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## **Newtonian Dynamics**

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- $\frac{d^2\vec{q}}{dt} = -\nabla\Pi$
- Second order system

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### **Hamiltonian Dynamics**

- $\frac{d\vec{p}}{dt} = -\frac{\partial H}{\partial \vec{q}}, \frac{d\vec{q}}{dt} = \frac{\partial H}{\partial \vec{p}}$
- First order, coupled system

### **Navier-Stokes Equations**

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- $\rho \frac{d\vec{u}}{dt} = -\nabla p + \rho \nabla \Pi + F$
- Coupled, first order, nonlinear system

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### System of PDEs

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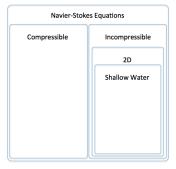
Hamiltonian

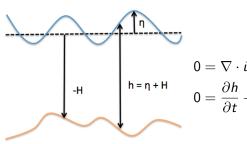
$$\mathcal{H} = \iiint_{\Omega} H(\mathbf{q}) dV$$

Canonical equations

$$\mathbf{q}_t = \mathbf{J} \frac{\delta \mathcal{H}}{\delta \mathbf{q}}$$

### Shallow Water Model

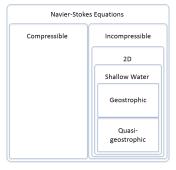




$$0 = \nabla \cdot \vec{u}$$

$$0 = \frac{\partial h}{\partial t} + \frac{\partial}{\partial x}(hu) + \frac{\partial}{\partial y}(hv)$$

# Geostrophic Model



$$\frac{d\vec{u}}{dt} + 2\vec{\Omega} \times \vec{u} = -\frac{\nabla p}{\rho} + \nabla \Pi + \frac{F}{\rho}$$

 $\vec{u} = \text{velocity field}$ 

 $\vec{\Omega} = \text{rotation vector}$ 

p = pressure

 $\Pi = scalar potential field$ 

F = viscous forces

$$0 = \frac{\partial q}{\partial t} + J(\psi, q)$$
$$J(a, b) = \frac{\partial a}{\partial x} \frac{\partial b}{\partial y} - \frac{\partial a}{\partial y} \frac{\partial b}{\partial x}$$

## References

1. Reference