

# Regularity as Regularization: Smooth and Strongly Convex Brenier Potentials in Optimal Transport

**Goal:** Estimate Wasserstein distances and Monge maps in high dimension, and regularize OT using regularity.

**Approach:** Enforce a Monge type optimal transport plan with prescribed regularity / distortion.

**Results:** Efficient algorithm in 1D, alternate convex minimization in higher dimension. New estimator for Wasserstein.

## I. Regularity in Optimal Transport

2-Wasserstein Distance

$$W_2^2(\mu, \nu) = \min_{\pi \in \Pi(\mu, \nu)} \int \|x - y\|^2 d\pi(x, y)$$

Brenier Theorem

If  $\mu$  has a density wrt Lebesgue, then the optimal transport plan  $\pi^*$  is deterministic, there exists a (Monge) map  $T^*(x)$  s.t.

$$d\pi^*(x, y) = d\mu(x) \delta_{T^*(x)}(y)$$

Moreover, there exists a convex function (Brenier potential)  $f^*$  s.t.

$$T^* = \nabla f^*$$

Monge-Ampère Equation

If  $\mu$  and  $\nu$  have densities  $p$  and  $q$ , the Brenier potential  $f^*$  is solution to

$$\det(\nabla^2 f) = \frac{p}{q \circ \nabla f}$$

Caffarelli Contraction Theorem

If  $V, W$  are convex, and  $\mu = e^V \gamma$  and  $\nu = e^{-W} \gamma$  where  $\gamma$  is the standard Gaussian, then any optimal Brenier potential  $f^*$  is 1-smooth.

More General Theorems: Caffarelli, De Philippis, Kim, Figalli, etc.

Under some assumptions on the measures (bounded support, convex support, bounded densities, etc.), we can get some (local, Hölder) regularity.

## II. Regularity as Regularization

Smooth and Strongly convex Nearest Brenier Potentials (SSNB)

Given a partition  $\mathcal{E}$  of  $\mathbb{R}^d$ , find a potential  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  s.t. for any cluster  $E \in \mathcal{E}$ ,  $f|_E$  is convex and any  $x, y \in E$ ,

$$\ell\|x - y\| \leq \|\nabla f(x) - \nabla f(y)\| \leq L\|x - y\| \quad (\mathcal{F}_{\ell, L, \mathcal{E}})$$

(Strong convexity and smoothness constraints)

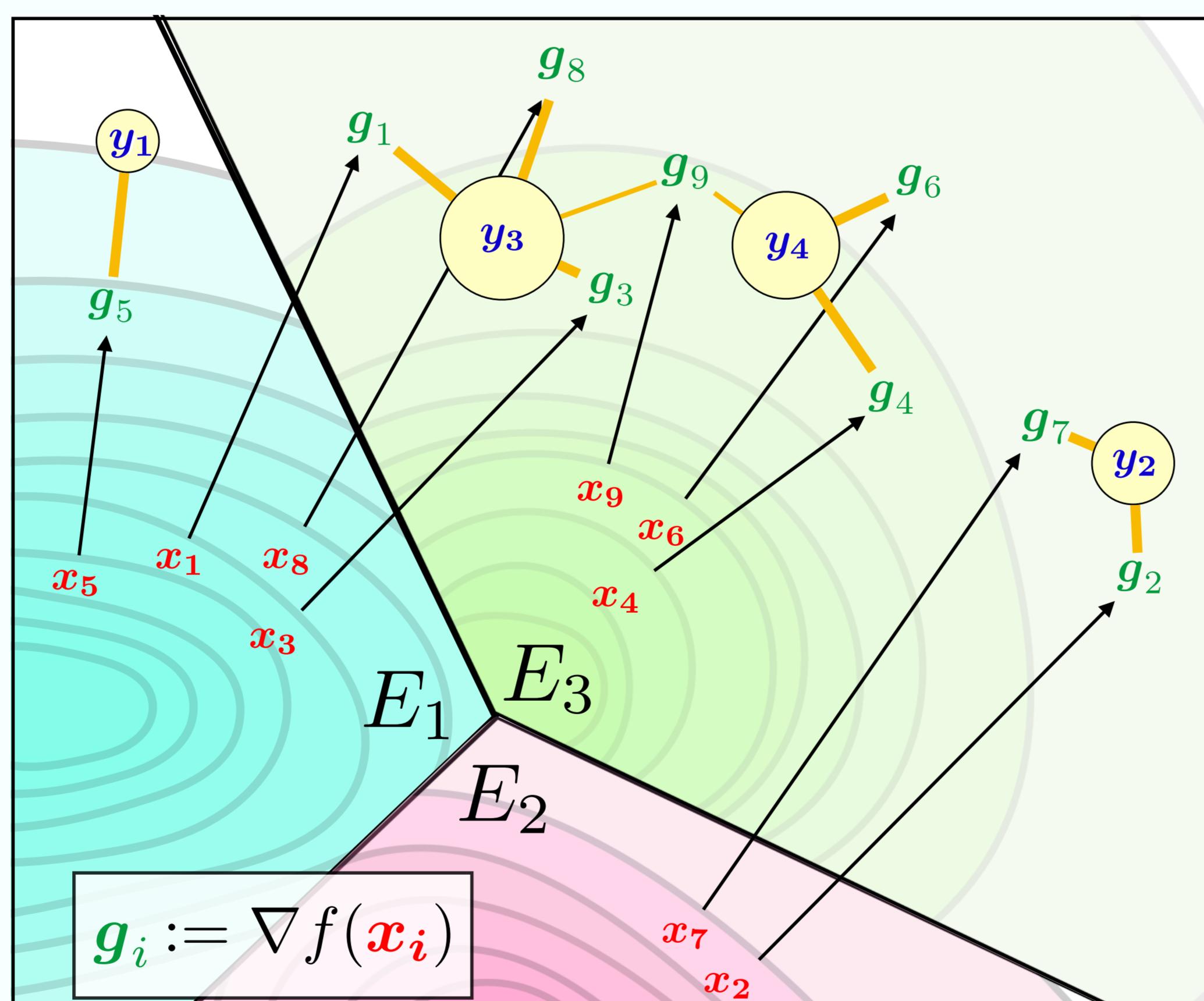
and  $\nabla f$  sends  $\mu$  as close as possible to  $\nu$  :

$$\min_{f \in \mathcal{F}_{\ell, L, \mathcal{E}}} W_2[\nabla f \sharp \mu, \nu]$$

In the discrete setting  $\mu = \sum_{i=1}^n a_i \delta_{x_i}$ , this can be recast as an alternate convex QCQP/OT minimization:

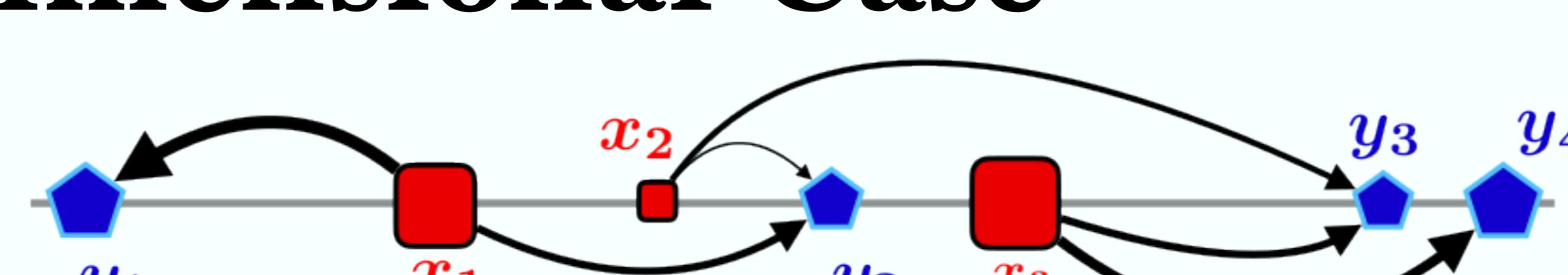
$$\min_{z_1, \dots, z_n \in \mathbb{R}^d, u \in \mathbb{R}^n} W_2^2 \left( \sum_{i=1}^n a_i \delta_{z_i}, \nu \right)$$

$$u_i \geq u_j + \langle z_j, x_i - x_j \rangle \\ + \frac{1}{2(1 - \ell/L)} \left( \frac{1}{L} \|z_i - z_j\|^2 + \ell \|x_i - x_j\|^2 - 2 \frac{\ell}{L} \langle z_j - z_i, x_j - x_i \rangle \right)$$



## III. One-Dimensional Case

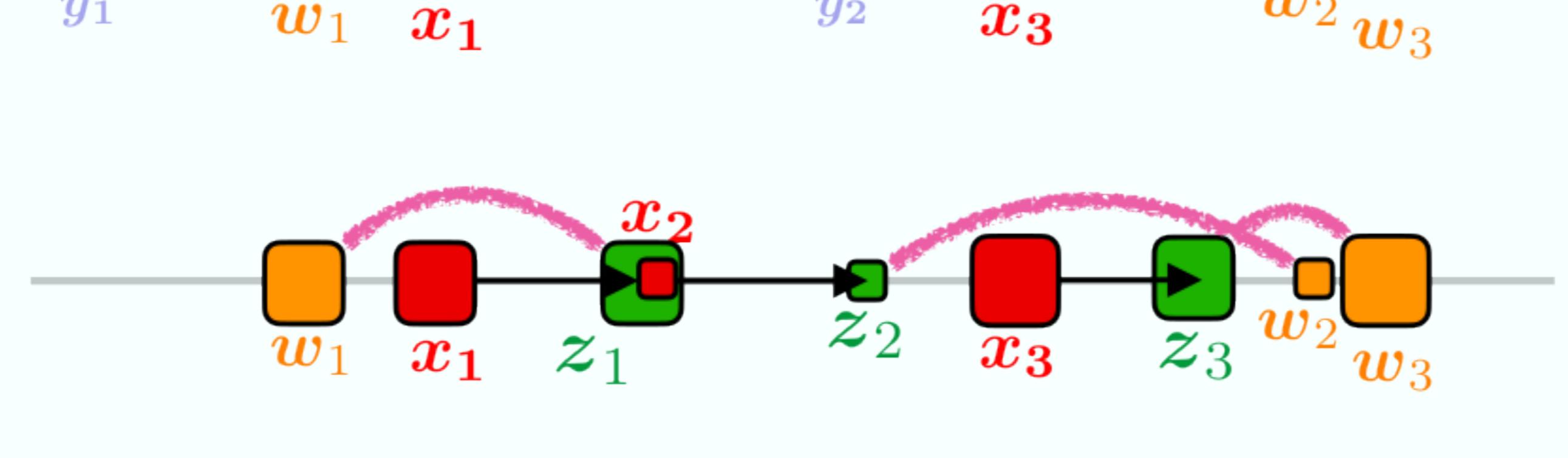
1. Compute classical OT plan



2. Compute the Barycentric Projection



3. Enforce regularity via strong-monotonic and Lipschitz isotonic regression



## IV. Estimation of Monge Map and Wasserstein Distance

Monge Map

Once a SSNB potential  $f^*$  has been computed, we can easily compute the map on any new point  $x \in \mathbb{R}^d$  by solving a cheap QCQP:

$$\begin{aligned} \min_{v \in \mathbb{R}, g \in \mathbb{R}^d} & v \\ \text{s.t. } & \forall i, v \geq u_i + \langle z_i, x - x_i \rangle \\ & + \frac{1}{2(1 - \ell/L)} \left( \frac{1}{L} \|g - z_i\|^2 + \ell \|x - x_i\|^2 - 2 \frac{\ell}{L} \langle z_i - g, x_i - x \rangle \right) \end{aligned}$$

Wasserstein Distance

Draw  $n$  iid samples  $x_1, \dots, x_n \sim \mu$  and  $y_1, \dots, y_n \sim \nu$ , and consider the empirical measures  $\hat{\mu}_n, \hat{\nu}_n$  on those points.

The classical OT estimator of  $W_2(\mu, \nu)$  is  $W_2(\hat{\mu}_n, \hat{\nu}_n)$ .

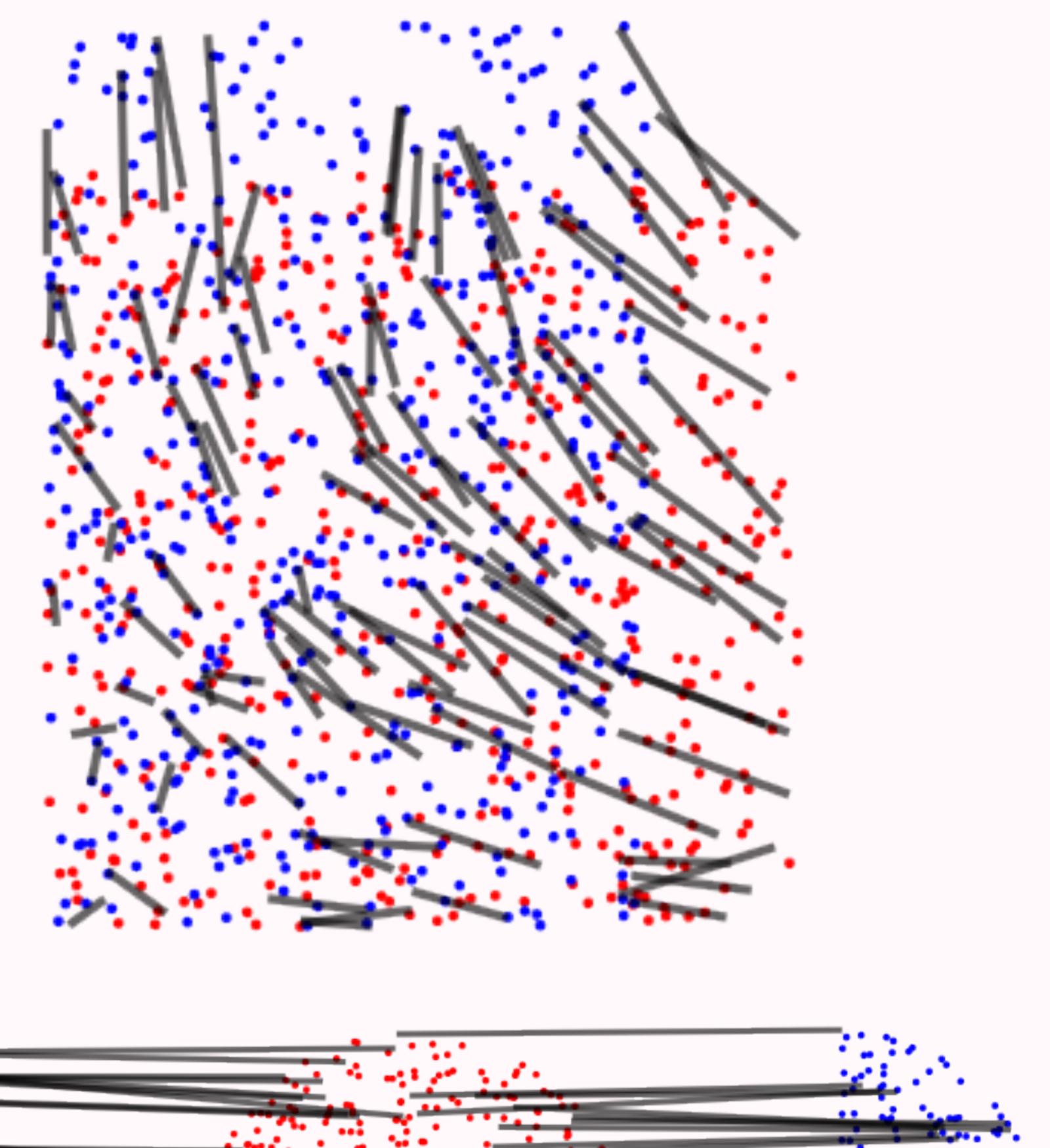
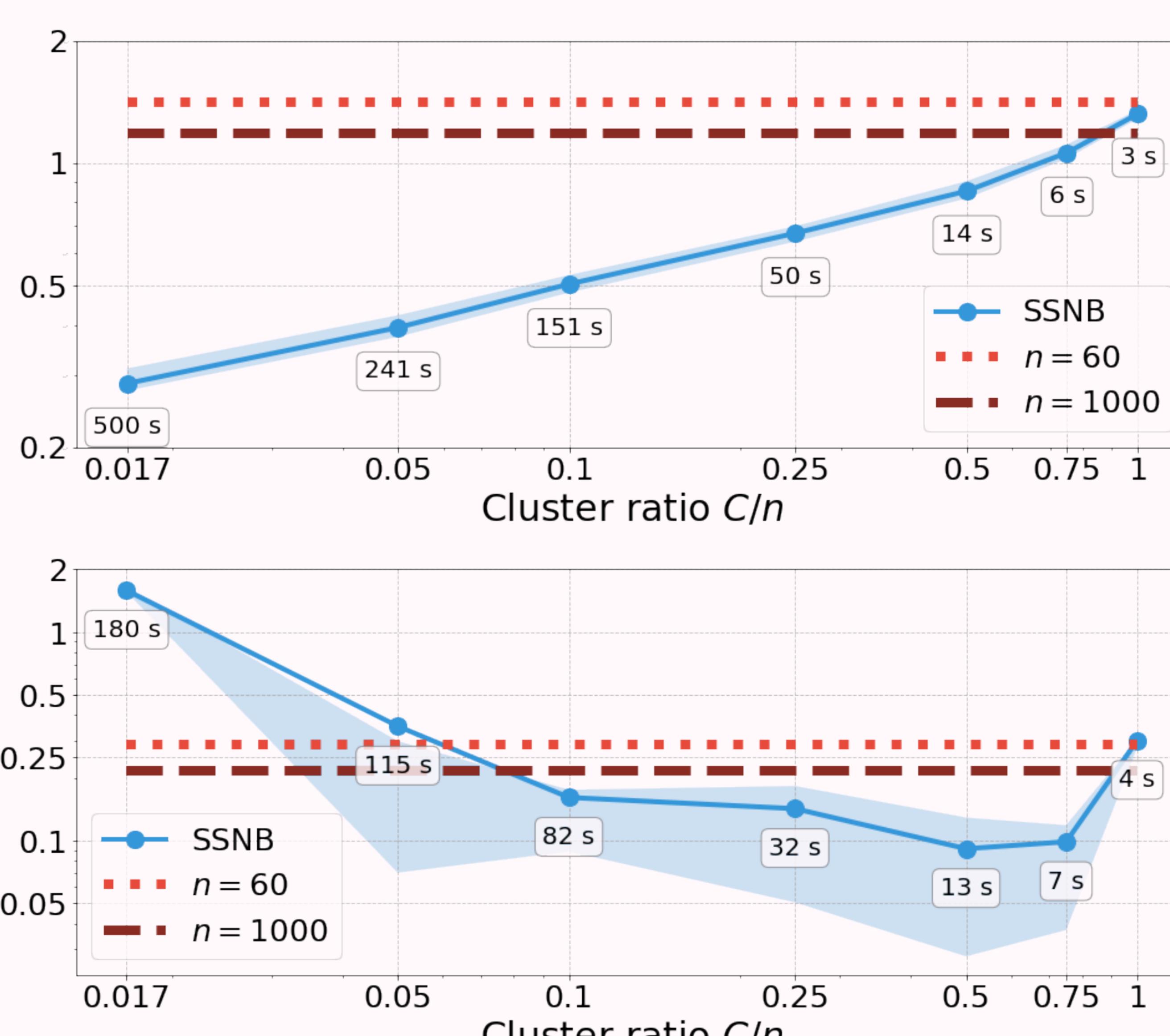
The SSNB estimator is  $W_2(\mu, f^* \sharp \mu)$ . If  $\mathcal{E} = \{\mathbb{R}^d\}$  (global regularity),

$$W_2(\mu, f^* \sharp \mu) = \left( \int \|x - \nabla f^*(x)\|^2 d\mu(x) \right)^{1/2}$$

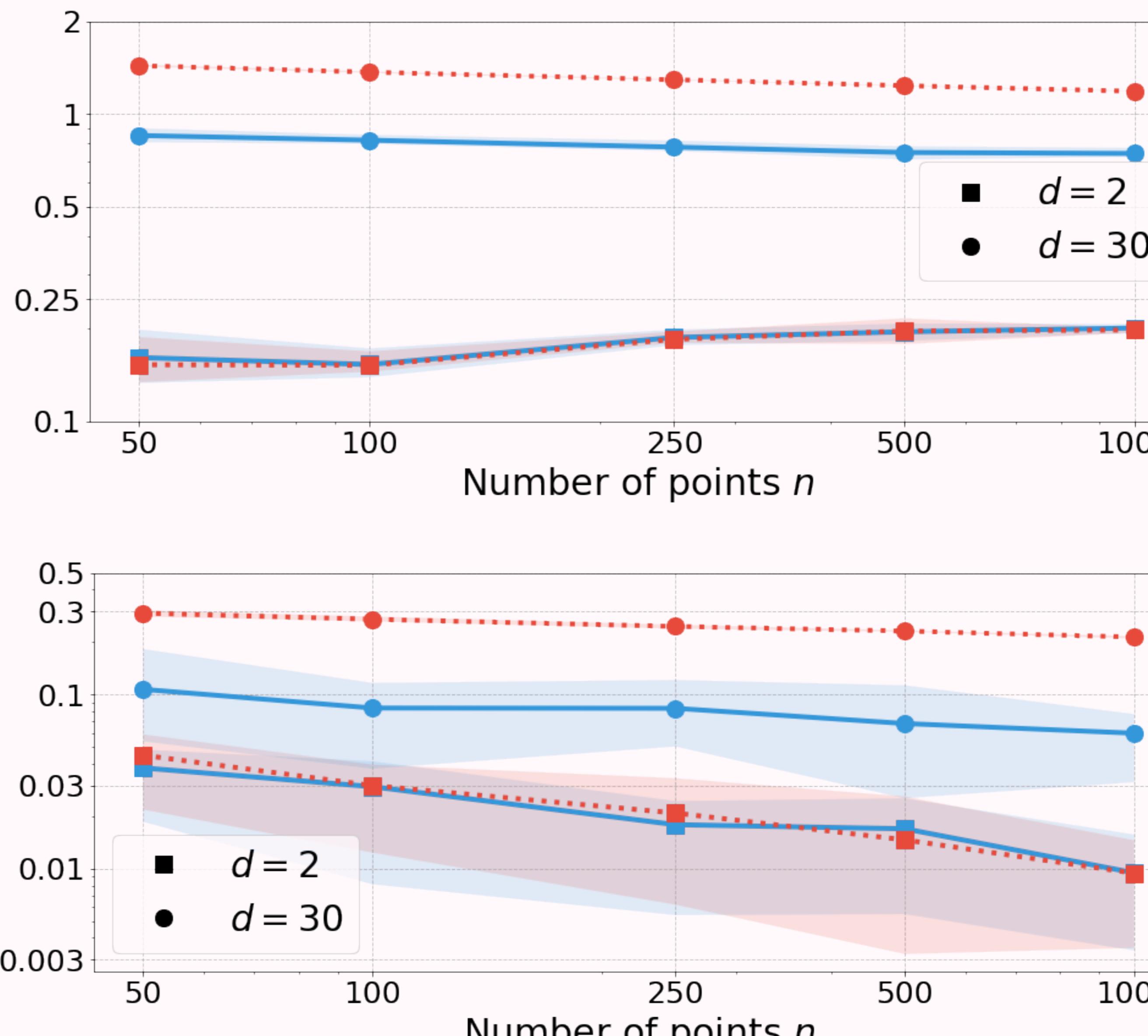
which can be computed using Monte-Carlo integration. If  $\mathcal{E} \neq \{\mathbb{R}^d\}$  (local regularity), this is only an upper bound on  $W_2(\mu, f^* \sharp \mu)$ .

## V. Experiments

Estimation Error Depending on the Number of Clusters



Estimation Error Depending on the Number of Points



Global regularity: trade-off between accuracy and computation time.

Local regularity: many small clusters are better in terms of both accuracy and computation time.

General case: SSNB estimator seem to have classical OT rate, but with a much better constant.