Tracker (SCT) modules are located before the Transition Radiation Tracker (TRT), which extends the overall ID detector size to a radius of 1082 mm. The ID allows for particle track reconstruction within $|\eta| < 2.5$.

The role of the ID is the trajectory tracking of charged particles to determine their charge and momentum. It is immersed in a 2 T magnet field generated by the ATLAS solenoid magnet system, that bends the trajectories of charged particles. The curvature radius is proportional to the particle momentum and its direction distinguishes positive from negative charges. The detected particle tracks allow for the reconstruction of primary collision vertices, which is important to distinguish pile-up collisions from the collision of interest, and of secondary decay vertices of longer-lived particles, which is crucial for the identification of e.g. B mesons or τ leptons.

IBL - Insertable B-layer After Run-1, during a long shutdown in 2013-2014, the pixel detector system was subject to maintenance and upgrades. Within this set of upgrades, a 4th pixel layer at a 3.3 cm distance from a new, smaller beam pipe (33 mm outer radius, originally 36 mm), which was the first in particle physics experiments [15, 16] and has led to significant improvements in interaction vertex reconstruction and identification of b-hadron jets.

Pixel Detector The innermost pixel layer, the IBL, is surrounded by three layers of pixel detectors, arranged in barrels around the beam pipe [17, 18]. The method of detection of charged particles is the measurement of deposited induced charges in a silicon layer, product of ionization. The first layer is at a distance of 50.5 mm from the beam pipe's centre. As can be seen in Figure 2.4a, the end caps of the pixel layer consist of 3 disks around the beampipe, stretching the length of the pixel component of the ID to 1.4 m length along the beam axis. The pixel detector consists of overall 1744 pixel modules with a nominal size of $50\mu\text{m} \times 400\mu\text{m}$ in the (ϕ, z) plane (ϕ, r for the disk panels), comprising over 80 million readout channels. The pixel and IBL part of the ATLAS detector is crucial for tracking, providing 4 pixel hits over the entire ID pseudorapidity coverage ($|\eta| < 2.5$.).

Semiconductor Tracker The pixel detector and IBL are located within SCT modules [19]. Similar to the pixel detector modules, the SCT modules are semiconductor-based, arranged into cylindrical layers around the beampipe in the barrel region, forming disks in the endcap. Since the SCT modules only provide precise location along one axis, two modules are combined back-to-back and rotated against each other to gain two dimensional spacial information. Four layers are arranged in the barrel, nine disks in each endcap side (see Figure 2.4a). Including the endcap disks, the SCT extends up to $|z| < 2735\text{mm}$.

Transition Radiation Tracker The last part of the ID is the TRT [20], in the barrel stretching from 554 mm to 1082 mm radial distance. This detector is composed of 4 mm diameter straw tubes, arranged in parallel to the beam pipe or radially in the barrel and end-cap, respectively. Within $|\eta| < 2.0$, three barrel rings and 18 end-cap units provide typically 36 hits per track. The straws are intertwined with polypropylene fibres for passing through particles to create transition radiation. Inside the straws is a thin tungsten wire, collecting charges drifting through the straws gas mixture (Xe, CO₂ and O₂). The level of radiation and collected charges in each straw can be used to discriminate between electrons and charged pions. The TRT only offers spatial information in the $(R - \phi)$ plane, no information in the z-direction can be extracted due to the straws orientation. There is a total of 50000 tubes in the barrel region, while the end-caps contain 320000 tubes.

2.2.3 Calorimeters

As previously mentioned, the ID system is surrounded by two calorimeters: the Electromagnetic Calorimeter (ECAL) and the Hadronic Calorimeter (HCAL), as shown in Figure 2.5. These calorimeters are designed to measure the energy and position of the incident particles, via the deposited energy by the secondary particle cascades produced by the incident ones. It covers the whole ϕ range and up to $|\eta| < 4.9$, with a finer granularity in the region that coincides with the ID. The calorimeter system allows for the discrimination between photons and electrons from hadrons (jets). Furthermore, it allows to measure the energetic imbalance (thanks to its

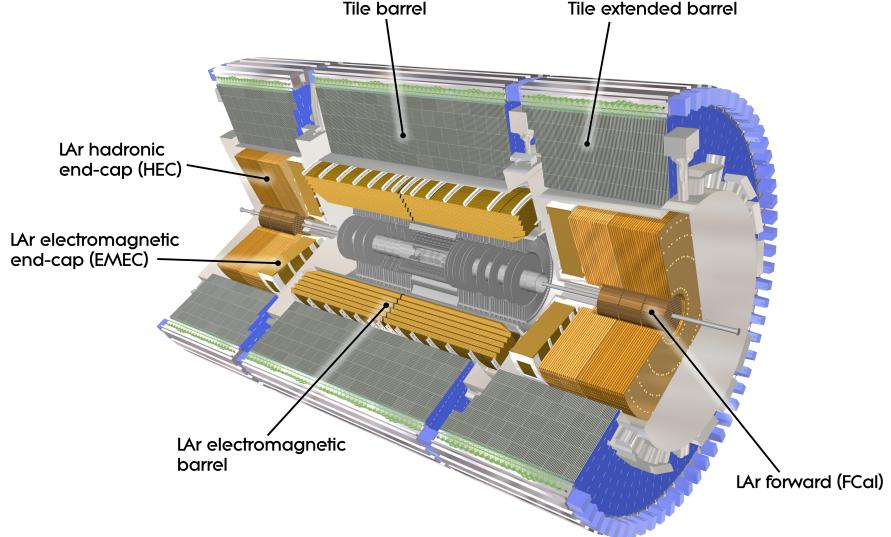


Figure 2.5: ATLAS calorimeter system, showing the Electromagnetic Calorimeter (ECAL) and the Hadronic Calorimeter (HCAL) [21].

total coverage and hermiticity) and it provides the trigger system with the necessary information for the event selection.

Both calorimeters are so-called sampling calorimeters with alternating layers of absorber and active material. The absorber layer triggers a shower development of consecutive interactions with the detector material, the active layer detects the signal. The shower development and properties are of vital importance for the particle identification, as it will be shown later. Two important quantities in connection with the calorimeters are the radiation length, X_0 , and the interaction length λ . The radiation length refers to the distance after which an particle (electrons for example) energy has been reduced to $1/e$ of its initial energy. The interaction length describes the mean free path before the occurrence of an hadronic interaction.

The design resolution of the system on the calorimetric energy is given by

$$\frac{\sigma(E)}{E} = \frac{a}{\sqrt{E}} \oplus b \oplus \frac{c}{E} \quad (2.6)$$

where \oplus means that the terms are summed in quadrature. The stochastic term $\frac{a}{\sqrt{E}}$ is related with the fluctuations on the shower developments, the constant term b takes into account the inhomogeneities of the detector, and the last term is associated with the electronic noise and is proportional to $\frac{1}{E}$. The value of the coefficients a and b depend on the incident objects. For the electrons' case in the ECAL, $a \sim 10\% \text{ GeV}^{1/2}$ and $b \sim 0.7\%$, while those for charged pions in the center of the detector are $a \sim 50\% \text{ GeV}^{1/2}$ and $b \sim 5\%$ [22].

Electromagnetic Calorimeter - ECAL

The ECAL specializes on the detection of electrons, positrons and photons, which deposit their energy in relatively dense showers: energetic electrons that radiate Bremsstrahlung photons,

while energetic photons convert to electron-positron pairs when traversing the dense material. The absorber is made of lead (Pb) with stainless steel sheets, while Liquid Argon ([LAr](#)) is used as the active material with copper and kapton electrodes for readout.

The calorimeter has an accordion geometry which provides complete ϕ symmetry without azimuthal cracks. It is divided into two half barrels covering the central detector region ($|\eta| < 1.475$), with a small (4 mm) gap at $z = 0$ and one end-cap on each side of the beamline ($1.375 < |\eta| < 3.2$). The transition region between the barrel and end-cap is referred as the *crack* region, and the majority of physics analysis using the [ECAL](#) require that the photons and electrons are outside of it. Additionally, the [LAr](#) technology is used for the hadronic calorimeters end-caps as well as a Forward Calorimeter ([FCAL](#)) ($3.1 < \eta < 4.9$).

The thickness of the [ECAL](#) is over $22 X_0$ in the barrel region, while over $24 X_0$ in the end-cap region. For photons, the distance at which the energy dropped to $1/e$ is $9/7 X_0$, therefore all the photon's electromagnetic energy is deposited in the [ECAL](#), and only a small part reaches the [HCAL](#).

The mode of measurement is as follows. The incident particles interact with the absorbent medium (Pb), initiating a shower of charged and neutral particles. The charged particles ionize the [LAr](#) medium and the electrodes, with the help of an applied magnetic field, collect the electrons produced in the ionization process. The total signal of the active medium is then proportional to the total real energy of the incident particle.

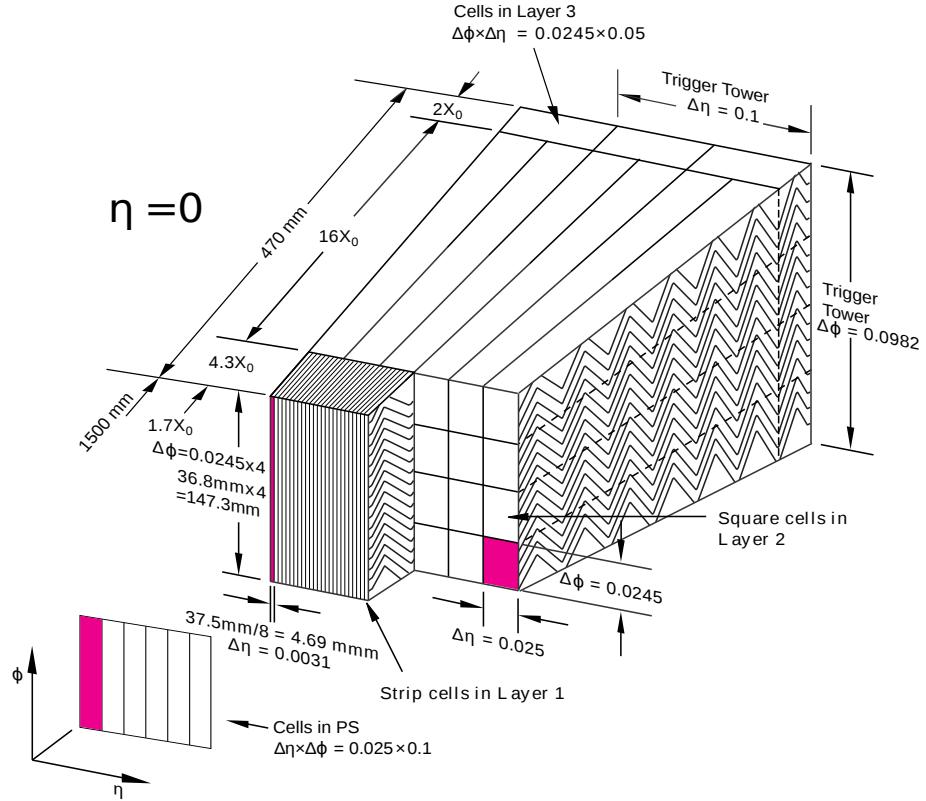


Figure 2.6: Segment of the [ECAL](#) showing the layer arrangement and cell dimensions in each layer [7].

Within the region accepted for precision measurements ($|\eta| < 2.5$ excluding the crack), the

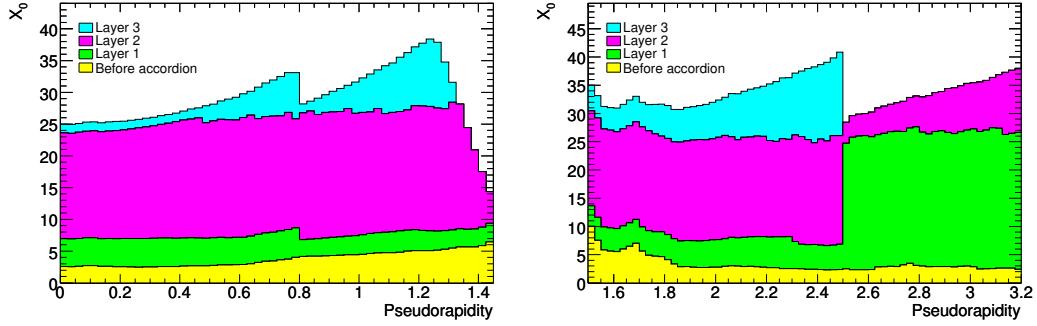


Figure 2.7: Radiation lengths as a function of $|\eta|$ for the [ECAL](#), separated for each sublayer [7].

[ECAL](#) is segmented in three longitudinal layers, displayed in Figure 2.6. The first layer consists on fine-granularity bands (also called the strip layer) which helps with the discrimination between isolated photons and pairs of photons spacialy closed originating from $\pi^0 \rightarrow \gamma\gamma$ decays. This layer has a constant thickness of $\sim 6X_0$ as a function of η (see Figure 2.7), and provides a precise measurement of this variable. For high energy photons and electrons, the majority of their energy is collected in the second layer, which has a lateral granularity of 0.025×0.025 in (η, ϕ) and a thickness of $\sim 24X_0$. The third layer collects the energy deposited by the tails of the electromagnetic shower, with thickness that varies between 2 and $12 X_0$. There is also a presampler (not shown in figures), that covers the region $|\eta| < 1.8$ that improves the energy measurement for particles that start showering before entering the calorimeter.

Hadronic Calorimeter - HCAL

Three hadronic calorimeter layers surround the [ECAL](#) and provide additional discrimination for electrons and photons when measuring the hadronic energy. The [HCAL](#) extends in pseudorapidity up to $|\eta| < 4.9$, allowing virtually the entirety of the solid angle to be covered from the interaction point. In the barrel region ($|\eta| < 1.7$), the tile calorimeter, a sampling calorimeter using steel as absorbing material and plastic scintillator tiles as active material [23], is located. It is divided into two parts ($|\eta| < 1.0$ and $0.8 < |\eta| < 1.7$). The scintillators, arranged in a periodic array, are connected to an optical fiber that carries the light produced by the passing particles to a photomultiplier tube. This array extends, in R , from 2.28 to 4.25 m. In the endcap region ($1.5 < |\eta| < 3.2$) there is an hadronic sampling calorimeter, the Hadronic End-Cap Calorimeter ([HEC](#)), with copper plates as absorber and liquid argon as active material. Each side of the endcap consists of two wheels, one behind the other with the flat Cu plates arranged perpendicular to the beam axis, with a radius of 2.3 m. Finally there is the [FCAL](#), a sampling calorimeter that extends the coverage of the system to $|\eta| < 4.9$, coaxial to the beam axis and located 4.7 m on either side of the interaction point. The main material of the modules is [LAr](#) (with copper or tungsten), and while not used for precision measurements, it provides information for computation of the missing transverse energy and reconstruction of jets in regions very close to the beam axis.

The [HCAL](#) has a thickness greater than 7.7λ in the barrel region (9.7λ in total if the [ECAL](#) is

counted). Analogous to the radiation length mentioned for the [ECAL](#), a hadronic interaction length is defined as the average distance over which the energy of a hadron is reduced to $1/e$ of its initial energy. Thus, all the energy with which the hadrons arrive at the [HCAL](#) is deposited there.

2.2.4 Muon spectrometer

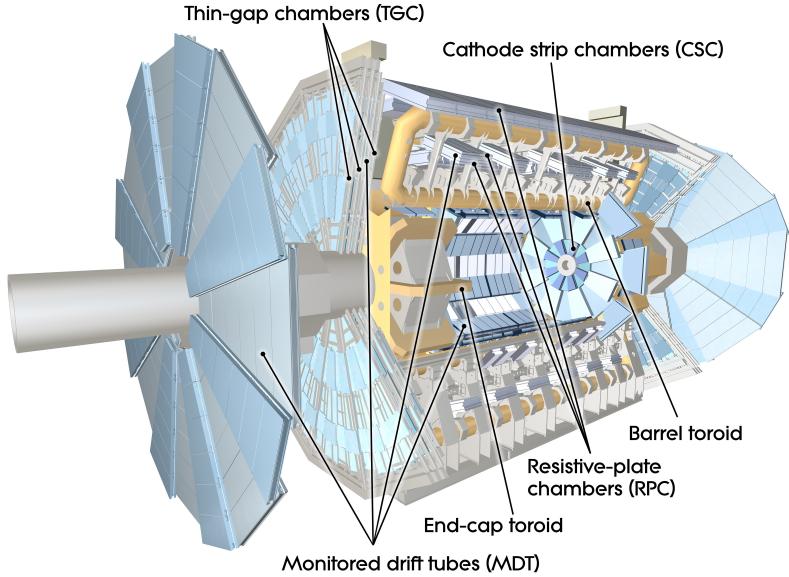


Figure 2.8: [ATLAS](#) Muon Spectrometer ([MS](#)) [7].

The high p_T muons generated at the interaction point have very high penetrating power and are poorly interacting. Therefore, the [MS](#) [24] is located in the outermost part of the [ATLAS](#) detector, embedded within the 4 T magnetic field generated by the barrel and endcap toroid magnets, and is designed to obtain high precision position and momentum measurements of high p_T muons. This is the largest subdetector and the one that gives [ATLAS](#) its size.

The [MS](#) is designed to precisely measure muons within $|\eta| < 2.7$ and to provide muon trigger information up to $|\eta| < 2.4$, shown in Figure 2.8, highlighting the different subsystems

The [MS](#) is composed of different types of muon detection chambers (see Figure 2.8). Monitored Drift Tubes ([MDTs](#)) are responsible for most of the precision measurements and cover the range of $|\eta| < 2.7$. They operate similarly to the [TRT](#), with tubes filled with an ionising gas and a central anode collecting the electrons produced, and the drift time is associated with the distance to the track. In the endcap region there are Cathode Strip Chamber ([CSC](#)) that have high spatiotemporal resolution and a coverage of $|\eta| > 2.0$. These chambers work by measuring the charge deposited on an anode as a result of the cascade of electrons created near the anode. Resistive-Plate Chambers ([RPCs](#)) provide a fast estimation of the muon momentum at trigger-level with a coverage of $|\eta| < 1.05$ ¹. [RPCs](#) measure the discharge between two parallel

¹ The innermost End-Cap layer has been replaced with the [ATLAS](#) New Small Wheel ([NSW](#)) after Run 2 [25]. It features MicroMegas as precision trackers as they provide better performance at the high rates expected in future LHC operations.

resistive plates subjected to a high potential difference, following the ionisation of the internal gas volume caused by the passage of energetic muons. Finally, in the endcap region, there are Thin-Gap Chambers (**TGCs**), similar in function to **CSCs**. They also provide information to the trigger system in this region and have a coverage of $|\eta| < 2.4$.

If hits in the **ID** and the **MS** can be associated with a single muon, a very good momentum resolution of up to

$$\frac{\sigma(p_T)}{p_T} = 0.02\% \cdot p_T [\text{GeV}] \oplus 2\% \quad (2.7)$$

is achieved. The momentum resolution degrades accordingly if a track is identified in only one of the two systems.

2.2.5 The Trigger System

The **ATLAS** trigger system [26–28] uses information from the detector to reject events that do not possess interesting physics (physics already known for example), reducing the event frequency from 40 MHz (bunch-crossing frequency mentioned in Section 2.1) to around 1.5 kHz. It is necessary to emphasize here the central role of the trigger system for the proper functioning of the whole experiment, being responsible for deciding which events are saved and, ultimately, which physics will be encountered (or not) during the event analysis. Without an efficient trigger system, all the subdetectors described above would be wasted. To achieve such a reduction in event frequency and, at the same time, have a high efficiency in selecting those of interest, the trigger system is composed of two consecutive levels capable of performing increasingly complex particle identification; a first hardware-based trigger level, Level-1 (**L1**), and then a high-level software-based trigger, the High Level Trigger (**HLT**). Each level allows events to be analyzed in greater detail, increasing the accuracy of the selection criteria and the complexity of the algorithms used.

Level-1 trigger

The trigger decision starts with the hardware-based **L1** trigger [29], which identifies Region of Interests (**ROIs**). These **ROI** consist of neighbouring cells in the **ECAL** and **HCAL** and are defined from the position in the calorimeter of each object found in a potentially interesting event, which extends as a cone from the interaction point along the detector. Regarding muons, it takes the information read by the **MS**, more specifically the **TGC** and **RPC** and allows to obtain a fast estimate of the muon p_T . The **L1** trigger also has a component that allows for topological requirements such as invariant mass selections and distance measures to be taken into account in the **L1** decision, referred as the Level-1 Topological (**L1Topo**).

The design of the **L1** allows to have an acceptability in the range of $|\eta| < 2.5$ for electrons, photons, muons and taus, up to $|\eta| < 3.2$ for jets, and $|\eta| < 4.9$ for the missing transverse momentum calculation. Using the **ROIs**, the **L1** trigger must make the decision to keep or discard the event, reducing the event rate from 40 MHz to less than 100 kHz in approximately 2.5 μ s,

time determined in part by the limited size of the memory buffers and in part by the time it takes for the muons produced in the event to reach the [MS](#). This final decision is done by the Central Trigger Processor ([CTP](#)), and then passes the [ROIs](#) to the next trigger level: the [HLT](#).

The High Level Trigger

When an event is accepted by the [L1](#), the [HLT](#) [30] executes a sequence of algorithms starting from the [ROIs](#) defined by the [L1](#), and allows to reduce the event rate that is stored at 1.5 kHz in 0.2 s. The reconstruction and identification of candidate particles in the [HLT](#) is evaluated in a sequence of steps where different algorithms are applied. If the selection fails in a certain step, the following steps are no longer executed to save execution time. In [HLT](#), the algorithms are grouped into sets of fast reconstruction algorithms executed first, and then a set of precision reconstruction algorithms similar to those used offline are executed, thanks to the latency time available. The fast reconstruction algorithms use the calorimeter and track information from the [ID](#) only within the [ROI](#) to perform candidate selection and identification, and perform background rejection as quickly and early as possible. If the candidate particle passes the criteria defined by the fast reconstruction selection, precision selection algorithms are run. These have access to detector information outside the RoI, at the highest granularity and including details on calorimeter energy calibration, sub-detector alignment and magnetic field mapping.

The exact sequence and type of algorithms considered at the [HLT](#) are defined in the trigger *menu*. This comprises a database of triggers, each of one defining a sequence of algorithms and requirements on these algorithms for an event to pass the [HLT](#). The trigger requirements are designed and budgeted in a way that the overall [HLT](#) rate does not exceed 1 kHz. In some cases, even the reduction in event rate achieved through the [HLT](#) algorithms for desired trigger requirements, such as low momentum triggers, is too high. To keep the overall [HLT](#) rate below 1 kHz in these cases, triggers can still be included in the menu, but with a prescale. A prescale is an artificial scaling of the trigger, only accepting every Nth trigger decision if the prescale factor is N. This allows triggers with an otherwise high rate to still collect events.

The [HLT](#) algorithms run on approximately 40 thousand CPU cores. In addition, partial event construction is used for trigger-level analysis, detector monitoring, and detector subsystem calibrations. Finally, the accepted events by the [HLT](#) are saved to a disk and distributed, available *offline* for any study or analysis.

2.3 Data-taking during Run-2

The operation of the [LHC](#) is organized into distinct periods known as data-taking Runs. Each run typically spans several years and is characterized by specific experimental conditions, including the energy at which the protons are collided and the intensity of the beams. Since its commissioning, the [LHC](#) has undergone multiple data-taking runs: Run-1 (2010-2013) oper-

ated at collision energies up to 8 TeV, Run-2 (2015-2018) at 13 TeV, and Run-3 (2022-present) at 13.6 TeV. Each data taking period, once the LHC announces stable beams, is divided into Luminosity-blocks (LBs) of approximately two minutes. At each LB, the instantaneous luminosity is practically constant and the beam conditions are stable. Due to the high complexity of the LHC and the ATLAS detector, it is expected to have inefficiencies in the detectors and sub-detectors and/or in the data acquisition chain. During each Run, each part of ATLAS is monitored and any failure or problem is registered, including inactive components, or problems on the LHC beam.

In order to guarantee the high-quality data, free from significant defects, the LBs and ranges within them that pass all the quality criteria are compiled into Good Runs List (GRL). The lists are produced and distributed in a centralized manner, in order to provide any ATLAS group with the same collection of LBs. Since during the runs different parts of the detector are available (in an optimal run, all of the subdetectors are available), there are multiple GRLs available to use. Each analysis, then, selects which GRL to use depending their tolerance to the subdetectors' faults.

The present thesis uses ATLAS data recollected from pp collisions during the Run-2 (2015-2018), at a centre of mass energy of $\sqrt{s} = 13$ TeV. During this run, the LHC delivered a total of 156 fb^{-1} , from which ATLAS collected 147 fb^{-1} . The total integrated luminosity available for Physics analysis is 140.07 fb^{-1} ², as seen from Figure 2.9a. The uncertainty in the combined integrated luminosity for Run-2 is 0.83% [31], obtained using the LUCID-2 detector [32]. Combining the 2022, 2023 and 2024 years of data taking for Run-3, 159 fb^{-1} of data was recollected, shown in Figure 2.9b [33, 34].

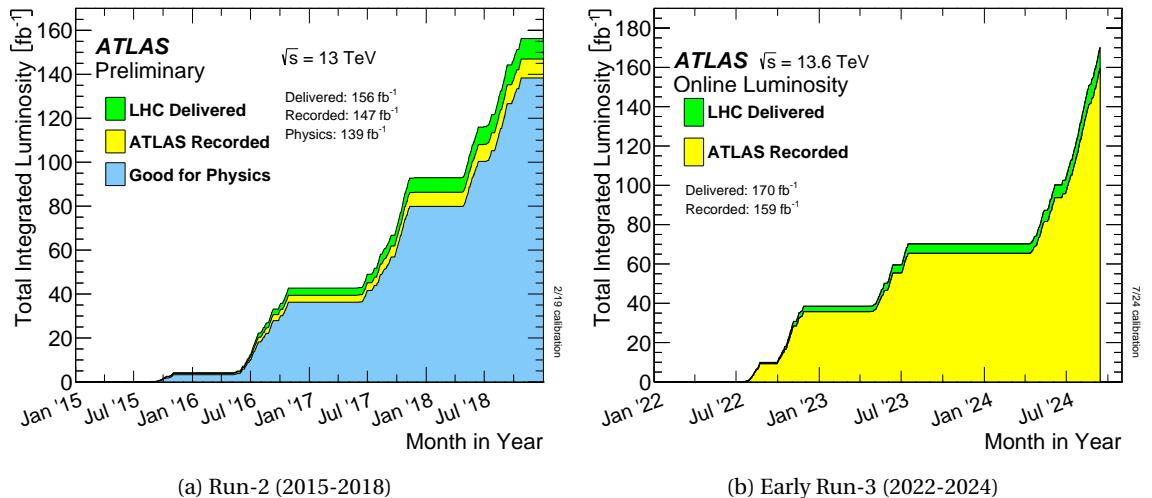


Figure 2.9: Luminosity delivered by the LHC and recorded by ATLAS during the Run-2 [31] and Run-3 data taking periods. For Run-2, the fraction of data good for physics analyses is also displayed.

Another important concept in ATLAS data acquisition is pileup, which occurs when particles produced in more than one pp collision arrive at the detector at the same time, or more generally, when signals overlap in a way that cannot be separated. When bunches of protons collide,

² First measurements and initial GRLs led to a total of 139 fb^{-1}

the probability of an interaction is proportional to the particle density, or better, to the particle flux, which is expressed by the instantaneous luminosity. The actual number of particle collisions that take place when two bunches intersect is a random variable that follows a Poisson distribution. For low luminosities, in most beam crossings, no collisions occur, but for high instantaneous luminosities, in most crossings many particle collisions occur at the same time. Depending on the subdetector and the type of measurement, it may or may not be possible to distinguish between particles coming from different simultaneous interactions. This is called in-time pile-up. In contrast, out-of-time pile-up includes the effects that arise when the time the detector needs to return to its waiting state is longer than the time between bunches crossing. A quantitative measure of pile-up and event activity is the mean value of pp inelastic interactions per bunches crossing, $\langle\mu\rangle$.

The maximum instantaneous luminosities increased by a factor of four over the four years of Run-2, resulting in an increase of $\langle\mu\rangle$ from 10 up to 60, as shown in Figure 2.10a. For Run-3, pileup was drastically increase up to values of 57 for year 2024, in average increasing up to 52 interactions per bunch crossing, displayed in Figure 2.10b.

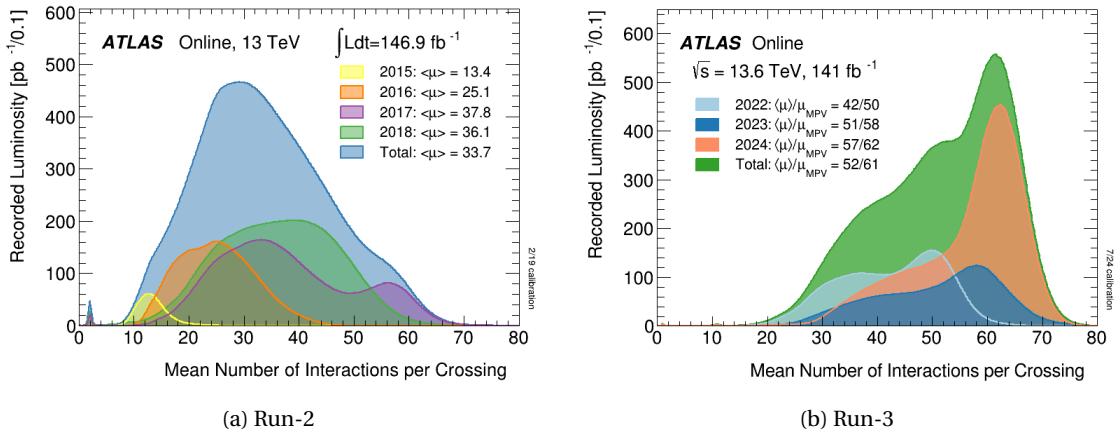


Figure 2.10: Pileup conditions during Run-2 and Run-3.

RECONSTRUCTION AND IDENTIFICATION OF PHYSICAL OBJECTS

3

“Champions keep playing until they get it right.”

Billie Jean King

The particles (and products of their decays) produced at every collision, interact with the detector in a particular manner according to their nature. The information recollected by all the sub-detectors described in the previous chapter allow for the reconstruction and identification of the physical objects present in each accepted event by the trigger system. Two types of reconstruction and identification exist. The *online* one, is carried out at the same time the pp collisions take place, and the *offline* one, done after the events are saved to storage. The reconstruction is done event by event, and is carried in the same way for events recorded by the [ATLAS](#) detector and for simulated [MC](#) events. In the following, a brief overview of the offline reconstruction and identification of the objects used in this thesis is given.

3.1 Track and vertex reconstruction

In a high-pile-up event, there can be of the order of 1000 charged particles passing through the [ATLAS](#) detector. The information from the [ID](#) (Section 2.2.2) is used to reconstruct the trajectories of charged particles, called *tracks*.

Tracking charged particles is a critical step in reconstruction. Tracks encode charged particles' momentum and trajectory, playing an essential role in particle identification and primary vertex reconstruction. As the inner detector is closest to the beamline and comprises minimally ionizing detector material with high granularity, it plays the main role in track reconstruction. A charged particle passing through different layers of [ID](#) leaves a signal via ionization. As the [ID](#) solenoidal field is homogenous, the resulting trajectory is circular in the xy plane. Five parameters shown in Figure 3.1 define charged particle tracks:

- q/p_T : the ratio of the charge and transverse momentum defining the curvature

- d_0 : the distance of the closest approach to the primary vertex in xy -plane defining the transverse impact parameter
- z_0 : the longitudinal impact parameter along the z -axis
- ϕ_0 : the azimuthal angle
- θ_0 : the polar angle of the particle direction at the closest point of approach [35].

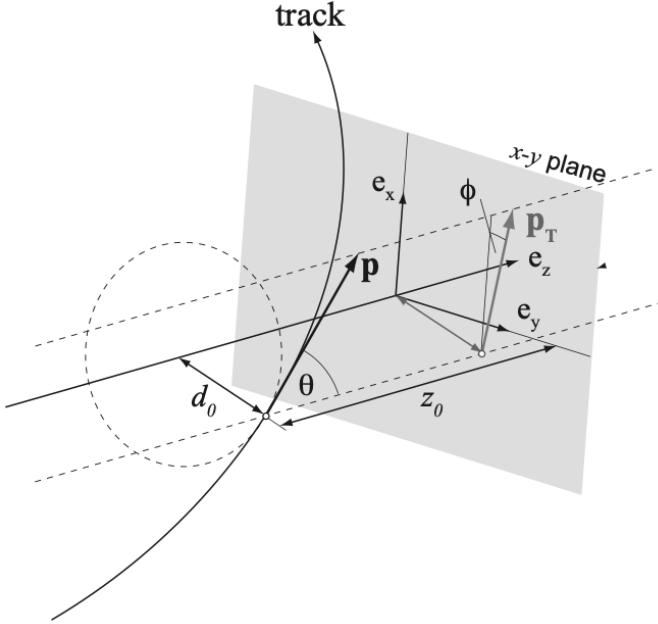


Figure 3.1: Schematic showing the tracking parametrization [36].

The track reconstruction used in Run-2 uses two complementary approaches: the *inside-out* approach, and the *outside-in* [37].

The first step in the inside-out track reconstruction is the seed-finding, where three hits in the silicon detector are searched for to seed the track reconstruction. Using these three hits and assuming an uniform magnetic field, a first estimate of the track parameters is obtained. Using the track seeds, the track is extrapolated to the other silicon layers, from which a combinatorial Kalman filter is used to estimate the track parameters. At this stage of the process there can be several track candidates for each track seed. Once the track is formed, an ambiguity resolution algorithm is applied to reassign shared clusters to the track with a better match [38], and the final track candidate is fitted using a global χ^2 method. The last part of the inside-out method consists on extending the tracks to the TRT, and including the TRT hits to the track, to improve the track's momentum resolution.

To improve the efficiency for tracks from decays displaced from the original collision point, an outside-in track reconstruction algorithm is also used. The track is seeded with hits from the TRT. The track is extended to include hits from the silicon detector, with an ambiguity solver again applied to mitigate the hit sharing between two tracks.

Primary and secondary vertices are of vital importance for the subsequent object reconstruction in **ATLAS**. In this step, the tracks found as explained previously are used as input to the vertexing algorithm [39, 40]. First of all, the Primary Vertex (**PV**) is defined as the location where two protons collide. **PVs** are reconstructed by matching up intersecting tracks, which proceeds in three main steps: seeding, track assignment, and fitting. The vertex with the largest $\sum p_T^2$ for all associated tracks is labeled as the hard-scatter vertex. There are some particles that decay rapidly after their production, such as τ leptons or heavier quarks (b or c -quarks), and their decay position can be measured. From the remaining tracks originated from these decays, it is possible to identify secondary vertices. All the remaining reconstructed vertices are considered to be pile-up.

3.2 Photons and electrons

The reconstruction of electrons and photons in **ATLAS** is based on the energy deposition in the **ECAL**. Since electrons and photons leave similar signals in the **ECAL**, their reconstruction is done simultaneously, distinguishing between them by the reconstructed track information left in the **ID**.

3.2.1 Reconstruction

The *offline* photon and electron reconstruction [41, 42] makes use of dynamic, variable-size clusters, connected topologically between the **ECAL** and **HCAL** cells [43], called topo-clusters. This approach allows for the clusters to recover energy from bremsstrahlung photons or from electrons from photon conversions. With this approach, there are three types of objects:

- Electrons: consists of a cluster built from the energy deposits in the **ECAL** and a matched track.
- Converted photons: consists of a cluster matched to a conversion vertex (or vertices)
- Unconverted photons: cluster matched to neither an electron track nor a conversion vertex.

The algorithm for the reconstruction of electrons and photons proceeds as shown in Figure 3.2. The reconstruction process begins with the topo-cluster formation. First, proto-clusters are formed in the **ECAL** and **HCAL** by grouping cells that have a required energy, and by subsequently adding neighbouring cells in four consecutive steps, obtaining the topo-cluster. Reconstructions starts only in those cases where the topo-clusters energy in the **ECAL** is greater than 400 MeV.

The algorithm also builds conversion vertices out of the refitted tracks and matches them to the selected topo-clusters. After the initial track-cluster matching and conversion building, the

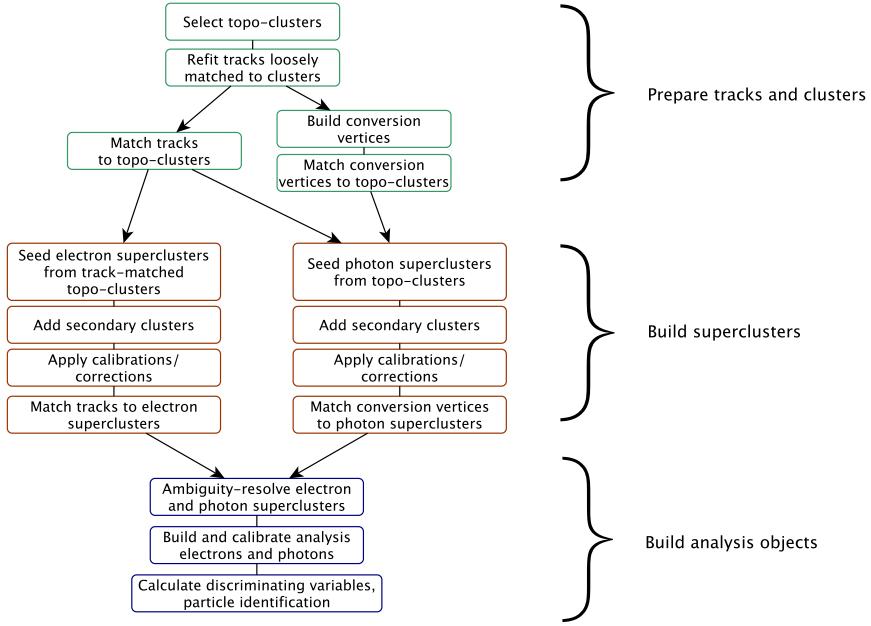


Figure 3.2: Diagram showing the reconstruction algorithm workflow for electrons and photons, extracted from Ref. [41]

electron and photon supercluster algorithms run separately in parallel. In the first stage, topo-clusters are evaluated for use as seed cluster candidates, which form the basis of superclusters; in the second stage, clusters near the seed candidates are identified as satellite cluster candidates, which may emerge from bremsstrahlung radiation or topo-cluster splitting. Satellite clusters are added to the seed candidates to form the final superclusters, if they pass the necessary selection criteria. After applying initial position corrections to the resultant superclusters, the reconstruction algorithm matches tracks to the electron superclusters and conversion vertices to the photon superclusters.

Since one object may be reconstructed as both an electron and a photon, an ambiguity resolution is performed to remove part of the overlap. However, some overlap is allowed in order to maintain a high reconstruction efficiency for electrons and photons, to which physics analyses may apply their own criteria. The final electrons and photons are then built and calibrated, facilitating the calculation of additional variables used for quality cuts and ambiguity resolution

3.2.2 Identification

In order to distinguish real photons (those coming from the collision) from background photons which have much larger production cross sections (coming from hadrons decays, also called fake photons), it is necessary to rely on a algorithm of identification with high signal efficiency and background rejection, for photon candidates with $p_T \sim 10$ GeV up to the TeV scale. Currently, photon identification in ATLAS is based on a set of rectangular cuts on **SSVs** computed from the energy deposited in the cells of the cluster in the first and second layer of the **ECAL**, and from the leakage to the **HCAL**. These variables describe the passage of the photons through

the calorimeters, characterizing the lateral and longitudinal electromagnetic showers. The full photon identification process is presented in Chapter 4, where the **SSVs** are explained one by one. Also, Chapters 5 and 6 present two approaches to correct the differences seen in these **SSVs** between data and **MC**.

Shower shape variable corrections

Due to the imperfection of the **ATLAS** simulation to model the **SSVs**, and that these variables are used as input to the identification step, it is important that they are corrected. Historically, the corrections are called Fudge Factors (**FFs**), and they comprised modifications to the mean value of the **SSVs**, calculated by minimizing the χ^2 value between the data and **MC SSVs**. More details on the **SSV** corrections are given in GIVE SECTION!!!

Additional corrections to all the reconstructed and identified photons in the simulation are applied event-by-event in the form of scale factors. These values, provided centrally by the EGAMMA group to **ATLAS**, represent the residual differences on the efficiencies between actual data and **MC**, computed as a function of the photon p_T and pseudo-rapidity η and separately for converted and unconverted photons.

3.2.3 Isolation

To further reduce the backgrounds of jets misidentified as photons and of hadron decay within the jets (such as the case of neutral pions), two isolation variables are defined: $E_T^{\text{cone}40}$ and $p_T^{\text{cone}20}$.

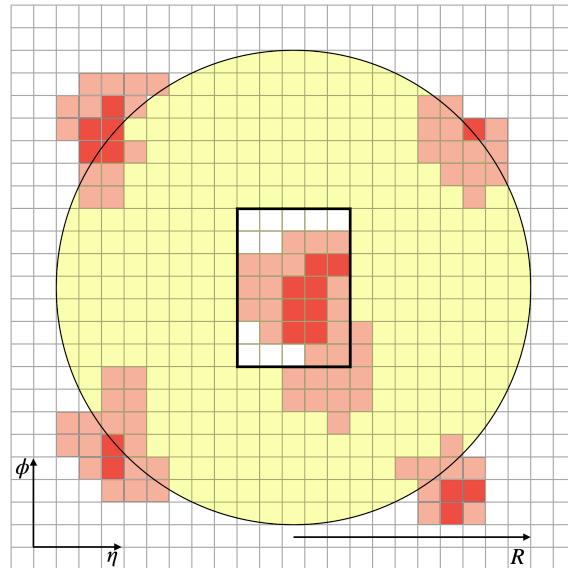


Figure 3.3: Diagram showing the calculation of the calorimetric isolation variable. When $R = 0.4$, $E_T^{\text{cone}40}$ is computed.

The procedure to compute the isolation energy $E_T^{\text{cone}40}$ is as follows, and showed in Figure 3.3. First, a cone of radius $\Delta R < 0.4$ is built around the photon or electron candidate, and the energies of all the cells in the topo-clusters (introduced in Section 3.2.1) whose bary-centers are

located inside the cone, are added together. Then, to this computed energy, the energy of all the cells in a 5×7 window (in units of $\eta \times \phi$ in the second layer of the [ECAL](#)) centered around the candidate are subtracted, in order to remove the energy of the candidate itself. Pile-up contributions and energy leakages outside the cone are also taken into account.

The track isolation variable $p_T^{\text{cone}20}$ is obtained by adding the p_T of the good-quality tracks in a cone of radius $\Delta R < 0.2$ around the electron candidate or in the direction of the converted photon cluster. The track associated to the track or to the converted photon are excluded from this computation, as well as those tracks which do not pass the *good-quality* track requirement. A *good-quality* track is defined as one in which the p_T is $p_T > 1$ GeV, and it has a minimum distance to the primary vertex along the z -axis of $|z_0 \sin\theta| < 3$ mm.

In general, for photons and electrons, there is no other energy deposited in the cone around the candidate, apart from the low-energy objects originating from the remnants of the collision, multiple interactions and pile-up. On the other hand, for fake photon candidates and non-direct photons, additional energy is observed within the cone, originating from objects accompanying the jet.

Table 3.1: Summary of electron and photon isolation [WPs](#) use throughout this thesis.

Object	WP	Calorimetric Isolation	Track Isolation
Photon	FixedCutLoose	$E_T^{\text{cone}20} < 0.065 \times p_T$	-
	FixedCutTightCaloOnly	$E_T^{\text{cone}40} < 0.022 \times p_T + 2.45$ GeV	-
	FixedCutTight	$E_T^{\text{cone}40} < 0.022 \times p_T + 2.45$ GeV	$p_T^{\text{cone}20} / p_T < 0.05$
Electron	Loose_VarRad	$E_T^{\text{cone}20} < 0.2 \times p_T$	$p_T^{\text{cone}30} / p_T < 0.15$
	HighPtCaloOnly	$E_T^{\text{cone}20} < \max(0.015 \times p_T, 3.5$ GeV)	-

From the calorimetric and track isolation different [WPs](#) can be defined separately for both electrons and photons. For electrons, two strategies are defined: either to achieve a fixed efficiency, or to apply fixed cuts on the isolation variables. In the case of photons, there are [WPs](#) which do not use both the isolation variable, as is the case of the [FixedCutTightCaloOnly WP](#), which only uses calorimetric isolation. The definitions of the different [WPs](#) used throughout this thesis is shown in Table 3.1. Also, it is common to define the following variables for the photon [FixedCutTight WP](#):

$$E_T^{\text{iso}} = E_T^{\text{cone}40} - 0.022 \times E_T - 2.45 \text{ GeV} \quad (3.1)$$

$$p_T^{\text{iso}} = p_T^{\text{cone}20} / E_T \quad (3.2)$$

therefore leaving the [FixedCutTight WP](#) defined as

$$E_T^{\text{iso}} < 0 \text{ GeV} \quad (3.3)$$

$$p_T^{\text{iso}} < 0.05 \quad (3.4)$$

3.3 Muons

The rate of bremsstrahlung radiation is inversely proportional to the square of a particle's mass. Since muons are about 200 times heavier than electrons, they primarily interact with the de-

tector material through ionization. Therefore, muons are minimally ionizing particles that do not create electromagnetic shower in the calorimeters and pass through all layers of the [ATLAS](#) detector. Hence, muon detection relies on track measurements from the [ID](#) and [MS](#). The combination of the two subdetectors define four types of muons, depending on the used information for the reconstruction:

- Combined Muons ([CBs](#)): muons reconstructed from a global refit of [ID](#) and [MS](#) tracks
- Segmented Muons ([STs](#)): muons reconstructed from a fitted [ID](#) track and [MS](#) segment track
- Calorimetric Muons ([CTs](#)): muons reconstructed using [ID](#) track matched to the minimum ionizing energy deposits in the calorimeters
- Standalone/Extrapolated Muons ([MEs](#)): muons reconstructed solely from [MS](#) tracks.

The overlap between different types of muons is resolved as follows. When two muon types share the same [ID](#) track, the order of preference is: first [CB](#), then [ST](#) and finally [CTs](#). The overlap with [MEs](#) is solved by analyzing the hits of the tracks, selecting those tracks with the best fit and the highest number of hits.

For the muon identification, quality cuts are applied to distinguish isolated muons from those coming from background processes, mainly from pion and kaon decay. The variables with good discriminating power used are described in Ref. [44]. Four identification selections are defined: Loose, Medium, Tight, and High- p_T . The first three categories are inclusive, and Medium being the default selection in [ATLAS](#). Finally, the muon candidates to be used by the analyses are asked to satisfy the isolation requirements, both at track and calorimetric levels, analogously to what was detailed for photons in the previous section. For the first case, a variable similar to that used for photons is used, but with a variable-radius cone $\Delta R = \min(10 \text{ GeV}/p_T, 0.3)$ around the muon p_T , excluding the muon track. For calorimetric isolation the same variable $E_T^{\text{cone}40}$ is used, with the difference of using a radius of $R = 0.2$, instead of 0.4 as before. Based on these variables, 7 isolation selection criteria (7 [WPs](#)), optimized for different analyses, are defined.

3.4 Jets

Due to color confinement in Quantum Chromodynamics ([QCD](#)), a quark or gluon cannot exist on its own and goes through hadronization to form a collimated color-neutral stream of particles, *jets*. Generally, jets penetrate through the [ECAL](#) and get fully absorbed by the material in the hadronic calorimeter. In the following, a brief description of the typical clustering method adopted by [ATLAS](#) is given. Also, the two existing types jet reconstruction are described.

3.4.1 Anti- k_t jet clustering algorithm

Given that jets are constituted by a high number of particles that leave energy depositions in the **ECAL** and **HCAL** and tracks in the **ID**, a clustering algorithm groups together constituents in the event to define the jets. Said algorithm is called the anti- k_t algorithm [45]. In the same way as for electrons and photons, **ATLAS** jet reconstruction relies on the formation of topo-clusters: grouped energy depositions in the calorimeters cells using a sequential combination algorithm. Then, the anti- k_t algorithm combines the topo-clusters with the following steps:

- Measure the distance between all topo-clusters between themselves, and of each topo-cluster with the beam:

$$d_{ij} = \min(p_{T,i}^{-2}, p_{T,j}^{-2}) \frac{\Delta_{i,j}^2}{R^2} \quad (3.5)$$

$$d_{iB} = p_{T,i}^{-2} \quad (3.6)$$

where $\Delta_{i,j}^2 = \Delta\phi_{i,j}^2 + \Delta\eta_{i,j}^2$ and R is the jet-radius.

- If the minimum of all the distances computed previously is d_{iB} , the topo-cluster i is classified as a jet, and is discarded in successive iterations.
- If the minimum of all the distances is d_{ij} , topo-clusters i and j are combined, all the distances are computed again with this new topo-cluster and the iteration is carried all over again.

This process is repeated until all the particles in the event have been clustered.

The anti- k_t algorithm starts by clustering the radiation around the hardest particle in the event since the leading p_T particle will define the $\min\left(\frac{1}{p_{T,i}^2}, \frac{1}{p_{T,j}^2}\right)$ term in the d_{ij} definition. This allows jets in the event to have a stable direction early on the combination process. The anti- k_t algorithm is preferred to other sequential jet algorithms since jets have regular boundaries which are approximately conical, shown in Figure 3.4. Jets originating from quarks or gluons in general are called small- R jets and a radius of $R = 0.4$ is used for their reconstruction. On the other hand, jets representing massive particles which decay hadronically are called large- R jets, and use $R = 1.0$. The usage of a wider cone helps to include the majority of the particles product of the decay.

3.4.2 Calorimeter Jets

One way to reconstruct jets is based on energy deposits in the calorimeter. In a similar way to what has been explained for electrons and photons in Section 3.2.1, energy depositions on the cells of the **ECAL** and **HCAL** are used to build topo-clusters, which approximates the energy deposits of individual hadrons [42, 43]. Jets reconstructed in this manner and clustered with the anti- k_t algorithm with a radius of $R = 0.4$ are referred as EMTOPO jets, and are the proxies for the individual quarks and gluons. In the jet reconstruction, only the topo-clusters with positive net energy are included.

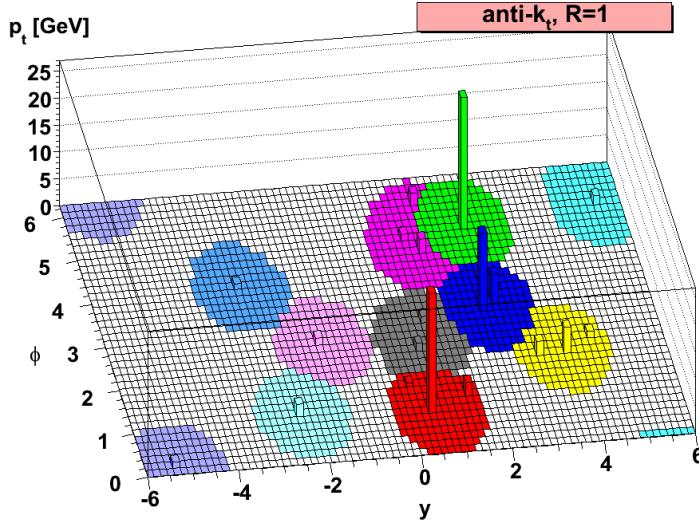


Figure 3.4: Schematic representation of the anti- k_t algorithm for jet clustering [45].

3.4.3 PFlow Jets

Another approach for jet reconstruction is taken in the particle flow algorithm, in which measurements from both the tracker and the calorimeter are combined to form the signals, which ideally represent individual particles. In this algorithm, tracks are matched to topo-clusters using proximity in (η, ϕ) space, also accounting for the size of the topo-cluster. The tracks are only “matched” if the cluster carries more than 10% of the track’s momentum. Sometimes the topo-cluster fails to cluster all of the hadron’s energy in a single topo-cluster. In cases where the expected energy of the track is less than the expected track’s energy, a “split shower recovery” combines nearby topo-clusters to form a topo-cluster set. From this topo-cluster set, the expected energy of the track is subtracted from the topo-cluster’s cells, starting with high-energy density cells. If the residual energy is consistent with the resolution of the expected track energy, the residual energy is also subtracted in the last step called “remnant removal”.

The result of this algorithm is a set of tracks, modified and unmodified topo-clusters which are the Particle Flow (**PFlow**) objects. The **PFlow** objects can also be clustered with the anti- k_t algorithm and the same $R = 0.4$ to form **PFlow** jets.

There quite a lot of benefits of using the **PFlow** algorithm over the EMTOPO one:

- The momentum resolution of the tracker is significantly better than the calorimeter’s energy resolution for low-energy charged particles.
- Allows for a higher acceptance for softer particles. Tracks are reconstructed for charged particles with a minimum p_T of 400 MeV, and oftentimes these particles’ energy deposits do not pass the thresholds to seed topo-clusters.
- Improved angular resolution of a single charged particle as it uses the tracker information instead of the calorimeter’s.

- Low- p_T charged particles originating within a hadronic jet are swept out of the jet cone by the magnetic field by the time they reach the calorimeter. By using the tracks azimuthal coordinate at the perigee, these particles are clustered into the jet.
- It is possible to remove those tracks originating from pile-up, knowing that these do not originate from the PV.

However, particle flow introduces a complication. For any particle whose track measurement ought to be used, it is necessary to correctly identify and subtract its signal in the calorimeter to avoid double-counting. In the particle flow algorithm, a boolean decision is made as to whether to use the tracker or calorimeter measurement. The ability to accurately subtract all of a single particle energy, without removing energy deposited by other particles, forms the key performance criterion upon which the algorithm is optimised.

In this thesis, PFlow jets are considered, as they have proven to provide better jet reconstruction [46], principally for those with low p_T and in the E_T^{miss} reconstruction [47].

3.4.4 Jet calibration

Once the jets are reconstructed, their 4-momentum is corrected to match the kinematics of a truth jet¹, as shown in Figure 3.5. The first three corrections account for contamination from the underlying pile-up distribution and fluctuations due to the origin of the jet [48]. The Global Sequential Calibration improves the jets p_T resolution (and associated uncertainties) by sequentially removing the dependence of the reconstructed jet response ($R = E^{\text{reco}}/E^{\text{truth}}$) on key event observables. Finally, the residual differences between data and MC are accounted for by measuring the momentum imbalance in $Z + \text{jets}$, $\gamma + \text{jet}$ and multi-jet events.

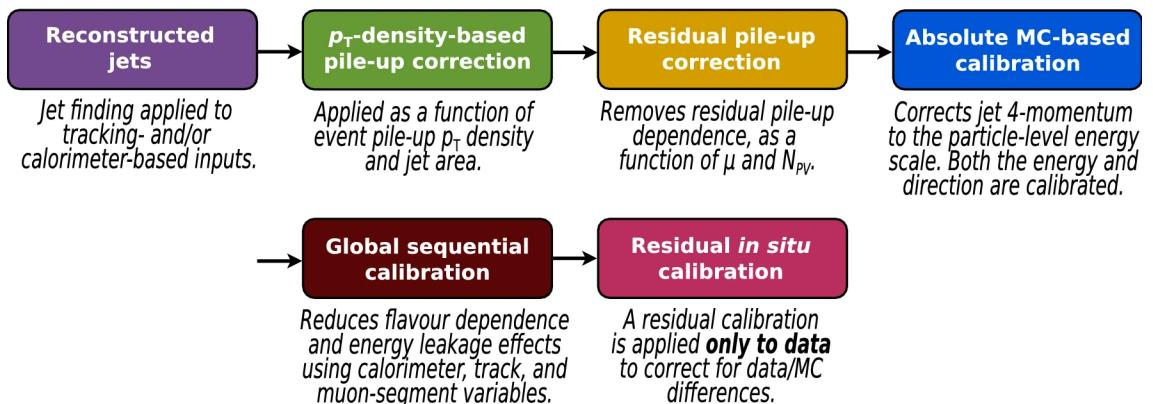


Figure 3.5: PFlow 4-momentum jet calibration steps [48].

To reduce the number of jets with a considerable fraction of energy coming from pile-up, the Jet vertex Tagger (JVT) algorithm is used. This algorithm update to NNJVT reconstructs a multivariate discriminant that combines, among other quantities, the Jet vertex Fraction (JVF) (fraction of the tracks' p_T associated to a jet originating from the PV, and the total number of tracks) and

¹ The truth jets come from the anti- k_t clustering of the stable final state truth particles (hadrons and charged leptons) in simulation.

the number of [PVs](#) in the event N_{PV} . As the jets that do not originate from the hard-scatter interaction are generally softer, the [JVT](#) cut is applied only to jets with $p_{\text{T}} < 60 \text{ GeV}$ and $|\eta| < 2.4$. The default [JVT WP](#) is 96% efficient for hard-scatter jets.

3.5 Jet flavor tagging

Heavy hadrons decays are governed mainly by the heaviest hadron in the decay cascade. A b -hadron generally decays through a cascade to a c -hadron, which in turn decays to an s -hadron, etc, which leads to the existence of multiple vertices.

Flavor Tagging ([FTAG](#)) is the classification of jets containing b -hadrons (b -jets), c -hadrons (c -jets) or neither b - or c -hadrons (light-flavour jets, or l -jets) by using algorithms sensitive to the distinctive properties of the respective classes. These complex algorithms rely on the multiple vertices, on the high mass, high decay multiplicity and characteristic decay modes of the b - and c -hadrons, as well as on the properties of heavy-quark fragmentation.

In [ATLAS](#) a two-step approach is employed to reconstruct key characteristics of heavy-flavour jets. In the first stage, low-level algorithms use complementary methods to extract track information from the charged particles linked to the jet. Some algorithms focus on the properties of individual tracks, while others analyse their correlations or combine them to explicitly reconstruct displaced vertices. In the second stage, the outputs from these algorithms are integrated into a high-level algorithm using multivariate classifiers to optimize performance. Over time, the algorithms have evolved significantly, starting with likelihood-based discriminants and boosted decision trees during [LHC](#) Run-1, and progressing to more advanced methods like recurrent and deep neural networks, resulting in notable improvements on the identification performance [49–52].

Starting in Run-3, a novel Transformer-based "GN2" algorithm is developed by the [FTAG](#) combined performance group in [ATLAS](#). The GN2 algorithm is a single trained model which supersedes DL1d [53] and the low level algorithms that feed it. It is based on GN1 [54], and was quickly refined into GN2. GN2 replaces the Graph Attention Network [55] used by GN1 with a Transformer [56], and also benefits from several other architectural optimisations and from an order of magnitude more training statistics.

GN2 directly accepts information about the jet and associated tracks and as such does not depend on other flavour tagging algorithms. GN2 retains the two auxiliary training objectives that were introduced with GN1: the grouping of tracks originating from a common vertex, and the prediction of the underlying physics process from which each track originated.

This new algorithm is also prepared to provide identification of c -jets and jets originating from τ decays. Outputs of this tagger comprise the probabilities of a jet to be tagged as a b -, c -, τ - and light-flavor jet, labeled as p_b , p_c , p_τ and p_w , respectively.

3.5.1 b -jet identification performance

In order to evaluate the performance of the tagger of identifying b -jets at a constant efficiency, the ability to reject c -, τ - and light-flavor jets is measured. The tagger output probabilities are combined to build a single discriminant GN2_b , defined as

$$\text{GN2}_b = \log\left(\frac{p_b}{f_c p_c + f_\tau p_\tau + (1 - f_c - f_\tau) p_u}\right). \quad (3.7)$$

The parameters $f_{c(\tau)}$ are free and determine the weighting between $p_{c(\tau)}$ and p_u in the discriminant. The specific values of these parameters are determined through an optimisation procedure aimed at maximising the rejection of c -jets (τ -jets) and l -jets and found to be 0.2 (0.01).

From the tagger discriminant score, several **WPs** can be defined, simply by requiring the GN2_b score to be above a certain threshold. The **FTAG** working group provides centrally to the whole **ATLAS** collaboration 5 different **WPs** to achieve a fixed overall b -tagging efficiency: 65, 70, 77, 85 and 90% efficiency, and are shown in Figure 3.6. In said figure, the data and **MC** GN2 tagger distributions are compared, where the different flavour contributions are shown with different colors.

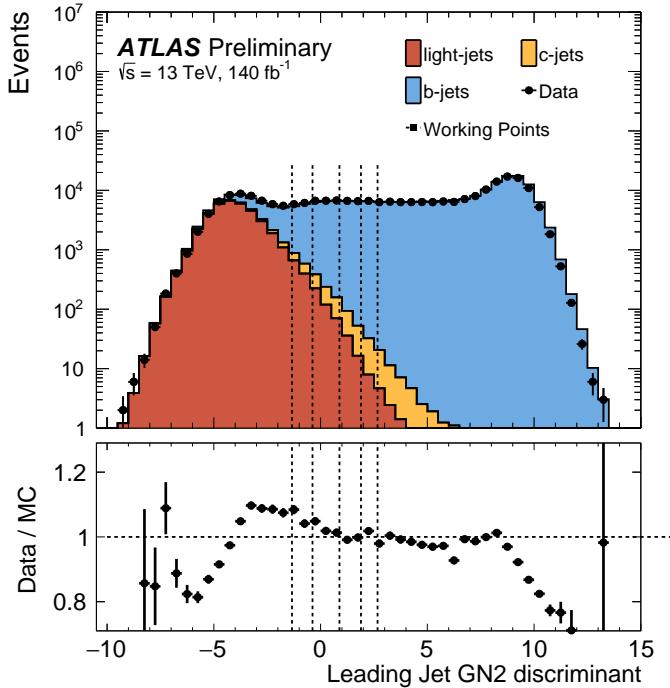


Figure 3.6: GN2 tagger discriminant comparison between data and single-lepton $t\bar{t}$ **MC** simulation. The l -, b - and c -jets are contributions shown with different colors, and the 5 b -tag **WPs** shown with the dashed vertical lines. From left to right, the dashed lines represent the 90, 85, 77, 70 and 65% efficiency **WPs**. The lower pad shows the ratio between data and the stacked **MC** [57].

One key challenge of b -tagging is the decrease in efficiency at higher p_T . In this high- p_T regime, particles become more collimated and they tend to travel further in the **ID** before decaying, potentially leading to a decay track with spurious hits. The degraded efficiency is visualised

in Table 3.2, where tagging efficiencies are shown for b -jets, along with c -jets, l -jets and τ -jets rejections, in the low and high- p_T regimes. The values shown are computed by using different samples, where $t\bar{t}$ is used at low- p_T and Z' decay events² are used in the high- p_T region. It can be seen that the b -tag efficiency drops by 30% for higher p_T jets.

Table 3.2: Measured b -tagging efficiencies and c -jets, l -jets and τ -jets rejections in the low and high- p_T regime.

Sample	p_T range [GeV]	b -efficiency	c -rejection	light-flavor rejection	τ -rejection
$t\bar{t}$	$20 < p_T < 250$	0.76	17.52	448.61	71.15
Z'	$250 < p_T < 6000$	0.41	20.27	179.99	452.94

3.5.2 c -jet identification performance

Similar to b -tagging, a single discriminant can be built from the output probabilities of the tagger in order to identify c -jets against b -jets, τ -jets and l -jets:

$$\text{GN2}_c = \log\left(\frac{p_c}{f_b p_b + f_\tau p_\tau + (1 - f_b - f_\tau) p_u}\right) \quad (3.8)$$

where now the $f_{b(\tau)}$ are the free parameters that control the rejection between b -, τ - and light-flavor jets. Using the same optimisation procedure as for b -tagging, the values for $f_{b(\tau)}$ are found to be 0.3 (0.05).

Thanks to the great b -tagging efficiency achieved by GN2, it is possible to design a c -tagging [WP](#) after applying b -tagging-veto, further separating c -jets from l -jets. By building this simultaneous tagging [WP](#) and assuming the fraction of τ -jets to be negligible, one can separate light-, c - and b -jets in three orthogonal regions. Starting from requiring a jet to *not* pass the 77% b -tagging [WP](#) (b -tag veto), three different c -tagging [WPs](#) are defined by fixing the GN2_c score: 10, 30 and 50% c -tag efficiency. The efficiency and rejection measurements for the both samples described above, after applying the 50% c -tag [WP](#) are shown in Table 3.3.

Table 3.3: Measured c -tagging efficiencies and b -jets, l -jets and τ -jets rejections in the low and high- p_T regime. The values shown correspond to those after applying the b -tagging 77% [WP](#) veto and the 50% c -tagging [WP](#). **rejection values not correct!**

Sample	p_T range [GeV]	c -efficiency	b -rejection	light-flavor rejection	τ -rejection
$t\bar{t}$	$20 < p_T < 250$	0.467	17.52	448.61	71.15
Z'	$250 < p_T < 6000$	0.344	20.27	179.99	452.94

Add plots with GN2 distributions?

² The leptophobic axial-vector Z' model is a simplified Dark-Matter model in which one of the theorised decay products are a pair of quarks.

Part III

Photon shower shape corrections

PHOTON IDENTIFICATION AND SHOWER SHAPES

4

“Champions keep playing until they get it right.”

Billie Jean King

The [ECAL](#) was presented briefly in Section 2.2.3, where the measurement mechanism and all the layers it has was described. In this subdetector, photons deposit their energy via electron-positron pair creation and bremsstrahlung radiation, creating an electromagnetic ([EM](#)) shower. The [ECAL](#) does a great job to compute the energy of the [EM](#) shower, but identifying the initiating particle remains a challenging task. However, by virtue of the different layers and granularities in the [ECAL](#), different characteristics of these [EM](#) showers can be studied, and are encoded by different variables called Shower Shape Variables ([SSVs](#)).

4.1 Shower shapes

As mentioned in Section 3.2.2, photon identification relies on rectangular cuts applied to [SSVs](#) that lead to an excellent separation power between real isolated photons from fake photons originating from hadrons. These [SSVs](#) are computed from the photon candidates' energy deposits in the [ECAL](#) and [HCAL](#) cells, and serve to describe the passage of the photons candidates throughout the calorimeters, characterizing the lateral and longitudinal [EM](#) showers.

In general, real photons produce narrower energy deposits in the [ECAL](#), and have lower leakages to the [HCAL](#), compared to those photons provenient from hadrons, where the presence of additional neighbouring hadrons close to the fake photon tend to widen the showers. Furthermore, since the first layer of the [ECAL](#) consists on fine strips, it is possible to discriminate photon candidates coming from $\pi^0 \rightarrow \gamma\gamma$ decays, characterized by two local maxima due to the presence of two nearby photons.

In the following, the [SSVs](#) used for photon identification are detailed, and shown summarised in Table 4.1. The first variable makes use of the energy measured in the [HCAL](#):

- Hadronic leakage: is the transverse energy deposited in the [HCAL](#), normalized to the

Table 4.1: Discriminative SSVs used for photon identification. The three columns on the right denote whether the variable is used for the *loose* (L), *medium* (M) or *tight* (T) identification WP.

Category	Description	Name	L	M	T
Hadronic leakage	Ratio of E_T in the first sampling layer of the HCAL to E_T of the EM cluster (used over the ranges $ \eta < 0.8$ and $ \eta > 1.52$)	$R_{\text{had}1}$	✓	✓	✓
	Ratio of E_T in the HCAL to E_T of the EM cluster (used over the range $0.8 < \eta < 1.37$)	R_{had}	✓	✓	✓
EM second layer	Ratio of the energy in $3 \times 7 \eta \times \phi$ cells over the energy in 7×7 cells centered around the photon cluster position	R_η	✓	✓	✓
	Lateral shower width in η	$w_{\eta 2}$	✓	✓	✓
	Ratio of the energy in $3 \times 3 \eta \times \phi$ cells over the energy of 3×7 cells centered around the photon cluster position	R_ϕ	✓	✓	
EM first layer	Lateral shower width in 3 strips around the maximum	$w_{\eta 1}$ or w_1	✓	✓	
	Total lateral width	$w_{\text{s tot}}$	✓	✓	
	Energy outside the core of the three central cells, within seven cells divided by the energy within the three central strips	f_{side}	✓	✓	
	Difference between the energy associated with the second maximum in the strip layer with the minimum value found between the first and second maxima.	ΔE	✓	✓	
	Ratio of the energy difference between the maximum energy deposit and the energy deposit in the secondary maximum in the cluster to the sum of these energies	E_{ratio}	✓	✓	
	Ratio of the energy in the first layer to the total energy of the EM cluster	f_1	✓	✓	

energy deposited in the **ECAL**:

$$R_{\text{had}(1)} = \frac{E_{\text{T}}^{\text{had}}}{E_{\text{T}}^{\text{EM}}} \quad (4.1)$$

In order to minimize the effects of resolution degradation, in the barrel-endcap transition region of the **HCAL** ($0.8 \leq |\eta| \leq 1.37$) the energy deposit in the whole **HCAL** is used (R_{had}). On the remaining of the detector, only the energy deposited in first layer of the **HCAL** is used ($R_{\text{had}1}$).

The following variables use the second-layer information of the **ECAL**:

- Lateral energy profile in η :

$$R_\eta = \frac{E_{3 \times 7}^{s2}}{E_{7 \times 7}^{s2}} \quad (4.2)$$

where $E_{i \times j}^{s2}$ is the energy sum in the second calorimeter layer contained in a window of $i \times j$ cells (units of $\eta \times \phi$ cells), centered at the most energetic cell. This variable gives a measure of the showers' width in the η direction.

- Lateral energy profile in ϕ :

$$R_\phi = \frac{E_{3 \times 3}^{s2}}{E_{3 \times 7}^{s2}} \quad (4.3)$$

defined in a similar way as R_η . However, this variable behaves very different for converted and unconverted photons. Due to the action of the magnetic field, the electrons and positrons are curved into opposite directions in ϕ , having as a result, **EM** showers much wider in the case of converted photons than those for unconverted ones.

- Lateral shower width in η :

$$w_{\eta^2} = \sqrt{\frac{\sum E_i \eta_i^2}{\sum E_i} - \left(\frac{\sum E_i \eta_i}{\sum E_i} \right)^2} \quad (4.4)$$

measures the proper width of the **EM** shower, where E_i is the energy in the i -th cell of the **ECAL**, measured in a window of 3×5 cells in $\eta \times \phi$.

The following variables use the information from the first **ECAL** layer, composed of the strip cells that allow for a high η resolution and allows for a good separation between isolated photons from photons product of the π^0 decay. Figure 4.1 shows the difference in the energy deposited in the **ECAL** between the two cases mentioned previously.

- Lateral energy profile in η

$$f_{\text{side}} = \frac{E_7^{s1} - E_3^{s1}}{E_3^{s1}} \quad (4.5)$$

measures the energy outside the core of the three central strips within a window of 7 cells, divided by the energy in the three central cells.

- Lateral shower width in η (3 strips)

$$w_1 = \sqrt{\frac{\sum E_i (i - i_{max})^2}{\sum E_i}} \quad (4.6)$$

where i runs over all cells in a window of 3 cells around the highest-energy-cell. This variable measures the width of the **EM** shower in the first layer of the calorimeter.

- Lateral shower width in η (full). It is defined in a similar way as w_1 , but uses all the cells in a window of $\delta\eta \times \delta\phi = 0.0625 \times 0.2$, corresponding to approximately to 20×2 strips $\eta \times \phi$.
- Energy difference

$$\Delta E = E_{\text{max},2}^{s1} - E_{\text{min}}^{s1} \quad (4.7)$$

represents the energy difference between the second maximum and the minimum reconstructed energy between the two maxima in the strip layer.

- Energy ratio

$$E_{\text{ratio}} = \frac{E_{\text{max},1}^{s1} - E_{\text{max},2}^{s1}}{E_{\text{max},1}^{s1} + E_{\text{max},2}^{s1}} \quad (4.8)$$

is the ratio of energy difference between the two maxima, normalized to the sum of those energies, in the strip layer.

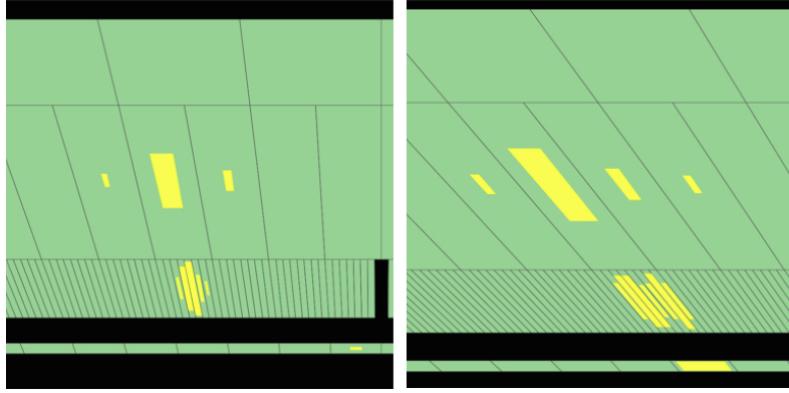


Figure 4.1: Characteristic energy deposits by an isolated photon (left), and a $\pi^0 \rightarrow \gamma\gamma$ event (right), which is possible to distinguish thanks to the granularity of the first ECAL layer [58].

4.2 Photon Identification

4.2.1 Optimisation

Starting from these discriminating SSVs, three WPs can be defined: *loose*, *medium* and *tight* WPs [59]. The loose WP is employs cuts to the variables defined in the second layer and to the hadronic leakage variable, used primarily by the trigger. The medium WP is a WP optimised to have a flat 95% efficiency. This WP applies cut to all the previously defined variables (strip and middle layer and leaks to the HCAL). Finally, the tight WP, uses all the SSVs defined and provides an excellent background rejection. TABLE shows which variables are used for each WP.

ADD PLOTS OF ALL THE VARIABLES COMPARING REAL AND FAKE

The cuts on the SSVs for each identification WP are optimised as a function of the transverse energy and the pseudo-rapidity of the photon candidate, to account for the shape of the variables for different η and for variations in the amount of material and the geometry of the calorimeter. The three WPs are also optimised separately for converted and unconverted photons. The optimisation is performed with a Multivariate (MV) approach where signal efficiencies are scanned between 0% and 100% while trying to maximise the background rejection. The resulting, optimised, cut values are subject to fluctuations and therefore they are manually smoothed.

Two different MC samples are used for the optimisation procedure, representative at different p_T^γ . For photons with $10 < p_T < 25$ GeV, radiative Z decays ($Z \rightarrow \ell^+ \ell^- \gamma$) samples are used as signal, while $Z +$ jets events accounts for the background. Events used are selected by requiring two opposite charged leptons and a minimum angular separation between the photon and the lepton of $\Delta R_{\min}(\ell, \gamma) > 0.4$. To reject non-radiating Z bosons, the dilepton invariant mass has to satisfy $m_{\ell\ell} < 83$ GeV, and the three-body invariant mass $m_{\gamma\ell\ell}$ needs to approximate the Z boson mass: 80 GeV $< m_{\gamma\ell\ell} < 100$ GeV. Finally, the photon is required to have $|\eta| < 2.37$, excluding the crack region. Finally, for higher p_T photons, $p_T > 25$ GeV, the inclusive-photon

$(\gamma+\text{jet})$ signal events are compared against dijet backgrounds. The event selection used in this case is simply requiring the photon to be in the [ECAL](#) acceptance region (excluding the crack).

4.2.2 Efficiency measurements

Photon identification efficiency measurements are carried out using three different methods that are detailed in Ref. [60] and that are combined to yield correction factors for analyses. In all cases, photons are required to satisfy the Loose isolation criterion defined in Ref. [60] and therefore the photon efficiencies are measured relative to this isolation criterion. In the following paragraphs, a brief description of each method is given.

For the lower p_{T} range ($7 < p_{\text{T}} < 100$ GeV), photons from radiative Z decays are used as signal photons, selecting the events in the same way as for the [WPs](#) optimisation (Section 4.2.1). The only difference in this case, is an additional lower limit on the di-lepton invariant mass of $40 < m_{\ell^+ \ell^-} < 83$ GeV. To estimate the number of signal and background events, template fits to the observed three-body invariant-mass distribution are performed.

The second method to compute efficiencies relies on Smirnov transformations [61] to the electrons' [SSs](#) to resemble those of photons'. The samples used in this approach are $Z \rightarrow ee$ decays, in which the electrons are required to pass loose photon isolation. The candidate electrons in data contain a small background from $W +$ jets and multijet production; this background is subtracted by fitting simulated signal samples and background templates derived from data control regions to the m_{ee} data distributions. The electron candidates are counted for events in the range $70 < m_{ee} < 110$ GeV, and the efficiencies are measured using the tag-and-probe method described in Ref. [41]. The p_{T} range in which this method is implemented is $25 < p_{\text{T}} < 250$ GeV.

The final and third method uses higher p_{T} photons originating from [QCD](#) $\gamma+\text{jet}$ production with transverse momenta in the range $50 < p_{\text{T}} < 1500$ GeV. The photons for this study are required to pass the loose identification [WP](#) employed in the trigger. This sample is dominated by background dijet events whose production cross section is orders of magnitude higher. The maxtrix method [60] is used in this case, which constructs four orthogonal regions that either pass or fail the tight identification [WP](#), and pass or fail the track-isolation (described in Section 3.2.3). For each region, two unknowns arise: the number of signal and background events. If the track isolation efficiencies are known for the signal and background components, then it is possible to estimate the efficiency for loose photons passing the tight identification criteria. The isolation efficiencies for signal photons are estimated using [MC](#) samples, and the ones for backgrounds are obtained in a jet-enriched control region constructed by inverting the identification criteria. The efficiency measurements in data for the tight identification [WP](#) then reads:

$$\epsilon^{\text{tight-ID}} = \frac{\frac{\hat{\epsilon}_{\text{ID}} - \hat{\epsilon}_{\text{ID}}^b}{\hat{\epsilon}_{\text{ID}}^s - \hat{\epsilon}_{\text{ID}}^b} \cdot N_{\text{ID}}^T}{\frac{\hat{\epsilon} - \hat{\epsilon}^b}{\hat{\epsilon}^s - \hat{\epsilon}^b} \cdot N^T}, \quad (4.9)$$

where N^T accounts for the totality of photons in the inclusive sample which consists on N^s prompt photons (or signal photons) and N^b fake photons (background photons). The number

N_{ID}^T is the subset of N^T that pass the identification requirement. Data, signal and background track isolation efficiencies are represented by $\hat{\varepsilon}$, $\hat{\varepsilon}^s$ and $\hat{\varepsilon}^b$, respectively. Similarly, the track isolation efficiencies for those photons passing tight identification are shown as $\hat{\varepsilon}_{\text{ID}}$, $\hat{\varepsilon}_{\text{ID}}^s$ and $\hat{\varepsilon}_{\text{ID}}^b$, respectively. The measured efficiencies for photons with $p_T > 150$ GeV is between 90 and 96%.

Since data and simulation measured efficiencies do not match, **MC** needs to be corrected to account for these differences. In the ideal case where one expects perfect agreement between both samples, ratios of the data efficiencies to simulation efficiencies in each $p_T - \eta$ -conversion status bin should be 1.0. These ratios are referred as Scale Factors (**SFs**) and are computed separately for each one of the methods described. Then, the different methods' **SFs** are combined using a weighted average in each bin, assuming the statistical and systematic uncertainties to be uncorrelated between the methods. Resulting **SFs** in all cases are consistent with 1.0, only deviating by a maximum of 2%. The only exception to this case is in the first p_T -bin ($7 < p_T < 10$ GeV) where deviations of up to 30% take place.

4.3 Shower shapes variables differences between data and MC

The **ATLAS MC** simulation does not perfectly describes data. This is clearly seen when computing the previously mentioned **SFs**, whose values were different from 1, meaning that different efficiencies are obtained in data and in **MC**. In particular, when comparing the **SSs** distributions, it is seen that **MC** distributions are shifted or even the whole shape differs.

The main differences on the distributions arise for the η shower profiles, where broader distributions were seen in data compared to **MC**. Part of the effect was corrected in 2010 after moving to detailed description of the material composition in the accordion absorbers in GEANT4. However, the remaining data-**MC** disagreements are still under study and could be due to several potential effects:

- Detector geometry description of the lead thickness (including possible variations of due to gravity) or material composition, material before the **ECAL**, a decrease of the width of cells caused by calorimeter contraction due to temperature (mainly in the first layer).
- Mismodeling of the electric field in the **LAr** gaps.
- Mismodeling of the cross-talk effect (energy sharing between calorimeter cells due to electronics possible in η direction).

To account for the differences in the **SSs**, historically, corrections were made in the form of shifts to each one of the **MC** distributions. These shifts comprised the so-called **FFs**, and were determined using a χ^2 minimisation on the comparison of data and **MC SSs** [41, 60]. Even though the differences decreased substantially after these corrections, some of them remained, shown in FIGURE. It is seen from the distributions that the main differences that remained are related to the shape of the distributions, therefore needing for higher order corrections.

In Chapter 5 a detailed description of newly derived corrections is presented. Since **SSs** are built from energy deposits on the **ECAL** cells, another possible way of correcting the current disagreement between data and **MC SSs** is to directly correct the energies on **MC** at a cell-level, fixing the differences in all **SSVs** at once. This new approach is studied in Chapter 6.

4.4 Samples and event selection for the SS correction studies

As mentioned above, the improved **FF** method and a novel cell-based reweighting method is presented in Chapters 5 and 6.

Similar to what had been done for the identification optimisation studies, two photon samples are used for the **FFs** calculation. For photons with $7 \leq p_T^\gamma \leq 50$ GeV, Final State Radiation (**FSR**) photons from Z -boson decay are considered, while photons from **QCD** γ +jet events are used for photons with $p_T^\gamma \geq 50$ GeV, hereinafter referred as Radiative Z (**RZ**) photons and Single Photon (**SP**) samples, respectively. On the other hand, for the cell-level corrections to the **SSVs**, only **RZ** photons are used. In what follows, event selection for both types of samples is detailed.

For both types of corrections, the **MC** samples are reweighted to match the luminosity of the collected **ATLAS** data, and also pileup re-weighted to match the pileup profile shown in Section 2.3.

4.4.1 Radiative Z boson decays

For low- p_T photons, **RZ** photons are used as signal photons, while backgrounds are modeled by $Z \rightarrow \ell\ell$ events. The photons are required to pass the following selection:

- **ECAL $|\eta|$ acceptance region.** First of all, the photons are required to be inside the **ECAL** acceptance region excluding the crack, detailed in Section 2.2.3, given by $|\eta| < 1.37$ or $1.52 < |\eta| < 2.37$.
- **Isolation.** Fake photon candidates are removed by imposing an isolation requirement on the calorimetric isolation variable with the `FixedCutTightCaloOnly WP`.
- **FSR selection.** As shown in FIGURE, the vast majority of events correspond to $m_{\gamma\ell\ell} > 100$ GeV and $m_{\ell\ell} \sim m_Z \approx 91$ GeV, which represent Initial State Radiation (**ISR**) photons (photons radiated from the initial quarks). Photon candidates from **ISR** are largely affected by the $Z +$ jets background, where a jet fakes a photon¹. However, a second peak appears in the distribution where the three-body invariant mass approximates the Z mass ($m_{\gamma\ell\ell} \approx m_Z$). These particular type of events are referred as **FSR** photons, characterised by high real photon purity, and are the ones of interest for the correction studies.

¹ The production cross-section of $Z +$ jets is about three orders of magnitude higher than that of $Z + \gamma$, and a non-negligible fraction of jets contains high- $p_T \pi^0$'s, decaying to collimated photon pairs

- **Photon-lepton overlap.** By requiring a minimum angular distance between the photon and the closest lepton ($\Delta R_{\min} > 0.4$), biases in the **ECAL** deposits by the objects are avoided.
- **Truth-matching.** [give description here](#)

Special selection for cell-based reweighting corrections

For the cell-energy reweighting method to correct the **SSs**, a special selection needs to be applied to the **EM** clusters. For the current studies, only **SSs** built from the second layer are studied. Clusters of 7×11 cells in $\eta \times \phi$ are considered, shown in FIGURE with the current cell arrangement used.

In this work, only "healthy clusters" are considered, that is, events need to be associated to clusters of 77 cells (no cells missing) and the central cell must be the one with highest energy in the corresponding cluster ("hottest" cell). In FIGURE, an example of the averaged energies at each cell, for events with unconverted photons in data is shown.

For these particular studies, the photon isolation requirement is relaxed to the **FixedCutLoose WP** is used.

4.4.2 Inclusive photons

Photon+jet events are used for the high- p_T regime of the **FFs** corrections. The events pass loose identification trigger requirements and for the nominal values of the corrections tight identification is applied. This selection is applied to reduce the vast di-jet background, which has much higher production cross-sections. As for the **RZ** photon samples, the photons are required to be within the **ECAL** acceptance region excluding the crack.

FUDGE FACTORS

5

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Billie Jean King

The **FF** method has been applied to photons in **ATLAS** as simple shifts of the distributions. In this chapter, a detailed explanation of the calculation is shown, with the addition of improvements derived for this type of corrections.

5.1 Calculation

FFs are computed in a series of steps that starts by preparing the input datasets up to the systematic uncertainties calculation. In the first step, histograms of all the **SSVs** are created and then smoothed, which are then used to perform the actual optimisation of the **FFs**. This process is repeated for different isolation and identification selection requirements, in order to compute the systematic uncertainties. In the following a step by step description of the process is described.

The calculation is performed separately for the two considered samples: **RZ** for photons with $7 \leq p_T \leq 50$ GeV and **SP** for photons with $p_T > 50$ GeV. Since **SSs** distributions vary as a function of p_T and $|\eta|$, the computation is done in bins of these mentioned variables:

$$p_T^\gamma : \begin{cases} \textbf{RZ} : [7, 15, 20, 30, 50] \text{ GeV} \\ \textbf{SP} : (50, 60, 80, 100, 150, 300, 600, \infty] \text{ GeV} \end{cases} \quad (5.1)$$

$$|\eta| : [0, 0.6, 0.8, 1.15, 1.37, 1.52, 1.81, 2.01, 2.37]. \quad (5.2)$$

Furthermore, as mentioned in Section 4.1, there are variables very sensitive to the conversion status of the photons, that is, whether if the photons are converted or unconverted. For this reason, the calculation is done separately for converted and unconverted photons. A total of nine variables are corrected using this method: E_{ratio} , f_{side} , R_η , R_ϕ , R_{had} , R_{had1} , w_1 , $w_{\eta2}$ and $w_{\text{s tot}}$; as they are the ones in which the largest discrepancies are seen between data and **MC**.

For each mentioned **SSV**, histograms of **MC** and data of 100 bins are created. The choice of the binning is done based on having sufficient statistics at each bin and also to capture all the features of the variables.

After that, each histogram is smoothed using the Kernel Density Estimator (**KDE**) tool from TMVA [62]. The **KDE** method consists of estimating the shape of a Probability Density Function (**pdf**) by the sum over smeared events. The **pdf** $p(x)$ of a variable x is

$$p(x) = \frac{1}{N} \sum_{i=1}^N K_h(x - x_i) \quad (5.3)$$

where N is the number of events, $K_h(t) = K(t/h)/h$ is the kernel function, and h is the bandwidth of the kernel. The basic idea is that each event is considered as a Dirac- δ -function, which are replaced by a Kernel function (Gaussian) and finally they are summed altogether to form the final Parton Distribution Function (**PDF**). The **KDE** smoothing can be applied in two forms: non-adaptive **KDE** or adaptive **KDE**, as seen in FIGURE. In the former, the bandwidth is constant for the entire sample h_{NA} , while in the latter, it uses the value from non-adaptive **KDE**, but it varies as a function of $p(x)$ as

$$h_A = \frac{h_{NA}}{\sqrt{p(x)}} \quad (5.4)$$

Adaptive **KDE** improves the shape of the estimated **pdf** in regions of low statistics, however, in high statistics regions it can give rise to "over-smoothing". The degree of smoothing is tuned by multiplying the bandwidth h by fine factors. These fine factors are user-defined parameter which are tuned to allow the **pdf** to retain the important features of the **SS** but to also avoid statistical fluctuations. Higher values indicate broader Kernel functions and therefore de **pdf** catches less statistical fluctuations. Examples of the smoothing procedure applied to R_η are shown in FIGURE for cases in which original histograms have low and high statistics.

Once the data and **MC pdfs** are created for a given variable, $p_T, |\eta|$ and conversion type, the **MC pdf** is normalised to data's and a χ^2 value is computed between both, excluding the underflow and overflow bins, as:

$$\chi^2 = \sum_{i=1}^N \frac{(w_{MC,i} W_{\text{data}} - w_{\text{data},i} W_{\text{MC}})^2}{s_{MC,i}^2 W_{\text{data}}^2 + s_{\text{data},i}^2 W_{\text{MC}}^2}. \quad (5.5)$$

N is the number of bins in the **pdfs**, $w_{MC,i}$ and $w_{\text{data},i}$ are the event numbers of **MC** and data at each bin, respectively, $s_{MC,i}$ and $s_{\text{data},i}$ are the bin errors and finally W_{data} and W_{MC} are the sum of weights for data and **MC**, respectively.

5.1.1 Shift-only corrections

Taking into account only the mean's correction of the **SSs**, the **MC pdf** is shifted to the left and right one bin at a time. As a consequence of this procedure, the shift **FF** resolution directly depends on the bin-width of the **pdfs**, and since the **pdfs** have been generated with high accuracy given the relatively small bin-width of the histograms, the **pdfs** are built to have a total of 5000 bins. The starting number of bins that the **MC** distribution needs to be shifted is estimated by

computing the difference on the means between data and simulation. From this starting value, shifts of 100 bins to each side are considered.

For each bin the distribution has been shifted, the aforementioned χ^2 value is computed and recorded. Assuming that the measurements errors $s_{MC,i}$ and $s_{data,i}$ have a normal gaussian distribution¹, and that the parameters for each χ^2 value are independent, it is expected that the shape followed by the χ^2 values is approximately paraboloidal, which can be seen from FIGURE.

To extract the FFs, the χ^2 scan near the minimum is fitted with a parabolic function (5 bins to each side of the minimum bin) and the shift FF is obtained from the fit minimum (see FIGURE).

Finally, the SSs can be corrected as

$$SS_{\text{new}} = SS_{\text{old}} + \text{shift},$$

shown for f_{side} in FIGURE.

5.1.2 Shift+stretch corrections

In order to improve the agreement between data and MC corrections to the widths of the distributions are introduced. To apply both corrections, first the maximum of the MC pdf is found and then the pdf is stretched around it. The stretch value is varied between 0.3 and 2.5 with a total of 300 steps. Since stretches are applied to the MC pdf, there might be cases in which the stretch is big enough to give rise to empty bins inbetween. To treat these empty bins, they are interpolated using the closest non-zero bins to each side. After the stretch has been applied, the MC pdf is shifted to the left and right, and then the same procedure as before is followed. As a result, a two-dimensional grid (shift and stretch plane) of χ^2 values is obtained, and the FFs are obtained from the center of the minimum bin. Finally, corrections are applied to MC SSs as

$$SS_{\text{new}} = \text{stretch} \times (SS_{\text{old}} - \text{stretch point}) + \text{shift} + \text{stretch point}. \quad (5.6)$$

This procedure is shown in FIGURE for the same shower shape shown in REFERENCE.

5.2 Uncertainties

5.2.1 Statistical uncertainties

To extract the statistical uncertainties on the shift and stretch FFs, the 1σ contour is needed. In the large sample limit and for two parameters x and y , the χ^2 values distribution near the minimum take the form

$$\chi^2 = \chi^2_{\min} + \frac{1}{1-\rho^2} \left[\left(\frac{x-x_0}{\sigma_x} \right)^2 + \left(\frac{y-y_0}{\sigma_y} \right)^2 - 2\rho \left(\frac{x-x_0}{\sigma_x} \right) \left(\frac{y-y_0}{\sigma_y} \right) \right], \quad (5.7)$$

¹ This requirement is satisfied as long as the bin contents of both pdfs are greater than 10.

where ρ is the correlation coefficient between both variables, and χ^2_{\min} is the χ^2 minimum value obtained from the 2D histogram.

The contour which gives the 1σ (68.3% confidence level) uncertainty on the parameters is given by $\chi^2_{\min} + 2.3$. To obtain the points that make any desired contour, bin content and bin centers are used to interpolate the points position.

Using a quadric to fit the ellipse and transforming it to the most general canonical form

$$\frac{((x - x_0) \cos \theta + (y - y_0) \sin \theta)^2}{a^2} + \frac{((x - x_0) \sin \theta - (y - y_0) \cos \theta)^2}{b^2} = 1, \quad (5.8)$$

it is possible to extract the ellipse center (x_0, y_0) , its tilt angle θ and its semi-major and semi-minor axis, a and b , respectively. Using this information, the x and y upper and lower limits are obtained as follows:

$$x_{\text{limits}} = x_0 \pm \sqrt{a^2 \cos^2 \theta + b^2 \sin^2 \theta} = x_0 \pm \sigma_x \quad (5.9)$$

$$y_{\text{limits}} = y_0 \pm \sqrt{a^2 \sin^2 \theta + b^2 \cos^2 \theta} = y_0 \pm \sigma_y \quad (5.10)$$

giving then the statistical uncertainties on x and y as

$$\sigma_x = \sqrt{a^2 \cos^2 \theta + b^2 \sin^2 \theta} \quad (5.11)$$

$$\sigma_y = \sqrt{a^2 \sin^2 \theta + b^2 \cos^2 \theta}. \quad (5.12)$$

FIGURE shows the ellipse parameters and limits shown previously, and FIGURE shown an example of application of the fit to the $w_{\text{s tot}}$ SS. Finally, it is also possible to get the correlation coefficient ρ as

$$\rho = \tan(2\theta) \frac{\sigma_x^2 - \sigma_y^2}{2\sigma_x \sigma_y}. \quad (5.13)$$

5.2.2 Systematic uncertainties

The systematic uncertainties are derived by varying the preselection criteria, that is, photon identification and photon isolation. Changing different preselection criteria allows the SSVs to vary depending on the amount of background contamination, and therefore also the FFs will change. The different selections (also named configurations) are:

- Radiative Z (RZ) sample:
 - Nominal configuration: No ID, FixedCutTightCaloOnly isolation.
 - Loose ID, no isolation.
 - Loose ID, FixedCutTightCaloOnly isolation.
 - No ID, FixedCutLoose isolation.
- Single Photon (SP) sample:

- Nominal configuration: Tight ID, FixedCutLoose isolation.
- Tight ID, FixedCutTight isolation.

All other combinations (or lack thereof) of selection criteria would result in either a sample with too low statistics, or too low purity.

FFs are derived for each one of the previous configurations, and the difference between the ones in the nominal configuration with the remaining ones is calculated. The maximum difference is taken as the systematic uncertainty, as the most conservative approach.

5.3 Results

CELL-BASED ENERGY REWEIGHTING

6

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Part IV

New Physics

ANALYSIS MOTIVATION AND STRATEGY

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SIGNAL AND BACKGROUND SAMPLES

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EVENT SELECTION

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BACKGROUND ESTIMATION**10**

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BACKGROUND MODELING**11**

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SYSTEMATIC UNCERTAINTIES

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STATISTICAL ANALYSIS

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RESULTS

14

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CONCLUSIONS

Don't let anyone rob you of your imagination, your creativity, or your curiosity.

Mae Jemison

GLOSSARY

CERN European Organization for Nuclear Research	6
ALICE A Large Ion Collider Experiment	
ATLAS A Toroidal LHC ApparatuS	ix
CMS Compact Muon Solenoid	
LHC Large Hadron Collider	ix
LHCb Large Hadron Collider beauty	
LHCf Large Hadron Collider forward	
LS2 Long Shut down 2	ix
TOTEM TOTal cross section, Elastic scattering and diffraction dissociation Measurement at the LHC	
MoEDAL Monopole & Exotics Detector At the LHC	
SPS Super Proton Synchrotron	6
L1 Level-1	16
L1Topo Level-1 Topological	16
LAr Liquid Argon	13
ECAL Electromagnetic Calorimeter	ix
CSC Cathode Strip Chamber	15
CTP Central Trigger Processor	17
FCAL Forward Calorimeter	13
HEC Hadronic End-Cap Calorimeter	14
HCAL Hadronic Calorimeter	ix
HLT High Level Trigger	16
IBL Insertable B-Layer	10
ID Inner Detector	ix

Glossary	59
SCT SemiConductor Tracker	10
RPC Resistive-Plate Chamber	15
TGC Thin-Gap Chamber	16
TRT Transition Radiation Tracker	10
NSW New Small Wheel	15
MDT Monitored Drift Tube	15
MS Muon Spectrometer	ix
GRL Good Runs List	18
LB Luminosity-block	18
PSB Proton Synchrotron Booster	6
MC Monte Carlo	ix
MV Multivariate	37
KDE Kernel Density Estimator	43
ROI Region of Interest	16
FF Fudge Factor	24
SF Scale Factor	39
SS Shower Shape	vii
SSV Shower Shape Variable	xi
WP Working Point	ix
pdf Probability Density Function	43
EM electromagnetic	34
FSR Final State Radiation	40
RZ Radiative Z	40
SP Single Photon	40
ISR Initial State Radiation	40
ME Matrix Element	26
PDF Parton Distribution Function	43
PS Parton Shower	6
QCD Quantum Chromodynamics	26
SM Standard Model	
JVT Jet vertex Tagger	29
JVF Jet vertex Fraction	29
PV Primary Vertex	22

Glossary	60
CB Combined Muon	26
ST Segmented Muon	26
CT Calorimetric Muon	26
ME Standalone/Extrapolated Muon	26
PFlow Particle Flow	28
FTAG Flavor Tagging	30

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