Hamiltonian fluid dynamics and stability

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Newtonian Dynamics

Newtonian Dynamics

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- $\mathbf{F} = -\nabla \Pi$
- Second order ODE

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Hamiltonian Dynamics

•
$$\frac{d\mathbf{p}}{dt} = -\frac{\partial H}{\partial \mathbf{q}}$$

•
$$\frac{d\mathbf{q}}{dt} = \frac{\partial \mathcal{H}}{\partial \mathbf{p}}$$

System of first order ODEs

Navier-Stokes Equations

Navier-Stokes Equations

- $\rho \frac{d\mathbf{u}}{dt} = \nabla \cdot \boldsymbol{\sigma} + \mathbf{F}$
- $\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{u} = 0$
- System of coupled, nonlinear, PDEs

Navier-Stokes Equations

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Hamiltonian

Navier-Stokes Equations

•
$$\rho \frac{d\mathbf{u}}{dt} = \nabla \cdot \sigma + \mathbf{F}$$

•
$$\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{u} = 0$$

 System of coupled, nonlinear, PDEs

Hamiltonian

•
$$\frac{d\mathbf{p}}{dt} = -\frac{\delta\mathcal{H}}{\delta\mathbf{q}}$$

•
$$\frac{d\mathbf{q}}{dt} = \frac{\delta \mathcal{H}}{\delta \mathbf{p}}$$

 More analytical tools to work with

System of PDEs

$$\mathbf{0} = \mathbf{F}\left(\mathbf{q}, \frac{\partial}{\partial x_i}, \frac{\partial}{\partial t}\right)$$

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$$\mathbf{q}_t = \mathbf{J} rac{\delta \mathcal{H}}{\delta \mathbf{q}}$$

Derivatives

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$$\lim_{\epsilon \to 0} \frac{\partial}{\partial \epsilon} \mathcal{F}(\mathbf{q} + \epsilon \delta \mathbf{q}) \equiv \left\langle \frac{\delta \mathcal{F}}{\delta \mathbf{q}}, \delta \mathbf{q} \right\rangle \equiv \int_{\Omega} \frac{\delta \mathcal{F}}{\delta \mathbf{q}} \delta \mathbf{q} \, d\mathbf{x}$$

Poisson Bracket

$$\begin{split} \frac{\partial \mathcal{F}}{\partial t} &= \int_{\Omega} \frac{\partial F}{\partial t} \, d\mathbf{x} \\ &= \int_{\Omega} \frac{\delta \mathcal{F}}{\delta \mathbf{q}}^{\top} \mathbf{q}_{t} \, d\mathbf{x} \\ &= \int_{\Omega} \frac{\delta \mathcal{F}}{\delta \mathbf{q}}^{\top} \mathbf{J} \frac{\delta \mathcal{H}}{\delta \mathbf{q}} \, d\mathbf{x} \\ &= \left\langle \frac{\delta \mathcal{F}}{\delta \mathbf{q}}, \mathbf{J} \frac{\delta \mathcal{H}}{\delta \mathbf{q}} \right\rangle \\ &\equiv \left\{ \mathcal{F}, \mathcal{H} \right\} \end{split}$$

$$\begin{array}{c} U_1 \Rightarrow \\ \\ U_2 \Rightarrow \end{array}$$

$$U_1 \Rightarrow \\ U_2 \Rightarrow$$

$$\psi_n = -U_n y$$

$$U_1 \rightarrow \\$$

$$U_2 \rightarrow$$

$$\psi_n = -U_n y$$

$$q_1 = \frac{1}{\alpha_1} \nabla^2 \psi_1 + (\psi_2 - \psi_1) = (U_1 - U_2) y$$

$$q_2 = \frac{1}{\alpha_2} \nabla^2 \psi_2 + (\psi_1 - \psi_2) = (U_2 - U_1) y$$

$$0 = \frac{\partial q_1}{\partial t} + D(\psi_1, q_1)$$
$$0 = \frac{\partial q_2}{\partial t} + D(\psi_2, q_2)$$
$$D(a, b) = \frac{\partial a}{\partial x} \frac{\partial b}{\partial y} - \frac{\partial a}{\partial y} \frac{\partial b}{\partial x}$$

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$$D(a, b) = \frac{\partial a}{\partial x} \frac{\partial b}{\partial y} - \frac{\partial a}{\partial y} \frac{\partial b}{\partial x}$$

$$\mathcal{H} = \frac{1}{2} \iint \sum_{n=1}^{2} \left[\frac{1}{\alpha_n} \vec{\nabla} \psi_n \cdot \vec{\nabla} \psi_n + 2C_n(q_n) \right] + (\psi_1 - \psi_2)^2 dA$$

$$\delta^2 \mathcal{H} = \iint \sum_{n} \left[\frac{1}{\alpha_n} \vec{\nabla} \delta \psi_n \cdot \vec{\nabla} \delta \psi_n + \psi_n' \cdot (\delta q_n)^2 \right] + (\delta \psi_1 - \delta \psi_2)^2 \, dA$$

$$\delta^{2}\mathcal{H} = \iint \sum_{n} \left[\frac{1}{\alpha_{n}} \vec{\nabla} \delta \psi_{n} \cdot \vec{\nabla} \delta \psi_{n} + \psi'_{n} \cdot (\delta q_{n})^{2} \right] + (\delta \psi_{1} - \delta \psi_{2})^{2} dA$$

$$U_{n} \frac{dq_{n}}{dy} > 0, \quad n = 1, 2$$

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$$U_{n} \frac{dq_{n}}{dy} > 0, \quad n = 1, 2$$

$$U_{1}(U_{1} - U_{2}) > 0$$

 $U_2(U_2-U_1)>0$

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