

Regularizing Optimal Transport Using Regularity Theory

Learning meets Astrophysics

January 17, 2020

FRANÇOIS-PIERRE PATY

francoispierrepaty.github.io

Based on a joint work with
Alexandre d'Aspremont and
Marco Cuturi (AISTATS 2020)

ENSAE



IP PARIS



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INTRODUCTION



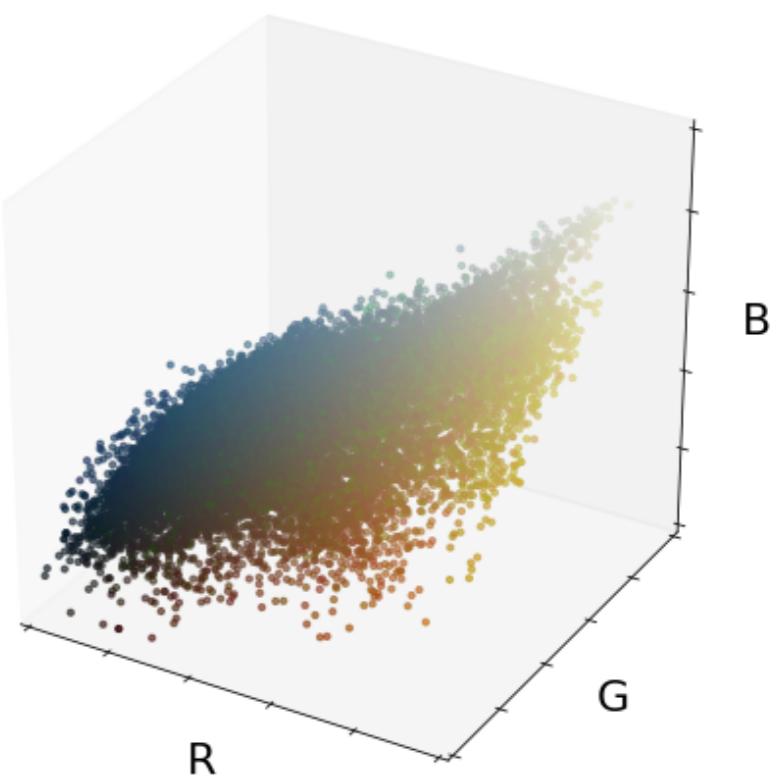
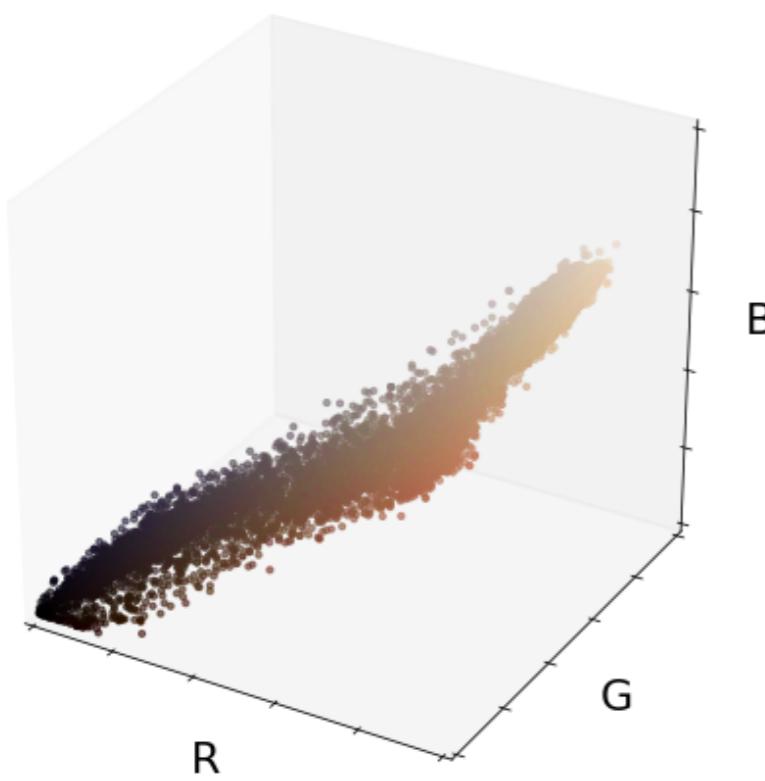


Color Transfer Map



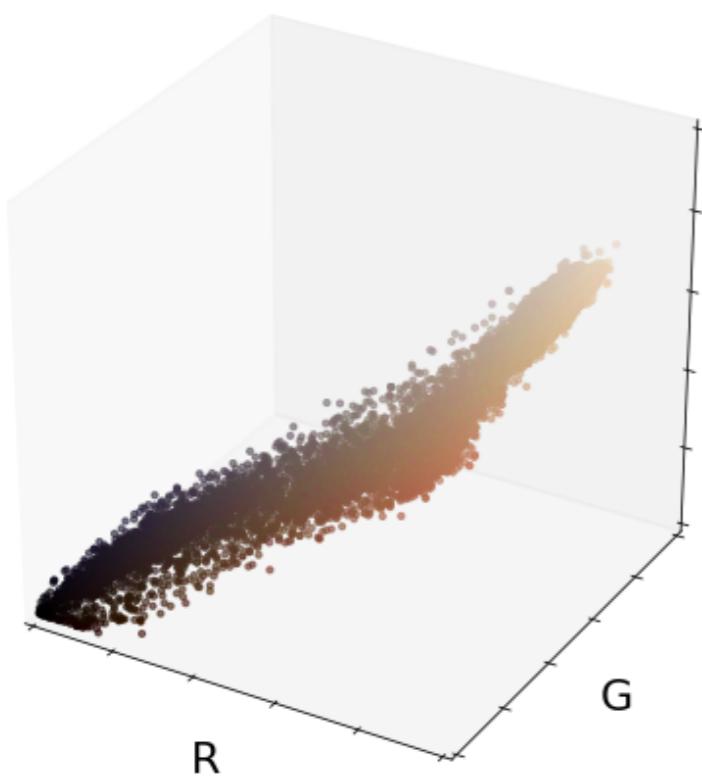


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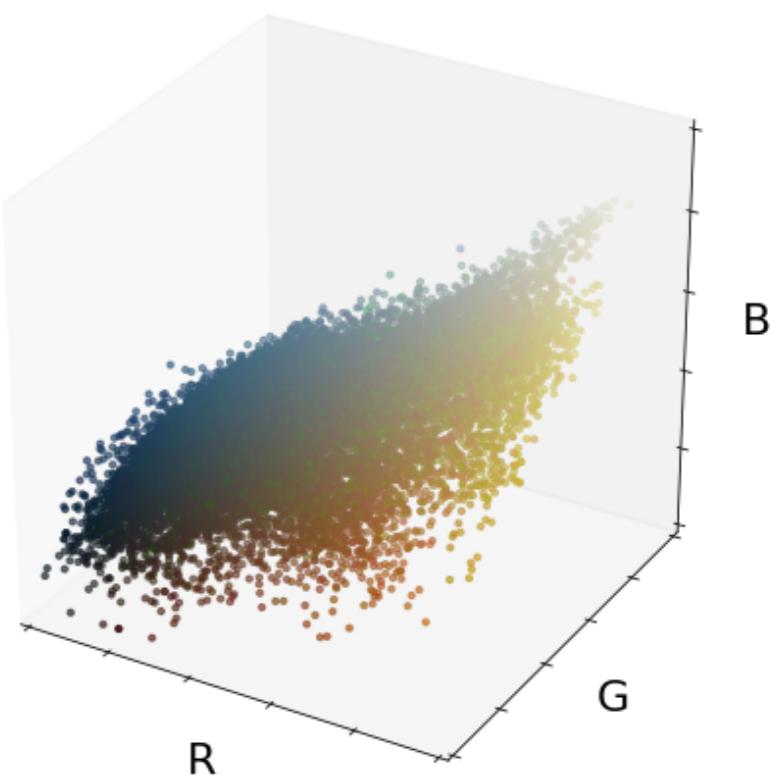




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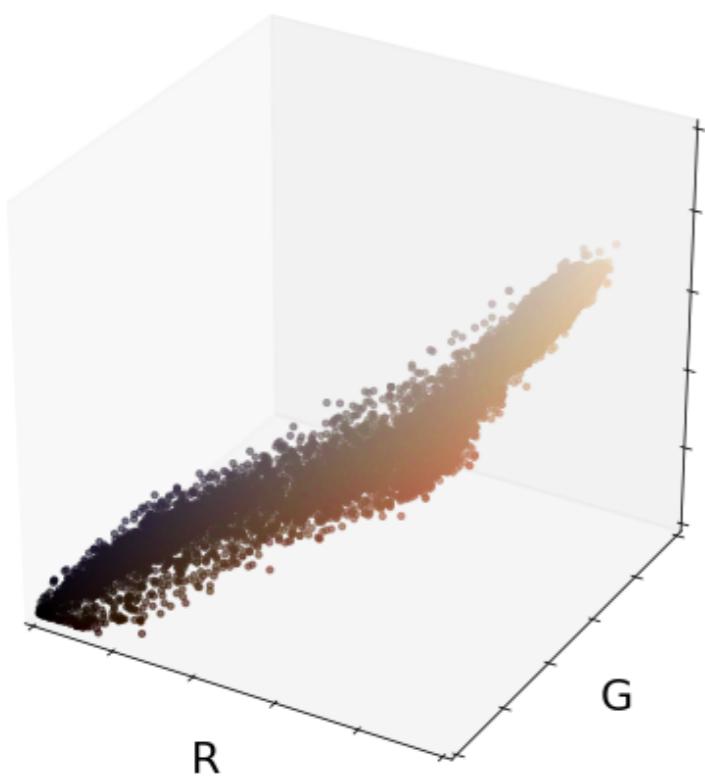


Matching

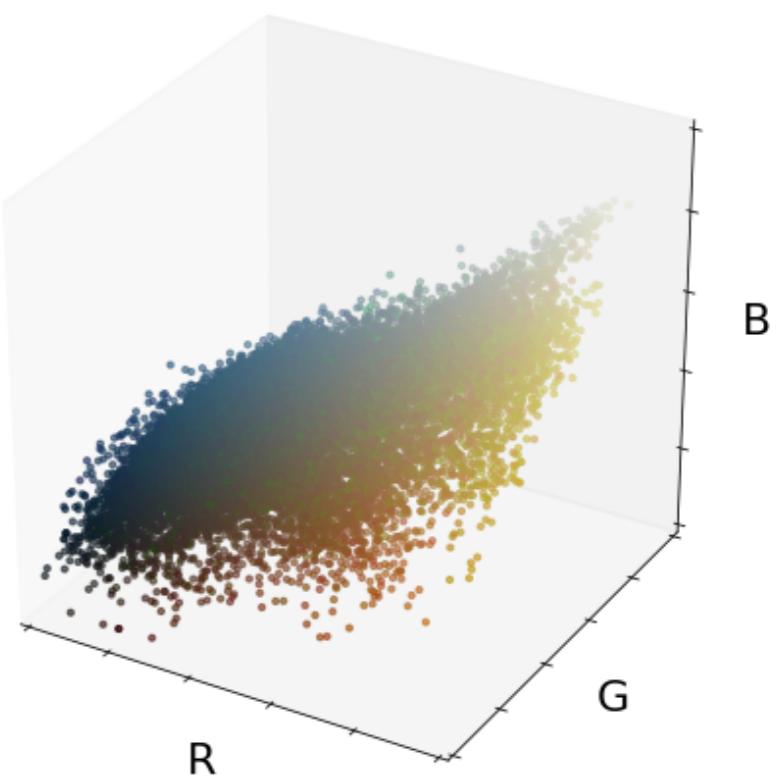


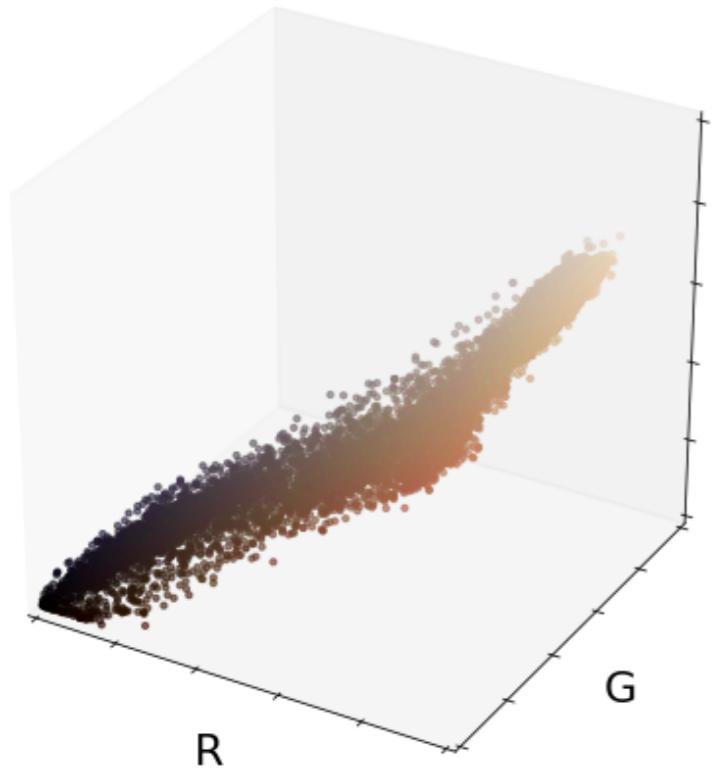


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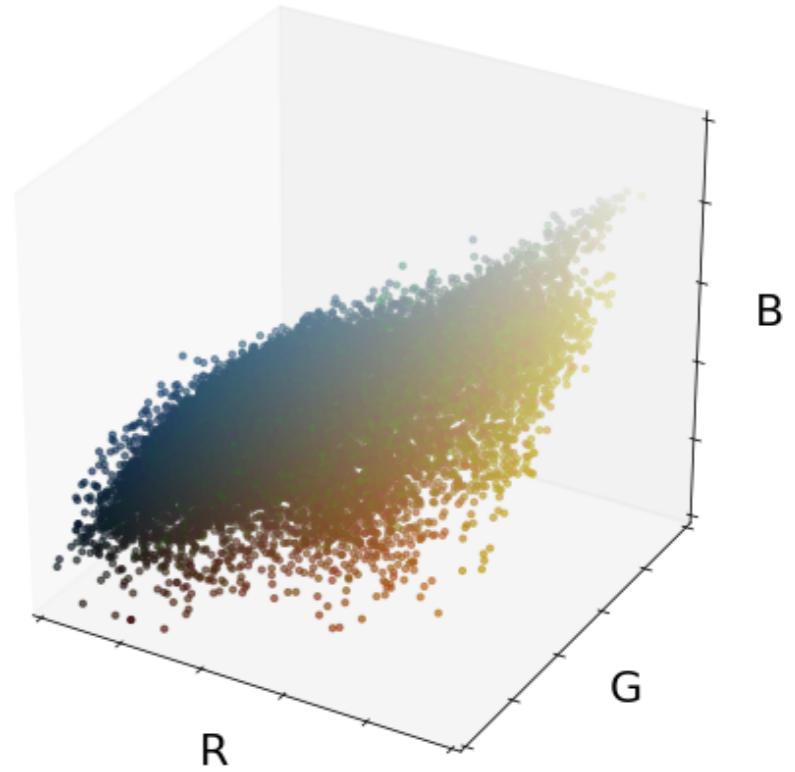
Matching





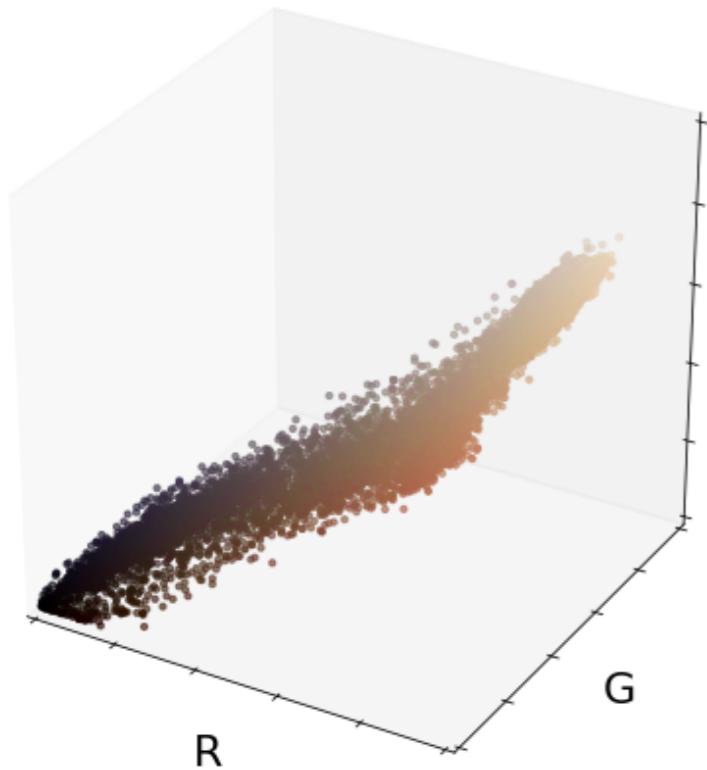
Matching

$$\sigma \in \mathfrak{S}_n$$

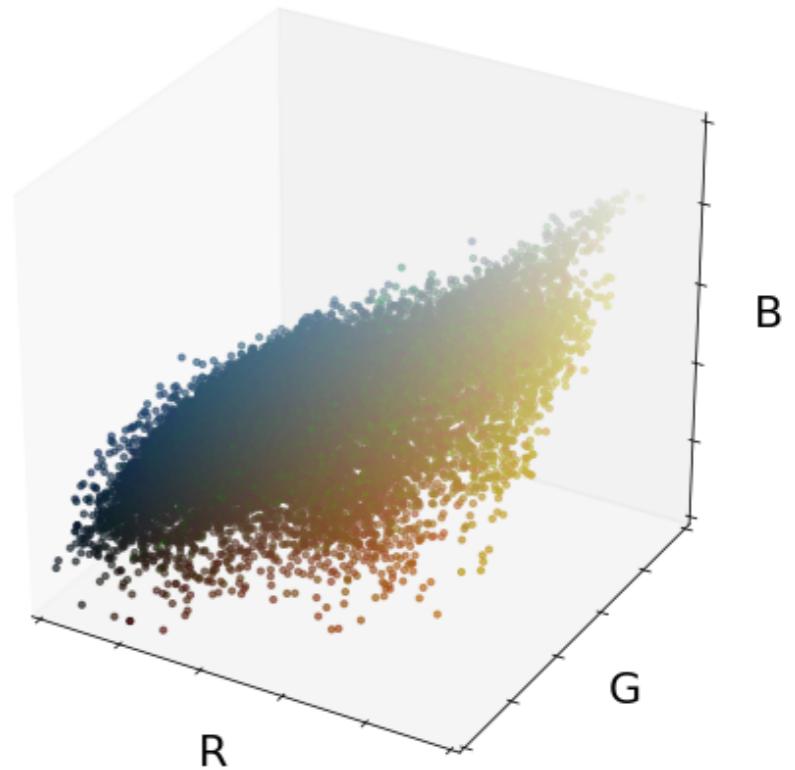


x_1, \dots, x_n

y_1, \dots, y_n



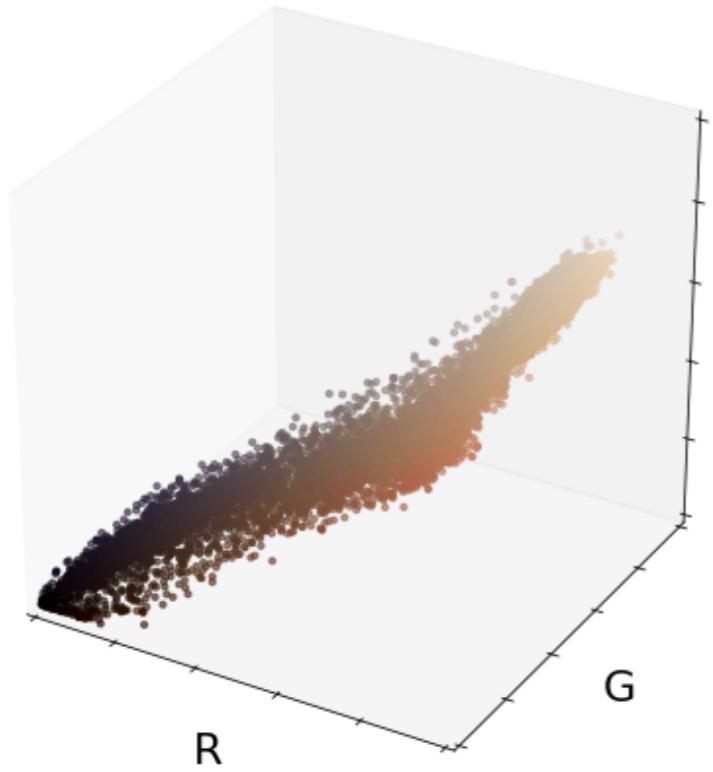
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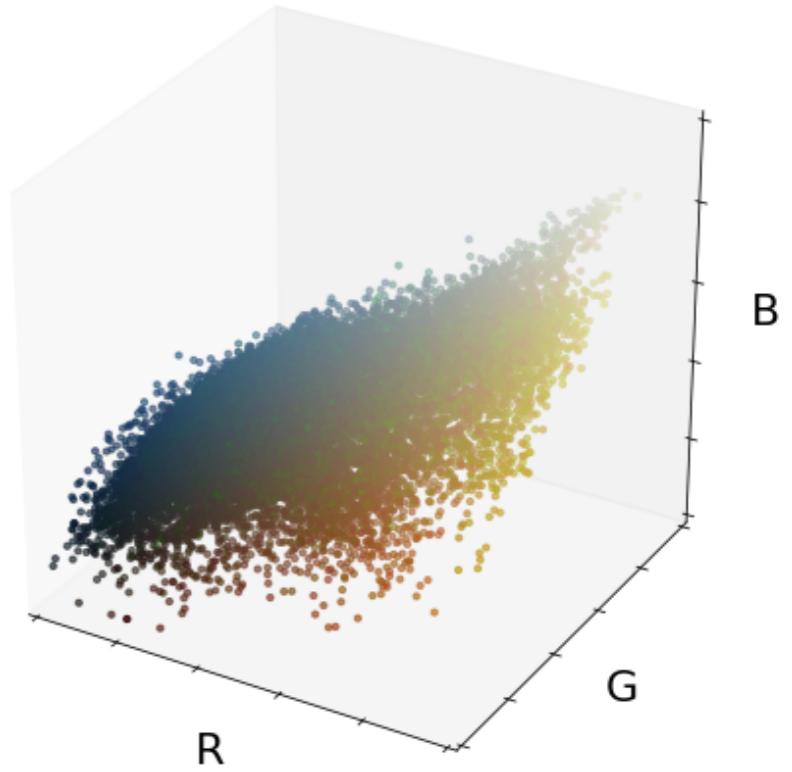
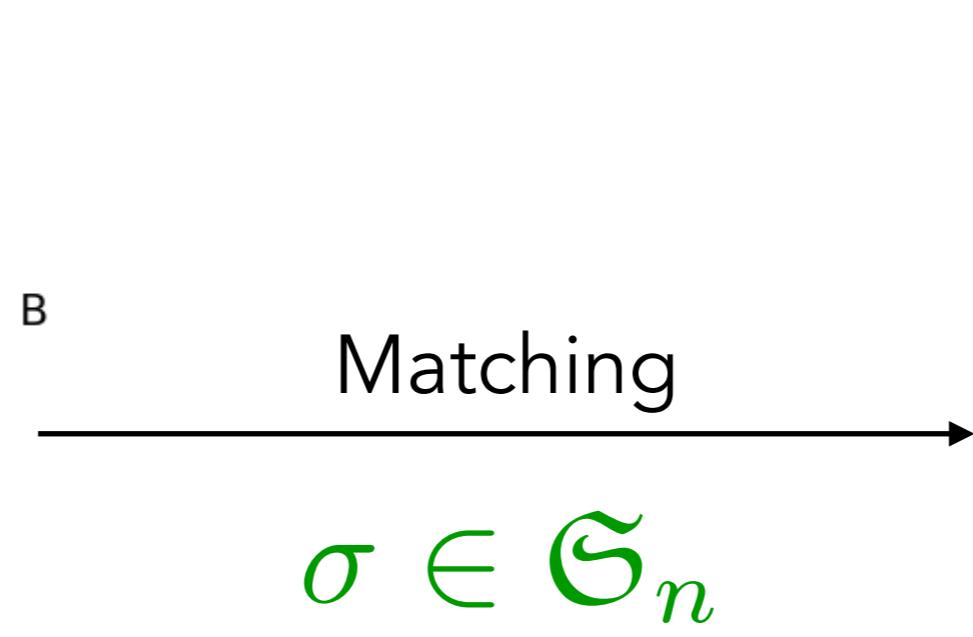
x_1, \dots, x_n

$\sigma \in \mathfrak{S}_n$

y_1, \dots, y_n

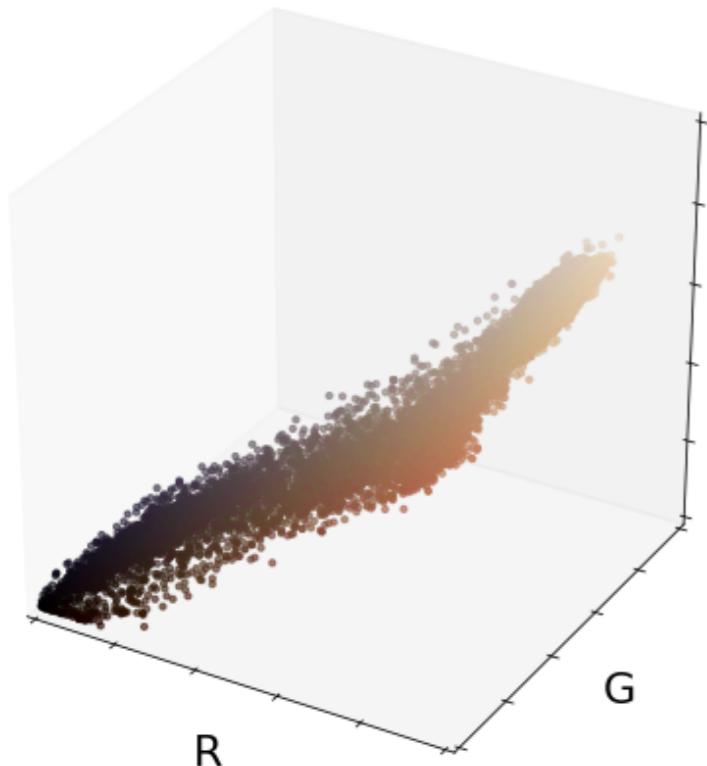


x_1, \dots, x_n



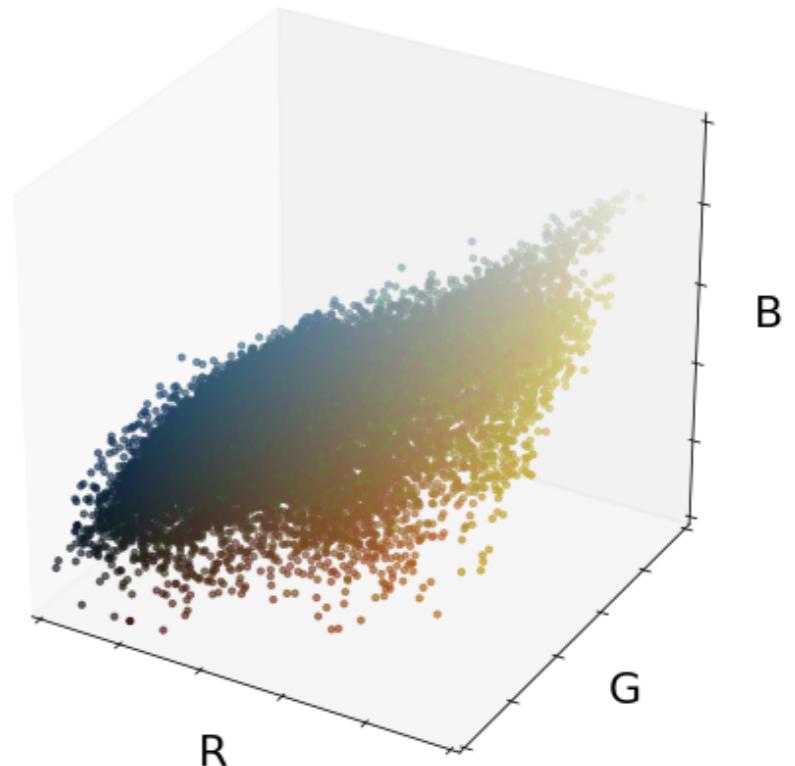
y_1, \dots, y_n

$$\|x_i - y_{\sigma(i)}\|^2$$



Matching

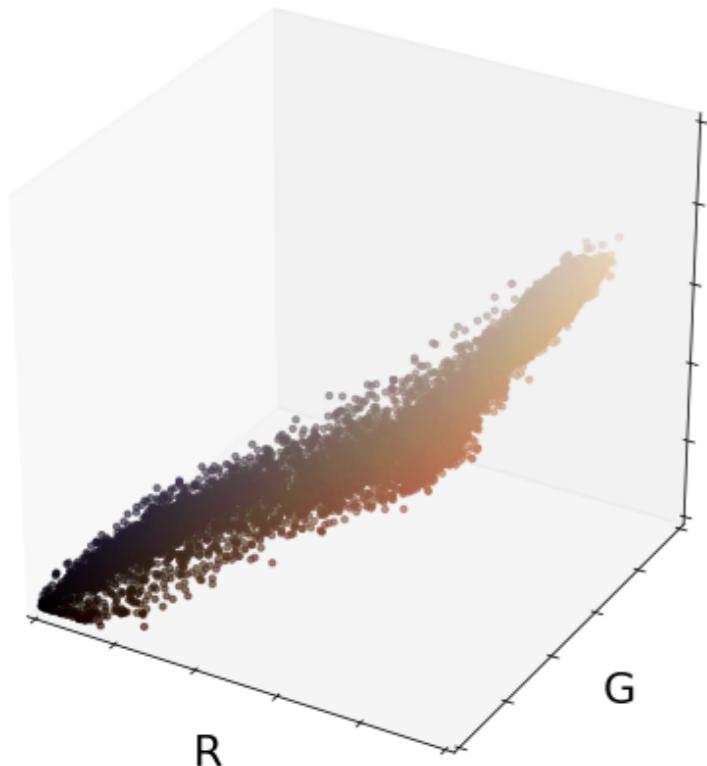
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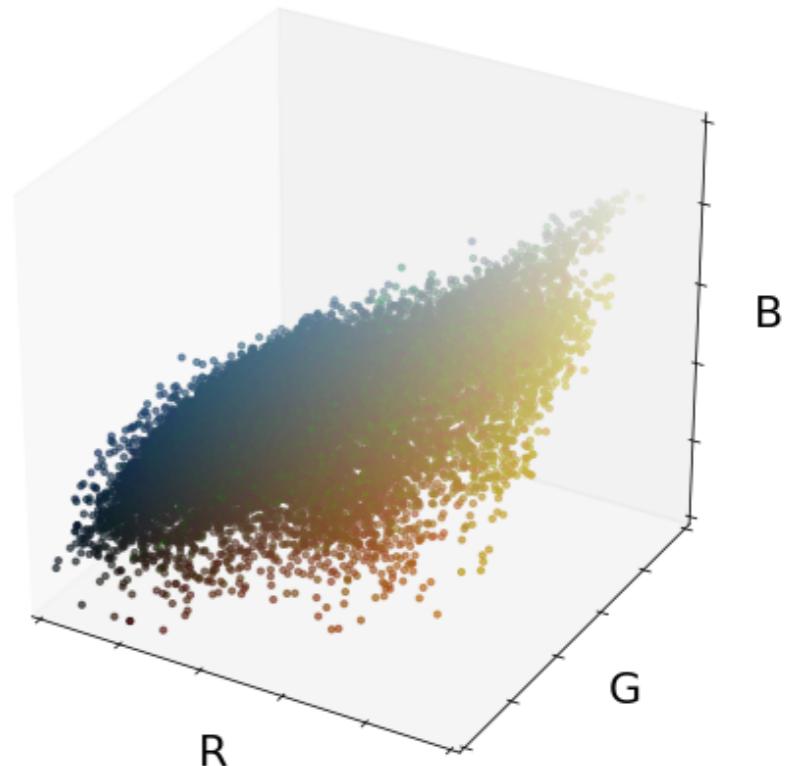
$$y_1, \dots, y_n$$

$$\sum_{i=1}^n \|x_i - y_{\sigma(i)}\|^2$$



Matching

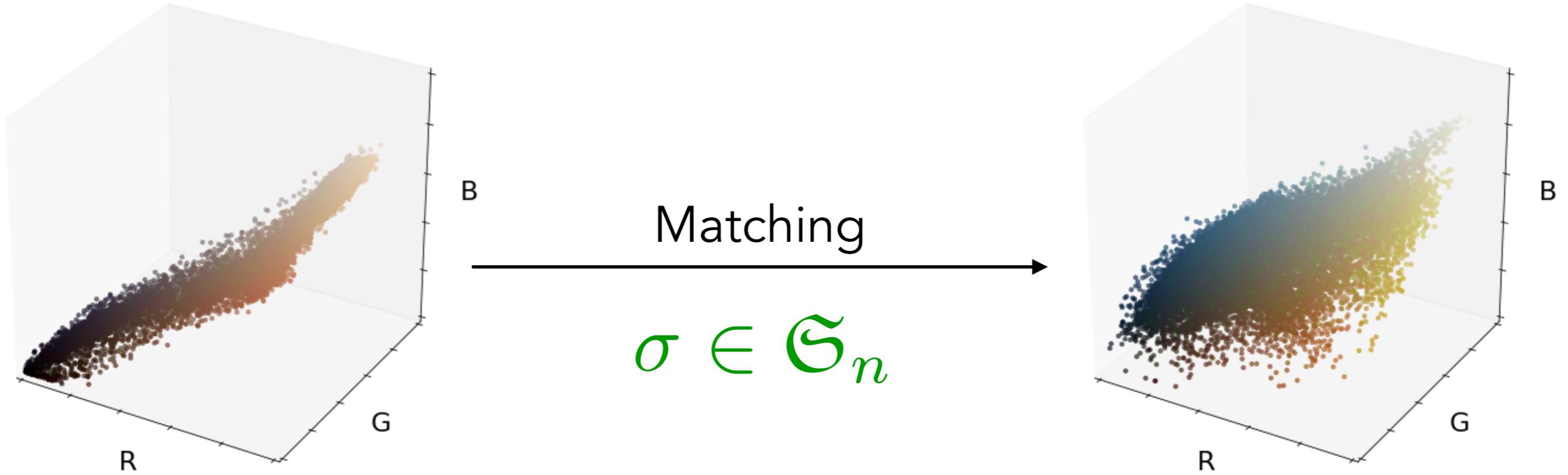
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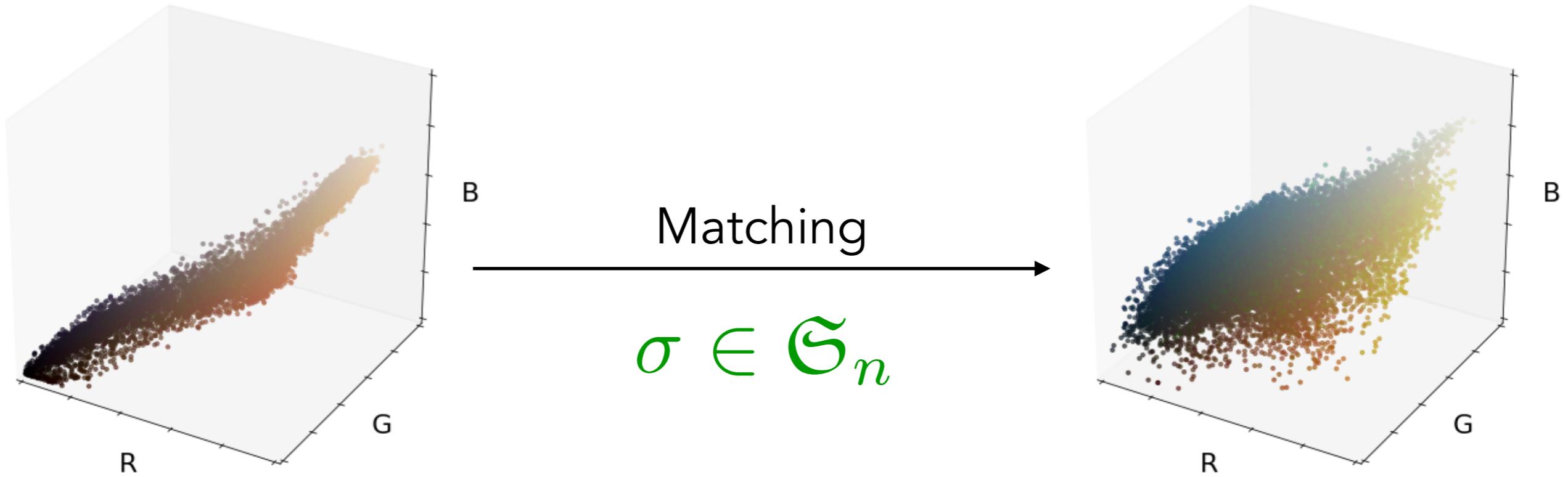
$$y_1, \dots, y_n$$

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \|x_i - y_{\sigma(i)}\|^2$$



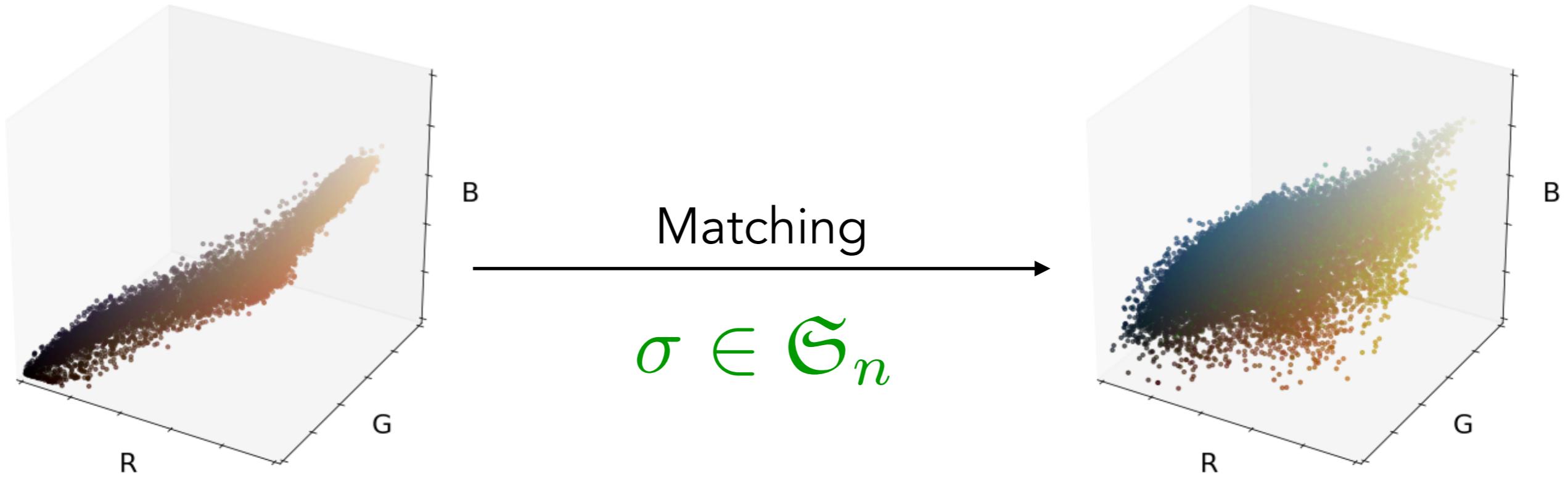
Discrete Monge Problem (1781)

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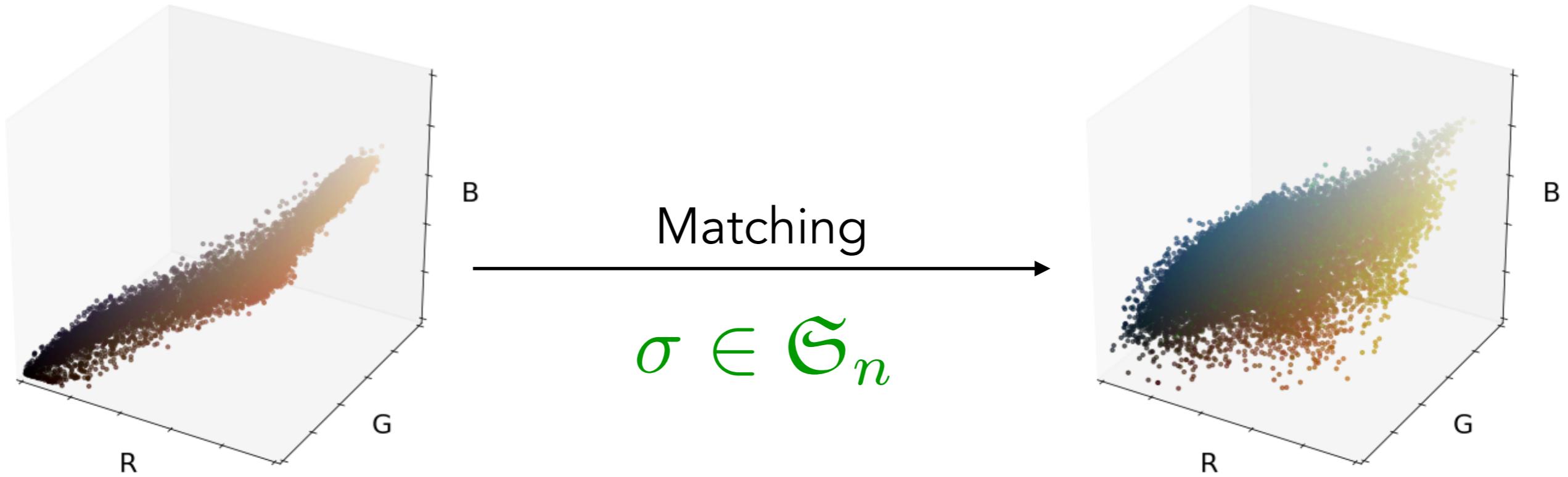
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- (i) How to handle repeated points ?
- (ii) How to handle different numbers of points ?
- (iii) How to compute this combinatorial problem ?

OPTIMAL TRANSPORT



Leonid Kantorovich

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \| \textcolor{red}{x}_{\textcolor{red}{i}} - \textcolor{blue}{y}_{\sigma(i)} \|^2$$

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \sum_{j=1}^n \| \textcolor{red}{x}_{\textcolor{red}{i}} - \textcolor{blue}{y}_j \|^2 \, 1_{\sigma(\textcolor{violet}{i}) = \textcolor{blue}{j}}$$

$$\min_{P \in \mathfrak{P}_n} \sum_{i=1}^n \sum_{j=1}^n \| \textcolor{red}{x_i} - \textcolor{blue}{y_j} \|^2 P_{ij}$$

$$\mathfrak{P}_n = \left\{ P \in \mathbb{R}^{n \times n} \text{ permutation matrix} \right\}$$

$$\min_{P \in \mathfrak{P}_n} \sum_{i=1}^n \sum_{j=1}^n \|x_i - y_j\|^2 P_{ij}$$

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We only have to convexify and generalize \mathfrak{P}_n .

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If $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$ are probability weights, we define the associated **transportation polytope**:

$$\min_{P \in \mathfrak{P}_n} \sum_{i=1}^n \sum_{j=1}^n \|\textcolor{red}{x}_i - \textcolor{blue}{y}_j\|^2 P_{ij}$$

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If $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$ are probability weights, we define the associated **transportation polytope**:

$$\mathfrak{U}(\mathbf{a}, \mathbf{b}) = \{P \in \mathbb{R}_+^{n \times m} \mid P\mathbf{1}_m = \mathbf{a}, P^\top \mathbf{1}_n = \mathbf{b}\}$$

Discrete Kantorovitch Problem

$$W_2^2(\mu, \nu) = \min_{P \in \mathfrak{U}(\mathbf{a}, \mathbf{b})} \sum_{i=1}^n \sum_{j=1}^m \|x_i - y_j\|^2 P_{ij}$$

where $\mu = \sum_{i=1}^n \mathbf{a}_i \delta_{x_i}$ and $\nu = \sum_{j=1}^m \mathbf{b}_j \delta_{y_j}$ are probability measures

2-Wasserstein distance

If $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$ are probability weights, we define the associated **transportation polytope**:

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**Why
should we
care?**

Many applications in Machine Learning, some related to Astrophysics:

- Brenier et al., Reconstruction of the early Universe as a convex optimization problem 1999
- Wasserstein Dictionary Learning
- Computer Graphics
- Generative Models
- Model fitting (Minimum Kantorovich Estimators)

In practice, one color should be mapped to exactly one color. In other words, we want to find a map

$$T : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

that is optimal in some sense.



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Monge problem

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$$\inf_{T \sharp \mu = \nu} \int \| x - T(\textcolor{red}{x}) \|^2 d\mu(x)$$

Monge problem

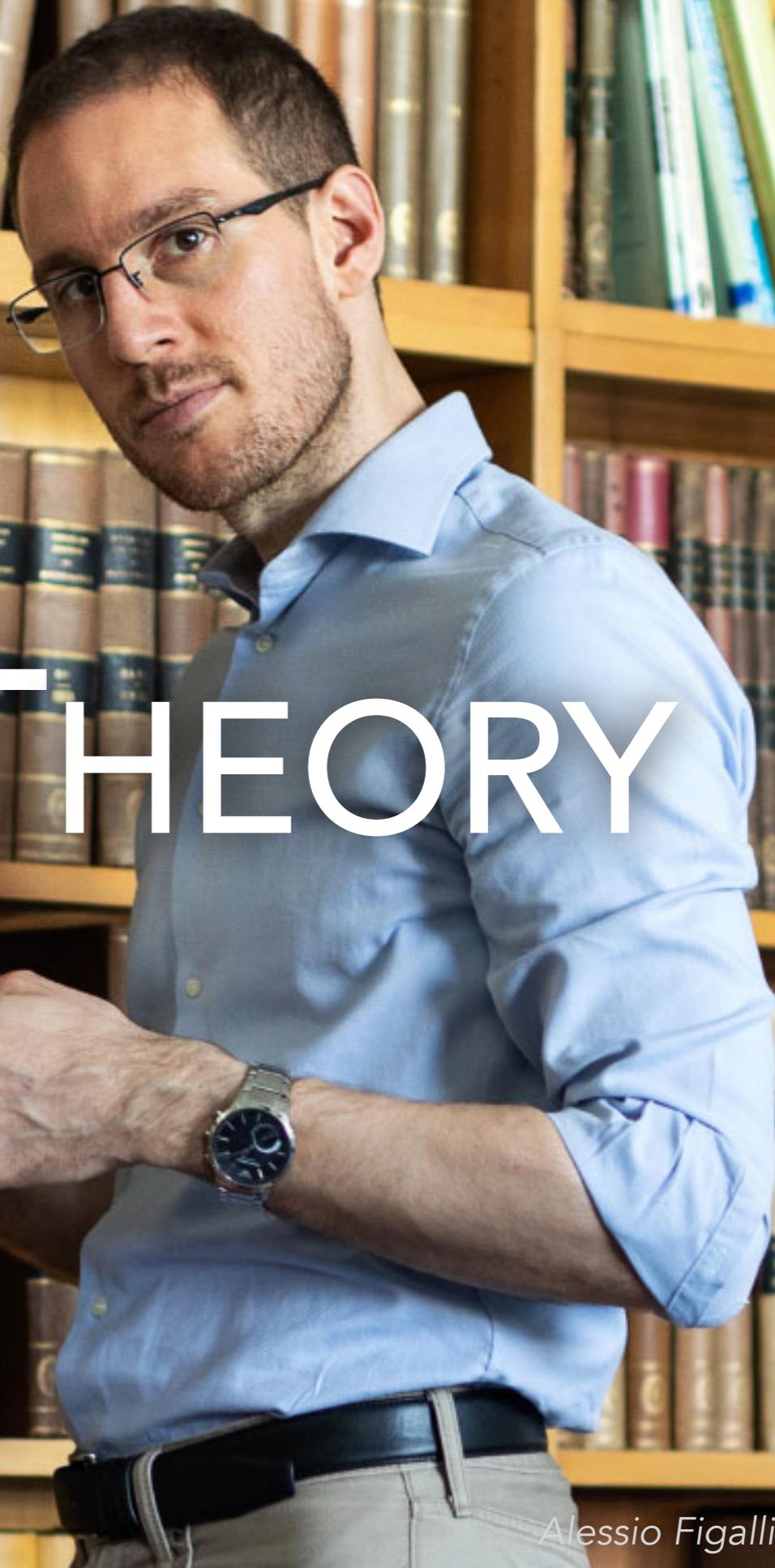
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$$X \sim \mu \implies T(X) \sim \nu$$

REGULARITY THEORY



Alessio Figalli

Let μ and ν be two probability measures over \mathbb{R}^d .

$$\inf_{T \# \mu = \nu} \int \|x - T(x)\|^2 d\mu(x)$$

When does the Monge problem admit a solution ?
What can be said about it ?

Let μ and ν be two probability measures over \mathbb{R}^d .

$$\inf_{T \# \mu = \nu} \int \|x - T(x)\|^2 d\mu(x)$$

Brenier Theorem

1. If μ is *absolutely continuous* with respect to the Lebesgue measure, the Monge problem admits a unique solution
2. If the Monge problem admits a solution T , then there exists a convex function f , called a **Brenier potential**, s.t.

$$T = \nabla f$$

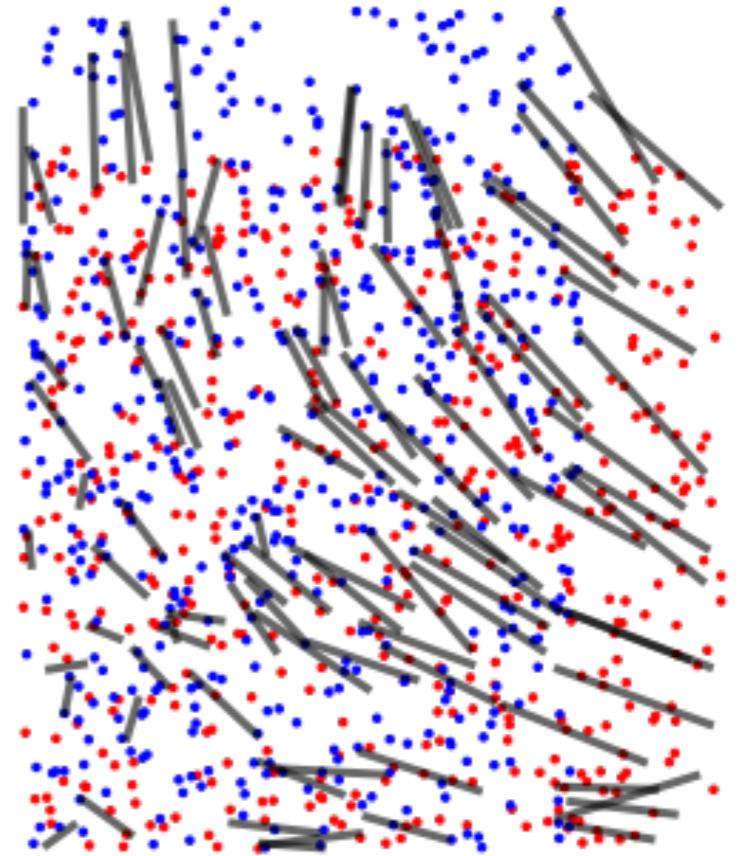
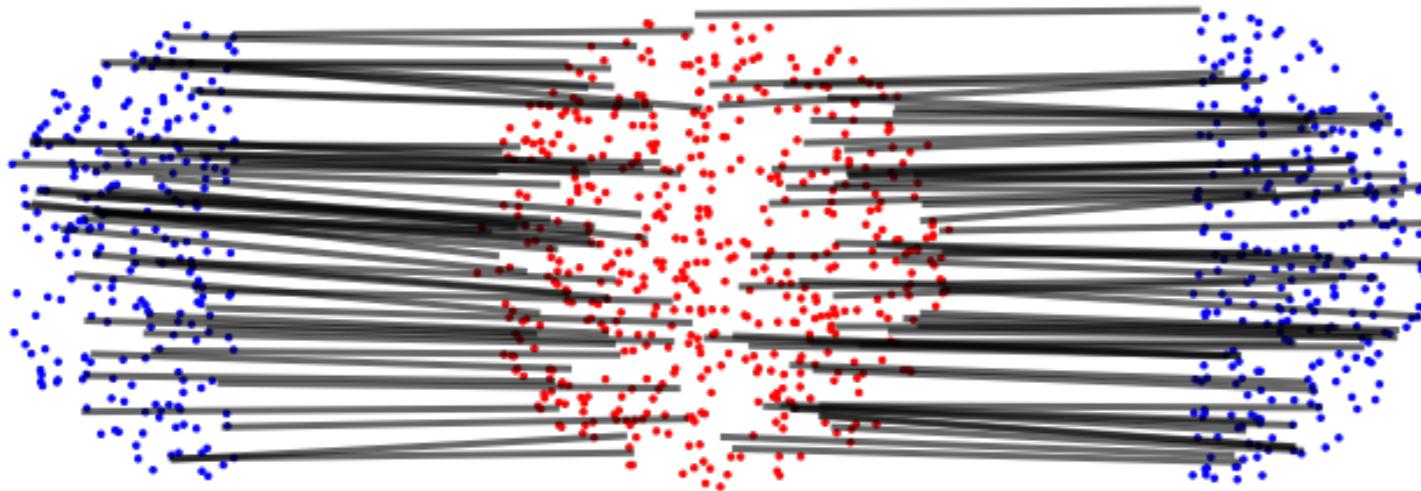
When the optimal map exists (e.g. when μ has a density), what kind of regularity does it exhibit ?

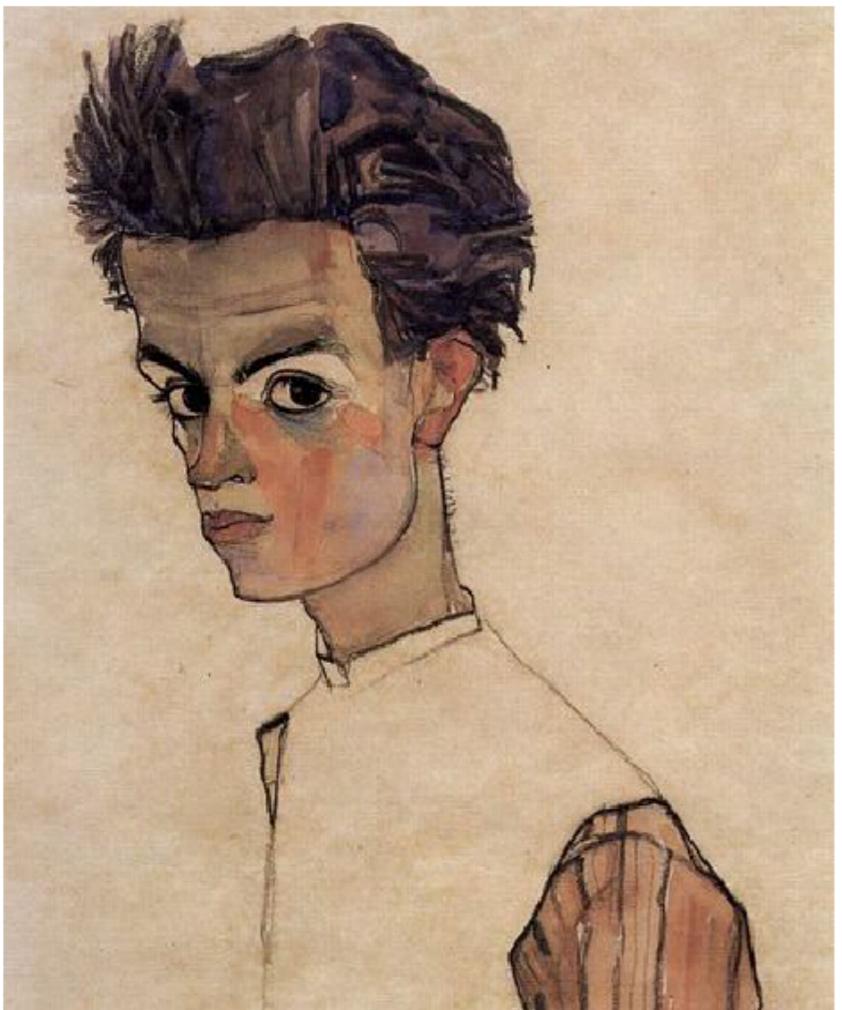
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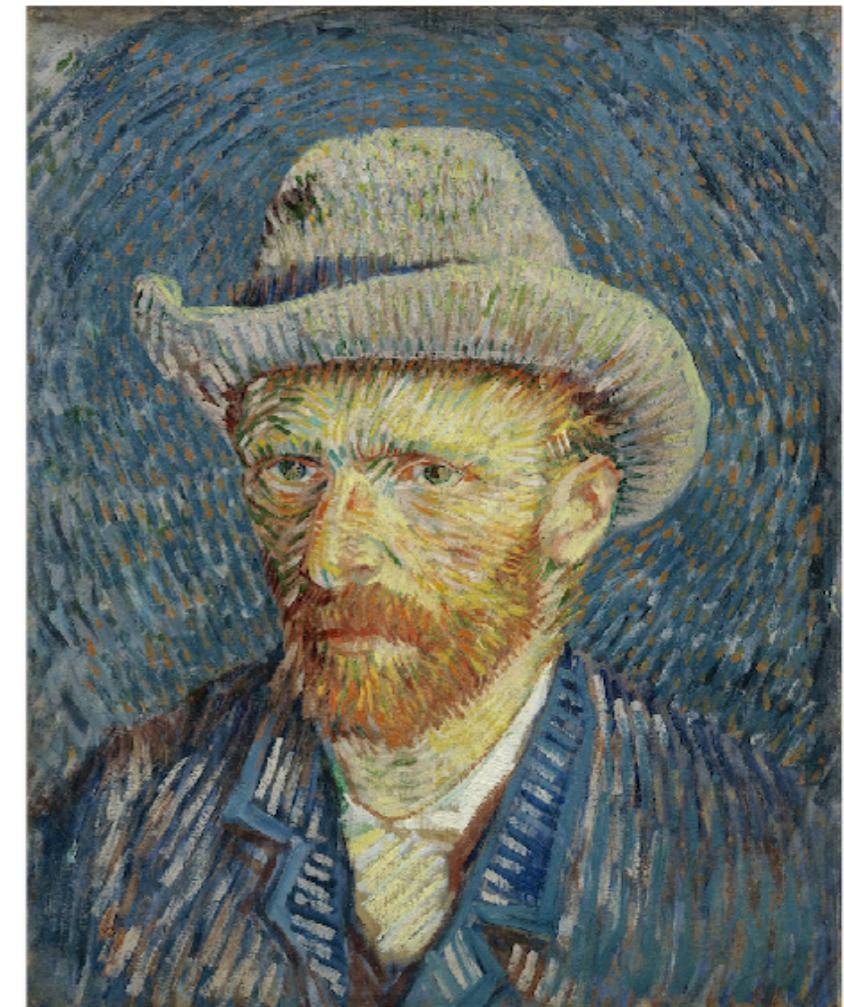
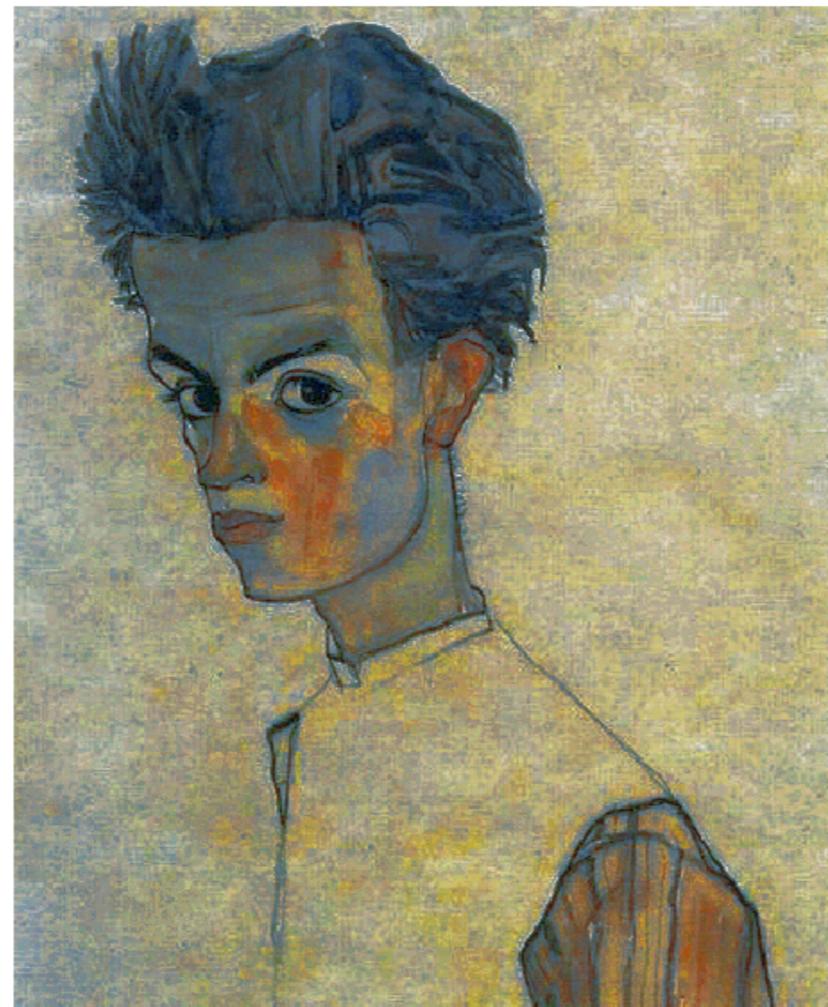
Without further assumptions on μ and ν , we cannot even hope for continuity. Many results by Caffarelli, De Philippis, Kim, Figalli...

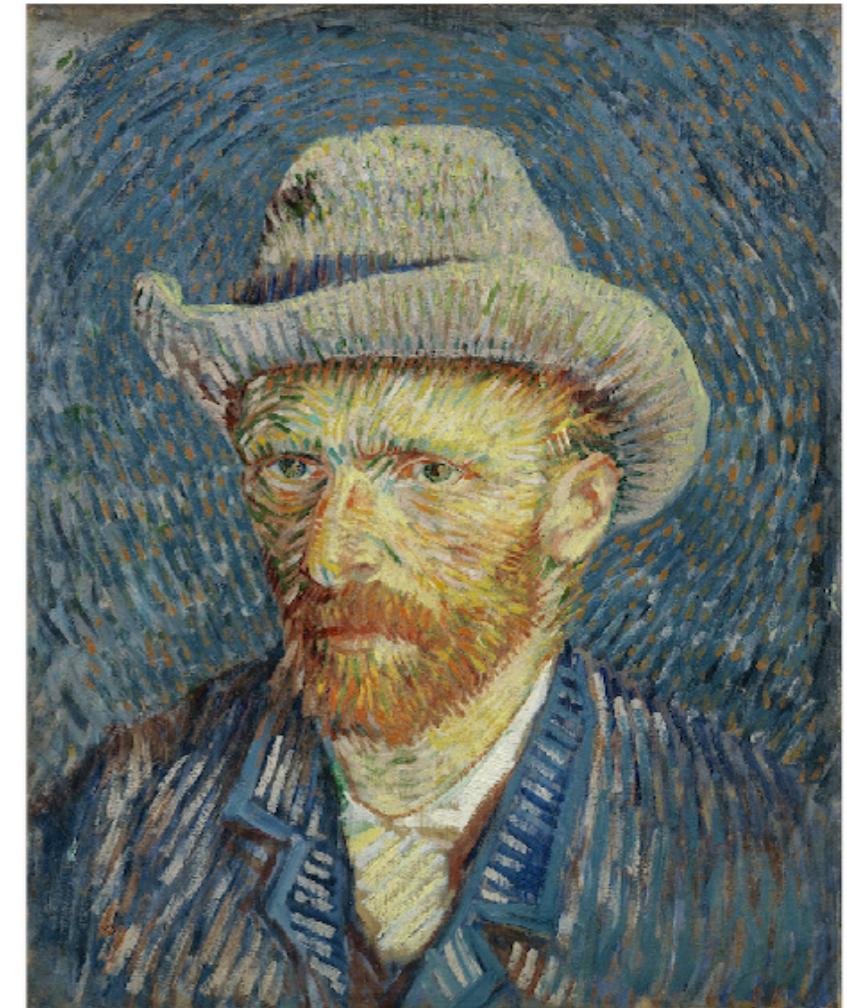
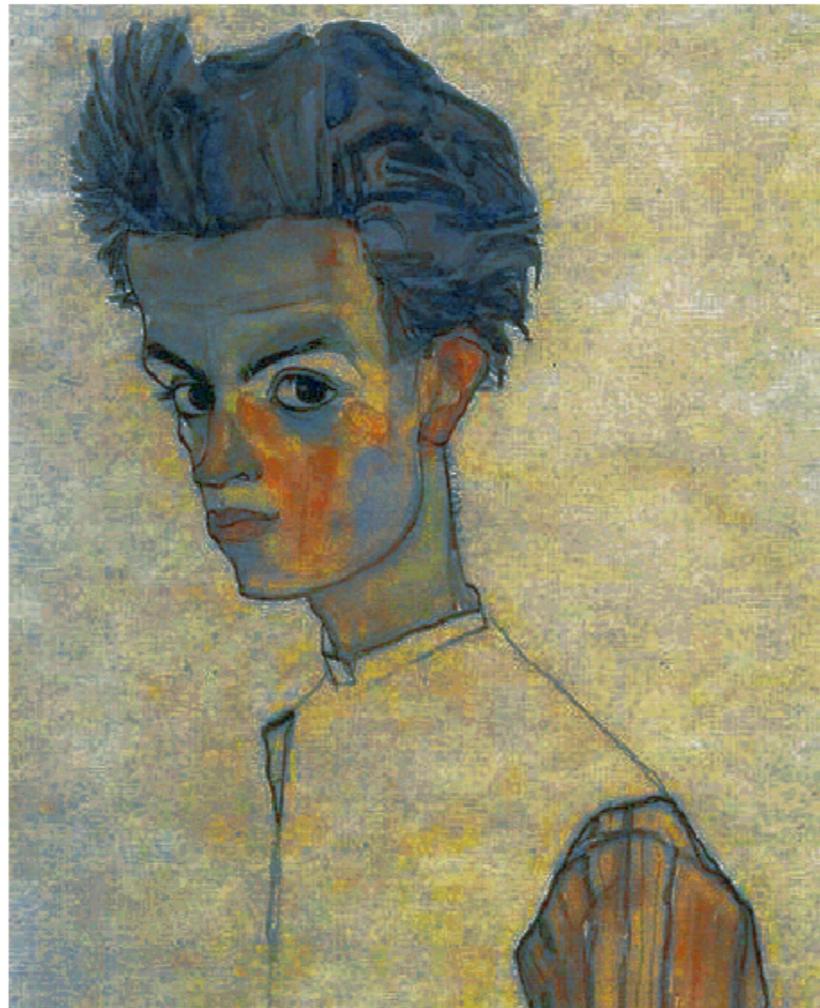
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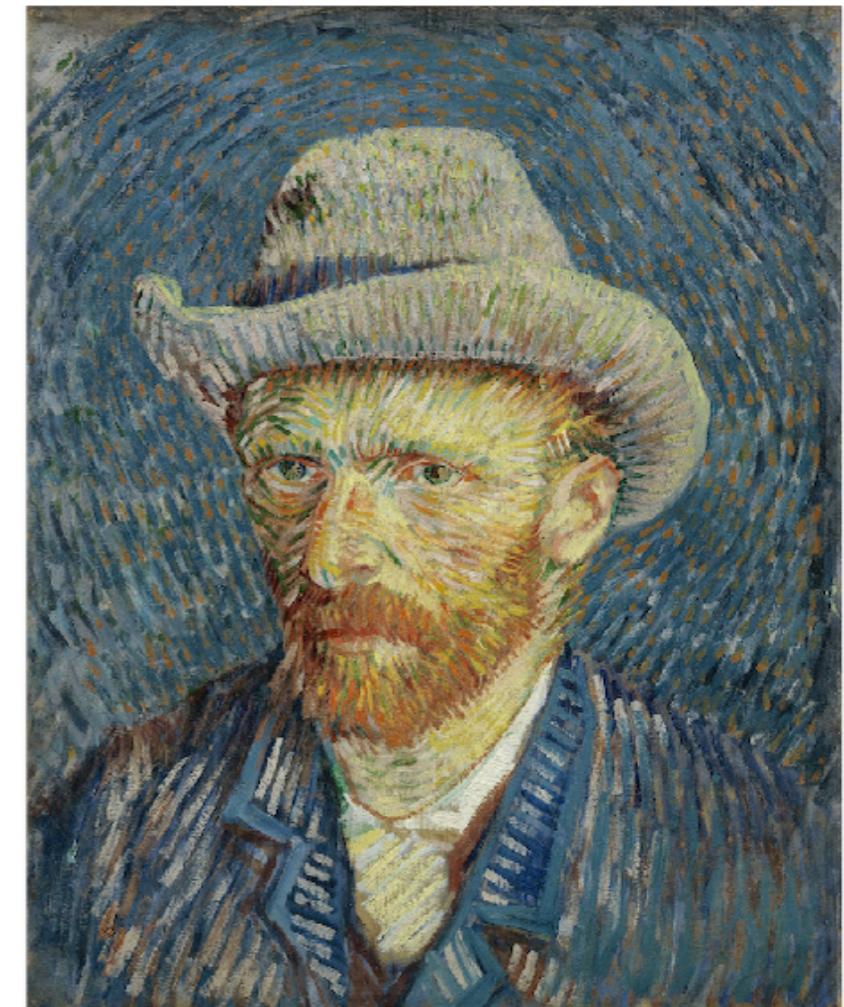
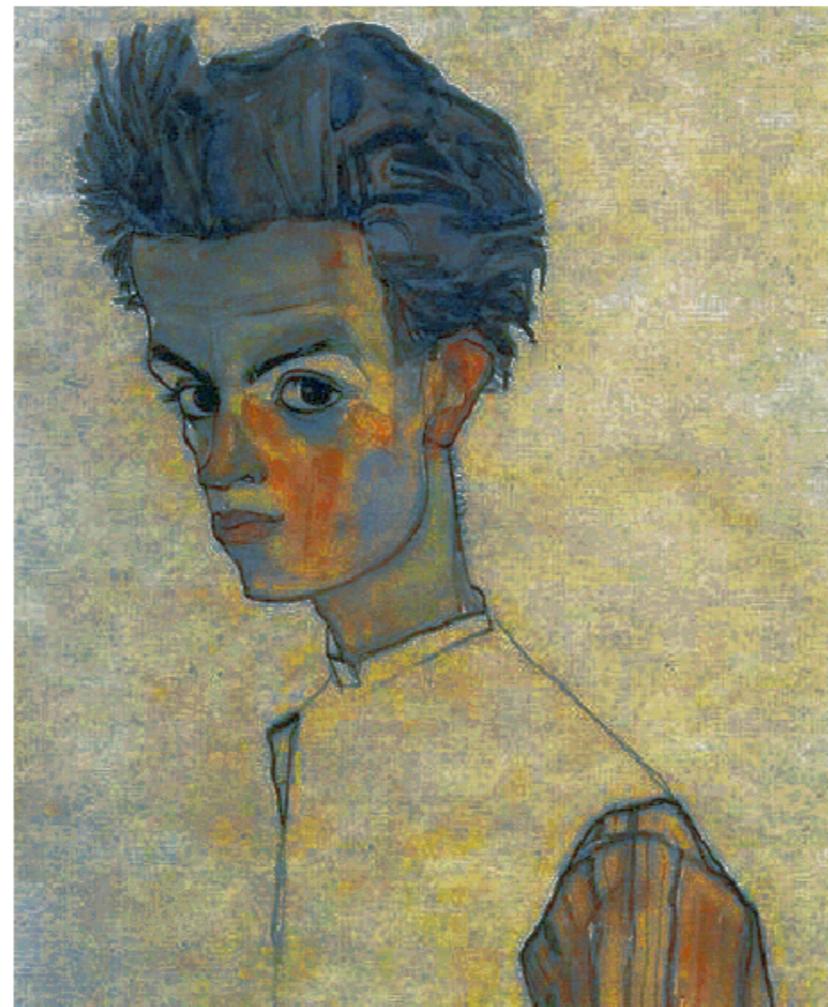


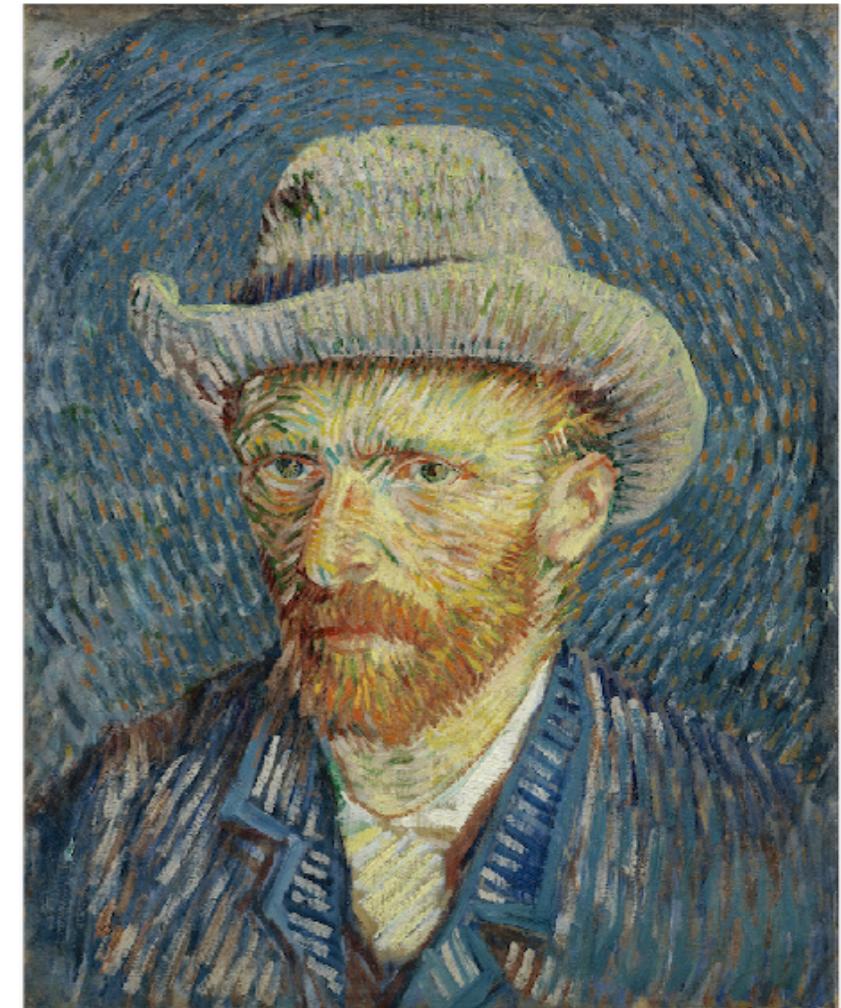
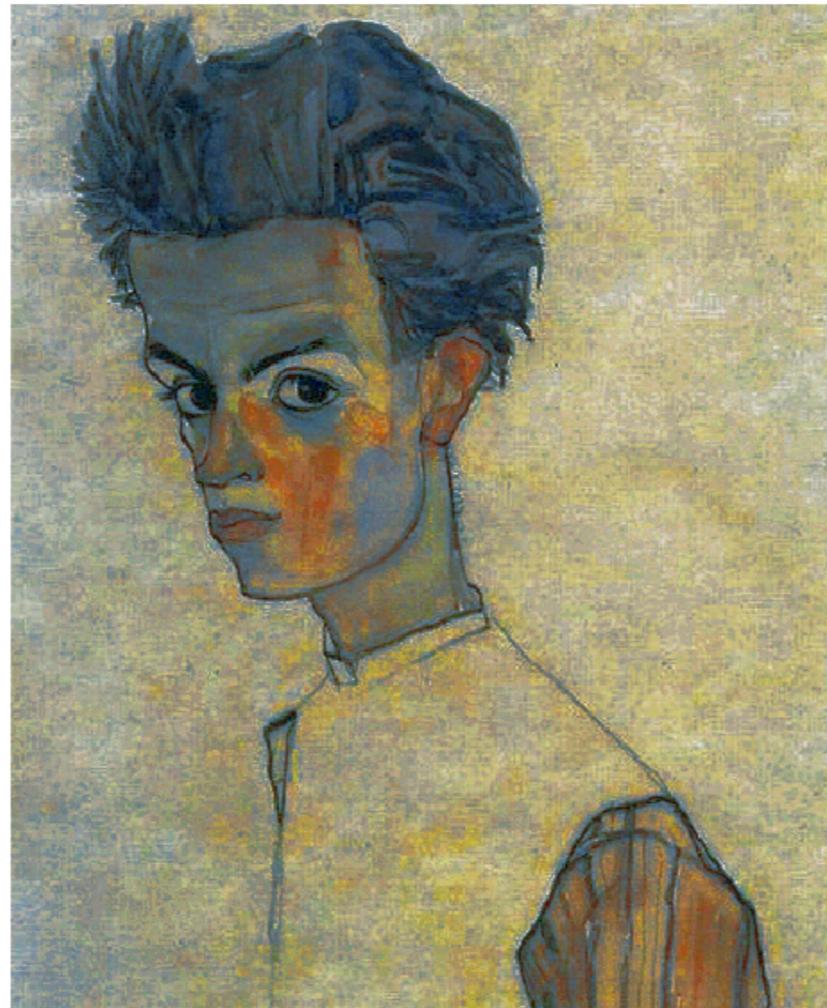




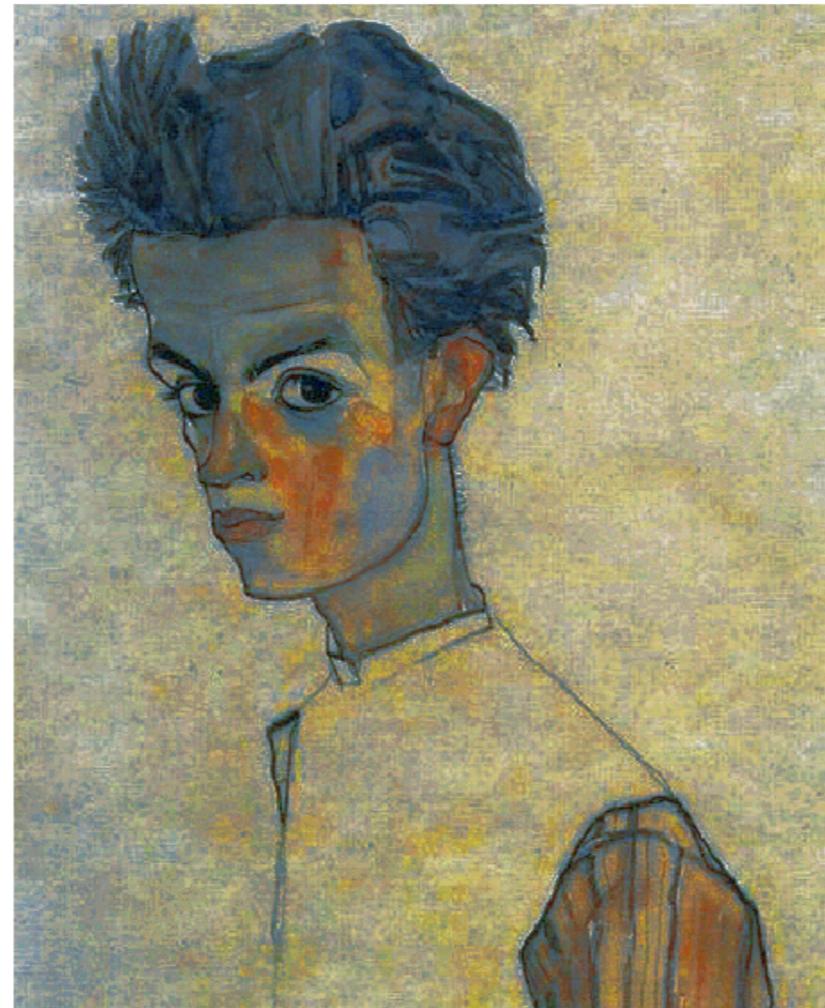
Instead of finding assumptions under which the optimal map exists and exhibits some regularity, we will enforce such regularity directly in the OT problem.

SMOOTH AND STRONGLY CONVEX BRENIER POTENTIALS



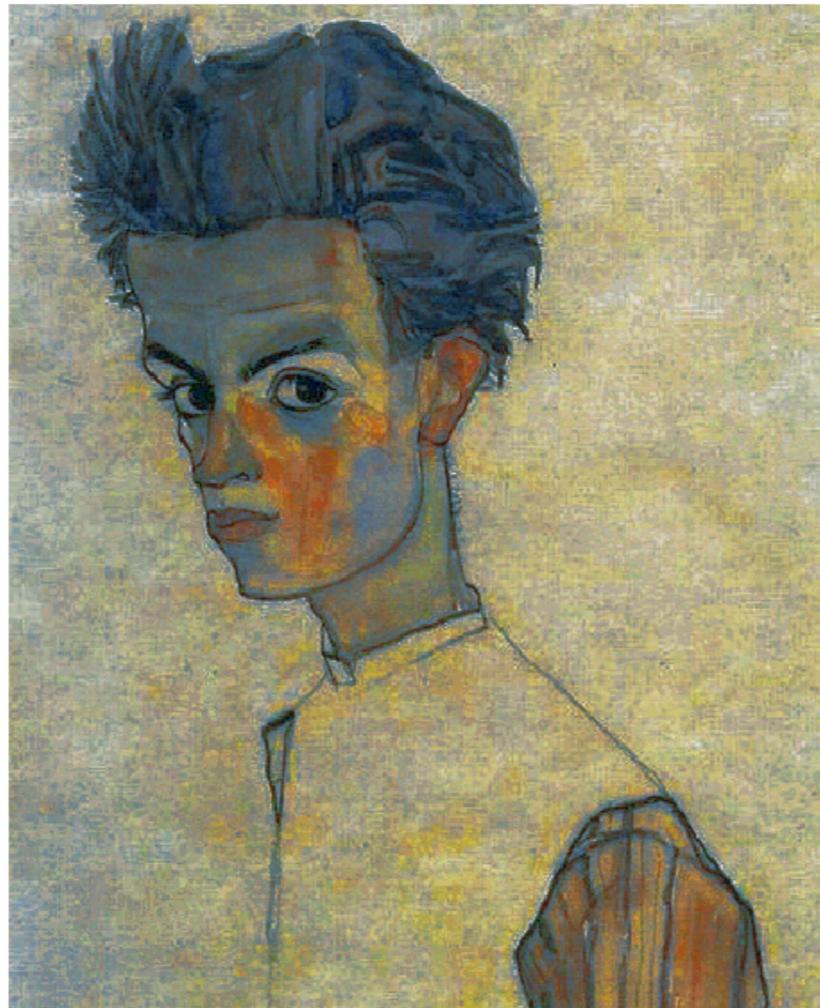


$$\ell\|x - y\| \leq \|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\|$$



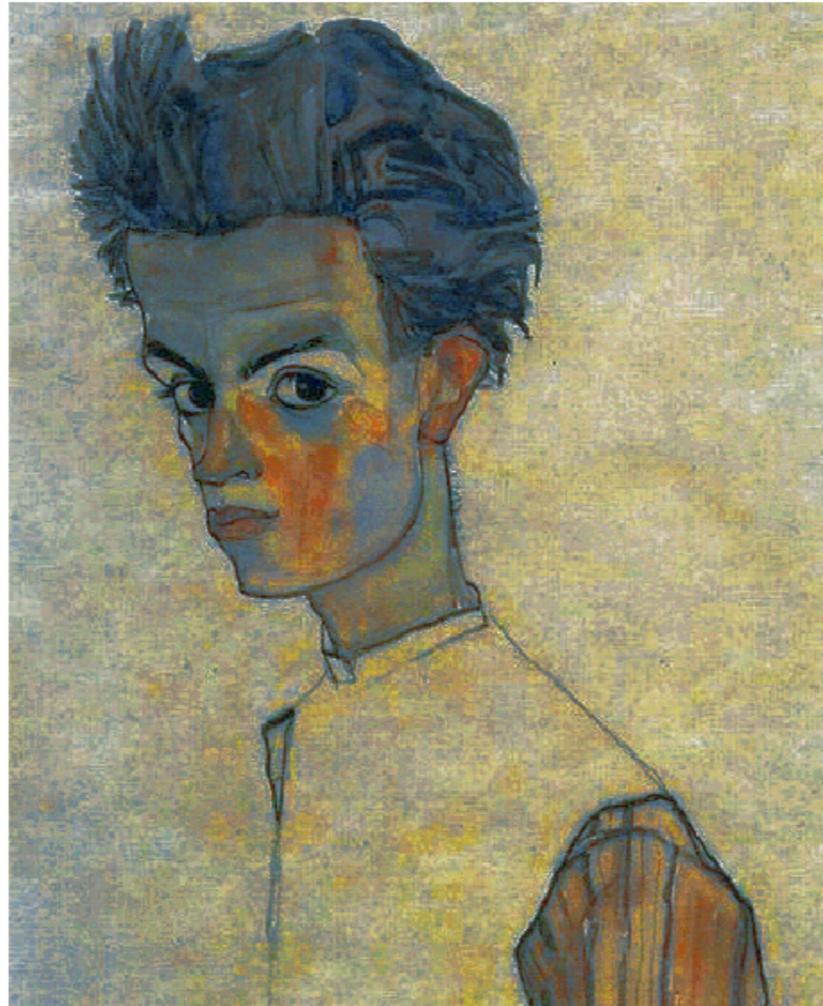
$$\ell\|x - y\| \leq \|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\|$$

We ask that $T = \nabla f$ is a bi-Lipschitz map



$$\ell\|x - y\| \leq \|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\|$$

We ask that f is **smooth** and **strongly convex**



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We ask that f is **smooth** and **strongly convex**

$$\hookrightarrow f \in \mathcal{F}_{\ell, L}$$

But there may not even such a regular f that is admissible for the Monge problem, i.e. such that $(\nabla f)_{\sharp} \mu = \nu$.

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Instead, we will try to best approximate ν as a push-forward of μ through a regular map:

$$\min_{f \in \mathcal{F}_{\ell, L}} W_2 [\nabla f_{\sharp} \mu, \nu]$$

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Smooth and Strong Convex

Brenier Potentials

Even when the measures are discrete, this is a
infinite dimensional optimization problem !

$$\min_{\textcolor{green}{f} \in \mathcal{F}_{\ell,L}} W_2 [\nabla f \sharp \textcolor{red}{\mu}, \textcolor{blue}{\nu}]$$

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$$\min_{f \in \mathcal{F}_{\ell,L}} W_2 [\nabla f \sharp \mu, \nu]$$

$$\min_{\substack{z_1, \dots, z_n \in \mathbb{R}^d \\ u \in \mathbb{R}^n}} W_2^2 \left(\sum_{i=1}^n a_i \delta_{z_i}, \nu \right)$$

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$$u_i \geq u_j + \langle z_j, x_i - x_j \rangle$$

$$+ \frac{1}{2(1 - \ell/L)} \left(\frac{1}{L} \|z_i - z_j\|^2 + \ell \|x_i - x_j\|^2 - 2 \frac{\ell}{L} \langle z_j - z_i, x_j - x_i \rangle \right)$$

$$\textcolor{red}{x}_1,\ldots,\textcolor{red}{x}_n \sim \mu$$

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{\textcolor{red}{x}_i}$$

$$y_1,\ldots,y_n \sim \nu$$

$$\hat{\nu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{\textcolor{blue}{y}_i}$$

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$$\textcolor{violet}{f}^\star \in \argmin_{\textcolor{violet}{f} \in \mathcal{F}_{\ell,L}} W_2\left[\nabla f_\sharp \hat{\mu}_n, \hat{\nu}_n\right]$$

$$\textcolor{red}{x}_1,\ldots,\textcolor{red}{x}_n \sim \mu$$

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{\textcolor{red}{x}_i}$$

$$y_1,\ldots,y_n \sim \nu$$

$$\hat{\nu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{\textcolor{blue}{y}_i}$$

$$\overrightarrow{f^\star}\in\argmin_{\textcolor{violet}{f}\in\mathcal{F}_{\ell,L}} W_2\left[\nabla f_\sharp\hat{\mu}_n,\hat{\nu}_n\right]$$

$$z_1^\star,\dots,z_n^\star,u^\star$$

$$x_1, \dots, x_n \sim \mu$$

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$$\begin{array}{c} \curvearrowright \\ f^\star \in \arg \min_{f \in \mathcal{F}_{\ell,L}} W_2 [\nabla f_\sharp \hat{\mu}_n, \hat{\nu}_n] \end{array}$$

$$z_1^\star, \dots, z_n^\star, u^\star$$

We can easily compute the map on any new point \mathcal{X} by solving a cheap QCQP

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$$z_1^\star, \dots, z_n^\star, u^\star$$

We can easily compute the map on any new point $\textcolor{brown}{x}$ by solving a cheap QCQP

$$\min_{v \in \mathbb{R}, g \in \mathbb{R}^d} v$$

$$\text{s.t. } \forall i, v \geq u_i + \langle \textcolor{green}{z}_i^\star, \textcolor{brown}{x} - \textcolor{red}{x}_i \rangle$$

$$+ \frac{1}{2(1 - \ell/L)} \left(\frac{1}{L} \|g - \textcolor{green}{z}_i^\star\|^2 + \ell \|\textcolor{brown}{x} - \textcolor{red}{x}_i\|^2 - 2 \frac{\ell}{L} \langle \textcolor{green}{z}_i^\star - g, \textcolor{red}{x}_i - \textcolor{brown}{x} \rangle \right)$$

$$x_1, \dots, x_n \sim \mu$$

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$$

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$$f^* \in \arg \min_{f \in \mathcal{F}_{\ell,L}} W_2 [\nabla f \sharp \hat{\mu}_n, \hat{\nu}_n]$$

$$z_1^*, \dots, z_n^*, u^*$$

We can easily compute the map on any new point x by solving a cheap QCQP

This defines an estimator ∇f^* of the optimal transport map sending μ to ν

$$x_1, \dots, x_n \sim \mu$$

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$$z_1^\star, \dots, z_n^\star, u^\star$$

We can easily compute the map on any new point \mathfrak{x} by solving a cheap QCQP

This defines an estimator ∇f^\star of the optimal transport map sending μ to ν

We define the SSNB estimator as a plug-in:

$$x_1, \dots, x_n \sim \mu$$

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$$

$$y_1, \dots, y_n \sim \nu$$

$$\hat{\nu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$$

 $f^* \in \arg \min_{f \in \mathcal{F}_{\ell,L}} W_2 [\nabla f \sharp \hat{\mu}_n, \hat{\nu}_n]$

$$z_1^*, \dots, z_n^*, u^*$$

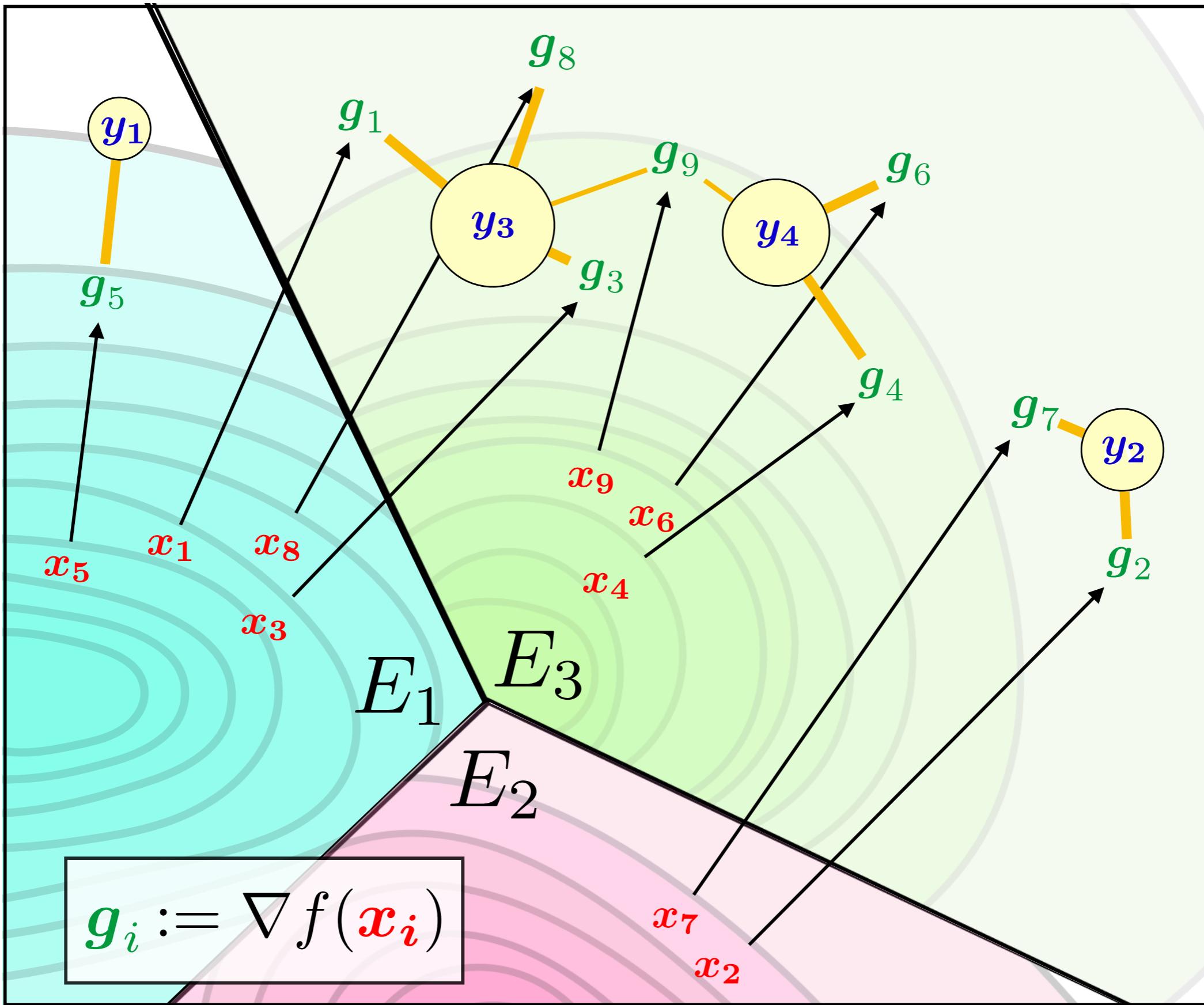
We can easily compute the map on any new point $\textcolor{brown}{x}$ by solving a cheap QCQP

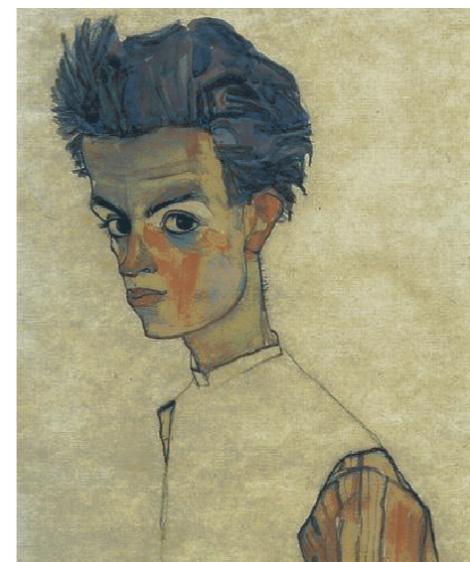
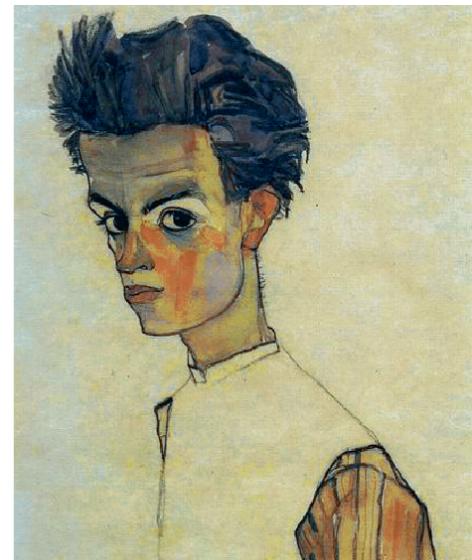
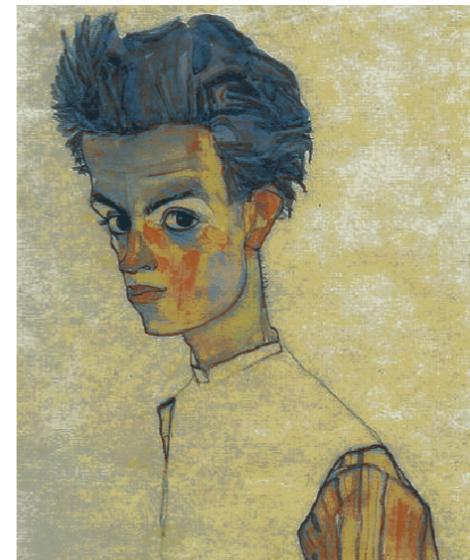
This defines an estimator ∇f^* of the optimal transport map sending μ to ν

We define the SSNB estimator as a plug-in:

$$\widehat{W}_2^2 = \int \| \textcolor{brown}{x} - \nabla f^*(\textcolor{brown}{x}) \|^2 d\mu(\textcolor{brown}{x})$$

Regularity "by part"



 $L = 1$  $\ell = 0$  $\ell = 0.5$  $\ell = 1$  $L = 2$  $L = 5$ 



QUESTIONS ?