

# De2 Meteo Station

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## Team members

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Link to this file in your GitHub repository:

<https://github.com/francois07/digital-electronics-project>

## Table of contents

- [De2 Meteo Station](#)
  - [Team members](#)
  - [Table of contents](#)
  - [Project objectives](#)
  - [Hardware description](#)
    - [Sensor - DHT12](#)
    - [LCD Display - HD44780](#)
    - [Servo Motor - SG90](#)
  - [Libraries description](#)
    - [Delay](#)
    - [IO](#)
    - [Interrupt](#)
    - [timer](#)
    - [stdlib](#)
    - [UART](#)
    - [TWI](#)
    - [LCD](#)
    - [GPIO](#)

- [Main application](#)
  - [Description](#)
  - [Flowcharts](#)
    - [Main function](#)
    - [displaySensor function](#)
    - [ISR function](#)
- [Video](#)
- [References](#)

## Project objectives

*Weather station with 2-axis solar tracking system. The following can be used: temperature, humidity, pressure, light intensity sensors, panel positioning motors, and others.*

We decided to focus more on the meteo station side, using a sensor to get temperature and humidity to then display them on screen in a pretty way.

## Hardware description

### Sensor - DHT12

This sensor is used to get temperature and humidity values.

### LCD Display - HD44780

This LCD display was used to display the temperature and humidity values we got from the sensor.

### Servo Motor - SG90

This motor was used to simulate rotations of a solar panel.

## Libraries description

## Delay

Functions for busy-wait delay loops

## IO

AVR device-specific IO definitions

## Interrupt

Interrupts standard C library for AVR-GCC

## timer

Timer library made in labs

## stdlib

Standart C Library providing type such as `uint8_t`

## UART

Peter Fleury's UART library

## TWI

TWI library for AVR-GCC

## LCD

LCD library for AVR-GCC

## GPIO

GPIO library made in labs

# Main application

## Description

As explained in project objectives, we decided to focus more on the meteo station side, since simulating the motors wasn't very relevant (only a few lines of code). To get temperature and humidity values, we used the DHT12 sensor with I2C communication. To display them one after they other, we defined a simple state machine.

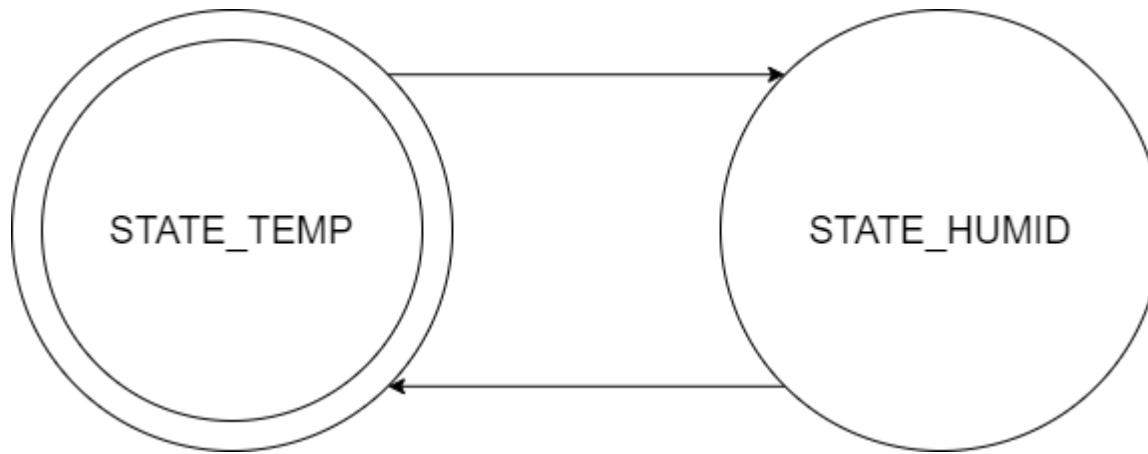
```
// FSM
switch (state)
{
    // Get humidity
    case STATE_HUMID:
        // Display humidity value
        // ...

        state = STATE_TEMP;
        break;

    // Get temperature
    case STATE_TEMP:
        // Display temperature value
        // ...

        state = STATE_HUMID;
        break;

    default:
        state = STATE_TEMP;
        break;
}
```



To display values, we used a custom helper function we called displaySensor

```
uint8_t displaySensor(char title[], uint8_t slave_adress, uint8_t reg_adress)
{
    uint8_t result = 1;
    char res_string[] = "000";

    lcd_gotoxy(1, 0);
    lcd_puts(title);

    twi_start((slave_adress<<1) + TWI_WRITE);
    twi_write(reg_adress);
    twi_stop();

    twi_start((slave_adress<<1) + TWI_READ);
    result = twi_read_ack();

    itoa(result, res_string, 10);

    lcd_gotoxy(0, 1);
    lcd_puts(res_string);

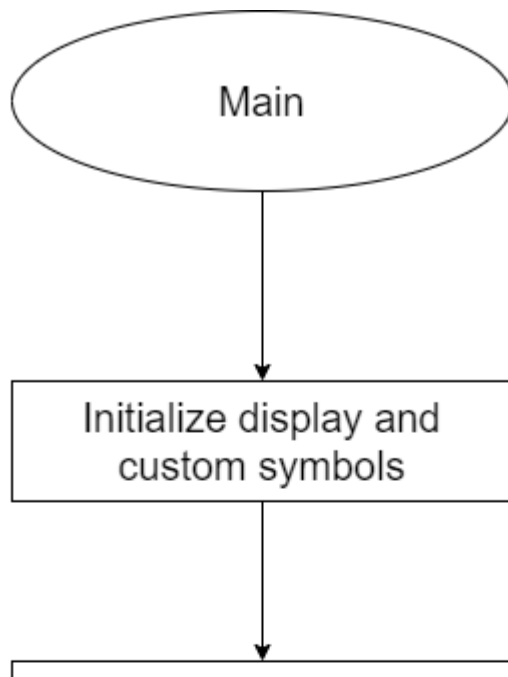
    return result;
}
```

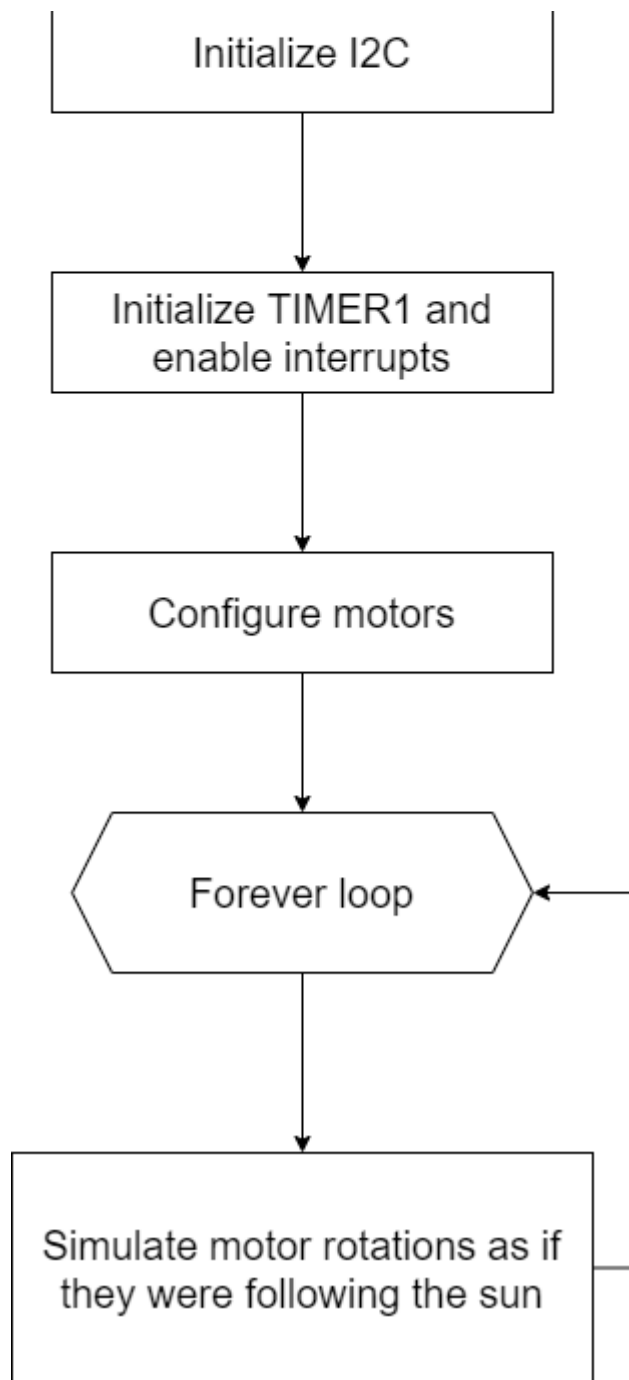
To simulate the solar panels' rotations, we rotate a motor on the side. If it was a real application, we would have to motors: 1 for X rotation and 1 for Y rotation. Also, there would be a scheduling of the rotation, unlike here where the motor just goes back and forth between -90deg and 90deg. We also made a helper function for rotating the motors called rotateMotor

```
void rotateMotor(volatile uint8_t *reg_name, uint8_t pin_num, uint8_t period, uint64_t pulse)
{
    GPIO_write_low(reg_name, pin_num);
    for(uint8_t i=0; i < period; i++){
        _delay_ms(20);
        GPIO_toggle(reg_name, pin_num);
        _delay_us(pulse);
        GPIO_toggle(reg_name, pin_num);
    }
}
```

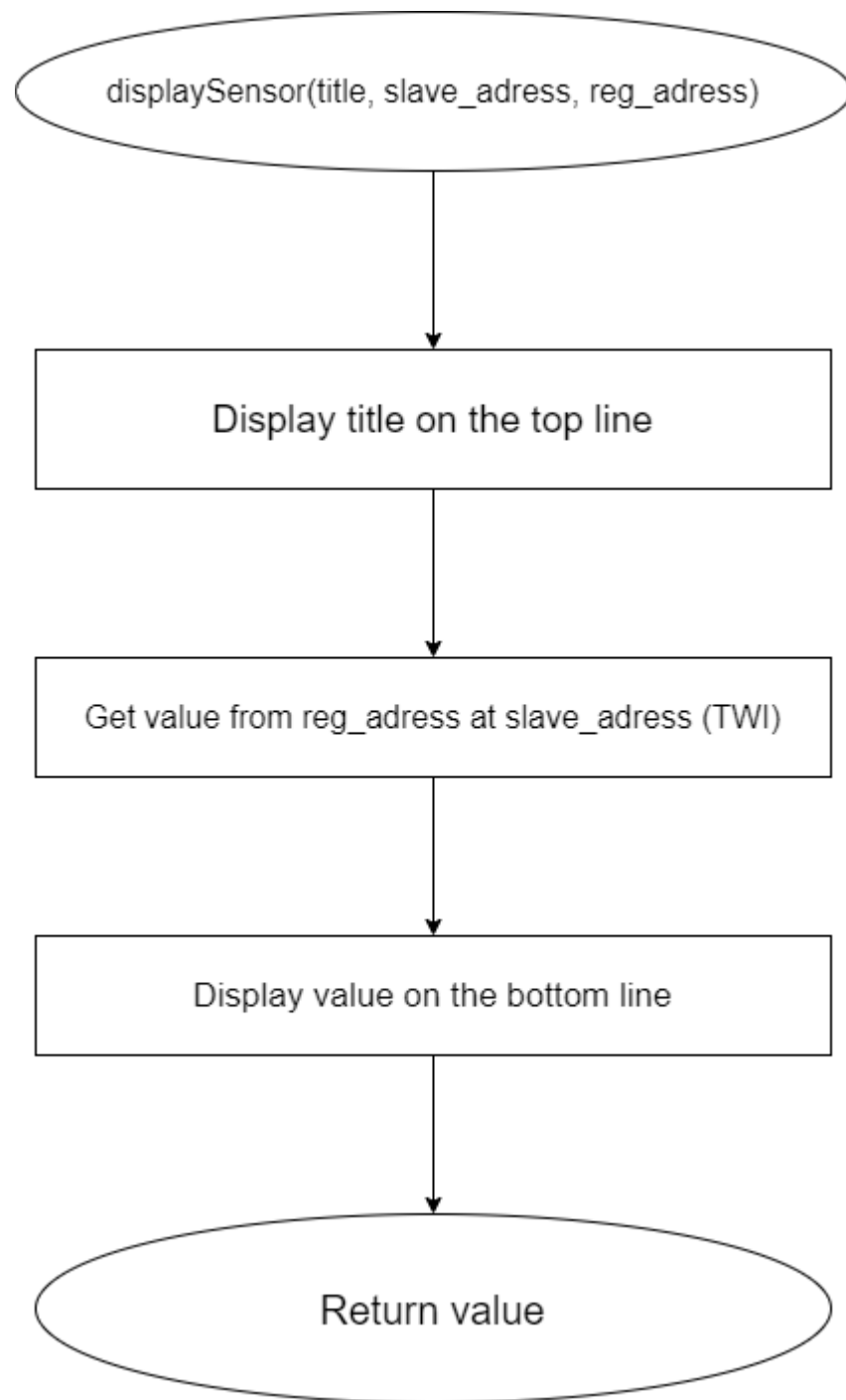
Flowcharts

**Main function**



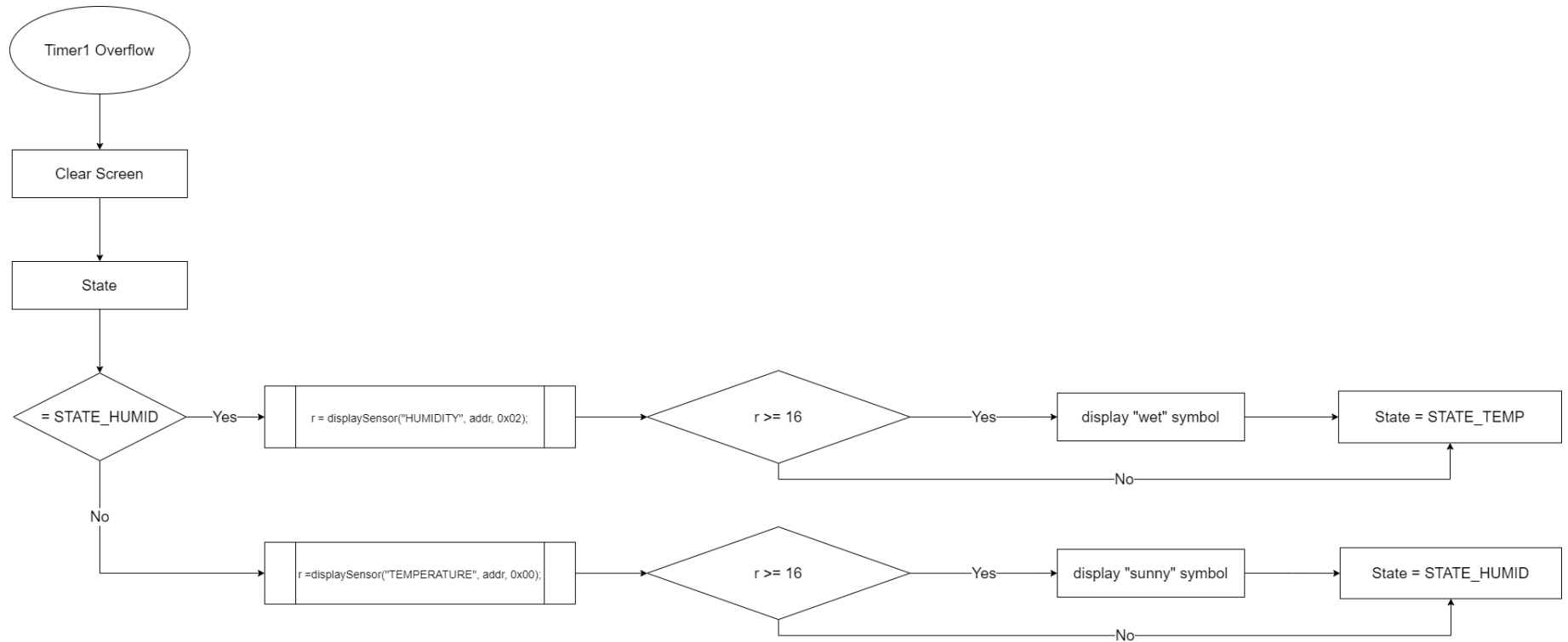


**displaySensor function**





## ISR function



## Video

You can find our project video [here](https://www.youtube.com/watch?v=LFCsTHv8JU4) (<https://www.youtube.com/watch?v=LFCsTHv8JU4>)

## References

1. [SG90 Servo Motor datasheet](#)
2. [DHT12 Sensor datasheet](#)
3. [Arduino Shield](#)